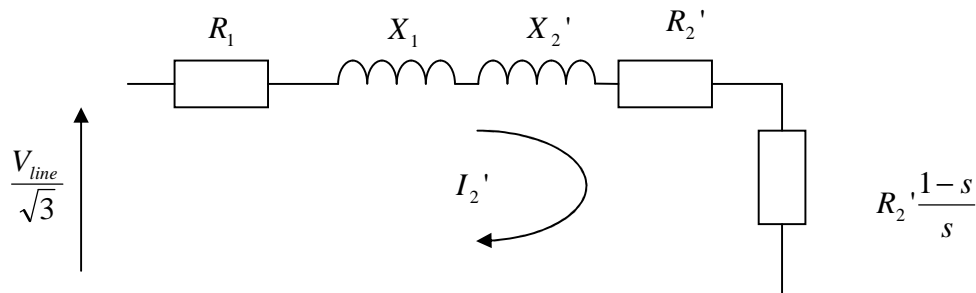


Tutorial Sheet 5 – Induction Motor Solutions

Equivalent circuit of an induction machine:



Question 1

$$N_s = \frac{60f}{p} = \frac{60 \times 50}{2} = 1500 \text{ rpm}$$

$$\text{Slip speed} = 1500 - 1455 = 45 \text{ rpm}$$

$$\text{Slip, } s = \frac{45}{1500} = 0.03$$

a) rated full-load current, I_2'

$$I_2' = \frac{V}{Z} = \frac{V_{phase}}{\sqrt{\left(R_1 + \frac{R_2'}{s}\right)^2 + (X_1 + X_2')^2}} = \frac{415/\sqrt{3}}{\sqrt{\left(0.2 + \frac{0.1}{0.03}\right)^2 + (0.9 + 0.7)^2}} = \underline{\underline{61.8A}}$$

b) Torque delivered by the motor

$$T = 3p \times \left(\frac{V}{Z}\right)^2 \times \frac{R_2'}{2\pi f s} = 3 \times 2 \times \frac{\left(\frac{415}{\sqrt{3}}\right)^2}{\left(0.2 + \frac{0.1}{0.03}\right)^2 + (0.9 + 0.7)^2} \times \frac{0.1}{2\pi(50)(0.03)} = \underline{\underline{243Nm}}$$

c) output power

$$P_{out} = \frac{I_2'^2 R_2' (1-s)}{s} = \frac{61.77^2 (0.1)(1-0.03)}{0.03} = \underline{\underline{12.3kW}}$$

d) power factor, $\cos\theta$, will be lagging because of inductive load...

$$P_{in} = I_2^2 \left(R_1 + \frac{R_2}{s} \right) = 13.483 \text{ kW}$$

$$\ggg P = VI \cos \theta \text{ then } \cos \theta = \frac{P}{VI} = \frac{13.483}{415 / \sqrt{3} (61.77)} = \underline{\underline{0.91 \text{ lag}}}$$

e) efficiency

$$\frac{P_{out}}{P_{in}} \times 100\% = \frac{12.3}{13.483} \times 100\% = \underline{\underline{91.6\%}}$$

Question 2

The essence of this question involves understanding that you are retaining the same T-w envelope, but using the supply frequency to change the speed. **Note: in the lecture notes the boost deals with a dc-voltage (and hence all impedance = 0), in this question the voltage is ac and hence the frequency change must be taken into account.**

a) The rotor frequency will be the same as in the first part at full-load speed....

$$f_2 = sf_1 = (0.03)(50) = 1.5 \text{ Hz}$$

Half sync speed is 750rpm or 25Hz, to achieve this at full torque in the same envelope the machine must be supplied with $25 + 1.5 = \underline{\underline{26.5 \text{ Hz}}}$

b) V_{phase} is calculated from the current (same current as same torque) and the impedance (different impedance as different frequency and new slip at new speed)

$$s = \frac{N_s - N_r}{N_s} = \frac{26.5 - 25}{26.5} = 0.0566$$

$$V_{\text{phase}} = I_2 \left[\left(R_1 + \frac{R_2}{s} \right) - j(X_1 - X_2) \right] = 61.77 \left(0.2 + \frac{0.1}{0.0566} \right) - j(0.9 - 0.7) \left(\frac{26.5}{50} \right)$$

$$= 61.77 \times \sqrt{(1.966)^2 + (0.848)^2} = 132.6 \text{ V}$$

$$V_{\text{line}} = \sqrt{3} V_{\text{phase}} = \underline{\underline{229.6 \text{ V}}}$$

c) Again this is an ac boost...(see graph)

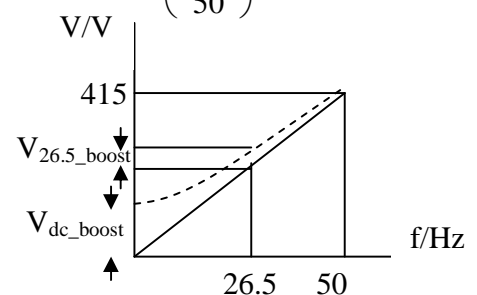
if it was $V_{\text{dc_boost}} = IR_1 = 61.8 \times 0.2 = 12.36 \text{ V}$.

So we know the value is between 0 and 12.36V.

So $V_{\text{line_old}} = 415 \text{ V}$, $V_{\text{line_new}} = 229.6 \text{ V}$ (dashed line), the original line voltage scaled by the frequency (solid line in the graph) = $415 \times 26.5 / 50$. Difference is the boost.

$$V_{\text{boost}} = V_{\text{line_new}} - V_{\text{line_scaled}} = V_{\text{line_new}} - V_{\text{line}} \frac{f_{\text{new}}}{f_{\text{old}}} = (229.6) - (415) \left(\frac{26.5}{50} \right) = \underline{\underline{10.05 \text{ V}}}$$

d) same current as same torque....61.8A



e) power factor (lagging: inductive)

$$\tan \theta = \frac{jX}{R} = \frac{0.848}{1.966} \Rightarrow \theta = 23.33^\circ$$

$$\cos \theta = \underline{\underline{0.91lag}}$$

f) efficiency

$$\frac{P_o}{P_i} = \frac{I_2'^2 R_2 \frac{1-s}{s}}{I_2'^2 \left(R_1 + \frac{R_2'}{s} \right)} = \frac{0.1 \frac{1-0.0566}{0.0566}}{\left(0.2 + \frac{0.1}{0.0566} \right)} = \underline{\underline{84.7\%}}$$

Question 3

This time we are increasing the rotor resistance in order to reduce the speed.

$$R_2' = x\Omega$$

$$s = \frac{1500 - 750}{1500} = 0.5$$

a) Calculate R_2' for Full load torque, half sync speed, rated voltage

$$T = \frac{3p}{2\pi fs} \times \left(\frac{V_{line}}{\sqrt{3}} \right)^2 x \frac{R_2'}{\left(R_1 + \frac{R_2'}{s} \right)^2 + (X_1 + X_2)^2} \Rightarrow \frac{6\pi fs T}{3p V_{line}^2} = \frac{x}{\left(0.1 + \frac{x}{0.5} \right)^2 + (0.9 + 0.7)^2}$$

$$\frac{3p V_{line}^2}{6\pi fs T} x = 0.04 + 0.8x + 4x^2 + 2.56 \Rightarrow 4x^2 + \left(0.8 - \frac{3p V_{line}^2}{6\pi fs T} \right) x + 2.6 = 4x^2 - 8.22x + 2.6 = 0$$

$$use \frac{-b \pm \sqrt{b^2 - 4ac}}{2a} \Rightarrow x = \underline{\underline{0.39\Omega}}$$

b) Rotor current with 1:2 rotor:stator winding ratio

$$I_2' = \frac{N_2}{N_1} I_2 \rightarrow \frac{V_{phase}}{\sqrt{\left(0.1 + \frac{0.39}{0.5} \right)^2 + (0.9 + 0.7)^2}} \times \frac{1}{2} = \underline{\underline{63.8A}}$$

c) efficiency, power out is only 2 x copper losses for $s = 0.5$, so the efficiency will be poor

$$\frac{P_o}{P_i} = \frac{I_2'^2 R_2 \frac{1-s}{s}}{I_2'^2 \left(R_1 + \frac{R_2'}{s} \right)} = \frac{0.39 \frac{1-0.5}{0.5}}{\left(0.2 + \frac{0.39}{0.5} \right)} = \underline{\underline{39.7\%}}$$

Question 4

This time we have replaced the wound rotor with a cage rotor and will control the speed with V-I adjustment.

a) new line voltage

$$s = \frac{1500 - 750}{1500} = 0.5$$

$$T_{\frac{1}{2}} = \frac{243}{2} = 121.5 \text{ Nm} = \frac{3p}{2\pi fs} \times \left(\frac{V_{line}}{\sqrt{3}} \right)^2 \times \frac{R_2'}{\left(R_1 + \frac{R_2'}{s} \right)^2 + (X_1 + X_2)^2}$$

$$\Rightarrow 121.5 = \frac{6}{2\pi(50)(0.5)} \times \frac{V_{line}^2}{3} \times \frac{0.3}{\left(0.1 + \frac{0.3}{0.5} \right)^2 + (0.9 + 0.7)^2}$$

$$V_{line} = \sqrt{(121.5)\pi(50)(0.5) \times \frac{\left(0.1 + \frac{0.3}{0.5} \right)^2 + (0.9 + 0.7)^2}{0.3}} = \underline{\underline{319V}}$$

b) new current

$$I_2' = \frac{V}{Z} = \frac{V_{phase}}{\sqrt{\left(R_1 + \frac{R_2'}{s} \right)^2 + (X_1 + X_2)^2}} = \frac{319/\sqrt{3}}{\sqrt{\left(0.2 + \frac{0.3}{0.5} \right)^2 + (0.9 + 0.7)^2}} = \underline{\underline{103A}}$$

c) efficiency

$$\frac{P_o}{P_i} = \frac{I_2'^2 R_2 \frac{1-s}{s}}{I_2'^2 \left(R_1 + \frac{R_2'}{s} \right)} = \frac{0.3 \frac{1-0.5}{0.5}}{\left(0.2 + \frac{0.3}{0.5} \right)} = \underline{\underline{37.5\%}}$$