

List of useful formulae

$$x[n] = \sum_{k=-\infty}^{\infty} x[k] \delta[n-k]$$

$$x(t) = \int_{-\infty}^{\infty} x(\lambda) \delta(t-\lambda) d\lambda$$

$$x(t) * h(t) = \int_{-\infty}^{\infty} x(\lambda) h(t-\lambda) d\lambda$$

$$x(t) = \sum_{n=-\infty}^{\infty} c_n e^{jn\omega_0 t}$$

$$c_0 = \frac{1}{T} \int_{\langle T \rangle} x(t) dt$$

$$c_n = \frac{1}{T} \int_{-T/2}^{T/2} x(t) e^{-jn\omega_0 t} dt$$

$$a_n = 2 \operatorname{Re}[c_n] = \frac{2}{T} \int_{\langle T \rangle} x(t) \cos n\omega_0 t dt$$

$$b_n = -2 \operatorname{Im}[c_n] = \frac{2}{T} \int_{\langle T \rangle} x(t) \sin n\omega_0 t dt$$

$$x(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(\omega) e^{j\omega t} d\omega$$

$$X(\omega) = \int_{-\infty}^{\infty} x(t) e^{-j\omega t} dt$$

$$X(\omega) = 2 \int_0^{\infty} x(t) \cos \omega t dt$$

$$X(\omega) = -j2 \int_0^{\infty} x(t) \sin \omega t dt$$

$$X(s) = \int_0^{\infty} x(t) e^{-st} dt$$

$$x(t) = \frac{1}{j2\pi} \int_{c-j\infty}^{c+j\infty} X(s) e^{st} dt$$

$$\cos(x) \cos(y) = \frac{1}{2} [\cos(x-y) + \cos(x+y)]$$

$$\sin(x) \sin(y) = \frac{1}{2} [\cos(x-y) - \cos(x+y)]$$

$$\sin(x) \cos(y) = \frac{1}{2} [\sin(x-y) + \sin(x+y)]$$

$$\cos(x+y) = \cos(x) \cos(y) - \sin(x) \sin(y)$$

$$\sin(x+y) = \sin(x) \cos(y) + \cos(x) \sin(y)$$

Fourier Transform Pairs

Signal

Fourier Transform

$$\sum_{n=-\infty}^{\infty} c_n e^{jn\omega_o t}$$

$$2\pi \sum_{n=-\infty}^{\infty} c_n \delta(\omega - n\omega_o)$$

$$e^{j\omega_o t}$$

$$2\pi \delta(\omega - \omega_o)$$

$$\cos \omega_o t$$

$$\pi [\delta(\omega + \omega_o) + \delta(\omega - \omega_o)]$$

$$\sin \omega_o t$$

$$j\pi [\delta(\omega + \omega_o) - \delta(\omega - \omega_o)]$$

$$1$$

$$2\pi \delta(\omega)$$

$$\delta(t)$$

$$1$$

$$u(t)$$

$$\frac{1}{j\omega} + \pi \delta(\omega)$$

$$\delta(t - t_o)$$

$$e^{-j\omega t_o}$$

$$e^{-at} u(t), a > 0$$

$$\frac{1}{a + j\omega}$$

$$x(t) = \begin{cases} 1, & |t| < \tau \\ 0, & |t| > \tau \end{cases}$$

$$\frac{2 \sin \omega \tau}{\omega} = 2\tau \text{Sa}(\omega \tau)$$

$$\frac{\sin \omega_c t}{\pi} = \frac{\omega_c}{\pi} \text{Sa}(\omega_c t)$$

$$X(\omega) = \begin{cases} 1, & |\omega| < \omega_c \\ 0, & |\omega| > \omega_c \end{cases}$$

$$\sum_{n=-\infty}^{\infty} \delta(t - nT)$$

$$\frac{2\pi}{T} \sum_{k=-\infty}^{\infty} \delta\left(\omega - \frac{2\pi k}{T}\right)$$

Laplace Transform pairs

| Signal | Transform |
|---------------------------------|---|
| Unit step: $u(t)$ | $\frac{1}{s}$ |
| Unit impulse: $\delta(t)$ | 1 |
| Unit ramp: $tu(t)$ | $\frac{1}{s^2}$ |
| $e^{-at}u(t)$ | $\frac{1}{s+a}$ |
| $t^n e^{-at}u(t)$ | $\frac{n!}{(s+a)^{n+1}}$ |
| $(\cos \omega_o t)u(t)$ | $\frac{s}{(s^2 + \omega_o^2)}$ |
| $(\sin \omega_o t)u(t)$ | $\frac{\omega_o}{(s^2 + \omega_o^2)}$ |
| $(e^{-at} \cos \omega_o t)u(t)$ | $\frac{s+a}{((s+a)^2 + \omega_o^2)}$ |
| $(e^{-at} \sin \omega_o t)u(t)$ | $\frac{\omega_o}{((s+a)^2 + \omega_o^2)}$ |
| $(t \cos \omega_o t)u(t)$ | $\frac{s^2 - \omega_o^2}{(s^2 + \omega_o^2)^2}$ |
| $(t \sin \omega_o t)u(t)$ | $\frac{2\omega_o s}{(s^2 + \omega_o^2)^2}$ |

Unit step response for 2nd order systems

| Damping factor, ζ | Unit step response |
|-------------------------|--|
| >1 | $y(t) = \frac{k}{p_1 p_2} + k_2 e^{p_1 t} .u(t) + k_3 e^{p_2 t} .u(t)$ |
| 1 | $y(t) = \frac{k}{\omega_n^2} (1 - (1 + \omega_n t) e^{-\omega_n t} .u(t))$ |
| $0 < \zeta < 1$ | $y(t) = \frac{k}{\omega_n^2} \left(1 - \frac{\omega_n}{\omega_d} e^{-\zeta \omega_n t} \sin(\omega_d t + \theta) .u(t) \right)$ |
| 0 | $y(t) = \frac{k}{\omega_n^2} (1 - \cos(\omega_n t) .u(t))$ |