

Tutorial 4: Solutions

1. Evaluate the Laplace transform of the signal $x(t) = e^{-t}u(t) + e^{-4t}u(t)$.

$$X(s) = \int_{-\infty}^{\infty} x(t)e^{-st} dt = \int_{-\infty}^{\infty} e^{-t}u(t)e^{-st} dt + \int_{-\infty}^{\infty} e^{-4t}u(t)e^{-st} dt = \int_0^{\infty} e^{-(s+1)t} dt + \int_0^{\infty} e^{-(s+4)t} dt$$

$$X(s) = \frac{1}{s+1} \left[-e^{-(s+1)t} \right]_0^{\infty} + \frac{1}{s+4} \left[-e^{-(s+4)t} \right]_0^{\infty} = \frac{1}{s+1} + \frac{1}{s+4}, \text{ Re}\{s\} > -1.$$

2. Verify the following Laplace transform pairs

(i) $\frac{dx(t)}{dt} \leftrightarrow sX(s)$

We know that $x(t) = \frac{1}{j2\pi} \int_{c-j\infty}^{c+j\infty} X(s)e^{st} ds$. Differentiate both sides w.r.t. to t gives

$$\frac{dx(t)}{dt} = \frac{1}{j2\pi} \int_{c-j\infty}^{c+j\infty} X(s)se^{st} ds = \frac{1}{j2\pi} \int_{c-j\infty}^{c+j\infty} (sX(s))e^{st} ds.$$

Therefore $\frac{dx(t)}{dt}$ is the inverse Laplace Transform of $sX(s)$, i.e., $\frac{dx(t)}{dt} \leftrightarrow sX(s)$.

(ii) $-tx(t) \leftrightarrow \frac{dX(s)}{ds}$

Start with $X(s) = \int_{-\infty}^{\infty} x(t)e^{-st} dt$. Differentiate both sides w.r.t. s gives,

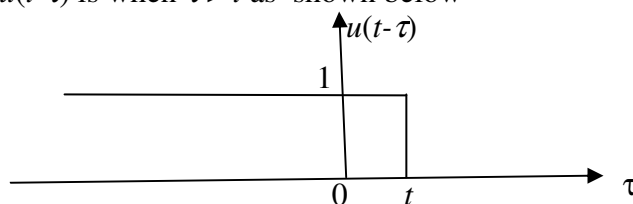
$$\frac{dX(s)}{ds} = \int_{-\infty}^{\infty} -tx(t)e^{-st} dt = \int_{-\infty}^{\infty} (-tx(t))e^{-st} dt.$$

Therefore the Laplace Transform of $-tx(t)$ is $\frac{dX(s)}{ds}$, i.e., $-tx(t) \leftrightarrow \frac{dX(s)}{ds}$.

(iii) $\int_{-\infty}^t x(\tau) d\tau \leftrightarrow \frac{X(s)}{s}$.

Consider, the time domain convolution defined by $x(t) * u(t) = \int_{-\infty}^{\infty} x(\tau)u(t-\tau) d\tau$. The

signal $u(t-\tau)$ is when $\tau > t$ as shown below



$$x(t) * u(t) = \int_{-\infty}^{\infty} x(\tau)u(t-\tau) d\tau = \int_{-\infty}^t x(\tau) d\tau$$

Using the convolution property we know that convolution in time domain is equivalent to multiplication in s-domain.

$$\int_{-\infty}^t x(\tau) d\tau = x(t) * u(t) \leftrightarrow X(s)U(s) = \frac{X(s)}{s}.$$

3. Find the values of $y(t) = 2e^{-2t}u(t) - e^{-t}u(t)$ for $t = 0$ and $t \rightarrow \infty$. Verify your answer using the initial and the final value theorems.

At $t = 0$, $y(0) = 2 - 1 = 1$.

As $t \rightarrow \infty$, $\lim_{t \rightarrow \infty} y(t) = 0$.

Taking the Laplace Transform of $y(t)$ gives,

$$Y(s) = \frac{2}{s+2} - \frac{1}{s+1} = \frac{2(s+1) - (s+2)}{(s+2)(s+1)} = \frac{s}{s^2 + 3s + 2}.$$

$$sY(s) = \frac{s^2}{s^2 + 3s + 2} = \frac{1}{1 + 3/s + 2/s^2}.$$

Using the initial value theorem,

$$y(0) = \lim_{s \rightarrow \infty} sY(s) = \lim_{s \rightarrow \infty} \frac{1}{1 + 3/s + 2/s^2} = 1.$$

Using the final value theorem,

$$\lim_{t \rightarrow \infty} y(t) = \lim_{s \rightarrow 0} \frac{s^2}{s^2 + 3s + 2} = 0.$$

These values are the same as those calculated above.

4. Compute the impulse response and the unit step response of a system with transfer

function described by $H(s) = \frac{3s}{2s^2 + 10s + 12}$.

$$H(s) = \frac{3s}{2s^2 + 10s + 12} = \frac{3s}{(2s+4)(s+3)} = \frac{3s/2}{(s+2)(s+3)} = k_0 + \frac{k_1}{s+2} + \frac{k_2}{s+3}.$$

Using partial fraction expansion,

$$k_0 = \left. \frac{3s}{s^2 + 10s + 12} \right|_{s=\infty} = \left. \frac{3/s}{1 + 10/s + 12/s^2} \right|_{s=\infty} = 0,$$

$$k_1 = \left. \frac{3s/2}{(s+2)(s+3)} (s+2) \right|_{s=-2} = \left. \frac{3s/2}{(s+3)} \right|_{s=-2} = \frac{-3}{1} = -3,$$

$$k_2 = \left. \frac{3s/2}{(s+2)(s+3)} (s+3) \right|_{s=-3} = \left. \frac{3s/2}{(s+2)} \right|_{s=-3} = \frac{-9/2}{-1} = \frac{9}{2}.$$

Alternatively,

$$\frac{3s/2}{(s+2)(s+3)} = \frac{k_0(s+2)(s+3) + k_1(s+3) + k_2(s+2)}{(s+2)(s+3)}$$

$$3s/2 = k_0(s^2 + 5s + 6) + (k_1 + k_2)s + 3k_1 + 2k_2 = k_0s^2 + (5k_0 + k_1 + k_2)s + (6k_0 + 3k_1 + 2k_2)$$

Comparing the coefficients for s^2 gives $k_0 = 0$.

Comparing the coefficients for s gives $k_1 + k_2 = 3/2$.

We also have $3k_1 + 2k_2 = 0$ and hence $k_2 = -3k_1/2$.

Substituting k_2 gives $k_1 - 3k_1/2 = 3/2$ and hence $k_1 = -3$ and $k_2 = 9/2$

The transfer function is

$$H(s) = -\frac{3}{s+2} + \frac{9/2}{s+3} = \frac{9}{2} \frac{1}{s+3} - \frac{3}{s+2}$$

Therefore the impulse response is described by $h(t) = \frac{9}{2}e^{-3t}u(t) - 3e^{-2t}u(t)$ in the time domain.

If the input is a unit step, The output is given by

$$Y(s) = H(s)U(s) = \frac{3s/2}{(s+2)(s+3)} \frac{1}{s} = \frac{3/2}{(s+2)(s+3)} = \frac{k_1}{(s+2)} + \frac{k_2}{(s+3)}.$$

Using partial fraction expansion,

$$k_1 = \frac{3/2}{(s+2)(s+3)}(s+2) \Big|_{s=-2} = \frac{3/2}{(s+3)} \Big|_{s=-2} = \frac{3/2}{1} = \frac{3}{2},$$

$$k_2 = \frac{3/2}{(s+2)(s+3)}(s+3) \Big|_{s=-3} = \frac{3/2}{(s+2)} \Big|_{s=-3} = \frac{3/2}{-1} = -\frac{3}{2}.$$

Alternatively,

$$\frac{3/2}{(s+2)(s+3)} = \frac{k_1(s+3) + k_2(s+2)}{(s+2)(s+3)}$$

$$3/2 = (k_1 + k_2)s + (3k_1 + 2k_2)$$

Comparing the coefficients for s , $k_1 = -k_2$.

$$k_1 = 3/2 \text{ and } k_2 = -3/2.$$

$$Y(s) = \frac{3}{2(s+2)} - \frac{3}{2(s+3)}.$$

Therefore the unit step response in time domain is

$$y(t) = \frac{3}{2}e^{-2t}u(t) - \frac{3}{2}e^{-3t}u(t) = \frac{3}{2}u(t)(e^{-2t} - e^{-3t}).$$

5. Determine the poles, the natural frequency and the damping factor of systems with the following transfer functions and state the nature of the system response:

$$(i) G(s) = \frac{0.3}{s^2 + 7s + 10} = \frac{0.3}{(s+5)(s+2)}$$

$$\text{Compare } G(s) = \frac{0.3}{s^2 + 7s + 10} \text{ with } \frac{k}{s^2 + 2\zeta\omega_n + \omega_n^2}.$$

Natural oscillating frequency is $\omega_n = \sqrt{10}$ rad/s.

$$\text{Damping factor is } \zeta = \frac{7}{2\omega_n} = \frac{7}{2\sqrt{10}} = 1.107.$$

The system is lightly overdamped. Poles are $p_1 = -5$ and $p_2 = -2$.

The unit step response is in the form, $y(t) = K_o + K_1e^{-5t}u(t) + K_2e^{-2t}u(t)$, where K_o , K_1 and K_2 are constants.

$$(ii) \ G(s) = \frac{1}{s^2 + 4s + 13} = \frac{1}{(s^2 + 4s + 4) + 9} = \frac{1}{(s + 2)^2 + (3)^2}.$$

Compare $G(s) = \frac{1}{s^2 + 4s + 13}$ with $\frac{k}{s^2 + 2\zeta\omega_n + \omega_n^2}$ and

$$G(s) = \frac{1}{(s + 2)^2 + (3)^2} \text{ with } \frac{k}{(s + \zeta\omega_n)^2 + \omega_d^2}.$$

Natural oscillating frequency is $\omega_n = \sqrt{13}$ rad/s.

Damping factor is $\zeta = \frac{4}{2\omega_n} = \frac{2}{\sqrt{13}} = 0.555$.

The system is underdamped. The poles are complex and are given by

$$p_{1,2} = -\zeta\omega_n \pm j\omega_d, \text{ where } \omega_d = 3.$$

$$p_{1,2} = -\frac{2}{\sqrt{13}}\sqrt{13} \pm j3 = -2 \pm j3. \text{ The unit step response is}$$

$y(t) = K_0 + K_1 e^{-2t} \sin(3t + \theta)u(t)$, where K_0 and K_1 are constants. $y(t)$ is a sinusoid with frequency 3 rad/s that decays exponentially with at a time constant 1/2 s.

$$(iii) \ G(s) = \frac{0.1}{s^2 + 16}$$

Compare $G(s) = \frac{0.1}{s^2 + 16}$ with $\frac{k}{(s^2 + \omega_n^2)}$.

Natural oscillating frequency is $\omega_n = \sqrt{16} = 4$ rad/s.

Damping factor is $\zeta = 0$.

The system is undamped. The poles are $p_{1,2} = \pm j\omega_n = \pm j4$.

The unit step response is $y(t) = K_0 + K_1 \cos(4t)u(t)$, where K_0 and K_1 are constants.

$$(iv) \ G(s) = \frac{15}{s^2 + 6s + 9}.$$

Compare $G(s) = \frac{15}{s^2 + 6s + 9}$ with $\frac{k}{s^2 + 2\zeta\omega_n + \omega_n^2}$

Natural oscillating frequency is $\omega_n = \sqrt{9} = 3$ rad/s.

Damping factor is $\zeta = \frac{6}{2\omega_n} = \frac{3}{3} = 1$.

The system is critically damped. The poles are $p_{1,2} = -\omega_n = -3$.

The unit step response is $y(t) = K_0(1 - (1 + 3t)e^{-3t}u(t))$ where K_0 is a constant.

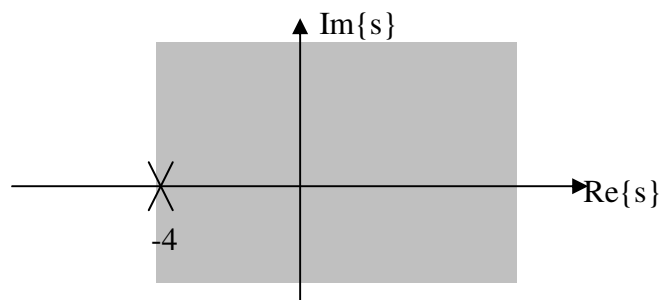
6. Determine the Laplace transforms of the following signals. Sketch the pole-zero plot and region of convergence (if it exists).

(i) $x(t) = e^{-4t}u(t)$

$$X(s) = \int_{-\infty}^{\infty} e^{-4t}u(t)e^{-st} dt = \int_0^{\infty} e^{-4t} e^{-(\sigma+j\omega)t} dt = \int_0^{\infty} e^{-(4+\sigma)t} e^{-j\omega t} dt. X(s) \text{ exists if } 4 + \sigma > 0, \text{ i.e.}$$

$$\sigma = \text{Re}\{s\} > -4. \text{ Therefore we have } X(s) = \int_0^{\infty} e^{-(s+4)t} dt = \frac{1}{s+4} \left[-e^{-(s+4)t} \right]_0^{\infty} = \frac{1}{s+4}.$$

$$X(s) = \frac{1}{s+4}, \text{Re}\{s\} > -4. \text{ Pole} = -4.$$



(ii) $x(t) = e^{-t}u(t) + e^{-3t}u(t)$

The Laplace Transform of $e^{-t}u(t)$ is

$$\int_{-\infty}^{\infty} e^{-t}u(t)e^{-st} dt = \int_0^{\infty} e^{-t} e^{-(\sigma+j\omega)t} dt = \int_0^{\infty} e^{-(1+\sigma)t} e^{-j\omega t} dt$$

with an region of convergence described by $\sigma = \text{Re}\{s\} > -1$.

The Laplace Transform of $e^{-3t}u(t)$ is

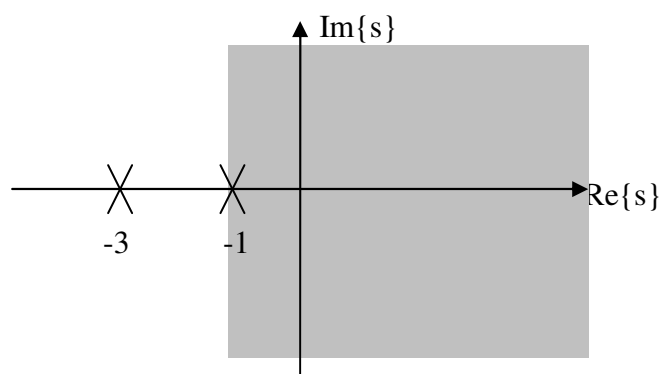
$$\int_{-\infty}^{\infty} e^{-3t}u(t)e^{-st} dt = \int_0^{\infty} e^{-3t} e^{-(\sigma+j\omega)t} dt = \int_0^{\infty} e^{-(3+\sigma)t} e^{-j\omega t} dt$$

with an region of convergence described by $\sigma = \text{Re}\{s\} > -3$.

Therefore for

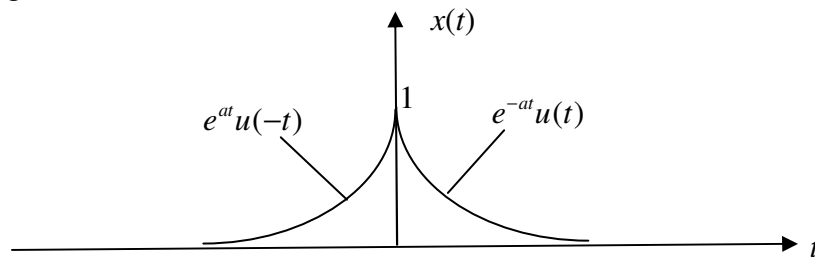
$$X(s) = \frac{1}{s+1} + \frac{1}{s+3}.$$

we have $\sigma = \text{Re}\{s\} > -1$.



(iii) $x(t) = e^{-a|t|}$, $a > 0$

The signal is shown below



We have $x(t) = e^{-a|t|} = e^{-at}u(t) + e^{at}u(-t)$ since $a > 0$.

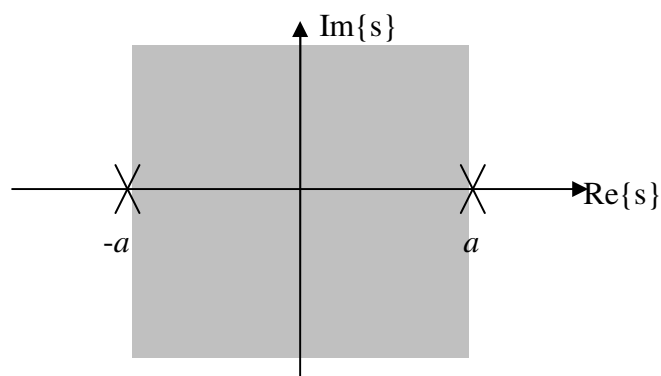
The Laplace transform for $e^{at}u(-t)$ is $\int_{-\infty}^0 e^{at}u(-t)e^{-st}dt = \int_{-\infty}^0 e^{at}e^{-(\sigma+j\omega)t}dt = \int_{-\infty}^0 e^{(a-\sigma)t}e^{-j\omega t}dt$.

The Laplace transform for $e^{at}u(-t)$ exists if $a - \sigma > 0$, i.e. $\sigma = \text{Re}\{s\} < a$.

$$\int_{-\infty}^0 e^{(a-s)t}dt = \frac{1}{a-s} \left[e^{(a-s)t} \right]_{-\infty}^0 = -\frac{1}{s-a}$$

The region of convergence for $\frac{1}{s+a}$, $\text{Re}\{s\} > -a$ and for $-\frac{1}{s-a}$, $\text{Re}\{s\} < a$

We have, $X(s) = \frac{1}{s+a} - \frac{1}{s-a}$ with region of convergence defined by $-a < \text{Re}\{s\} < a$.



Therefore $x(t) = e^{-a|t|} \leftrightarrow X(s) = \frac{1}{s+a} - \frac{1}{s-a}$, $-a < \text{Re}\{s\} < a$.

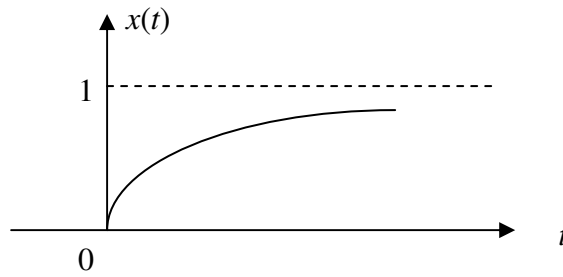
7. Find the Laplace transforms of the signal $x(t) = e^{-t}u(t) * u(t)$ and sketch $x(t)$.

Using the convolution property, $X(s) = \frac{1}{s+1} \times \frac{1}{s} = \frac{k_1}{s} + \frac{k_2}{s+1}$.

Using partial fraction expansion,

$$k_1 = \frac{1}{s+1} \Big|_{s=0} = 1 \text{ and } k_2 = \frac{1}{s} \Big|_{s=-1} = -1.$$

Therefore $X(s) = \frac{1}{s} - \frac{1}{s+1}$, $\text{Re}\{s\} > -1$ and $x(t) = 1 - e^{-t}u(t)$.



8. Determine the initial and the final values of the signal with Laplace transform

$$X(s) = \frac{10s}{s^2 + 10s + 300}.$$

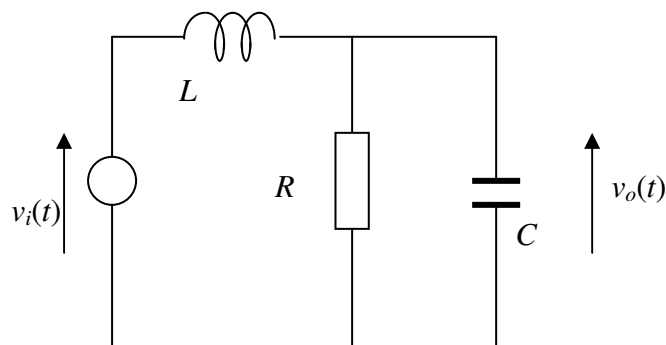
Using the initial value theorem,

$$x(0) = \lim_{s \rightarrow \infty} (sX(s)) = \lim_{s \rightarrow \infty} \left(s \frac{10s}{s^2 + 10s + 300} \right) = \lim_{s \rightarrow \infty} \left(\frac{10}{1 + 10/s + 300/s^2} \right) = 10.$$

Using the final value theorem,

$$\lim_{t \rightarrow \infty} x(t) = \lim_{s \rightarrow 0} (sX(s)) = \lim_{s \rightarrow 0} \left(s \frac{10s}{s^2 + 10s + 300} \right) = \lim_{s \rightarrow 0} \left(\frac{10s^2}{s^2 + 10s + 300} \right) = 0$$

9. Determine the transfer function of the circuit shown below.



- (i) If $R = 1 \Omega$ and $C = 1 \text{ pF}$ calculate the value of L required so that the circuit is critically damped. Sketch $v_o(t)$ if $v_i(t)$ is a unit step function.

$$\text{Let } Z_1 = \frac{R/sC}{R + 1/sC} = \frac{R}{1 + sRC}.$$

$$\text{The transfer function, } H(s) = \frac{V_o(s)}{V_i(s)} = \frac{Z_1}{Z_1 + sL} = \frac{\frac{R}{1 + sRC}}{\frac{R}{1 + sRC} + sL}.$$

$$H(s) = \frac{R}{R + sL(1 + sRC)} = \frac{R}{R + sL + s^2RLC} = \frac{1/LC}{s^2 + (1/RC)s + (1/LC)}.$$

The natural oscillating frequency is, $\omega_n = \frac{1}{\sqrt{LC}}$ and the damping factor is

$$\zeta = \frac{1/RC}{2\omega_n}. \text{ To achieve critical damping, } \zeta = \frac{1/RC}{2\omega_n} = 1.$$

If $R = 1\Omega$ and $C = 1\text{pF}$, $\omega_n = \frac{1}{2RC} = \frac{1}{2 \times 1 \times 1 \times 10^{-12}} = \frac{1}{2 \times 10^{-12}}$.

$\frac{1}{L} = C\omega_n^2$. Therefore $L = \frac{1}{C\omega_n^2} = \frac{(2 \times 10^{-12})^2}{1 \times 10^{-12}} = 4 \times 10^{-12} \text{H}$.

If $v_i(t) = u(t)$, $V_i(s) = 1/s$.

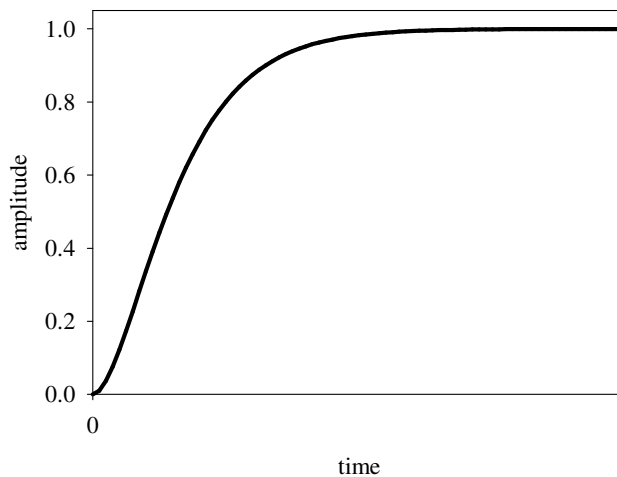
$$H(s) = \frac{1/LC}{s^2 + (1/RC)s + 1/LC} = \frac{(1/4 \times 10^{-24})}{s^2 + (1/1 \times 10^{-12})s + (1/4 \times 10^{-12})} = \frac{(1/4 \times 10^{-24})}{(s + 1/2 \times 10^{-12})^2} = \frac{k}{(s + \omega_n)^2}$$

The Laplace Transform of the unit step response is

$$V_o(s) = H(s)V_i(s) = \frac{k}{s(s + \omega_n)^2}.$$

From lecture notes, the unit step response in time domain is

$$v(t) = \frac{k}{\omega_n^2} - \frac{k}{\omega_n^2} [1 + \omega_n t] e^{-\omega_n t} u(t) = 1 - [1 + 5 \times 10^{11} t] e^{-t/2 \times 10^{-12}} u(t).$$



- (ii) If $R = 50\Omega$, $C = 1\text{ nF}$ and $L = 2.5\mu\text{H}$ calculate the damping factor and natural oscillating frequency. Sketch and describe $v_o(t)$ if $v_i(t)$ is a unit step function.

If $R = 50\Omega$, $C = 1\text{ nF}$ and $L = 2.5\mu\text{H}$, $\omega_n = \sqrt{\frac{1}{LC}} = \frac{1}{\sqrt{2.5 \times 10^{-6} \times 1 \times 10^{-9}}} = 20 \times 10^6$

rad/s.

$$\zeta = \frac{1/RC}{2\omega_n} = \frac{1/50 \times 10^{-9}}{2 \times 20 \times 10^6} = 0.5.$$

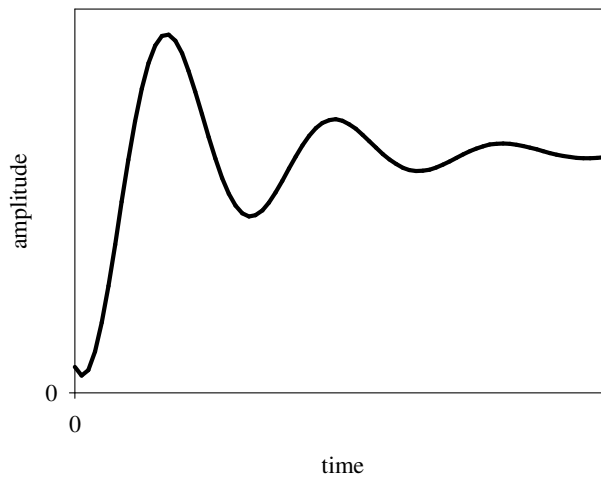
The system is underdamped. The unit step response is

$$y(t) = \frac{k}{\omega_n^2} \left(1 - \frac{k}{\omega_n \omega_d} e^{-\zeta \omega_n t} \sin(\omega_d t + \phi) u(t) \right).$$

$$\omega_d = \omega_n \sqrt{1 - \zeta^2} = 20 \times 10^6 \sqrt{1 - 0.5^2} = 17.32 \times 10^6 \text{ rad/s.}$$

$$\phi = \tan^{-1}(\omega_d / \zeta \omega_n) = \tan^{-1}(17.32 \times 10^6 / 0.5 \times 20 \times 10^6) = 1.565 \text{ rad.}$$

$$1/\zeta \omega_n = 1/0.5 \times 20 \times 10^6 = 1/10 \times 10^6 = 0.1 \times 10^{-6} \text{ s.}$$



The unit step response is a sinusoid with a frequency of $\omega_d = 17.32 \times 10^6$ rad/s that decays exponentially with a time constant of $1/\zeta\omega_n = 0.1 \times 10^{-6}$ s.

10. (i) The response is

$$Y(s) = \frac{sL \cdot X(s)}{sL + R + \frac{1}{sC}} = \frac{s^2 LC \cdot X(s)}{s^2 LC + sRC + 1}$$

The response to a unit step function is

$$Y(s) = \frac{s^2(2)(0.25)1/s}{s^2(2)(0.25) + (6)(0.25)s + 1} = \frac{s/2}{(\frac{1}{2})s^2 + (3/2)s + 1}$$

$$Y(s) = \frac{s}{s^2 + 3s + 2} = \frac{s}{(s+1)(s+2)} = \frac{2}{(s+2)} - \frac{1}{(s+1)}$$

Taking the inverse Laplace Transform gives

$$y(t) = (2e^{-t} - e^{-2t})u(t).$$

We have $X(s) = Y(s) + I(s)R + I(s)/sC$. When $x(t) = 0$, we have

$$0 = Y(s) + I(s)R + I_c(s)/sC$$

$I(s)$ and $I_c(s)$ are currents flowing through the resistor and capacitor associated with the initial conditions.

$$I(s) = I_L(s) = \frac{Y(s)}{sL} + \frac{i(0)}{s} \quad [\text{note that } Y(s) = sLI_L(s) - Li(0)] \text{ and}$$

$$v_c(t) = \frac{1}{C} \int_0^t i(\tau) d\tau + v_c(0)$$

$$V_c(s) = \frac{I(s)}{sC} + \frac{v_c(0)}{s}$$

$$I_c(s) = sCV_c(s) = I(s) + Cv_c(0) = \frac{Y(s)}{sL} + \frac{i(0)}{s} + Cv_c(0)$$

Substituting $I(s)$ and $I_c(s)$ we have

$$0 = Y(s) + \left[\frac{Y(s)}{sL} + \frac{i(0)}{s} \right] R + \frac{1}{sC} \left[\frac{Y(s)}{sL} + \frac{i(0)}{s} + Cv_c(0) \right]$$

$$Y(s) \left[\frac{s^2 LC + sRC + 1}{s^2 LC} \right] = - \left[\frac{i(0)sRC + i(0) + v_c(0)sC}{s^2 C} \right]$$

$$Y(s) = - \left[\frac{i(0)sLRC + i(0)L + v_c(0)sLC}{s^2LC + sRC + 1} \right]$$

$$Y(s) = - \left[\frac{i(0)L(sRC + 1) + v_c(0)sLC}{s^2LC + sRC + 1} \right]$$

$$Y(s) = - \left[\frac{1(2)(3s/2 + 1) + s/2}{(\frac{1}{2})s^2 + 3s/2 + 1} \right] = - \frac{7s + 4}{(s + 2)(s + 1)} = \frac{3}{(s + 1)} - \frac{10}{(s + 2)}$$

Therefore $y(t) = (3e^{-t} - 10e^{-2t})u(t)$

11. Consider a system with a transfer function $H(s) = \frac{1}{s+3}$. Find the forced and natural responses of this system if the input signal is given by $x(t) = \exp(-3t)u(t)$ and an initial condition of $y_o(0) = 1$, where $y_o(0)$ is the output signal at $t = 0$.

To work out the forced response, $Y_{forced}(s) = \frac{X(s)}{(s+3)} = \frac{1}{(s+3)(s+3)} = \frac{1}{(s+3)^2}$.

Therefore we have time domain forced response given by $y_{forced}(t) = t \exp(-3t)u(t)$.

To work out the natural response, $Y_{natural}(s) = \frac{y(0)}{(s+3)} = \frac{1}{(s+3)}$ and therefore the corresponding expression in time domain is $y_{natural}(t) = [\exp(-3t)]u(t)$.