## Solution EEE201 Jan 2008

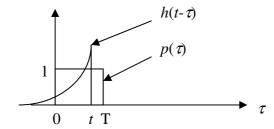
Q1)

a) The response is 
$$y(t) = p(t) * h(t) = \int_{-\infty}^{\infty} p(\tau)h(t-\tau)d\tau$$
.

Alternatively evaluate  $y(t) = h(t) * p(t) = \int_{-\infty}^{\infty} h(\tau) p(t - \tau) d\tau$ .

For 
$$t < 0$$
,  $p(\tau)h(t-\tau) = 0$ .

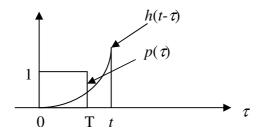
For 0 < t < T,



We need to integrate from 0 to t.

$$y(t) = \int_{-\infty}^{\infty} p(\tau)h(t-\tau)d\tau = \int_{0}^{t} \frac{1}{RC} e^{-(t-\tau)/RC} d\tau = \frac{RC}{RC} \left[ e^{-(t-\tau)/RC} \right]_{0}^{t} = 1 - e^{-t/RC}$$

For  $t \ge T$ ,

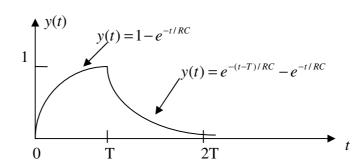


We need to integrate from 0 to T.

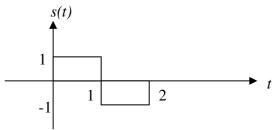
$$y(t) = \int_{0}^{T} \frac{1}{RC} e^{-(t-\tau)/RC} d\tau = \frac{RC}{RC} \left[ e^{-(t-\tau)/RC} \right]_{0}^{T} = e^{-(t-T)/RC} - e^{-t/RC}$$

Therefore we have

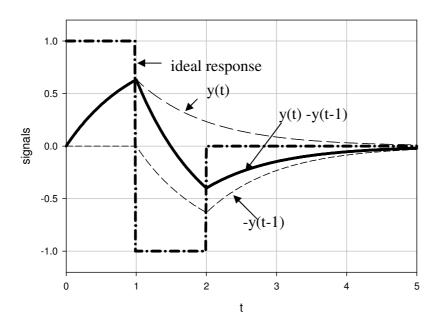
$$y(t) = \begin{cases} 0 & t < 0 \\ 1 - e^{-t/RC} & 0 < t < T \\ e^{-(t-T)/RC} - e^{-t/RC} & t \ge T \end{cases}$$



Q1bi) The sequence "1 0" looks like



ii) The sequence can be written as s(t) = p(t) - p(t-1). Since the system is LTI, the response is given by r(t) = y(t) - y(t-1). Therefore we have



iii) The response r(t) showed a severely distorted pulse shape due to very significant ISI. When the time constant is small, i.e RC is << 1, the circuit has high bandwidth and the response r(t) will approach that of the ideal response. When RC ~ 1 the circuit behaves like a low pass filter causing the distortion in the pulse shape and produces ISI. The peak at t=2s is significantly lower than -1, potentially causing an error during decoding.

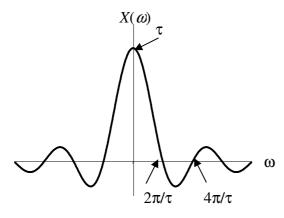
a) i)

$$\begin{split} X(\omega) &= \int\limits_{-\infty}^{\infty} x(t) e^{-j\omega t} dt = \int\limits_{-\tau/2}^{\tau/2} e^{-j\omega t} dt = \frac{1}{j\omega} \Big[ -e^{-j\omega t} \Big]_{-\tau/2}^{\tau/2} = \frac{1}{j\omega} \Big[ e^{j\omega\tau/2} - e^{-j\omega\tau/2} \Big] = 2 \frac{\sin(\omega\tau/2)}{\omega} \\ &= \tau \frac{\sin(\omega\tau/2)}{(\omega\tau/2)} \,. \end{split}$$

ii) The maximum value of  $X(\omega)$  is  $\tau$  when  $\omega = 0$ .

Using L'Hopital rule 
$$\frac{\sin(\omega \tau/2)}{(\omega \tau/2)}\Big|_{\omega=0} = 1$$
.

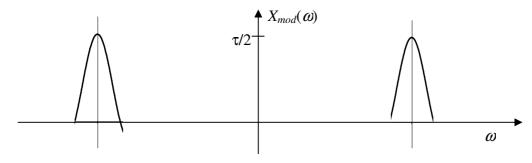
The nulls occur when  $\sin(\omega \tau/2) = 0$  at  $\omega = 2 n\pi/\tau$ , where n = 1, 2, 3...



b) The modulated signal is given by  $x_{mod}(t) = x(t)\cos(\omega_t t)$ . Using Frequency shift property of FT

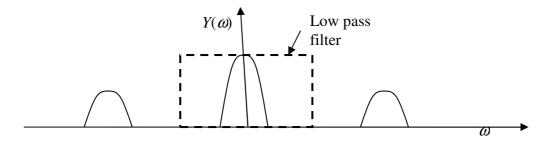
$$X_{\text{mod}}(\omega) = \frac{1}{2} \left[ X(\omega + \omega_c) + X(\omega - \omega_c) \right] = \frac{1}{2} \left[ \tau \frac{\sin((\omega + \omega_c)\tau/2)}{((\omega + \omega_c)\tau/2)} - \tau \frac{\sin((\omega - \omega_c)\tau/2)}{((\omega - \omega_c)\tau/2)} \right]$$

c) Ignoring spectrum above  $2\pi/\tau$ , we have



To demodulate using a synchronous demodulator, we multiply  $x_{mod}(t)$  with  $x_c(t)$ .  $y(t) = x_{mod}(t)x_c(t) = x_{mod}(t)\cos(\omega_c t)$ 

$$Y(\boldsymbol{\omega}) = \frac{1}{2} \left[ X_{\text{mod}}(\boldsymbol{\omega} + \boldsymbol{\omega}_c) + X_{\text{mod}}(\boldsymbol{\omega} - \boldsymbol{\omega}_c) \right] = \frac{1}{2} \left[ \frac{1}{2} X(\boldsymbol{\omega} + 2\boldsymbol{\omega}_c) + X(\boldsymbol{\omega}) + \frac{1}{2} X(\boldsymbol{\omega} - 2\boldsymbol{\omega}_c) \right]$$
$$= \frac{1}{2} X(\boldsymbol{\omega}) + \frac{1}{4} X(\boldsymbol{\omega} + 2\boldsymbol{\omega}_c) + \frac{1}{4} X(\boldsymbol{\omega} - 2\boldsymbol{\omega}_c)$$



The low pass filter bandwidth needs to be  $\frac{2\pi}{\tau} < BW < 2\omega_c - \frac{2\pi}{\tau}$ .

Q3) a) Poles =  $-\zeta \omega_n \pm j\omega_d = -2 \pm j2$ . Zero = -4.

$$H(s) = \frac{(s+4)}{(s+2+j2)(s+2-j2)} = \frac{(s+4)}{(s^2+2s-j2s+2s+4-j4+j2s+j4+4)} = \frac{(s+4)}{(s^2+4s+8)}$$

or

$$H(s) = \frac{(s+4)}{(s+2)^2 + 2^2}$$
.

Therefore N(s) = s + 4 and  $D(s) = s^2 + 4s + 8$ .

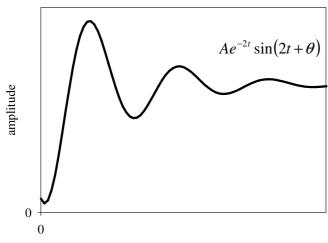
b)  $H(s) = \frac{(s+4)}{s^2 + 4s + 8}$ , therefore we have,  $2\zeta\omega_n = 4$  and  $\omega_n = \sqrt{8}$ .  $\zeta = \frac{2}{\omega} = \frac{2}{\sqrt{8}} = \frac{1}{\sqrt{2}}$ .

The unit step response is  $Ae^{-\zeta\omega_n t}\sin(\omega_n t + \theta)$  where

$$\omega_d = \omega_n \sqrt{1 - \zeta^2} = \sqrt{8} \sqrt{1 - \left(\frac{1}{\sqrt{2}}\right)^2} = \sqrt{8} \cdot \sqrt{\frac{1}{2}} = \sqrt{4} = 2 \text{ rad/s}.$$

c) The step response of the system is a sinusoidal oscillation with a frequency of  $\omega_d = 2$  rad/s and amplitude modulated by a decaying exponential with a

time constant of  $\tau = \frac{1}{\zeta \omega_n} = 1/2$  s.



When  $\omega_n$  is doubled, the oscillation frequency increases to  $2\omega_d$  and the time constant reduces to  $\tau = \frac{1}{4}s$ . Therefore the system response oscillates at a higher frequency and the amplitude of the oscillation decays faster.

d) If  $x(t) = e^{-4t} \cdot u(t)$ ,  $X(s) = \frac{1}{s+4}$ . The Laplace Transform of the response is  $Y(s) = X(s) \cdot H(s)$  $= \frac{s+4}{\left((s+2)^2 + 2^2\right)\left(s+4\right)} = \frac{1}{\left((s+2)^2 + 2^2\right)} = \frac{1}{2} \frac{2}{\left((s+2)^2 + 2^2\right)}.$ 

Therefore the system response when  $x(t) = e^{-4t} \cdot u(t)$  is  $y(t) = \frac{1}{2}e^{-2t} \cdot \sin(2t) \cdot u(t)$ .

Q4 a) The signal has an odd symmetry. Therefore d.c and even terms are zero.

$$b_{n} = \frac{2}{T} \int_{-T/2}^{T/2} x(t) \sin(n\omega_{0}t) dt = \frac{2}{T} \left[ \int_{-T/2}^{0} -A \sin(n\omega_{0}t) dt + \int_{0}^{T/2} A \sin(n\omega_{0}t) dt \right]$$

$$= \frac{2}{T} \left[ \frac{A \cos(n\omega_{0}t)}{n\omega_{0}} \right]_{-T/2}^{0} + \frac{2}{T} \left[ \frac{-A \cos(n\omega_{0}t)}{n\omega_{0}} \right]_{0}^{T/2}$$

$$= \frac{2A}{n\omega_{0}T} \left[ 1 - \cos(n\omega_{0}T/2) - \cos(n\omega_{0}T/2) + 1 \right] = \frac{4A}{n\omega_{0}T} \left[ 1 - \cos(n\omega_{0}T/2) \right]$$

$$= \frac{4A}{n\left(\frac{2\pi}{T}\right)T} \left[ 1 - \cos\left(n\left(\frac{2\pi}{T}\right)\frac{T}{2}\right) \right] = \begin{cases} \frac{4A}{n\pi} & n = 1,3,5,\dots,odd \\ 0 & n = 2,4,6,\dots,even \end{cases}$$

b) 
$$p(t) = \frac{4A}{\pi} \left[ \sin(\omega_0 t) + \frac{1}{3} \sin(3\omega_0 t) + \frac{1}{5} \sin(5\omega_0 t) \right] = \frac{4}{\pi} \left[ \sin(2\pi t) + \frac{1}{3} \sin(6\pi t) + \frac{1}{5} \sin(10\pi t) \right]$$
 c) The transfer function is 
$$\frac{V_o(\omega)}{V_i(\omega)} = \frac{1/j\omega C}{1/j\omega C + R} = \frac{1}{1+j\omega RC} = \frac{1}{1+j\omega I\omega_c}$$
 where  $\omega_c = 1/RC$ .

d) i)To make sure that the magnitude of the  $5^{th}$  harmonic is > 69% of its value before filtering,  $|H(10\pi)| > 0.69$ .

If 
$$\frac{1}{\sqrt{1+\left(\frac{10\pi}{\omega_c}\right)^2}} = 0.69$$
, we have  $1 + \frac{100\pi^2}{\omega_c^2} = \frac{1}{0.69^2}$ .  $\omega_c = 30$  RC=1/30, C=10 $\mu$ F.

After filtering the amplitude of the 5<sup>th</sup> harmonic =  $0.69 \times 4/5\pi = 0.176$ .

ii) 
$$|H(2\pi)| \frac{1}{\sqrt{1 + \left(\frac{2\pi}{30}\right)^2}} = 0.979$$
,  $|H(6\pi)| \frac{1}{\sqrt{1 + \left(\frac{6\pi}{30}\right)^2}} = 0.847$ 

The amplitudes of the 1<sup>st</sup> and 3<sup>rd</sup> harmonics are  $0.979\times4/\pi=1.247$  and  $0.847\times4/3\pi=0.359$  respectively.

Therefore the RMS value = 
$$\frac{1}{\sqrt{2}}\sqrt{1.247^2 + 0.359^2 + 0.176^2} = \frac{1.309}{\sqrt{2}} = 0.926$$