

Tutorial Sheet – No 3 Answers

- 1 The general expression for a sinusoidal waveform is:

$$v(t) = A_{pk} \sin(2\pi ft + \phi)$$

where:

A_{pk} is the peak amplitude

f is the frequency in Hertz

ϕ is the phase angle

comparing

$$v = 339.4 \sin(100\pi t) \text{ Volts}$$

with the general expression gives:

$$A_{pk} = 339.4 \text{ V}$$

$$f = 50 \text{ Hz}$$

and for a sinusoidal waveform the rms value is $1/\sqrt{2}$ times the peak value:

$$V_{rms} = \frac{A_{pk}}{\sqrt{2}} = \frac{339.4}{\sqrt{2}} = 240 \text{ V}_{rms}$$

- 2 Using the general expression from question 1 we can write:

$$i(t) = 100 \times \sqrt{2} \sin(2\pi \times 200 \times t + 0) = 141.4 \sin(400\pi t)$$

- 3 Remember that the peak-to-peak value is double the peak value. The frequency can be obtained from:

$$f = \frac{1}{T} = \frac{1}{25 \times 10^{-3}} = 40 \text{ Hz}$$

hence:

$$v(t) = \frac{198}{2} \sin(2\pi \times 40 \times t + 0) = 99 \sin(80\pi t)$$

and for a sinusoidal waveform the rms value is $1/\sqrt{2}$ times the peak value:

$$V_{rms} = \frac{A_{pk}}{\sqrt{2}} = \frac{99}{\sqrt{2}} = 70 \text{ V}_{rms}$$

- 4 Comparing the expression for the current with the general expression shown in question 1 we can obtain the following:

$$I_{pk} = 14.14 \text{ V}$$

$$I_{rms} = I_{pk} / \sqrt{2} = 10 \text{ V}_{rms}$$

$$f = 50 \text{ Hz}$$

$$\phi = -\pi/6 \text{ or } -30^\circ$$

(negative sign indicates current lags behind the voltage)

Expressing the voltage and current in polar form and taking the voltage as reference gives:

$$V = 240 \angle 0^\circ \quad \text{and} \quad I = 10 \angle -30^\circ$$

and hence the impedance can be obtained as:

$$Z = \frac{V}{I} = \frac{240 \angle 0^\circ}{10 \angle -30^\circ} = 24 \angle 30^\circ = 20.78 + j12 \quad \Omega$$

since the current is lagging behind the voltage this implies the circuit is inductive.

Comparing the above expression with the general expression for impedance of a circuit containing a series R L combination and looking at real and imaginary parts gives:

$$Z = R + jX_L = R + j2\pi fL$$

and:

$$R = 20.78 \Omega$$

$$X_L = 12 \Omega \quad \text{and} \quad L = \frac{X_L}{2\pi f} = \frac{12}{2\pi \times 50} = 38.2\text{mH}$$

- 5 The power factor is the cosine of the phase angle, hence:

$$pf = \cos \phi = \cos 30^\circ = \mathbf{0.866 \text{ lagging}}$$

The input power to the circuit is given by:

$$P = V_{rms} I_{rms} \cos \phi = 240 \times 10 \times \cos 30^\circ = \mathbf{2.08\text{kW}}$$

Since power can only be dissipated in a resistor then:

$$P = I_{rms}^2 R = 10^2 \times 20.78 = \mathbf{2.08\text{kW}}$$

- 6 The voltage of $100V_{rms}$ appears across each limb of the circuit. It is therefore easier to calculate the current in each limb and sum them to obtain the total current.

For limb 1:

$$Z_1 = 20 + j0 = 20\angle 0^\circ \Omega$$

$$I_1 = \frac{V}{Z_1} = \frac{100\angle 0^\circ}{20\angle 0^\circ} = 5\angle 0^\circ = 5 + j0 \text{ A}_{rms}$$

For limb 2:

$$Z_2 = 10 + j10 = 14.14\angle 45^\circ \Omega$$

$$I_2 = \frac{V}{Z_2} = \frac{100\angle 0^\circ}{14.14\angle 45^\circ} = 7.07\angle -45^\circ = 5 - j5 \text{ A}_{rms}$$

Summing the two currents gives:

$$I_T = I_1 + I_2 = 5 + j0 + 5 - j5 = 10 - j5 = \mathbf{11.18\angle -26.6^\circ \text{ A}_{rms}}$$

The power factor is the cosine of the phase angle, hence:

$$pf = \cos \phi = \cos 26.6^\circ = \mathbf{0.89 \text{ lagging}}$$

The input power to the circuit is given by:

$$P = V_{rms} I_{rms} \cos \phi = 100 \times 11.18 \times 0.89 = \mathbf{1\text{kW}}$$

- 7 Using the values for the limb current calculated in the previous question:

$$P_1 = I_{1rms}^2 R_1 = 5^2 \times 20 = \mathbf{500\text{W}}$$

$$P_2 = I_{2rms}^2 R_2 = 7.07^2 \times 10 = \mathbf{500\text{W}}$$

$$P_T = P_1 + P_2 = \mathbf{1\text{kW}}$$

Calculate the voltages across the components in limb 2:

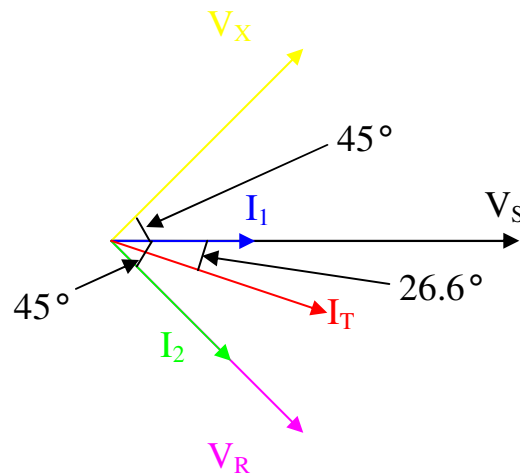
$$V_R = I_2 \times R = 7.07\angle -45^\circ \times 10 = \mathbf{70.7\angle -45^\circ \text{ V}_{rms}}$$

$$V_X = I_2 \times X_L = 7.07\angle -45^\circ \times 10\angle 90^\circ = \mathbf{70.7\angle 45^\circ \text{ V}_{rms}}$$

These quantities are vectors and hence their sum is:

$$V_S = \sqrt{V_R^2 + V_X^2} = \sqrt{70.7^2 + 70.7^2} = \mathbf{100 \text{ V}_{rms}}$$

The phasor diagram for the circuit is:



- 8 For a series combination of a resistance and an inductance:

$$Z = R + j2\pi fL = 10 + j2\pi \times 50 \times 0.1 = 10 + j31.4 = 32.96 \angle 72.3^\circ \Omega$$

Now:

$$I = \frac{V \angle 0^\circ}{Z \angle \phi} = \frac{100 \angle 0^\circ}{32.95 \angle 72^\circ} = 3.03 \angle -72.3^\circ \text{ A}_{\text{rms}}$$

The power factor is given by:

$$pf = \cos \phi = \cos 72.3^\circ = \mathbf{0.304 \text{ lagging}}$$

- 9 With the two components connected in parallel the supply voltage will appear across each component, therefore it is easiest to calculate the current in R and L and then sum them.
For the resistor:

$$I_R = \frac{V}{Z_R} = \frac{100 \angle 0^\circ}{10 \angle 0^\circ} = 10 \angle 0^\circ = 10 + j0 \text{ A}_{\text{rms}}$$

For the inductive reactance:

$$I_X = \frac{V}{Z_X} = \frac{100 \angle 0^\circ}{31.4 \angle 90^\circ} = 3.18 \angle -90^\circ = 0 - j3.18 \text{ A}_{\text{rms}}$$

Summing the two currents gives:

$$I_T = I_R + I_X = 10 + j0 + 0 - j3.18 = 10 - j3.18 = \mathbf{10.5 \angle -17.6^\circ \text{ A}_{\text{rms}}}$$

The power factor is given by:

$$pf = \cos \phi = \cos 17.6^\circ = \mathbf{0.95 \text{ lagging}}$$

- 10 Using Ohm's law for a dc circuit the resistance of the coil can be obtained:

$$R = \frac{V}{I} = \frac{24}{4} = 6 \Omega$$

Now when an ac supply is used:

$$Z = \frac{V}{I} = \frac{40}{4} = 10 \Omega$$

Let the reactance of the coil be $X_L \Omega = j\omega L$, then:

$$|Z| = \sqrt{R^2 + \omega^2 L^2}$$

or

$$|X_L| = \sqrt{Z^2 - R^2} = \sqrt{100 - 36} = 8 \Omega$$

$$\phi = \tan^{-1}\left(\frac{X_L}{R}\right) = \tan^{-1}\left(\frac{8}{6}\right) = 53.1^\circ$$

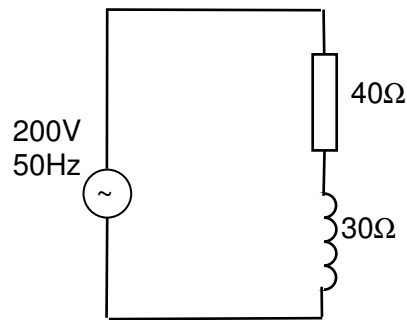
The power supplied is obtained from:

$$P = VI \cos \phi = 40 \times 4 \times \cos 53.1 = \mathbf{96 \text{ W}}$$

Alternatively power dissipated in the real part of impedance (resistance):

$$P = I^2 R = 4^2 \times 6 = \mathbf{96 \text{ W}}$$

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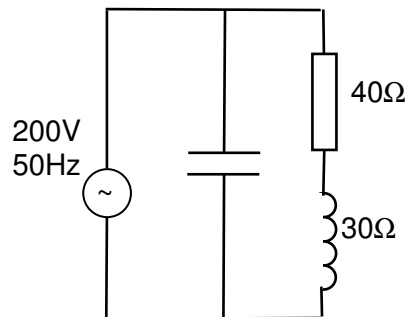
The impedance of the motor is given by:

$$Z = R + jX_L = 40 + j30 = 50 \angle 36.87^\circ \Omega$$

The current can then be found from:

$$I = \frac{V}{Z} = \frac{200 \angle 0^\circ}{50 \angle 36.87^\circ} = 4 \angle -36.87^\circ = 3.2 - j2.4 \text{ A}_{\text{rms}}$$

A capacitor is now connected in parallel:



When the power factor is unity, then the phase angle is zero and the imaginary component of the supply current is zero. Therefore the capacitor current must be equal to $j2.4$ or $2.4 \angle 90^\circ \text{ A}_{\text{rms}}$. Hence:

$$|X_C| = \frac{200}{2.4} = 83.33 \Omega$$

and:

$$C = \frac{I}{2\pi f X_C} = \frac{I}{2\pi f X_C} = \frac{I}{2\pi \times 50 \times 83.33} = \mathbf{38.2 \mu F}$$

The current drawn from the supply is then:

$$I_T = I_M + I_C = 3.2 - j2.4 + 0 + j2.4 = 3.2 + j0 = \mathbf{3.2 \angle 0^\circ \text{ A}_{\text{rms}}}$$

For an overall power factor of 0.9, the real power remains unchanged, therefore:

$$VI_{\text{NEW}} \times 0.9 = VI_{\text{TOLD}} \times 1$$

hence:

$$I_{TNEW} = I_{TOLD} \times \frac{I}{0.9} = 3.2 \times \frac{I}{0.9} = \mathbf{3.56 \text{ A}_{rms}}$$

and since the power factor is 0.9 the current may be written as:

$$I_{TNEW} = 3.56 \cos \phi - j3.56 \sin \phi = 3.56 \times 0.9 - j3.56 \times \sqrt{1-0.9^2} = 3.2 - j1.55 \text{ A}_{rms}$$

The capacitor current must therefore be equal to $j2.4 - j1.55 = j0.85 \text{ A}_{rms}$.

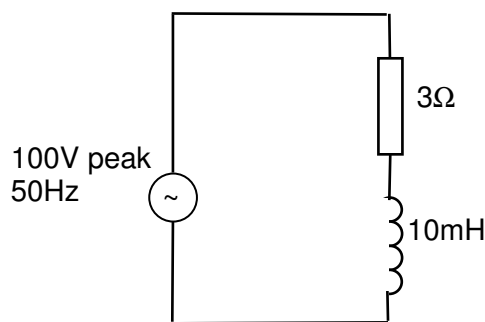
$$|X_C| = \frac{200}{0.85} = 253.3 \Omega$$

and:

$$C = \frac{I}{2\pi f X_C} = \frac{I}{2\pi f X_C} = \frac{I}{2\pi \times 50 \times 253.3} = \mathbf{13.5 \mu F}$$

$$P = I^2 R = 4^2 \times 6 = \mathbf{96 \text{ W}}$$

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First we need to obtain the rms current:

$$Z_T = R + j\omega L = 3 + j2\pi \times 50 \times 0.01 = 3 + j3.14 = 4.34 \angle 46.3^\circ \Omega$$

The rms value of the voltage is related to the peak value by:

$$V_{RMS} = \frac{V_{PK}}{\sqrt{2}} = \frac{100}{\sqrt{2}} = 70.7 \text{ V}_{rms}$$

If we take the supply voltage as reference then:

$$I_{RMS} = \frac{V_{RMS}}{Z} = \frac{70.7 \angle 0^\circ}{4.34 \angle 46.3^\circ} = 16.3 \angle -46.3^\circ \text{ A}_{rms}$$

The input power to the circuit is given by:

$$P = V_{rms} I_{rms} \cos \phi = 70.7 \times 16.3 \times \cos 46.3^\circ = \mathbf{796 \text{ W}}$$

The power transfer could be increased by adding a series capacitor to resonate at 50Hz with the inductor. At resonance this series RCL circuit will appear purely resistive:

$$I_{RMS} = \frac{V_{RMS}}{R} = \frac{70.7 \angle 0^\circ}{3 \angle 0^\circ} = 23.6 \angle 0^\circ \text{ A}_{rms}$$

and the power dissipated in the 3Ω resistor would now be:

$$P = I_{RMS}^2 R = 23.6^2 \times 3 = \mathbf{1.67 \text{ kW}}$$