



The
University
Of
Sheffield.

Data Provided:

$$\epsilon_0 = 8.854 \times 10^{-12} \text{ F/m},$$

$$\mu_0 = 4\pi \times 10^{-7} \text{ H/m},$$

Formulae for Vector Differential Operations

DEPARTMENT OF ELECTRONIC AND ELECTRICAL ENGINEERING

Spring Semester 2008-2009 (2 hours)

Applied Electromagnetics 6

Answer **THREE** questions. **No marks will be awarded for solutions to a fourth question.** Solutions will be considered in the order that they are presented in the answer book. Trial answers will be ignored if they are clearly crossed out. **The numbers given after each section of a question indicate the relative weighting of that section.**

1. Figure 1 represents an elemental length of a transmission line.

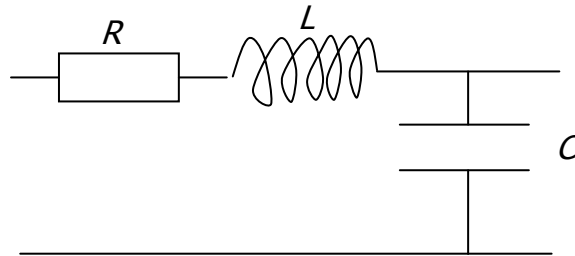


Fig. 1

R , L and C are the resistivity, inductance and capacitance of the line per unit length respectively.

- a) By examining the voltage (V) and current (I) differences over a length of Δx of this line in time Δt , show that

$$-\frac{\partial V}{\partial x} = RI + L \frac{\partial I}{\partial t} \quad \text{equation 1}$$

and

$$-\frac{\partial I}{\partial x} = C \frac{\partial V}{\partial t} \quad \text{equation 2}$$

(3)

- b) Show that when R is negligibly small, then

$$\frac{\partial^2 V}{\partial t^2} = v^2 \frac{\partial^2 V}{\partial x^2} \quad \text{equation 3}$$

(3)

- c) Show that

$$V(x, t) = 3e^{j(\omega t - \beta x)} + 3e^{j(\omega t + \beta x)} \quad \text{equation 4}$$

where ω and β are real constants, is a solution of equation 3. Explain what this function physically represents and sketch the magnitude of the time-independent amplitude of the voltage disturbance as a function of x , labelling the x axis scale in terms of β .

(5)

- d) What is the voltage standing wave ratio of $V(x, t)$ in equation 4.

(2)

- e) How is the quantity β affected if the resistance per unit length of the line is small but finite? Sketch how this would affect the amplitude of the first term on the RHS of equation 4 as a function of x .

(3)

- f) Consider the terminated transmission line in Fig. 2.

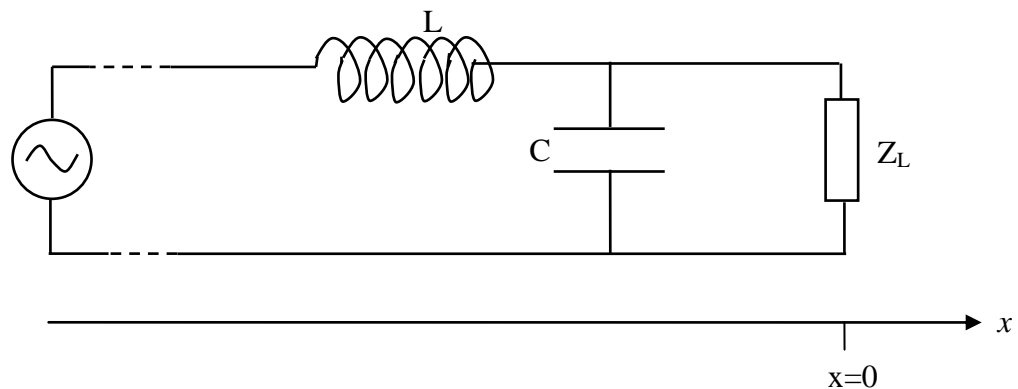


Fig. 2

A sinusoidal voltage of frequency 3GHz is applied to the line at some distance to left of the diagram. The line is terminated at $x=0$ with an impedance of Z_L . Given that $v = 2 \times 10^8$ m/s, and $C = 80$ pF/m, find the value of Z_L which will result in there only being a wave travelling in the positive x direction. Sketch the amplitude of the *current* as a function of x , near $x=0$, in the cases when $Z_L = 0$ and $Z_L = \infty$.

(4)

2. A transmission line consists of two conducting parallel plates of width w separated by a distance b , as shown in Fig. 3

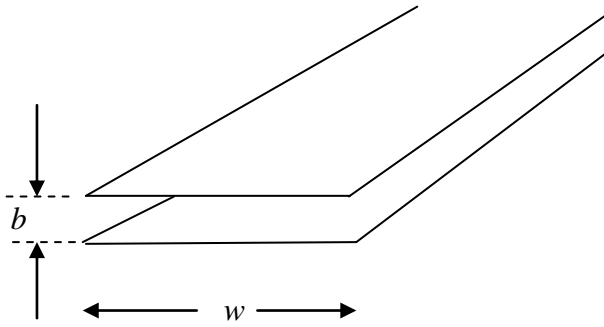


Fig. 3

A periodic voltage of the form $V = V_0 \cos \omega t$ is applied across the plates at one end of the line, causing time-dependent electromagnetic fields to propagate down the line. The relative permeability and permittivity of space between the plates is μ_r and ϵ_r respectively. Assume that $w \gg b$, so that non-parallel components of the magnetic and electric fields at the edges of the plates can be ignored.

- a) By considering the voltage across and the current down a short length of the line a , derive expressions in terms of μ_r and ϵ_r for
- The capacitance, C , per unit length of the line.
 - The inductance, L , per unit length of the line.
 - The characteristic impedance, Z_0 , of the line.
 - The phase velocity of the wave that propagates down the line.

(8)

If b and w are made very large, the electric and magnetic fields in free space between the plates can be described by

$$\mathbf{E}(x,t) = E_0 \hat{\mathbf{y}} \cos(\omega t - \beta x)$$

$$\mathbf{H}(x,t) = H_0 \hat{\mathbf{z}} \cos(\omega t - \beta x)$$

- b) On a diagram similar to the one above, indicate the relationship of the x , y and z axes. If the frequency of the source is 1GHz, draw the relationship between the vector components of \mathbf{E} and \mathbf{H} as a function of x .
- c) Such a wave travels through a medium with $\mu_r = \epsilon_r = 1$ before it encounters a planar surface of a second medium lying normal to the x -axis at $x=0$. For $x>0$, $\mu_r=1$, $\epsilon_r=1.25$, by equating the continuity of components of \mathbf{E} and \mathbf{H} at the interface, determine the electric field amplitude of the transmitted wave relative to the incident wave.
- d) Calculate the energy per unit area incident upon the surface described above if the average value of electric field of the wave travelling in the positive x direction is 2.3×10^{-7} V/m.

(4)

(6)

(2)

3. a. The electric scalar potential, V , in a region of free space ($\epsilon_0 = 8.85 \times 10^{-12} \text{ F/m}$) is given by:

$$V = x^2 + y + z^3 \text{ (V)}$$

- (i) Calculate the electric field strength and charge density at the point $(x, y, z) = (1.0, 0.5, 0.2) \text{ m}$.
- (ii) Determine the total electric flux through the surface of the cube, as shown in Fig. 4, and the total charge inside the cube.

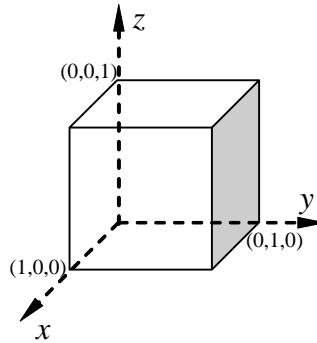


Fig. 4

(6)

- b. Using the conservative property of electrostatic field strength \vec{E} , $\oint_C \vec{E} \cdot d\vec{l} = 0$, and Gauss's Law, $\oiint_S \vec{D} \cdot d\vec{S} = Q$, show that

- (i) the boundary condition at the interface between a conductor and dielectric material, as shown in Fig. 5, is given by:

$$E_t = 0$$

- (ii) the charge density, σ , at the conductor surface is given by:

$$\sigma = D_n$$

where E_t and D_n are the tangential component of the electric field strength and the normal component of the electric flux density, respectively, in the dielectric region at the interface.

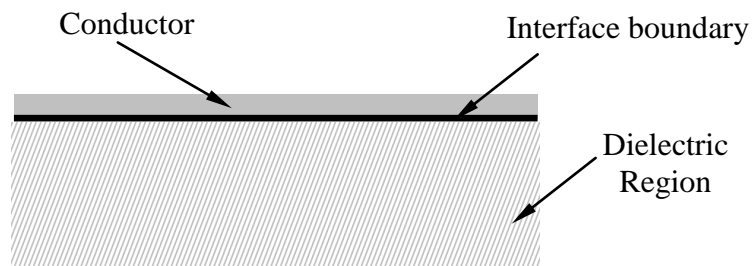


Fig. 5

(6)

- c. Two coaxial conducting cylinders are located at $r = 0.005$ m and $r = 0.012$ m. The region between the cylinders is filled with a homogeneous perfect dielectric. If the inner cylinder is at 100 V and the outer at 0 V, by solving Laplace's equation, find
- (i) the location of the 20 V equipotential surface,
 - (ii) the maximum electrical field strength E_{rmax} ,
 - (iii) the permittivity of the dielectric if the charge per unit length on the inner cylinder is $0.03 \mu\text{C/m}$,
 - (iv) the capacitance per unit length.

Laplace operator in cylindrical co-ordinate systems is given by:

$$\nabla^2 = \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2}{\partial \theta^2} + \frac{\partial^2}{\partial z^2} \quad (8)$$

4. a. The vector magnetic potential \mathbf{A} in a region of free space ($\mu_0 = 4\pi \times 10^{-7} \text{ H/m}$) is given by:

$$\mathbf{A} = (0.3xyz) \mathbf{e}_x + (0.4xy) \mathbf{e}_y + (0.3) \mathbf{e}_z \quad (\text{Wb/m})$$

Calculate the magnetic flux density \mathbf{B} and current density \mathbf{J} at the point (1, 3, 9)m. (5)

- b. Figure 6 shows a schematic representation of the track section of a levitated rapid transport system. It consists of a sheet of infinitely permeable iron ($\mu = \infty$) on which there is a surface current sheet $J \sin(px)$ A/m. Starting from the appropriate governing magneto-static field equation, derive expressions for the x and y components of flux density in the air region above the track.

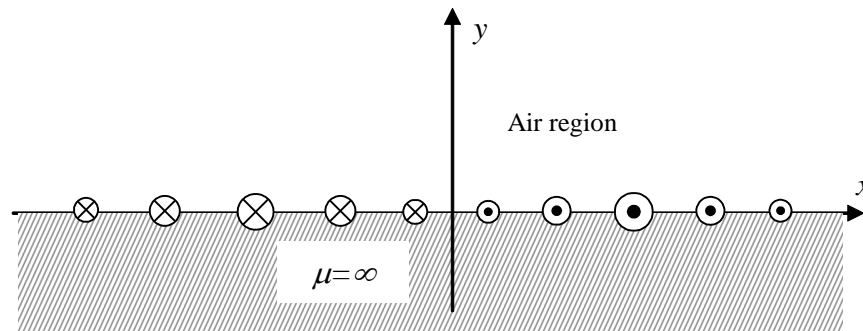


Fig. 6

(6)

- c. Explain what is meant by “skin effect” in relation to time-varying electromagnetic fields, and indicate how the skin depth depends on the properties of a material. (3)
- d. A circular copper conductor has a diameter of 4mm and carries a current at a frequency of 20kHz. Estimate the per unit length ac resistance of the conductor if the resistivity of copper is $1.7 \times 10^{-8} \Omega\text{m}$. (6)

Vector differential operations

Let Φ be a scalar function and \mathbf{D} , \mathbf{H} and \mathbf{A} be vector functions.

Cartesian Co-ordinates (x, y, z)

$$\nabla\Phi = \frac{\partial\Phi}{\partial x}e_x + \frac{\partial\Phi}{\partial y}e_y + \frac{\partial\Phi}{\partial z}e_z$$

$$\nabla \cdot \mathbf{D} = \frac{\partial D_x}{\partial x} + \frac{\partial D_y}{\partial y} + \frac{\partial D_z}{\partial z}$$

$$\nabla \times \mathbf{H} = \left(\frac{\partial H_z}{\partial y} - \frac{\partial H_y}{\partial z} \right) e_x + \left(\frac{\partial H_x}{\partial z} - \frac{\partial H_z}{\partial x} \right) e_y + \left(\frac{\partial H_y}{\partial x} - \frac{\partial H_x}{\partial y} \right) e_z$$

$$\nabla^2\Phi = \frac{\partial^2\Phi}{\partial x^2} + \frac{\partial^2\Phi}{\partial y^2} + \frac{\partial^2\Phi}{\partial z^2}$$

$$\nabla^2\mathbf{A} = \nabla^2 A_x e_x + \nabla^2 A_y e_y + \nabla^2 A_z e_z$$

Cylindrical Co-ordinates (r, θ, z)

$$\nabla\Phi = \frac{\partial\Phi}{\partial r}e_r + \frac{1}{r} \frac{\partial\Phi}{\partial \theta}e_\theta + \frac{\partial\Phi}{\partial z}e_z$$

$$\nabla \cdot \mathbf{D} = \frac{1}{r} \frac{\partial}{\partial r}(rD_r) + \frac{1}{r} \frac{\partial D_\theta}{\partial \theta} + \frac{\partial D_z}{\partial z}$$

$$\nabla \times \mathbf{H} = \left[\frac{1}{r} \frac{\partial H_z}{\partial \theta} - \frac{\partial H_\theta}{\partial z} \right] e_r + \left[\frac{\partial H_r}{\partial z} - \frac{\partial H_z}{\partial r} \right] e_\theta + \left[\frac{1}{r} \frac{\partial(rH_\theta)}{\partial r} - \frac{1}{r} \frac{\partial H_r}{\partial \theta} \right] e_z$$

$$\nabla^2\Phi = \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial\Phi}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2\Phi}{\partial \theta^2} + \frac{\partial^2\Phi}{\partial z^2} = \frac{\partial^2\Phi}{\partial r^2} + \frac{1}{r} \frac{\partial\Phi}{\partial r} + \frac{1}{r^2} \frac{\partial^2\Phi}{\partial \theta^2} + \frac{\partial^2\Phi}{\partial z^2}$$

$$\nabla^2\mathbf{A} = \left(\nabla^2 A_r - \frac{2}{r^2} \frac{\partial A_\theta}{\partial \theta} - \frac{A_r}{r^2} \right) e_r + \left(\nabla^2 A_\theta + \frac{2}{r^2} \frac{\partial A_r}{\partial \theta} - \frac{A_\theta}{r^2} \right) e_\theta + (\nabla^2 A_z) e_z$$

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