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## DEPARTMENT OF ELECTRONIC AND ELECTRICAL ENGINEERING

Autumn Semester 2012-13 (2.0 hours)

## EEE6021 Energy Utilisation 6

Answer **THREE** questions. **No marks will be awarded for solutions to a fourth question.** Solutions will be considered in the order that they are presented in the answer book. Trial answers will be ignored if they are clearly crossed out. **The numbers given after each section of a question indicate the relative weighting of that section.**

1. a. Describe, with the aid of an appropriate diagram, the basic principle of operation of an alkaline electrolyte fuel cell, and the key factors that may influence its reaction rate. (6)
- b. In an ideal system, the change of molar specific Gibbs free energy of formation  $\Delta \bar{g}_f$  of an alkaline hydrogen fuel cell is fully converted into electrical energy. Derive an expression for the reversible open-circuit voltage of the fuel cell. (5)
- c. The changes of molar specific Gibbs free energy of formation,  $\Delta \bar{g}_f$ , for the basic hydrogen fuel cell reaction as a function of temperature under standard pressure 0.1 MPa (or 1 bar) are given in Table 1.

Table 1		
Form of H <sub>2</sub> O	Temperature °C	$\Delta \bar{g}_f$ (kJ/mole)
Liquid	25	-237.2
Liquid	80	-228.2
Gas	80	-226.1
Gas	100	-225.2
Gas	200	-220.4
Gas	400	-210.3
Gas	600	-199.6
Gas	800	-188.6
Gas	1000	-177.4

Faraday constant = 96485 (C), molar gas constant = 8.314 (J/K/mole).

- (i) Explain the underlying cause of why  $\Delta \bar{g}_f$  decreases with increase in temperature. (2)
- (ii) If oxygen is supplied at a pressure of 2 bars from air with 20.95% oxygen concentration, and pure hydrogen is used at the same pressure, the reaction (5)

produces water vapour at a pressure of 1.8 bars. Calculate the reversible open-circuit voltage of the fuel cell at 200 °C and the maximum theoretical efficiency, given the “high heating value” of hydrogen being 285.84 (kJ/mole).

(iii) If pure oxygen is supplied and other operating conditions are the same, calculate the change in reversible open-circuit voltage. (2)

2. a. Sketch the output voltage versus load current density characteristic of a hydrogen fuel cell operating at a temperature below 100 °C, and describe the main causes of the cell voltage reduction from its ideal value with increasing current density. (10)
- b. Describe the charge double layer effect in a fuel cell, and explain how this effect can be represented in an equivalent electrical circuit. (6)
- c. Figure 1 shows the schematic of a fuel cell powered drive train for electric vehicles. Explain why a DC/DC converter and energy storage devices, e.g., battery or super-capacitors are often required in such a system. (4)

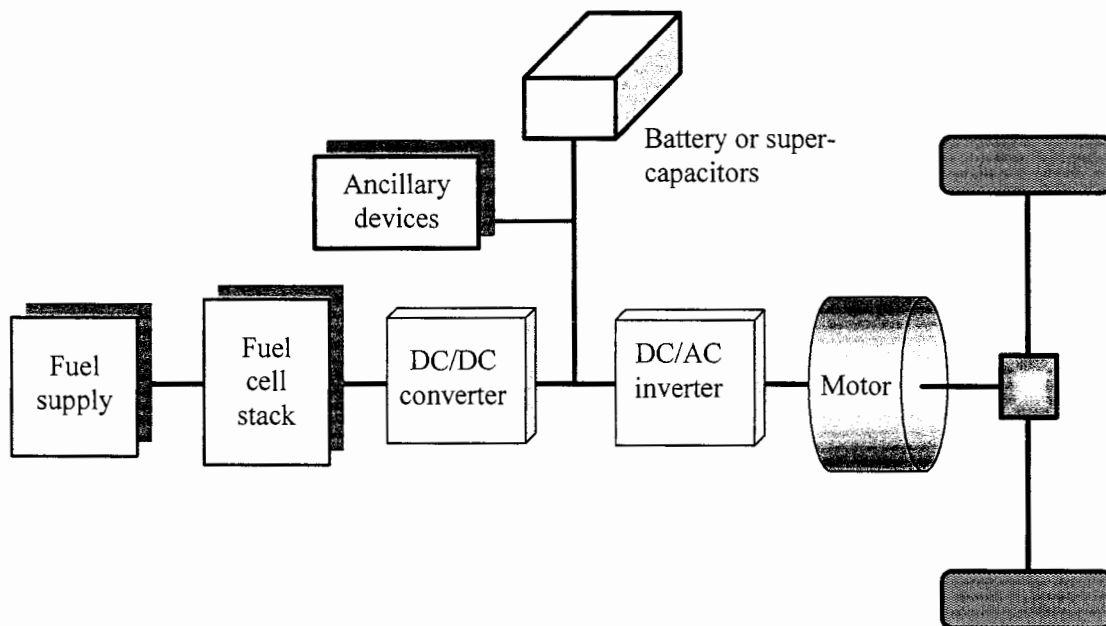


Figure 1

3. A passenger vehicle is fitted with an electric drive train which comprises a battery, a traction brushless dc permanent magnet motor and an IGBT power electronic controller. The traction motor is connected to the vehicle front wheels via a fixed ratio transmission.

Vehicle:

Gross weight	$m = 1200 \text{ kg}$
Rolling resistance coefficient	$\lambda_f = 0.009$
Drag coefficient	$C_d = 0.35$
Frontal area	$A_f = 1.6 \text{ m}^2$
Wheel rolling radius	$r_w = 296.5 \text{ mm}$

Transmission:

Fixed ratio	$R_t = 10/56$
Efficiency	$\eta_t = 95\%$

(You may assume the gravitational acceleration  $g = 9.81 \text{ m/s}^2$  and the density of air  $\rho_a = 1.225 \text{ kg/m}^3$ )

- a. Cite the advantages and disadvantages of super capacitors. (3)
- b. When the traction motor is delivering a maximum torque of  $T_p = 72 \text{ Nm}$ , and the vehicle accelerates from standstill to a speed  $v_c = 60 \text{ MPH}$ :
  - i) Listing any assumptions that you make, calculate the traction force  $F$ . (4)
  - ii) Calculate the time it takes the vehicle to reach the speed  $v_c = 60 \text{ MPH}$ . (3)
  - iii) Calculate the energy delivered by the drive-train. (3)
  - iv) Calculate the kinetic energy of the vehicle at the speed  $v_c = 60 \text{ MPH}$  and discuss any discrepancies with the energy delivered by the drive-train. (2)

(For a constant traction force, the differential equation describing the motion of a vehicle can be written as:  $p \frac{dv}{dt} = q^2 - v^2$ , where  $p$  and  $q$  are constants, and  $v$  is the speed of the vehicle, and the solution of the equation is given by:  $v(t) = q \tanh\left(\frac{q}{p}t + C\right)$ ; where  $C = \tanh^{-1}\left(\frac{v_0}{q}\right)$  and  $v_0$  is the initial speed of the vehicle. You may also assume that  $\int \tanh(ax + b)dx = \frac{1}{a} \ln(\cosh(ax + b))$ )

- c. Show that for a constant acceleration  $\gamma$  the energy delivered by the drive-train is given by:

$$E = \frac{1}{2} m v^2 + \frac{1}{2} \lambda_f m g \frac{v}{\gamma} + \frac{1}{8} C_d \rho_a A_f \frac{v^4}{\gamma} \quad (5)$$

4. a. A parallel-hybrid vehicle is equipped with a 4-speed gearbox, a 30kW permanent magnet brushless DC machine, connected to the battery via an IGBT power electronic controller.

The vehicle and traction system have the following parameters:

Vehicle:

Gross weight	$m = 1900 \text{ kg}$
Rolling resistance coefficient	$\lambda_f = 0.013$
Drag coefficient	$C_d = 0.37$
Frontal area	$A_f = 2.45 \text{ m}^2$
Wheel rolling radius	$r_w = 296.5 \text{ mm}$

(You may assume the gravitational acceleration  $g = 9.81 \text{ m/s}^2$ )

Transmission:

Gearbox

Gear	Ratio $R_g$	Efficiency $\eta_g (\%)$
1 <sup>st</sup>	12/41	93.24
2 <sup>nd</sup>	21/38	94.06
3 <sup>rd</sup>	31/35	94.25
4 <sup>th</sup>	43/35	94.52

Differential

Ratio  $R_d = 18/62$

Losses: negligible

Nickel-Cadmium Battery:

Open circuit voltage  $E_o = 200 - 0.25 Q_d \text{ (V)}$

Internal resistance  $R_i = 100 + 1.25 Q_d \text{ (m}\Omega\text{)}$

$Q_d$ : State of discharge in (%) (100% as fully discharged).

Traction machine and converter:

The combined losses of the drive-train, excluding the battery, are given by:

$$L_d = 5T + 3.75 \times 10^{-2} T^2 + 3.65 \times 10^{-3} \Omega^2$$

where,  $T$  and  $\Omega$  are the torque and speed of the traction motor machine.

Draw a schematic showing a basic parallel-hybrid drive-train and major energy flow paths, and list its main features.

(4)

- b. Calculate the torque  $T$  and the speed  $\Omega$  of the traction motor and the output power  $P_d$  of the battery, when 3<sup>rd</sup> gear is selected and the vehicle is cruising at a speed of 30MPH into a headwind  $v_w = 20\text{MPH}$ . (6)
- c. Assuming the power delivered by the battery is  $P_d = 7.85\text{kW}$ , calculate its efficiency when  $\eta_d = 50\%$ . (5)
- d. When 3<sup>rd</sup> gear is selected and no mechanical or re-generative braking is applied, calculate the maximum downwards inclination angle  $\alpha$ , for which the vehicle can travel at constant speed of 30MPH into a headwind  $v_w = 20\text{MPH}$ . (5)

*(You may assume that the rolling resistance is independent of the inclination angle  $\alpha$  and that the iron loss of the traction machine at a speed  $\Omega$  is given by  $P_i = 3.65 \times 10^{-3} \Omega^2$ )*

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