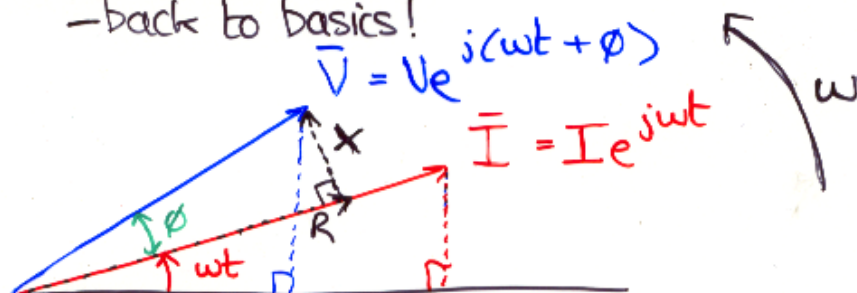


VECTOR & MATRIX POWER

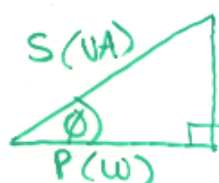
- back to basics!



$$\vec{V} = V(\cos(\omega t + \phi) + j\sin(\omega t + \phi)) = V e^{j(\omega t + \phi)}$$

$$\vec{I} = I(\cos \omega t + j\sin \omega t) = I e^{j\omega t}$$

Power triangle recall...



$$\text{Real Power} = S \cos \phi$$

$$\text{Reactive Power} = S \sin \phi$$

$$\text{COMPLEX POWER, } S = P + j\phi = S \cos \phi + jS \sin \phi$$

$$\vec{V} \vec{I} = V I e^{j(2\omega t + \phi)} \rightarrow \text{DOES NOT GIVE POWER!}$$

$$\text{However, } \vec{V} \times \vec{I}^* = V e^{j(\omega t + \phi)} \cdot I e^{j\omega t}$$

$$= V I e^{j\phi} = V I (\cos \phi + j\sin \phi) \quad (VA)$$

$$\Rightarrow \text{REAL POWER} = \text{Re}\{\vec{V} \vec{I}^*\} \quad (W)$$

$$\text{alternatively, REAL POWER} = \text{Re}\{\vec{V}^* \vec{I}\}$$

- Consider a simple dc system, where power (total) made from no. of sub-systems....

$$P = V_1 I_1 + V_2 I_2 + V_3 I_3 + \dots V_n I_n$$

.... to represent in matrix form, this becomes....

$$P = [V_1 \ V_2 \ V_3 \ \dots \ V_n] \begin{bmatrix} I_1 \\ I_2 \\ I_3 \\ \vdots \\ I_n \end{bmatrix} \quad \text{i.e. } P = V_t I$$

or, $P = I_t V$, so for ac systems:-

$$\dots \text{matrix power} = \text{Re} \{ [V_t] [I]^* \} = \text{Re} \{ [I_t]^* [V] \}$$

- Combining the definition of matrix power with both definitions of complex power also gives us...

$$\text{matrix power} = \text{Re} \{ [V_t]^* [I] \} = \text{Re} \{ [I_t] [V]^* \}$$

i.e. four equivalent forms of power depending upon which vector is conjugated, & which is transposed!!