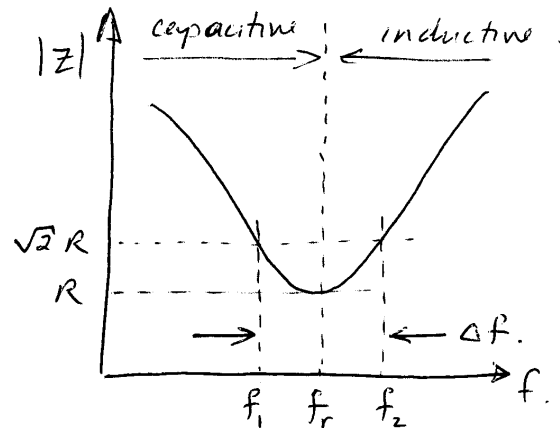


①

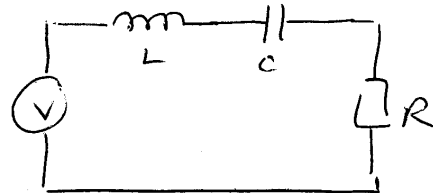
## Resonance - proof of $Q = \frac{f_r}{\Delta f}$

The current is proportional to  $1/|Z|$  for a series circuit driven by a constant  $V_0$ . Thus the current will have fallen by a factor of  $\sqrt{2}$  from its maximum value when  $|Z|$  has increased by a factor of  $\sqrt{2}$  from its minimum value.



$$Z = j\omega L + \frac{1}{j\omega C} + R$$

$$= R + j\left(\omega L - \frac{1}{\omega C}\right)$$



and

$$|Z| = \sqrt{R^2 + \left(\omega L - \frac{1}{\omega C}\right)^2}$$

The minimum  $|Z| = R$  and this occurs at  $\omega = \frac{1}{\sqrt{LC}}$

For  $\omega_2 (= 2\pi f_2)$ , ckt is inductive so  $\omega L > \frac{1}{\omega C}$   
we want to know when  $|Z|$  increases to  $\sqrt{2}|Z|_{\min}$ .

$$\text{i.e. } \sqrt{2}|Z|_{\min} = \sqrt{R^2 + \left(\omega_2 L - \frac{1}{\omega_2 C}\right)^2} = \sqrt{2}R$$

$$\text{or } 2R^2 = R^2 + \left(\omega_2 L - \frac{1}{\omega_2 C}\right)^2$$

$$\text{or } R^2 = \left(\omega_2 L - \frac{1}{\omega_2 C}\right)^2$$

$$\text{or } R = \omega_2 L - \frac{1}{\omega_2 C}$$

$$\text{or } 0 = \omega_2^2 LC - \omega_2 CR - 1$$

$$\omega_2 = \frac{CR \pm \sqrt{C^2 R^2 + 4LC}}{2LC}$$

(2)

since the -ve root would give a negative frequency, take the +ve root...

$$\omega_2 = \frac{CR + \sqrt{C^2 R^2 + 4LC}}{2LC} = 2\pi f_2$$

For  $\omega_1 (= 2\pi f_1)$  the ckt is capacitive so  $\frac{1}{\omega_1 C} > \omega_1 L$

$$\text{so } \sqrt{2} R = \sqrt{R^2 + \left(\frac{1}{\omega_1 C} - \omega_1 L\right)^2}$$

$$\text{or } R^2 = \left(\frac{1}{\omega_1 C} - \omega_1 L\right)^2$$

$$\text{or } R = \frac{1}{\omega_1 C} - \omega_1 L$$

following the same process as for  $\omega_2$  leads to...

$$\omega_1 = \frac{-CR + \sqrt{C^2 R^2 + 4LC}}{2LC} = 2\pi f_1$$

$$\begin{aligned} \omega_2 - \omega_1 &= \frac{CR + \sqrt{(CR)^2 + 4LC}}{2LC} - \frac{-CR + \sqrt{(CR)^2 + 4LC}}{2LC} \\ &= \frac{CR}{LC} = \frac{R}{L} \end{aligned}$$

$$\frac{f_r}{f_2 - f_1} = \frac{\omega_r}{\omega_2 - \omega_1} = \frac{1}{\sqrt{LC}} \cdot \frac{L}{R} = \frac{1}{R} \sqrt{\frac{L}{C}} = \underline{\underline{Q}}$$

also

$$\begin{aligned} \sqrt{\omega_1 \omega_2} &= \sqrt{\frac{CR \sqrt{(CR)^2 + 4LC} + C^2 R^2 + 4LC - C^2 R^2 - CR \sqrt{(CR)^2 + 4LC}}{4L^2 C^2}} \\ &= \sqrt{\frac{4LC}{4L^2 C^2}} = \frac{1}{\sqrt{LC}} = \underline{\underline{\omega_r}} \end{aligned}$$

## Admittance, Conductance + Susceptance

These are the inverse of impedance, resistance and reactance.

$$\text{Conductance, } G = \frac{1}{R} = \frac{1}{\text{resistance}}$$

$$\text{Susceptance, } B = \frac{1}{X} = \frac{1}{\text{reactance}}$$

$$\text{Admittance, } Y = \frac{1}{Z} = \frac{1}{\text{impedance}} = \frac{I}{V}$$

$Y, G + B$  have units of  $\Omega^{-1}$ , sometimes written  $\mathcal{S}$ , mhos, or Siemens.

"Siemens" is the standard SI unit for  $\frac{1}{\text{ohms}}$ .

$Y, G$  and  $B$  are particularly useful for parallel networks which often occur naturally at very high frequencies. If one writes down the impedance of a parallel network it is always of the form

$$Z = \frac{1}{\frac{1}{R_1} + \frac{1}{R_2} + \frac{1}{R_3} + \frac{1}{X_1} + \frac{1}{X_2} + \frac{1}{X_3}}$$

$$\text{or } \frac{1}{Z} = \frac{1}{R_1} + \frac{1}{R_2} + \frac{1}{R_3} + \frac{1}{X_1} + \frac{1}{X_2} + \frac{1}{X_3}$$

using  $Y, G + B$  this would become

$$Y = G_1 + G_2 + G_3 + B_1 + B_2 + B_3$$

An inductive susceptance =  $\frac{1}{j\omega L}$ .

A capacitive susceptance =  $j\omega C$

The significance of "j" is the same as for  $Z$  but the phase of  $Y$  (ie  $\tan^{-1}(\frac{\text{im } Y}{\text{re } Y})$ ) is the phase of  $I$  with respect to  $V_0$ .

(4)

### Series to Parallel Transformation

What values of  $L'$  and  $R'_s$  will make circuit (2) have the same impedance as circuit (1)?

We must have

$$Z(1) = Z(2)$$

$$\text{or } Y(1) = Y(2)$$

$$Z(1) = R_s + j\omega L \quad Y(2) = \frac{1}{R'_s} + \frac{1}{j\omega L'}$$

$$Y(1) = \frac{1}{Z(1)} = \frac{1}{R_s + j\omega L} = \frac{R_s - j\omega L}{R_s^2 + \omega^2 L^2}$$

$$= \frac{R_s}{R_s^2 + \omega^2 L^2} - \frac{j}{\omega \left( \frac{R_s^2 + \omega^2 L^2}{\omega L} \right)}$$

$$= \frac{1}{R_s \left( \frac{R_s^2 + \omega^2 L^2}{R_s^2} \right)} - \frac{j}{\omega L \left( \frac{R_s^2 + \omega^2 L^2}{\omega^2 L^2} \right)}$$

Compare with  $Y(2) = \frac{1}{R'_s} - \frac{j}{\omega L'}$ , for equivalence

$$R'_s = R_s \left( \frac{R_s^2 + \omega^2 L^2}{R_s^2} \right)$$

$$L' = L \left( \frac{R_s^2 + \omega^2 L^2}{\omega^2 L^2} \right)$$

Similar processes can be used to find equivalent series elements that will represent a given parallel combination.

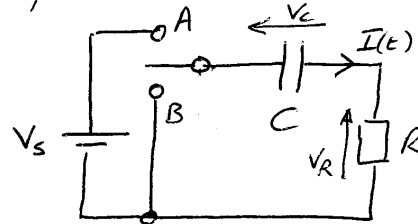
A similar process can be used to transform a series CR circuit to a parallel equivalent

If there is more than one reactive element in the original circuit it will usually transform to a single susceptance.

### Transient Responses.

Analysis performed using the "jw" or phasor diagram approach assumes a sinusoidal source and allows the calculation of circuit parameters as a function of frequency. A transient analysis works out the response of a circuit to a source as a function of time. The approach to a transient analysis is as follows...

Assume that switch has been in position B for a long time so that there is no charge in C.



At  $t=0$ , the switch is switched to position A....

$$V_s = V_C + V_R = \frac{1}{C} \int I(t) dt + I(t)R.$$

First get rid of the integral by differentiating both sides

$$\frac{dV_s}{dt} = \frac{1}{C} I(t) + R \frac{dI(t)}{dt} = 0 \quad \text{since } V_s = \text{const.}$$

Then rearrange the equation...

$$\frac{dI(t)}{I(t)} = -\frac{dt}{CR}$$

Then integrate to get an expression for  $I(t)$ ...

$$\int \frac{dI(t)}{I(t)} = -\int \frac{dt}{CR} + \text{const.}$$

$$\ln I(t) = -\frac{t}{CR} + \text{const.}$$

$$\text{or } I(t) = e^{-t/CR + \text{const}} = A e^{-t/CR}$$

We now need to use boundary conditions to define A. When  $t = 0 + \delta t$  where  $\delta t \rightarrow 0$ ,  $V_C = 0$  because there has been no time for charge to flow in the circuit. Therefore  $V_R = V_s$  and  $I(t)$  at  $t = 0 + \delta t = V_s/R$

(6)

Thus  $I(0) = \frac{V_s}{R} = A e^{-0} = A$

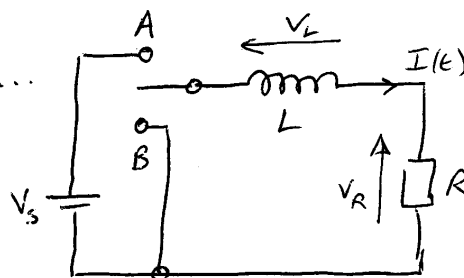
$$\therefore I(t) = \frac{V_s}{R} e^{-t/RC}$$

$RC$  is called the time constant,  $\tau$ .

$$\left[ R \times C = \frac{V}{A} \times \frac{Q}{V} = \frac{V}{Q/s} \times \frac{Q}{V} = s \right]$$

An inductor example...

This time assume that the switch has been in position A for a long time.



The equation describing  $I(t)$  is

$$0 = L \frac{dI(t)}{dt} + I(t)R \quad \text{immediately after the switch has been moved to B.}$$

Following the same process as for the previous case...

$$\frac{dI(t)}{I(t)} = - \frac{R}{L} dt$$

$$\int \frac{dI(t)}{I(t)} = - \frac{R}{L} \int dt + C$$

$$\text{or} \quad \ln I(t) = - \frac{R}{L} t + C$$

$$\text{or} \quad I(t) = A e^{-\frac{R}{L} t}$$

The boundary condition here is that  $I(t)$  immediately after switching is the same as the  $I(t)$  immediately before switching - ie  $I(t)$  at  $t=0-\delta t$  where  $\delta t \rightarrow 0 = V_s/R$ .

$$\therefore A = \frac{V_s}{R} \quad \text{and} \quad I(t) = \frac{V_s}{R} e^{-t/\tau} \quad \text{where} \quad \tau = L/R$$

### dB and Filter Responses

The dB (decibel) is a logarithmic unit used to express ratios of quantities such as current, voltage, power. It was originally devised as a measure of sound level in the context of loss of intensity in early telephone systems. Used in many applications today.

(i) As a power ratio  $dB = 10 \log \frac{P_1}{P_2}$

(ii) As a voltage ratio  $dB = 10 \log \frac{V_1^2}{V_2^2} = 20 \log \frac{V_1}{V_2}$

(iii) As a current ratio  $dB = 10 \log \frac{I_1^2}{I_2^2} = 20 \log \frac{I_1}{I_2}$

Often the lower part of the ratio ( $P_2, V_2, I_2$ ) is a fixed reference - eg

dBV  $\rightarrow$  reference level is 1V rms

dBu  $\rightarrow$  reference level is 1mW in 600 $\Omega$  (0.775Vrms)

dBm  $\rightarrow$  reference level is 1mW in 50 $\Omega$  (0.223Vrms)

dB(SPL)  $\rightarrow$  reference level is 20 $\mu$ Pa. } threshold of human

dB(SWL)  $\rightarrow$  reference level is  $10^{-12}$ W } hearing

If  $V_1 = \frac{V_{rm}}{\sqrt{2}}$  and  $V_2 = V_{rm}$ , the change in dB involved in that factor of  $\frac{1}{\sqrt{2}}$  is  $20 \log \frac{V_r/\sqrt{2}}{V_r} = -3.01 \text{ dB}$   
 $\approx -3 \text{ dB}$

This is why the width of a resonant peak when  $V_r$  is  $\frac{1}{\sqrt{2}} \times V_{max}$  is called the -3dB bandwidth.

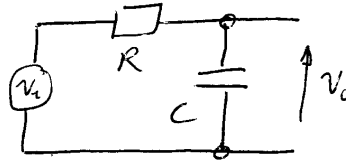
The dBm is used as an absolute power measure in 50 $\Omega$  impedance matched systems such as satellite, radar and other microwave systems

The dBu is similarly used in audio systems which use impedance matched 600 $\Omega$  signal transfer methods.

dB are used extensively in their ratio form in the plotting of the magnitude responses of frequency dependent circuits.

Consider the circuit consisting of  $C + R$ .

$$\frac{V_o}{V_i} = \frac{1/j\omega C}{R + 1/j\omega C} = \frac{1}{1 + j\omega CR}$$



To work out the response of this circuit the first step would normally be to let  $CR = 1/\omega_0$ . This is an arbitrary substitution and is done simply because if one wants to evaluate behaviour as a function of frequency, it makes sense to have constants defined in terms of frequency rather than time...

$$\text{so } \frac{V_o}{V_i} = \frac{1}{1 + j\omega/\omega_0} \quad \text{and} \quad \left| \frac{V_o}{V_i} \right| = \left[ \frac{1}{1 + (\omega/\omega_0)^2} \right]^{1/2}$$

$$\text{when } \omega \ll \omega_0, \quad 1 + (\omega/\omega_0)^2 \approx 1 \quad \text{so } \left| \frac{V_o}{V_i} \right| = 1 \equiv 0 \text{ dB}$$

$$\text{when } \omega = \omega_0, \quad 1 + (\omega/\omega_0)^2 \approx 2 \quad \text{so } \left| \frac{V_o}{V_i} \right| = \frac{1}{\sqrt{2}} \equiv -3 \text{ dB}$$

$$\text{when } \omega \gg \omega_0, \quad 1 + (\omega/\omega_0)^2 \approx (\omega/\omega_0)^2 \quad \text{so } \left| \frac{V_o}{V_i} \right| = \frac{\omega_0}{\omega}$$

ie if  $\omega$  increases by a factor of 10 (a decade)  
 $\left| \frac{V_o}{V_i} \right|$  decreases by a factor of 10 ( $-20 \text{ dB}$ )

so in the region  $\omega \gg \omega_0$ , gain "rolls off" at  $-20 \text{ dB/decade}$ .

