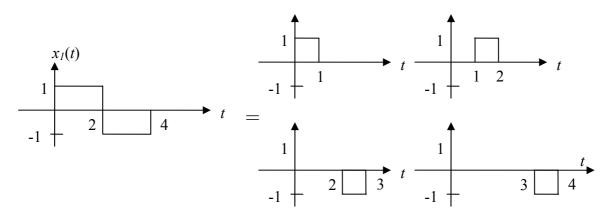
Q1.a.

i) Let x(t) be the input to a system and y(t) be the corresponding output of the system. The system is said to be linear if it satisfies the additivity and the homogeneity properties as follows:

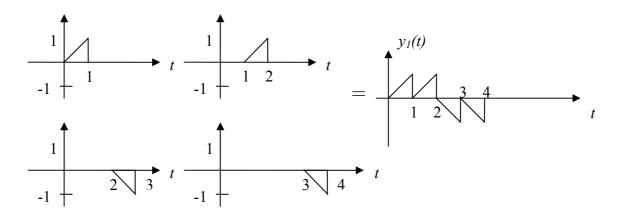
- 1) if input = $x_1(t) + x_2(t)$ then output = $y_1(t) + y_2(t)$, ADDITIVITY PROPERTY.
- 2) if input = $ax_1(t)$ then output = $ay_1(t)$, HOMOGENEITY PROPERTY.

A system is said to be time invariant if the characteristics of the system are independent of time.

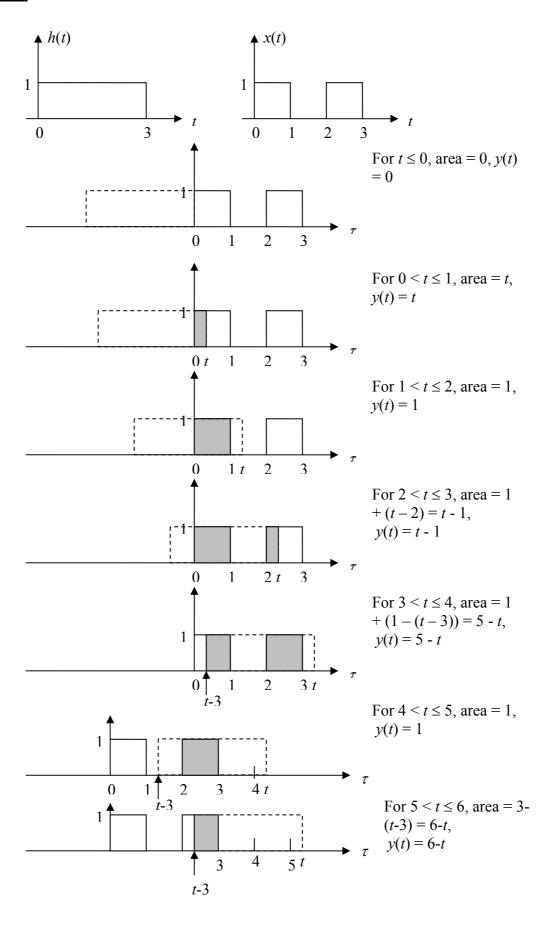
ii)



Therefore the output is



Q1.b.



Q1.b.

In summary
$$y(t) = \begin{cases} 0 & t \le 0 \\ t & 0 < t \le 1 \\ 1 & 1 < t \le 2 \\ t - 1 & 2 < t \le 3 \\ 5 - t & 3 < t \le 4 \\ 1 & 4 < t \le 5 \\ 6 - t & 5 < t \le 6 \\ 0 & t > 6 \end{cases}$$

$$\begin{cases} 0 & t \le 0 \\ t & 0 < t \le 1 \\ 2 & 1 \end{cases}$$

$$\begin{cases} 0 & t \le 0 \\ t & 1 & 2 \end{cases}$$

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<u>Q2.</u>

a. The d.c. term is
$$a_o = \frac{1}{T} \int_{-T/2}^{T/2} x(t) dt = \int_{-\tau}^{\tau} 1 dt = 2\tau$$
, since T = 1.

This is an even signal, $b_n = 0$.

$$a_n = \frac{2}{T} \int_{-T/2}^{T/2} x(t) \cos n\omega_0 t dt$$
, where $\omega_0 = 2\pi/T = 2\pi$.

$$= \frac{2}{T} \int_{-\tau}^{\tau} x(t) \cos n\omega_0 t dt = \frac{2}{T} \int_{-\tau}^{\tau} \cos n\omega_0 t dt$$

$$= \frac{2}{n\omega_0} \sin n\omega_0 t \bigg|_{\tau}^{\tau} = \frac{2}{2n\pi} \left[\sin(2n\pi\tau) - \sin(-2n\pi\tau) \right] = \frac{2}{n\pi} \sin(2n\pi\tau).$$

Therefore the Trigonometric Fourier Series is

$$x(t) = 2\tau + \sum_{n=1}^{\infty} \frac{2}{n\pi} \sin(2n\pi\tau) \cos(2n\pi t).$$

b. If $\tau = 1/4$,

$$a_n = \sin(2n\pi/4) = \sin(n\pi/2) = 0$$
 when $n = 0,2,4...$ and $a_n = \pm 1$ when $n = 1,3,5...$

Therefore we have

$$x(t) = \frac{1}{2} + \frac{2}{\pi} \left[\cos(2\pi t) - \frac{1}{3} \cos(6\pi t) + \frac{1}{5} \cos(10\pi t) \right].$$

c. At
$$\omega = \omega_0$$
, $H(\omega_0) = \frac{1}{1 + j\omega_0/\omega_c} = \frac{1}{1 + j2\pi/\pi} = \frac{1}{\sqrt{5}} \angle -1.107 \text{ rad.}$

The amplitude of the fundamental after low pass filtering = $\frac{2}{\pi} \times \frac{1}{\sqrt{5}} = \frac{2}{\pi\sqrt{5}}$.

At
$$\omega = 3\omega_0$$
, $H(3\omega_0) = \frac{1}{1 + i3\omega_0/\omega_0} = \frac{1}{1 + i6\pi/\pi} = \frac{1}{\sqrt{37}} \angle -1.406 \text{ rad.}$

The amplitude of the 3rd harmonic after low pass filtering = $\frac{2}{3\pi} \times \frac{1}{\sqrt{37}} = \frac{2}{3\pi\sqrt{37}}$.

At
$$\omega = 5\omega_0$$
, $H(5\omega_0) = \frac{1}{1 + j5\omega_0/\omega_c} = \frac{1}{1 + j10\pi/\pi} = \frac{1}{\sqrt{101}} \angle -1.471 \text{ rad.}$

The amplitude of the 5th harmonic after low pass filtering = $\frac{2}{5\pi} \times \frac{1}{\sqrt{101}} = \frac{2}{5\pi\sqrt{101}}$.

Therefore after filtering v(t) becomes

$$v(t) = \frac{1}{2} + \frac{2}{\pi} \left[\frac{1}{\sqrt{5}} \cos(2\pi t - 1.107) - \frac{1}{3\sqrt{37}} \cos(6\pi t - 1.406) + \frac{1}{5\sqrt{101}} \cos(10\pi t - 1.471) \right].$$

<u>Q.3</u>

a. i)
$$W(\omega) = \int_{-\infty}^{\infty} w(t)e^{-j\omega t}dt = \int_{-\tau/2}^{\tau/2} e^{-j\omega t}dt$$

$$W(\omega) = \frac{1}{j\omega} \left[-e^{-j\omega t} \right]_{-\tau/2}^{\tau/2} = \frac{e^{j\omega\tau/2} - e^{-j\omega\tau/2}}{j\omega} = \frac{e^{j\omega\tau/2} - e^{-j\omega\tau/2}}{j2\omega/2} = \frac{\tau}{\omega\tau/2} \frac{e^{j\omega\tau/2} - e^{-j\omega\tau/2}}{j2}$$

$$W(\omega) = \tau \frac{\sin(\omega \tau/2)}{(\omega \tau/2)}.$$

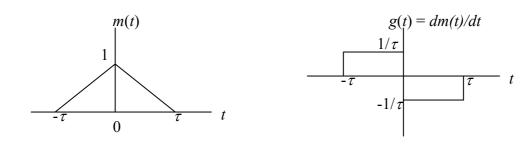
ii) Peak amplitude of $W(\omega)$ occur when $\omega = 0$. Using l'Hopital's rule,

$$\frac{\sin(\omega\tau/2)}{(\omega\tau/2)}\Big|_{\omega=0} = 1$$
. Therefore the peak amplitude $W(0) = \tau$.

The nulls occur when $\sin(\omega \tau/2) = 0$, i.e when $\omega \tau/2 = k\pi$, where k is an integer.

Therefore nulls occur at frequencies $\omega = \pm 2\pi/\tau, \pm 4\pi/\tau, \pm 6\pi/\tau, \dots$

b.



We know that the Fourier Transform of a rectangular pulse with duration of τ and amplitude of 1 is $\tau \frac{\sin(\omega \tau/2)}{(\omega \tau/2)}$. Using the time shift property,

$$G(\omega) = \tau \left(\frac{1}{\tau}\right) \frac{\sin(\omega\tau/2)}{(\omega\tau/2)} e^{j\omega\tau/2} - \tau \left(\frac{1}{\tau}\right) \frac{\sin(\omega\tau/2)}{(\omega\tau/2)} e^{-j\omega\tau/2}$$

$$= \frac{\sin(\omega\tau/2)}{(\omega\tau/2)} (e^{j\omega\tau/2} - e^{-j\omega\tau/2})$$

$$= \frac{\sin(\omega\tau/2)}{(\omega\tau/2)} (2j\sin(\omega\tau/2)) = j\omega\tau \left[\frac{\sin(\omega\tau/2)}{(\omega\tau/2)}\right]^{2}.$$

$$m(t) = \int_{-1}^{1} g(\tau) d\tau \leftrightarrow \frac{1}{j\omega} G(\omega) + \pi G(0) \delta(\omega).$$

$$m(t) = \int_{-\infty}^{\infty} g(\tau)d\tau \leftrightarrow \frac{1}{j\omega}G(\omega) + \pi G(0)\delta(\omega)$$

$$M(\omega) = G(\omega)/j\omega$$
 since $G(0) = 0$.

Finally we have,
$$M(\omega) = \tau \left[\frac{\sin(\omega \tau / 2)}{(\omega \tau / 2)} \right]^2$$
.

Q4.

a.
$$\frac{V_o(s)}{V_i(s)} = \frac{1/sC}{R + sL + 1/sC} = \frac{1}{sRC + s^2LC + 1} = \frac{1/LC}{s^2 + (R/L)s + 1/LC}$$
.

b. Comparing
$$\frac{1/LC}{s^2 + (R/L)s + 1/LC}$$
 with $\frac{{\omega_n}^2}{s^2 + 2\zeta\omega_n s + {\omega_n}^2}$ we have

$$\omega_n = 1/\sqrt{LC}$$
 and $2\zeta\omega_n = R/L$. Therefore the natural frequency is

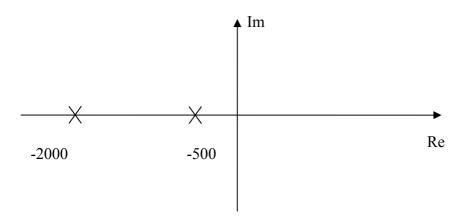
$$\omega_n = 1/\sqrt{LC} = 1/\sqrt{10 \times 10^{-3} \times 100 \times 10^{-6}} = 1000 \text{ rad/s or } f_n = 159 \text{ Hz.}$$

and the damping factor is
$$\zeta = \frac{R}{L(2/\sqrt{LC})} = \frac{25}{10 \times 10^{-3} (2 \times 1000)} = 1.25$$
.

c. The system is overdamped, the poles are given by $p_{1,2} = -\zeta \omega_n \pm \omega_n \sqrt{\zeta^2 - 1}$.

$$\zeta = 1.25$$
, $\omega_n = 1000$ rad/s.

Therefore the poles = $-1.25 \times 1000 \pm \left(1000 \times \sqrt{(1.25)^2 - 1}\right) = -500$ and -2000.



d. The unit step response is given by $y(t) = \frac{k}{p_1 p_2} + k_2 e^{p_1 t} \cdot u(t) + k_3 e^{p_2 t} \cdot u(t)$ where $p_1 =$

-500 and p_2 = -2000, k = 1/LC, k_2 and k_3 are constants. Since p_1 is the dominant pole the response is

$$y(t) \approx \frac{k}{p_1 p_2} + k_2 e^{p_1 t} . u(t)$$

