

Lecture 6: Lattice defects



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Lecture 6: Lattice defects

- classification of lattice defects according to their dimensionality
- · point defects
- line defects
- · two-dimensional lattice defects
- · three-dimensional defects



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classification of lattice defects

dimensionality and types of lattice defects:

- OD or point defects: vacancies, dopants, interstitials, Schottky defects, Frenkel-pairs, colour centres
- 1D or line defects: dislocations
- 2D defects: special grain boundaries (antiphase, inversion domain), stacking faults
- 3D defects: pores, precipitates, clusters, general phase boundaries



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point defects (0D): types

- vacancies: atom missing on lattice site
- dopants: foreign atom on lattice site
- interstitials: additional atom between lattice sites
- Schottky defects: vacancy left behind by atom having moved to the surface of the crystal
- Frenkel-pairs: thermal vacancy & interstitial
- colour centres: electron on interstitial site





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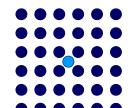


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point defects (0D): types

 vacancies: atom missing on lattice site

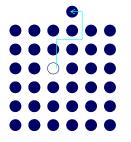


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point defects (0D): formation

thermal anneal (heating)

(e.g. hardening of metal alloys)

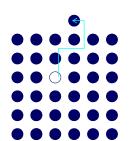
irradiation (e.g. by X-rays)

(e.g. steels for nuclear reactors)

· doping by diffusion from surface

(e.g. for solid state electrolytes)

 doping by ion implantation and anneal (e.g. for pn diodes for electronics)





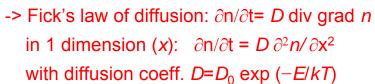
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example of doping by ion implantation and annealing

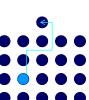
principle of diffusion:

- particle current density: *j***=** *D* grad *n*
- continuity equation: ∂n/∂t= -div *j*



(D_0 = diffusion constant, k=Boltzmann const., T=temp.)

solutions depend on boundary conditions:





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example of doping by surface diffusion and annealing

a) constant concentration on the surface:

 $n(x,0)=0 & n(0,t)=n_0=\text{const}$

-> $n(x,t)=n_0 \left[1-2/\sqrt{\pi} \int_0^\infty \exp(-u^2) du\right]$ with $a=x/(2\sqrt{Dt})$ is error function with penetration depth $x=1.28\sqrt{Dt}$

The University Of Sheffield.

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example of doping by surface diffusion and annealing

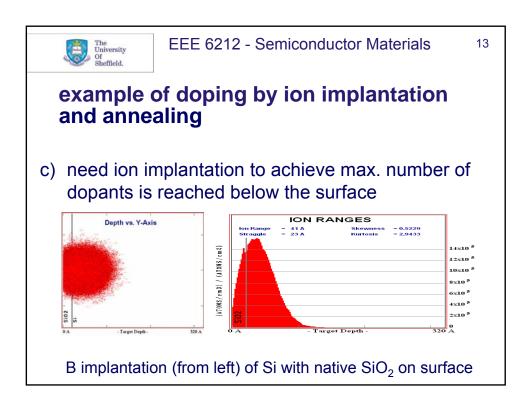
b) constant number of dopant atoms on the surface:

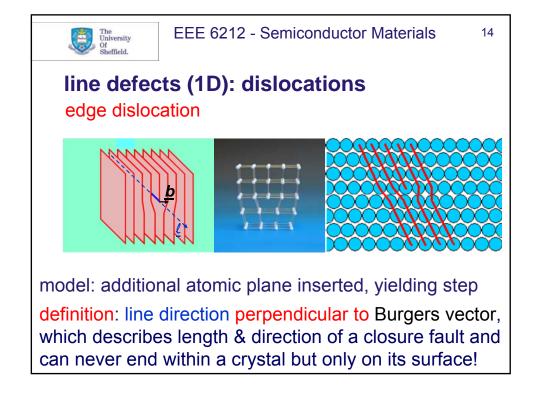
n(x,0)=0 for x>0, $N(0,0)=n_0 d \delta(x)$ for x=0 & $n(0,0)=n_0$

-> $n(x,t)=n_0 d/(\sqrt{\pi D}t) \exp{-[x^2/(4Dt)]}$

is Gauss function with depth $x=2\sqrt{Dt} >> d$, area n_0d





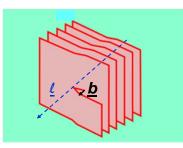


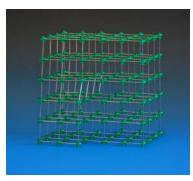


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line defects (1D): dislocations

screw dislocation





model: twisted atomic planes, yielding spiral staircase definition: line direction parallel to Burgers vector

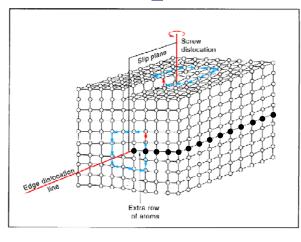


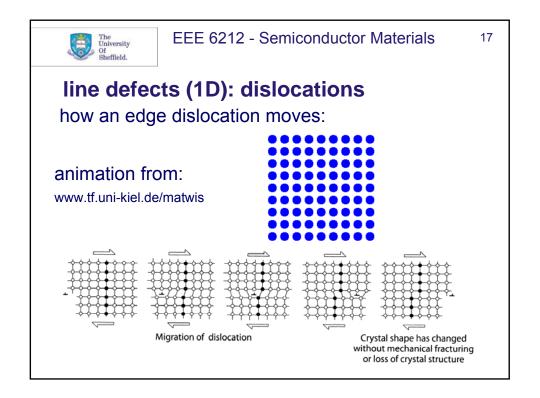
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line defects (1D): dislocations

mixed dislocation: **<u>b</u>**=const but line direction changes







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line defects (1D): dislocations

elastic energy per length stored within a screw dislocation: consider cylinder with embedded

screw dislocation where torus of radius r and thickness dr is displaced along dislocation line by b.

If G=shear modulus, then

- -> shear angle: $\alpha = b/(2\pi r)$
- -> shear stress: $\tau = G\alpha = Gb/(2\pi r)$
- -> elastic energy stored per length and volume: $dE/dV=G\int\alpha\ d\alpha$ and $dV=2\pi\ rdr$
- -> $dE = G \int \alpha \ d\alpha \ dV = G \alpha^2/2 \ dV = Gb^2/(4\pi) 1/r \ dr$



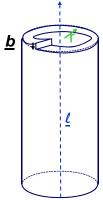
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line defects (1D): dislocations

elastic energy per length stored within a screw dislocation:

->
$$dE = G \int \alpha \ d\alpha \ dV = G \alpha^2/2 \ dV$$

 $= Gb^2/(4\pi) \ 1/r \ dr$
-> $E = \int dE \qquad r_0$
 $= Gb^2/(4\pi) \ \ln r \mid^{r_0 \approx 5b}$
 $= Gb^2/(4\pi) \ \ln r_0/r_1$
 $\approx \frac{1}{2} \ Gb^2$



where, b=length of Burgers vector,

 $r_{\rm o}$ = outer radius of cylinder around screw dislocation, $r_{\rm i} \approx 5b$



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line defects (1D): dislocations

total energy: $E\ell = Gb^2\ell/(4\pi) \ln r_0/r_1 \approx \frac{1}{2} Gb^2\ell$

(note: edge dislocations: similar apart from a factor of $1/(1-\nu)$ where ν is Poisson ratio)

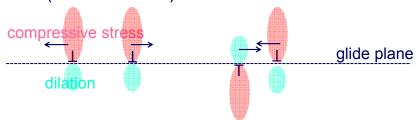
The energy of such a dislocation is ~5-8eV, far too large to be produced thermally at any temperature. The only way to form them is by force, i.e.: deformation, stress at surfaces & interfaces or by dislocation reactions (multiplication).



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line defects (1D): dislocations

Because of $E \propto b_{tot}^2$, and $\underline{\boldsymbol{b}}_{tot} = \Sigma \underline{\boldsymbol{b}}_i$, dislocations with the same Burgers vector direction repel each other, (often leading to equidistant spacings within a plane) while those with opposite Burgers vector attract each other (-> annihilation).





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