Using the vars package

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Abstract

The utilisation of the functions contained in the package 'vars' are explained by employing a data set of the Canadian economy. The package's scope includes functions for estimating vector autoregressive (henceforth: VAR) and structural vector autoregressive models (henceforth: SVAR). In addition to the two cornerstone functions VAR() and SVAR() for estimating such models, functions for diagnostic testing, estimation of restricted VARs, prediction of VARs, causality analysis, impulse response analysis (henceforth: IRA) and forecast error variance decomposition (henceforth: FEVD) are provided too. In each section, the underlying concept and/or method is briefly explained, thereby drawing on the exibitions in Lütkepohl [2006], Lütkepohl, Krätzig, Phillips, Ghysels & Smith [2004], Lütkepohl & Breitung [1997], Hamilton [1994] and Watson [1994].

The package's code is purely written in R and S3-classes with methods have been utilised. It is shipped with a NAMESPACE and a ChangeLog file. It has dependencies to MASS (see Venables & Ripley [2002]) and strucchange (see Zeileis, Leisch, Hornik & Kleiber [2002]).

Contents

1	Inti	roduction	2		
2	VAR: Vector autoregressive models				
	2.1	Definition	2		
	2.2	Estimation			
	2.3	Restricted VARs			
	2.4	Diagnostic testing			
	2.5	Causality Analysis			
	2.6	Forecasting	17		
	2.7	Impulse response analysis	19		
	2.8	Forecast error variance decomposition	21		
3	SVA	AR: Structural vector autoregressive models	23		
	3.1	Definition	23		
	3.2	Estimation	24		
	3.3	Impulse response analysis	27		
	3.4	Forecast error variance decomposition			
4	VE	CM to VAR	28		

1 Introduction

Since the critique of Sims [1980] in the early eighties of the last century, VAR analysis has evolved as a standard instrument in econometrics for analysing multivariate time series. Because statistical tests are highly used in determining interdependencies and dynamic relationships between variables, it became soon evident to enrich this methodology by incorporating non-statistical a priori information, hence SVAR models evolved which try to bypass these shortcomings. At the same time as Sims jeopardised the paradigm of multiple structural equation models laid out by the Cowles Foundation in the fourties and fifties of the last century, Granger [1981] and Engle & Granger [1987] endowed econometricians with a powerful tool for modelling and testing economic relationships, namely, the concept of integration and and cointegration. Nowadays these traces of research are unified in the form of vector error correction and structural vector error correction models. Although these latter topics are left out in this vignette, the interested reader is referred to the monographies of Lütkepohl [2006], Hendry [1995], Johansen [1995], Hamilton [1994], Banerjee, Dolado, Galbraith & Hendry [1993] and Pfaff [2006] for an exhibition of unit root tests and co-integration analysis in R.

To the author's knowledge, currently only functions in the base distribution of R and in the CRAN-packages dse (package bundle, see Gilbert 1993, 1995, 2000) and fMultivar (Würtz 2006) are made available for estimating ARIMA and VARIMA time series models. Though, the CRAN-package MSBVAR (Brandt 2006) provides methods for estimating frequentist and Bayesian Vector Autoregression (BVAR) models, the methods and functions provided in the package vars try to fill a gap in the econometrics' methods landscape of R by providing the 'standard' tools in the context of VAR and SVAR analysis.

The vignette is structured as follows: the next section is entirely devoted to VARs (definition, estimation, restrictions, diagnostic testing, forecasting, IRA and FEVD). In the ensuing section the topic of SVAR is elucidated (definition, estimation, IRA and FEVD). Finally, the transformation of a VECM to a VAR in levels is exhibited with its associated methods and functions.

2 VAR: Vector autoregressive models

2.1 Definition

In its basic form, a VAR consists of a set of K endogenous variables $\mathbf{y}_t = (y_{1t}, \dots, y_{kt}, \dots, y_{Kt})$ for $k = 1, \dots K$. The VAR(p)-process is then defined as:

$$\mathbf{y}_t = A_1 \mathbf{y}_{t-1} + \ldots + A_p \mathbf{y}_{t-p} + \mathbf{u}_t \quad , \tag{1}$$

with A_i are $(K \times K)$ coefficient matrices for i = 1, ..., p and \mathbf{u}_t is a K-dimensional white noise process with time invariant positive definite covariance matrix $E(\mathbf{u}_t \mathbf{u}_t') = \Sigma_{\mathbf{u}}^{-1}$.

par One important characteristic of a VAR(p)-process is its stability. This

 $^{^{1}}$ Vectors are assigned by small bold letters and matrices by capital letters. Scalars are written out as small letters. which are possibly subscripted.

means that it generates stationary time series with time invariant means, variances and covariance structure, given sufficient starting values. One can check this by evaluating the reverse characteristic polynomial:

$$\det(I_K - A_1 z - \dots - A_p z^p) \neq 0 \text{ for } |z| \leq 1.$$
 (2)

If the solution of the above equation has a root for z=1, then either some or all variables in the VAR(p)-process are integrated of order one, *i.e.* I(1). It might be the case, that cointegration between the variables does exist. This instance can be better analysed in the context of a vector-error-correction model (VECM). The reader is referred to the monography of Johansen [1995] for a theoretical exposition and to Pfaff [2006] for an implementation with the CRAN-package 'urca' in R.

In practice, the stability of an empirical VAR(p)-process can be analysed by considering the companion form and caculating the eigenvalues of the coefficient matrix. A VAR(p)-process can be written as a VAR(1)-process as:

$$\xi_t = A\xi_{t-1} + \mathbf{v}_t \;, \tag{3}$$

with:

$$\xi_{t} = \begin{bmatrix} \mathbf{y}_{t} \\ \vdots \\ \mathbf{y}_{t-p+1} \end{bmatrix}, A = \begin{bmatrix} A_{1} & A_{2} & \cdots & A_{p-1} & A_{p} \\ I & 0 & \cdots & 0 & 0 \\ 0 & I & \cdots & 0 & 0 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & \cdots & I & 0 \end{bmatrix}, \mathbf{v}_{t} = \begin{bmatrix} \mathbf{u}_{t} \\ \mathbf{0} \\ \vdots \\ \mathbf{0} \end{bmatrix}, (4)$$

whereby the dimensions of the stacked vectors ξ_t and \mathbf{v}_t is $(Kp \times 1)$ and of the matrix A is $(Kp \times Kp)$. If the moduli of the eigenvalues of A are less than one, then the VAR(p)-process is stable. The calculation of the eigenvalues is made available with the function roots(). The function has an argument 'modulus' of type logical that returns by default the moduli of the eigenvalues, otherwise a vector of complex numbers is returned (for an application see section 2.2 below).

2.2 Estimation

For a given sample of the endogenous variables $\mathbf{y}_1, \dots \mathbf{y}_T$ and sufficient presample values $\mathbf{y}_{-p+1}, \dots, \mathbf{y}_0$, the coefficients of a VAR(p)-process can be estimated efficiently by least-squares applied separately to each of the equations.

Before considering the implementation in the package 'vars', let us briefly discuss the utilised data set and plot the series (see figure 1). The original time series are published by the OECD and the transformed series, as described in the help page to Canada are provided with JMulti (see Lütkepohl et al. [2004]). The sample range is from the 1stQ 1980 until 4thQ 2000.

```
> library(vars)
> data(Canada)
> layout(matrix(1:4, nrow = 2, ncol = 2))
> plot.ts(Canada$e, main = "Employment", ylab = "", xlab = "")
> plot.ts(Canada$prod, main = "Productivity", ylab = "", xlab = "")
> plot.ts(Canada$rw, main = "Real Wage", ylab = "", xlab = "")
```

> plot.ts(Canada\$U, main = "Unemployment Rate", ylab = "", xlab = "")

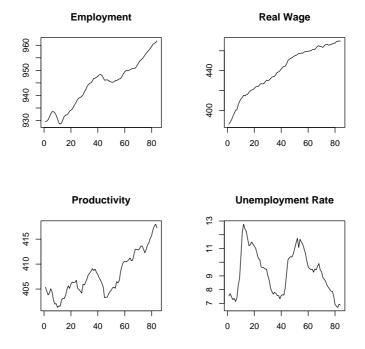


Figure 1: Canada: Macroeconomic series

The variable ${\bf e}$ is used for employment; ${\bf prod}$ is a measure of labour productivity; ${\bf rw}$ assigns the real wage and finally U is the unemployment rate. The function for estimating a VAR is VAR(). It consists of three arguments: the data matrix object y (or an object that can be coerced to a matrix), the integer lag-order p and the type of deterministic regressors to include into the VAR(p). An optimal lag-order can be determined according to an information criteria or the final prediction error of a VAR(p) with the function VARselect(). Its arguments are exhibited in the code snippet below.

\$criteria

```
1 2 3 4 5
AIC(n) -5.817851996 -6.35093701 -6.397756084 -6.145942174 -5.926500201
HQ(n) -5.577529641 -5.91835677 -5.772917961 -5.328846166 -4.917146309
SC(n) -5.217991781 -5.27118862 -4.838119523 -4.106417440 -3.407087295
FPE(n) 0.002976003 0.00175206 0.001685528 0.002201523 0.002811116
```

The VARselect() enables the user to determine an optimal lag length according to an information criteria or the final prediction error of an empirical VAR(p)-process. Each of these measures are defined in the function's help file. The function returns a list object with the optimal lag-order according to each of the criteria, as well as a matrix containing the values for all lags up to lag.max. According to the more conservative SC(n) and HQ(n) criteria, the empirical optimal lag-order is 2. Please note, that the calculation of these criteria is based upon the same sample size, and hence the criteria might take slightly different values whence a VAR for the choosen order is estimated.

In a next step, the VAR(2) is estimated with the function VAR() and as deterministic regressors a constant is included.

```
> var.2c <- VAR(Canada, p = 2, type = "const")
> names(var.2c)

[1] "varresult"    "datamat"    "y"    "type"    "p"
[6] "K"    "obs"    "totobs"    "restrictions" "call"
```

The function returns a list object of class varest and the list elements are explained in detail in the function's help file. Let us now focus on two methods, namely summary and plot.

```
> summary(var.2c)
> plot(var.2c)
```

The summary method simply applies the summary.1m method to the 1m objects contained in varresult. The OLS results of the example are shown in separate tables 1-4 below. It turns out, that not all lagged endogenous variables enter significanctly into the equations of the VAR(2). The estimation of a restricted VAR is the topic of the next section.

	Estimate	Std. Error	t value	$\Pr(\setminus t)$
		ota. Error		$\Pr(> \mathbf{t})$
e.l1	1.6378	0.1500	10.92	0.0000
prod.l1	0.1673	0.0611	2.74	0.0078
rw.l1	-0.0631	0.0552	-1.14	0.2569
U.l1	0.2656	0.2028	1.31	0.1944
e.l2	-0.4971	0.1595	-3.12	0.0026
prod.l2	-0.1017	0.0661	-1.54	0.1282
rw.l2	0.0038	0.0555	0.07	0.9450
U.l2	0.1327	0.2073	0.64	0.5242
const	-136.9984	55.8481	-2.45	0.0166

Table 1: Regression result for employment equation

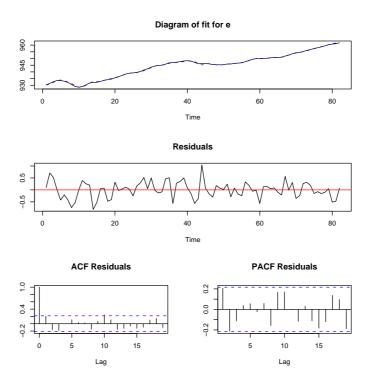


Figure 2: Employment equation: Diagram of fit, residuals with ACF and PACF

Before we proceed with the estimation of restricted VARs, let us first look at the plot method for objects with class attribute varest and the roots() function for checking the VAR's stability, that was briefly mentioned at the end of the previous section. For each equation in a VAR, a plot consisting of a diagram of fit, a residual plot, the autocorrelation and partial autocorrelation function of the residuals are shown. If the plot method is called interactively, the user is requested to enter <RETURN> for commencing to the next plot. Currently, the ...-argument of the plot method is unused. However, given the information contained in an object of class varest, it is fairly easy to set up such plots and tailormade them to her/his needs. The plots of the four equations are shown in the exhibits 2 to 5. Whence, we have estimated a VAR(p), we should check its stability. Here, stability does not refer to the coefficients' stability, i.e. the stability of the regressions, but rather the stability of the system of difference equations. As pointed out above, if the moduli of the eigenvalues of the companion matrix are less than one, the system is stable.

> roots(var.2c)

[1] 0.9950338 0.9081062 0.9081062 0.7380565 0.7380565 0.1856381 0.1428889

[8] 0.1428889

Although, the first eigenvalue is pretty close to unity, for the sake of simplicity, we assume a stable VAR(2)-process with a constant as deterministic regressor.

	Estimate	Std. Error	t value	$\Pr(> t)$
e.l1	-0.1728	0.2698	-0.64	0.5239
prod.l1	1.1504	0.1099	10.46	0.0000
rw.l1	0.0513	0.0993	0.52	0.6071
U.l1	-0.4785	0.3647	-1.31	0.1936
e.l2	0.3853	0.2869	1.34	0.1835
prod.l2	-0.1724	0.1188	-1.45	0.1510
rw.l2	-0.1189	0.0998	-1.19	0.2378
U.12	1.0159	0.3728	2.72	0.0080
const	-166.7755	100.4339	-1.66	0.1011

Table 2: Regression result for productivity equation

	Estimate	Std. Error	t value	$\Pr(> t)$
e.l1	-0.2688	0.3226	-0.83	0.4074
prod.l1	-0.0811	0.1315	-0.62	0.5395
rw.l1	0.8955	0.1188	7.54	0.0000
U.l1	0.0121	0.4361	0.03	0.9779
e.l2	0.3678	0.3431	1.07	0.2872
prod.l2	-0.0052	0.1421	-0.04	0.9710
rw.l2	0.0527	0.1194	0.44	0.6604
U.l2	-0.1277	0.4459	-0.29	0.7754
const	-33.1883	120.1105	-0.28	0.7831

Table 3: Regression result for real wage equation

2.3 Restricted VARs

From tables 1-4 it is obvious that not all regressors enter significanctly. With the function restrict() the user has the option to re-estimate the VAR either by significance (argument method = 'ser') or by imposing zero restrictions manually (argument method = 'manual'). In the former case, each equation is re-estimated separately as long as there are t-values that are in absolut value below the threshhold value set by the function's argument thresh. In the latter case, a restriction matrix has to be provided that consists of 0/1 values, thereby selecting the coefficients to be retained in the model. The function's arguments are therefore:

> args(restrict)

function (x, method = c("ser", "manual"), thresh = 2, resmat = NULL)
NULL

- > var2c.ser <- restrict(var.2c, method = "ser", thresh = 2)
- > var2c.ser\$restrictions

```
e.l1 prod.l1 rw.l1 U.l1 e.l2 prod.l2 rw.l2 U.l2 const
                                        0
                                              0
                      1
                          1
                               1
е
        1
                1
                      0
                           0
                                        0
        0
                1
                                1
                                              1
                                                   1
                                                         1
prod
                           0
                                        0
                                                         0
        0
                      1
                                1
                                              0
rw
                1
                                                   1
U
        1
                           1
```

> B(var2c.ser)

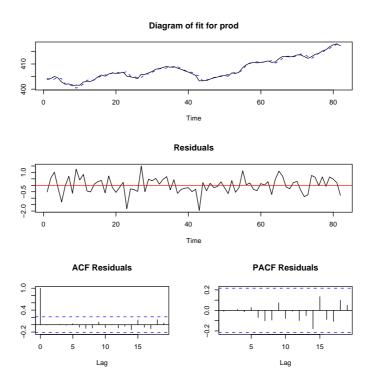


Figure 3: Productivity equation: Diagram of fit, residuals with ACF and PACF

```
e.12 prod.12
           e.11
                   prod.l1
                                 rw.l1
                                            U.11
      prod 0.0000000 1.00809918 0.00000000 0.0000000 0.28943990
                                                                   0
     0.0000000 \ -0.11816412 \ \ 0.96382332 \ \ 0.0000000 \ \ \ 0.07092345
                                                                   0
     -0.6954549 0.00000000 0.00000000 0.5600228 0.52253799
U
                                                                   0
          rw.12
                      U.12
                                const
     0.00000000 0.0000000 -128.8945
е
prod -0.09728839 0.7503647 -240.5605
rw
     0.00000000 -0.1930013
                              0.0000
      0.05670873 0.0000000 142.6316
> res <- matrix(rep(1, 36), nrow = 4, ncol = 9)
> res[1, 3] <- 0
> res[1, 4] <- 0
> var2c.man <- restrict(var.2c, method = "manual", resmat = res)</pre>
> var2c.man$restrictions
     e.11 prod.11 rw.11 U.11 e.12 prod.12 rw.12 U.12 const
       1
               1
                     0
                          0
                                1
                                       1
                                             1
prod
       1
               1
                      1
                          1
                                1
                                       1
                                             1
                                                   1
                                                        1
               1
                      1
                          1
                                1
                                        1
                                             1
                                                   1
                                                        1
rw
       1
U
                           1
        1
                      1
                                1
                                             1
> B(var2c.man)
                                             U.11
           e.11
                   prod.l1
                                rw.l1
                                                        e.12
                                                                  prod.12
      1.5079689 \quad 0.16584386 \quad 0.00000000 \quad 0.00000000 \quad -0.4043821 \quad -0.095383974
```

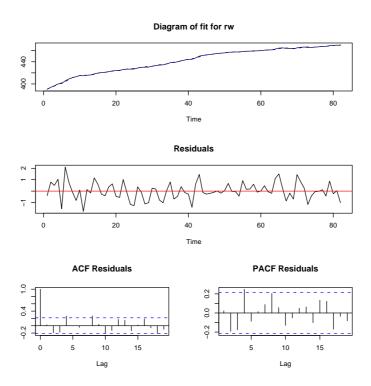


Figure 4: Real wage equation: Diagram of fit, residuals with ACF and PACF

```
prod -0.1727658 1.15042820 0.05130390 -0.47850131 0.3852589 -0.172411873
     -0.2688329 \ -0.08106500 \ 0.89547833 \ \ 0.01213003 \ \ 0.3678489 \ -0.005180947
rw
     -0.5807638 -0.07811707 0.01866214
U
                                         0.61893150 0.4098182 0.052116684
           rw.12
                         U.12
                                   const
     -0.04593897
                  0.33088442 -109.20640
е
prod -0.11885104 1.01591801 -166.77552
      0.05267656 -0.12770826
                               -33.18834
rw
U
      0.04180115 -0.07116885
                               149.78056
```

In the example above, the third and fourth coefficient of the employment equation (i.e., the first equation) are set to zero for method = 'manual'. The function restrict() returns a list object with class attribute varest. The coefficients of these objects can be displayed conveniently by either B() (all coefficients, including deterministic coefficients) or by A() (only coefficients of lagged endogenous variables). The output of the former is shown in the code snippet above. It should be noted at this point, that a restricted VAR is estimated by OLS too, instead of employing the EGLS method (see Lütkepohl [2006] for an exposition and section ??).

2.4 Diagnostic testing

In package 'vars' the functions for diagnostic testing are arch(), normality(), serial() and stability(). The former three functions return a list object with class attribute varcheck for which a plot-method exists. The plots, one for each equation, include a residual plot, an empirical distribution plot and the ACFs and PACFs of the residuals and their

	Estimate	Std. Error	t value	$\Pr(> t)$
e.l1	-0.5808	0.1156	-5.02	0.0000
prod.l1	-0.0781	0.0471	-1.66	0.1017
rw.l1	0.0187	0.0426	0.44	0.6625
U.l1	0.6189	0.1563	3.96	0.0002
e.l2	0.4098	0.1230	3.33	0.0014
prod.l2	0.0521	0.0509	1.02	0.3095
rw.l2	0.0418	0.0428	0.98	0.3319
U.12	-0.0712	0.1598	-0.45	0.6574
const	149.7806	43.0481	3.48	0.0009

Table 4: Regression result for unemployment equation

squares. The function stability() returns a list object with class attribute varstabil. The function itself is just a wrapper for the function efp() from package strucchange. The first element of the returned list object is itself a list of objects with class attribute efp. Hence, the plotmethod for objects of class varstabil just call the plot-method for objects of class efp. Let us now turn to each of these functions in more detail.

The implemented tests for heteroscedasticity are the univariate and multivariate ARCH test (see Engle [1982], Hamilton [1994] and Lütkepohl [2006]). The multivariate ARCH-LM test is based on the following regression (the univariate test can be considered as special case of the exhibtion below and is skipped):

$$vech(\hat{\mathbf{u}}_{t}\hat{\mathbf{u}}_{t}') = \beta_0 + B_1 vech(\hat{\mathbf{u}}_{t-1}\hat{\mathbf{u}}_{t-1}') + \dots + B_q vech(\hat{\mathbf{u}}_{t-q}\hat{\mathbf{u}}_{t-q}') + \mathbf{v}_t ,$$
(5)

whereby \mathbf{v}_t assigns a spherical error process and vech is the column-stacking operator for symmetric matrices that stacks the columns from the main diagonal on downwards. The dimension of β_0 is $\frac{1}{2}K(K+1)$ and for the coefficient matrices B_i with $i=1,\ldots,q,\,\frac{1}{2}K(K+1)\times\frac{1}{2}K(K+1)$. The null hypothesis is: $H_0:=B_1=B_2=\ldots=B_q=0$ and the alternative is: $H_1:B_1\neq 0\cap B_2\neq 0\cap\ldots\cap B_q\neq 0$. The test statistic is defined as:

$$VARCH_{LM}(q) = \frac{1}{2}TK(K+1)R_m^2$$
 , (6)

with

$$R_m^2 = 1 - \frac{2}{K(K+1)} tr(\hat{\Omega}\hat{\Omega}_0^{-1}) \quad , \tag{7}$$

and $\hat{\Omega}$ assigns the covariance matrix of the above defined regression model. This test statistic is distributed as $\chi^2(qK^2(K+1)^2/4)$.

In the code example below this test is applied to the var.2c object.

> args(arch)

function (x, lags.single = 16, lags.multi = 5, multivariate.only = TRUE)
NULL

- > var2c.arch <- arch(var.2c)
- > names(var2c.arch)
- [1] "resid" "arch.mul"
- > var2c.arch

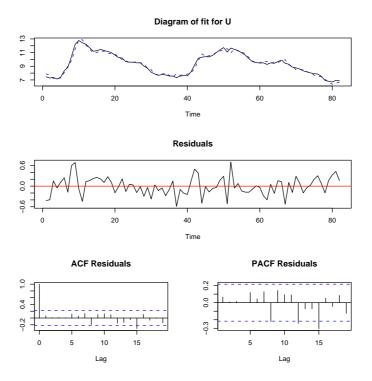


Figure 5: Unemployment equation: Diagram of fit, residuals with ACF and PACF

ARCH (multivariate)

data: Residuals of VAR object var.2c
Chi-squared = 538.8897, df = 500, p-value = 0.1112

The Jarque-Bera normality tests for univariate and multivariate series are implemented and applied to the residuals of a VAR(p) as well as seperate tests for multivariate skewness and kurtosis (see Bera & Jarque [1980], [1981] and Jarque & Bera [1987] and Lütkepohl [2006]). The univariate versions of the Jarque-Bera test are applied to the residuals of each equation. A multivariate version of this test can be computed by using the residuals that are standardized by a Choleski decomposition of the variance-covariance matrix for the centered residuals. Please note, that in this case the test result is dependant upon the ordering of the variables.

```
> var2c.norm <- normality(var.2c, multivariate.only = TRUE)
> names(var2c.norm)
[1] "resid" "jb.mul"
> var2c.norm
$JB
JB-Test (multivariate)
```

data: Residuals of VAR object var.2c

Chi-squared = 5.094, df = 8, p-value = 0.7475

\$Skewness

Skewness only (multivariate)

data: Residuals of VAR object var.2c
Chi-squared = 1.7761, df = 4, p-value = 0.7769

\$Kurtosis

Kurtosis only (multivariate)

data: Residuals of VAR object var.2c
Chi-squared = 3.3179, df = 4, p-value = 0.5061

> plot(var2c.norm)

The test statistics for the mutlivariate case are defined as:

$$JB_{mv} = s_3^2 + s_4^2 \,, (8)$$

whereby s_3^2 and s_4^2 are computed according to:

$$s_3^2 = T\mathbf{b}_1'\mathbf{b}_1/6 \tag{9a}$$

$$s_4^2 = T(\mathbf{b}_2 - \mathbf{3}_K)'(\mathbf{b}_2 - \mathbf{3}_k)/24$$
, (9b)

with \mathbf{b}_1 and \mathbf{b}_2 are the third and fourth non-central moment vectors of the standardized residuals $\hat{\mathbf{u}}_t^s = \tilde{P}^-(\hat{\mathbf{u}}_t - \bar{\hat{\mathbf{u}}}_t)$ and \tilde{P} is a lower triangular matrix with positive diagonal such that $\tilde{P}\tilde{P}' = \tilde{\Sigma}_{\mathbf{u}}, i.e.$, the Choleski decomposition of the residual covariance matrix. The test statistic JB_{mv} is distributed as $\chi^2(2K)$ and the multivariate skewness, s_3^2 , and kurtosis test, s_4^2 are distributed as $\chi^2(K)$. Likewise to ARCH, these tests are returned in the list elements jb.uni and jb.mul, which consist of objects with class attribute htest. Hence, the print-method for these objects is employed in print.varcheck. In the code example above, the null hypothesis of normality cannot be rejected.

For testing the lack of serial correlation in the residuals of a VAR(p), a Portmanteau test and the LM test proposed by Breusch & Godfrey are implemented in the function serial(). For both tests small sample modifications are calculated too, whereby the modification for the LM has been introduced by Edgerton & Shukur [1999]. Likewise, to the function normality(), the test statistics are list elements of the returned object and have class attribute htest.

The Portmanteau statistic is defined as:

$$Q_h = T \sum_{j=1}^h tr(\hat{C}_j' \hat{C}_0^{-1} \hat{C}_j \hat{C}_0^{-1}) , \qquad (10)$$

with $\hat{C}_i = \frac{1}{T} \sum_{t=i+1}^T \hat{\mathbf{u}}_t \hat{\mathbf{u}}'_{t-i}$. The test statistic has an approximate $\chi^2(K^2h - n^*)$ distribution, and n^* is the number of coefficients excluding deterministic terms of a VAR(p). The limiting distribution is only valid for h tending to infinity at suitable rate with growing sample size. Hence, the

trade-off is between a decent approximation to the χ^2 distribution and a loss in power of the test, when h is choosen too large. The small sample properties of the test statistic:

$$Q_h^* = T^2 \sum_{j=1}^h \frac{1}{T-j} tr(\hat{C}_j' \hat{C}_0^{-1} \hat{C}_j \hat{C}_0^{-1})$$
 (11)

may be better, and is available as the second entry in the list element pt.mul.

> var2c.pt.asy <- serial(var.2c, lags.pt = 16, type = "PT.asymptotic")
> var2c.pt.asy

Portmanteau Test (asymptotic)

data: Residuals of VAR object var.2c
Chi-squared = 205.3538, df = 224, p-value = 0.8092

> var2c.pt.adj <- serial(var.2c, lags.pt = 16, type = "PT.adjusted")
> var2c.pt.adj

Portmanteau Test (adjusted)

data: Residuals of VAR object var.2c
Chi-squared = 231.5907, df = 224, p-value = 0.3497

> plot(var2c.pt.asy)

The Breusch-Godfrey LM-statistic (see Breusch 1978, Godfrey 1978) is based upon the following auxiliary regressions:

$$\hat{\mathbf{u}}_t = A_1 \mathbf{y}_{t-1} + \ldots + A_p \mathbf{y}_{t-p} + CD_t + B_1 \hat{\mathbf{u}}_{t-1} + \ldots + B_h \hat{\mathbf{u}}_{t-h} + \varepsilon_t . \tag{12}$$

The null hypothesis is: $H_0: B_1 = \cdots = B_h = 0$ and correspondingly the alternative hypothesis is of the form $H_1: \exists B_i \neq 0 \text{ for } i=1,2,\ldots,h$. The test statistic is defined as:

$$LM_h = T(K - tr(\tilde{\Sigma}_R^{-1}\tilde{\Sigma}_e)) \quad , \tag{13}$$

where $\tilde{\Sigma}_R$ and $\tilde{\Sigma}_e$ assign the residual covariance matrix of the restricted and unrestricted model, respectively. The test statistic LM_h is distributed as $\chi^2(hK^2)$ and is returned by the function serial() as list element LMh with class attribute htest.

> var2c.BG <- serial(var.2c, lags.pt = 16, type = "BG")
> var2c.BG

Breusch-Godfrey LM test

data: Residuals of VAR object var.2c
Chi-squared = 92.6282, df = 80, p-value = 0.1581

> var2c.ES <- serial(var.2c, lags.pt = 16, type = "ES")
> var2c.ES

Edgerton-Shukur F test

data: Residuals of VAR object var.2c
F statistic = 1.1186, df1 = 80, df2 = 199, p-value = 0.2648

Edgerton & Shukur [1999] proposed a small sample correction, which is defined as:

$$LMF_h = \frac{1 - (1 - R_r^2)^{1/r}}{(1 - R_r^2)^{1/r}} \frac{Nr - q}{Km} , \qquad (14)$$

with $R_r^2=1-|\tilde{\Sigma}_e|/|\tilde{\Sigma}_R|,\ r=((K^2m^2-4)/(K^2+m^2-5))^{1/2},\ q=1/2Km-1$ and N=T-K-m-1/2(K-m+1), whereby n is the number of regressors in the original system and m=Kh. The modified test statistic is distributed as $F(hK^2,int(Nr-q))$. This test statistic is returned by serial() as list element LMFh and has class attribute htest.

The stability of the regression relationships in a VAR(p) can be assessed with the function stability(). An empirical fluctuation process is estimated for each regression by passing the function's arguments to the efp()-function contained in the package strucchange. The function stability() returns a list object with class attribute varstabil. The first element, stability, is itself a list with objects of class efp. For more information about efp() see its help file and the cited literature therein.

```
> args(stability)
```

```
function (x, type = c("Rec-CUSUM", "OLS-CUSUM", "Rec-MOSUM",
    "OLS-MOSUM", "RE", "ME", "Score-CUSUM", "Score-MOSUM", "fluctuation"),
    h = 0.15, dynamic = FALSE, rescale = TRUE)
NULL
> var2c.stab <- stability(var.2c, type = "OLS-CUSUM")
> names(var2c.stab)
```

> plot(var2c.stab)

[1] "stability" "names"

In the R-code example above, an OLS-Cusum test is applied to the varest object var.2c. The graphical output is displayed in figures 6–9 on the following pages. The null hypothesis of a stable relationship cannot be rejected for neither regression in the VAR.

"K"

2.5 Causality Analysis

Often researchers are interested in the detection of causalities between variables. The most common one is the Granger-Causality test (Granger 1969). Incidentally, this test is not suited to test causal relationships in the strict sense, because the possibility of a post hoc ergo proper hoc fallacy cannot be excluded. This is true for any so called "causality test" in econometrics. It is therefore common practice to say that variables x does granger-cause variable y if variable x helps to predict variable y. Aside of this test, within the function causality() a Wald-type instantaneous causality test is implemented too. It is characterized by testing for nonzero correlation between the error processes of the cause and effect variables.

```
> args(causality)
function (x, cause = NULL)
```

NULL

The function causality() has two arguments. The first argument, x, is an object of class varest and the second, cause, is a character vector of the variable names, that are assumed to be causal to the remaining variables in a VAR(p)-process. If this argument is unset, then the variable

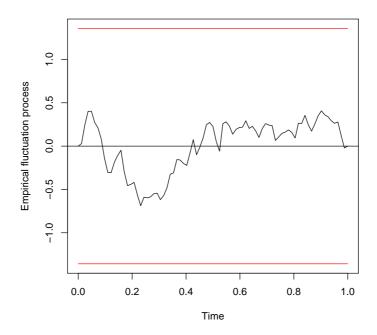


Figure 6: Employment equation: OLS-Cusum test

in the first column of x\$y is used as cause variable and a warning is printed.

For both tests the vector of endogenous variables \mathbf{y}_t is split into two subvectors \mathbf{y}_{1t} and \mathbf{y}_{2t} with dimensions $(K_1 \times 1)$ and $(K_2 \times 1)$ with $K = K_1 + K_2$. For the rewritten VAR(p):

$$\begin{bmatrix} \mathbf{y}_{1t} \\ \mathbf{y}_{2t} \end{bmatrix} = \sum_{i=1}^{p} \begin{bmatrix} \alpha_{11,i} & \alpha_{12,i} \\ \alpha_{21,i} & \alpha_{22,i} \end{bmatrix} \begin{bmatrix} \mathbf{y}_{1,t-i} \\ \mathbf{y}_{2,t-i} \end{bmatrix} + CD_t + \begin{bmatrix} \mathbf{u}_{1t} \\ \mathbf{u}_{2t} \end{bmatrix} , \qquad (15)$$

the null hypothesis that the subvector \mathbf{y}_{1t} does not Granger-cause \mathbf{y}_{2t} , is defined as $\alpha_{21,i}=0$ for $i=1,2,\ldots,p$. The alternative is: $\exists \alpha_{21,i}\neq 0$ for $i=1,2,\ldots,p$. The test statistic is distributed as $F(pK_1K_2,KT-n^*)$, with n^* equal to the total number of parameters in the above VAR(p)-process, including deterministic regressors. The null hypothesis for non-instantaneous causality is defined as: $H_0:C\sigma=0$, where C is a $(N\times K(K+1)/2)$ matrix of rank N selecting the relevant co-variances of \mathbf{u}_{1t} and \mathbf{u}_{2t} ; $\tilde{\sigma}=vech(\tilde{\Sigma}_u)$. The Wald statistic is defined as:

$$\lambda_W = T\tilde{\sigma}'C'[2CD_K^+(\tilde{\Sigma}_u \otimes \tilde{\Sigma}_u)D_K^{+'}C']^{-1}C\tilde{\sigma} , \qquad (16)$$

hereby assigning the Moore-Penrose inverse of the duplication matrix D_K with D_K^+ and $\tilde{\Sigma}_u = \frac{1}{T} \Sigma_{t=1}^T \hat{\mathbf{u}}_t \hat{\mathbf{u}}_t'$. The duplication matrix D_K has dimension $(K^2 \times \frac{1}{2}K(K+1))$ and is defined such that for any symmetric $(K \times K)$ matrix A, $vec(A) = D_K vech(A)$ holds. The test statistic λ_W is asymptotically distributed as $\chi^2(N)$.

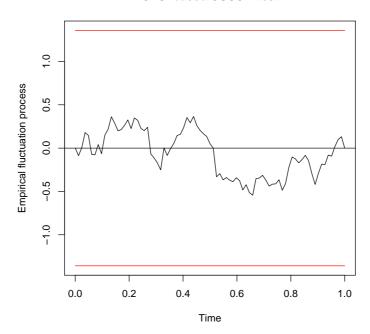


Figure 7: Productivity equation: OLS-Cusum test

The function causality() is now applied for investigating if the real wage and productivity is causal to employment and unemployment.

```
> causality(var.2c, cause = c("rw", "prod"))
```

\$Granger

Granger causality HO: prod rw do not Granger-cause e U

```
data: VAR object var.2c
F-Test = 3.4529, df1 = 8, df2 = 292, p-value = 0.0008086
```

\$Instant

 $\ensuremath{\text{HO}}\xspace$. No instantaneous causality between: prod rw and e U

```
data: VAR object var.2c
Chi-squared = 2.5822, df = 4, p-value = 0.63
```

The null hypothesis of no Granger-causality from the real wage and labour productivity to employment and unemployment must be rejected; whereas the null hypothesis of non-instantenous causality cannot be rejected. This test outcome is economically plausible, given the frictions observed in labour markets.

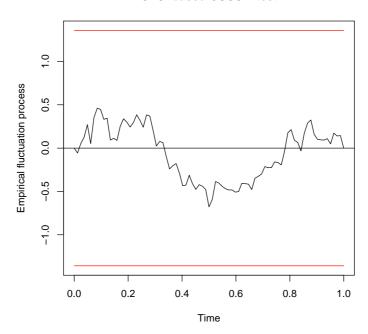


Figure 8: Real wage equation: OLS-Cusum test

2.6 Forecasting

> plot(var.f10)
> fanchart(var.f10)

A predict-method for objects with class attribute varest is available. The n.ahead forecasts are computed recursively for the estimated VAR, beginning with $h=1,2,\ldots,n.ahead$:

$$\mathbf{y}_{T+1|T} = A_1 \mathbf{y}_T + \ldots + A_p \mathbf{y}_{T+1-p} + CD_{T+1} \tag{17}$$
 > var.f10 <- predict(var.2c, n.ahead = 10, ci = 0.95)
> names(var.f10)
[1] "fcst" "endog" "model" "exo.fcst"
> class(var.f10)
[1] "varprd"

Beside the function's arguments for the varest object and the n.ahead forecast steps, a value for the forecast confidence interval can be provided too. Its default value is 0.95. The forecast error covariance matrix is given as:

$$Cov\left(\begin{bmatrix} \mathbf{y}_{T+1} - \mathbf{y}_{T+1|T} \\ \vdots \\ \mathbf{y}_{T+h} - \mathbf{y}_{T+h|T} \end{bmatrix}\right) = \begin{bmatrix} I & 0 & \cdots & 0 \\ \Phi_1 & I & & 0 \\ \vdots & & \ddots & 0 \\ \Phi_{h-1} & \Phi_{h-2} & \cdots & I \end{bmatrix} (\Sigma_{\mathbf{u}} \otimes I_h) \begin{bmatrix} I & 0 & \cdots & 0 \\ \Phi_1 & I & & 0 \\ \vdots & & \ddots & 0 \\ \Phi_{h-1} & \Phi_{h-2} & \cdots & I \end{bmatrix}$$

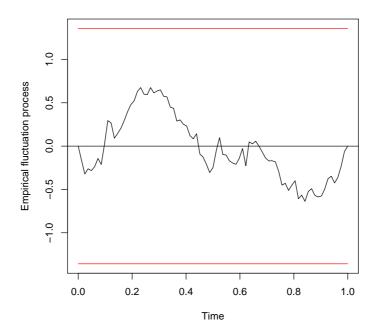


Figure 9: Unemployment equation: OLS-Cusum test

and the matrices Φ_i are the coefficient matrices of the Wold moving average representation of a stable VAR(p)-process:

$$\mathbf{y}_{t} = \Phi_{0}\mathbf{u}_{t} + \Phi_{1}\mathbf{u}_{t-1} + \Phi_{2}\mathbf{u}_{t-2} + \dots , \qquad (18)$$

with $\Phi_0 = I_K$ and Φ_s can be computed recursively according to:

$$\Phi_s = \sum_{j=1}^s \Phi_{s-j} A_j \text{ for } s = 1, 2, \dots, ,$$
(19)

whereby $A_j = 0$ for j > p.

The predict-method does return a list object of class varprd with three elements. The first element, fcst, is a list of matrices containing the predicted values, the lower and upper bounds according to the choosen confidence interval, ci and its size. The second element, endog is a matrix object containing the endogenous variables and the third is the submitted varest object. A plot-method for objects of class varprd does exist as well as a fanchart() function for plotting fan charts as described in Britton, Fisher & Whitley [1998].

```
> args(fanchart)
```

Forecast of series e

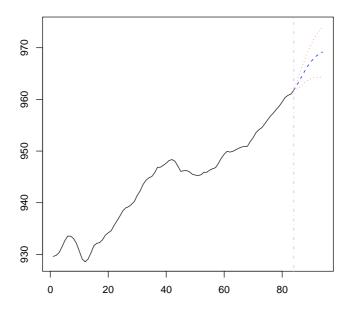


Figure 10: Employment: 10-step ahead forecasts with 95% confidence

The fanchart() function has colors and cis arguments, allowing the user to input vectors of colors and critical values. If these arguments are left NULL, then as defaults a heat.map color scheme is used and the critical values are set from 0.1 to 0.9 with a step size of 0.1. In order to save space, the predict plot for employment and a fan chart for unemployment is shown in the exhibits 10 and 11, respectively.

2.7 Impulse response analysis

The impulse response analysis is based upon the Wold moving average representation of a VAR(p)-process (see equations (18) and (19) above). It is used to investigate the dynamic interactions between the endogenous variables. The (i,j)th coefficients of the matrices Φ_s are thereby interpreted as the expected response of variable $y_{i,t+s}$ to a unit change in variable y_{jt} . These effects can be cumulated through time $s=1,2,\ldots$ and hence one would obtain the cumulated impact of a unit change in variable j to the variable i at time s. Aside of these impulse response coefficients, it is often conceivable to use orthogonalised impulse reponses as an alternative. This is the case, if the underlying shocks are less likely to occur in isolation, but rather contemporaneous correlation between the components of the error process \mathbf{u}_t are existent, i.e., the off-diagonal elements of $\Sigma_{\mathbf{u}}$ are non-zero. The orthogonalised impulse responses are derived from a Choleski decomposition of the error variance-covariance matrix: $\Sigma_{\mathbf{u}} = PP'$ with P being a lower triangular. The moving average

Fan chart for variable U

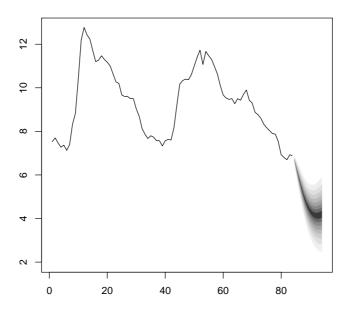


Figure 11: Unemployment: Fan chart with default settings

representation can then be transformed to:

$$\mathbf{y}_t = \Psi_0 \varepsilon_t + \Psi_1 \varepsilon_{t-1} + \dots \,\,\,(20)$$

with $\varepsilon_t = P^{-1}\mathbf{u}_t$ and $\Psi_i = \Phi_i P$ for $i = 0, 1, 2, \ldots$ and $\Psi_0 = P$. Incidentally, because the matrix P is lower triangular, it follows that only a shock in the first variable of a VAR(p)-process does exert an influence on all the remaining ones and that the second and following variables cannot have a direct impact on y_{1t} . One should bear this in mind whence orthogonal impulse responses are employed (see the code snippet below and figure 12 for a re-ordering of the data to compute the impulse responses originating from a real wage shock to employment and unemployment). Please note further, that a different ordering of the variables might produce different outcomes with respect to the impulse responses. As we shall see in section 3, the non-uniqueness of the impulse reponses can be circumvented by analysing a set of endogenous variables in the structural VAR (SVAR) framework.

```
> args(irf)
```

```
function (x, impulse = NULL, response = NULL, n.ahead = 10, ortho = TRUE,
    cumulative = FALSE, boot = TRUE, ci = 0.95, runs = 100, seed = NULL,
    ...)
NULL
> Canada2 <- Canada[, c(3, 1, 4, 2)]
> names(Canada2)
```

> plot(irf.rw.eU)

The function for conducting impulse response analysis is irf(). It is a method for objects with class attribute varest and svarest. The function's arguments are displayed in the R-code example above. The impulse variables are set as a character vector impulse and the responses are provided likewise in the argument response. If either one is unset, then all variables are considered as impulses or responses, respectively. The default length of the impulse reponses is set to 10 via argument n.ahead. The computation of orthogonalised and/or cumulated impulse responses is controlled by the logical switches ortho and cumulative, respectively. Finally, confidence bands can be returned by setting boot = TRUE (default). The pre-set values are to run 100 replications and return 95% confidence bands. It is at the user's leisure to specify a seed for replicability of the results. The standard percentile interval is calculated as $CI_s = [s_{\gamma/2}^*, s_{(1-\gamma)/2}^*], \text{ where } s_{\gamma/2}^* \text{ and } s_{(1-\gamma)/2}^* \text{ are the } \gamma/2 \text{ and } (1-\gamma)/2$ quantiles of the estimated bootstraped impulse response coefficients $\hat{\Phi}^*$ or $\hat{\Psi}^*$ (Efron & Tibshirani 1993). The function irf() returns an object with class attribute varirf for which a plot method does exist. In figure 12 the result of the impulse response analysis is depicted. Although a positive real wage shock does influence employment and unemployment in the directions one would a priori assume, it does so only significantly for unemployment during the time span ranging from the third period to the sixth period. 2

2.8 Forecast error variance decomposition

The forecast error variance decomposition (henceforth: FEVD) is based upon the orthogonalised impulse response coefficient matrices Ψ_n (see section 2.7 above). The FEVD allows the user to analyse the contribution of variable j to the h-step forecast error variance of variable k. If the elementwise squared orthogonalised impulse reponses are divided by the variance of the forecast error variance, $\sigma_k^2(h)$, the resultant is a percentage figure. Formally, the forecast error variance for $y_{k,T+h} - Y_{k,T+h|T}$ is defined as:

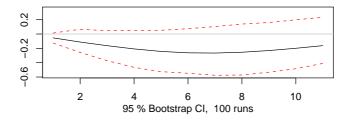
$$\sigma_k^2(h) = \sum_{n=0}^{h-1} (\psi_{k1,n}^2 + \dots + \psi_{kK,n}^2)$$
 (21)

which can be written as:

$$\sigma_k^2(h) = \sum_{j=1}^K (\psi_{kj,0}^2 + \dots + \psi_{kj,h-1}^2) . \tag{22}$$

 $^{^2}$ Incidentally, the result should not be mistaken or interpreted as demanding higher real wages, *i.e.*, having a free lunch, without facing the consequences beyond of the model's scope. The example has been primarily choosen for demonstrations purposes only.

Orthogonal Impulse Response from rw to e



Orthogonal Impulse Response from rw to U

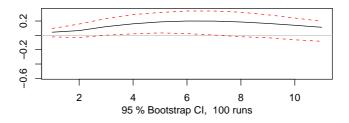


Figure 12: Orthogonal impulse responses from real wage to employment and unemployment (95% confidence bands, boots trapped with 100 replications)

Dividing the term $(\psi_{kj,0}^2 + \ldots + \psi_{kj,h-1}^2)$ by $\sigma_k^2(h)$ yields the forecast error variance decompositions in percentage terms:

$$\omega_{kj}(h) = (\psi_{kj,0}^2 + \ldots + \psi_{kj,h-1}^2) / \sigma_k^2(h) . \tag{23}$$

The method fevd is available for conducting FEVD. Functions for objects of classes varest and svarest do exist. The argument aside of an object with class attribute being either varest or svarest is the number of forecasting steps, n.ahead. Its default value has been set to 10. Currently, the ...-argument is unused.

> args(fevd)

function (x, n.ahead = 10, ...) NULL

The method does return a list object with class attribute varfevd for which a plot-method does exists. The list elements are the forecast error variances organised on a per-variable basis.

- > var2c.fevd <- fevd(var.2c, n.ahead = 5)
 > class(var2c.fevd)
- [1] "varfevd"
- > names(var2c.fevd)
- [1] "e" "prod" "rw" "U"

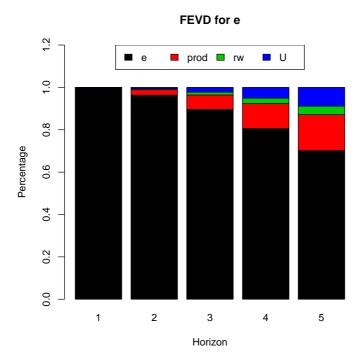


Figure 13: Forecast error variance decomposition for employment

> var2c.fevd\$e

	е	prod	rw	U
[1,]	1.0000000	0.0000000	0.00000000	0.00000000
[2,]	0.9633815	0.02563062	0.004448081	0.006539797
[3,]	0.8961692	0.06797131	0.013226872	0.022632567
[4,]	0.8057174	0.11757589	0.025689192	0.051017495
[5.]	0.7019003	0.16952744	0.040094324	0.088477959

From the example above, it is evident that aside of employment itself, the influence of productivity is contributing the most to the forecast uncertainty of employment. In the exhibit 13, the FEVD of employment for five ahead steps is plotted as a bar graph. 3

3 SVAR: Structural vector autoregressive models

3.1 Definition

Recall from section 2.1 on page 2 the definition of a VAR(p)-process, in particular equation (1). A VAR(p) can be interpreted as a reduced form

³If the plot-method is called interactively, the user is enforced to go through the bar graphs for all variables. In order to save space, only the FEVD for the employment variable is shown in figure 13.

model. A SVAR-model is its structural form and is defined as:

$$A\mathbf{y}_t = A_1^* \mathbf{y}_{t-1} + \ldots + A_p^* \mathbf{y}_{t-p} + B\varepsilon_t.$$
 (24)

It is assumed that the *structural errors*, ε_t , are white noise and the coefficient matrices A_i^* for $i = 1, \ldots, p$, are structural coefficients that might differ from their reduced form counterparts. To see this, consider the resulting equation by left-multiplying equation (24) with the inverse of A:

$$\mathbf{y}_{t} = A^{-1} A_{1}^{*} \mathbf{y}_{t-1} + \dots + A^{-1} A_{p}^{*} \mathbf{y}_{t-p} + A^{-1} B \varepsilon_{t}$$

$$\mathbf{y}_{t} = A_{1} \mathbf{y}_{t-1} + \dots + A_{p} \mathbf{y}_{t-p} + \mathbf{u}_{t} .$$
(25)

A SVAR-model can be used to identify shocks and trace these out by employing IRA and/or FEVD through imposing restrictions on the matrices A and/or B. Incidentally, though a SVAR-model is a structural model, it departs from a reduced form VAR(p)-model and only restrictions for A and B can be added. It should be noted that the reduced form residuals can be retrieved from a SVAR-model by $\mathbf{u}_t = A^{-1}B\varepsilon_t$ and its variance-covariance matrix by $\Sigma_{\mathbf{u}} = A^{-1}BB'A^{-1'}$.

Depending on the imposed restrictions, three types of SVAR- models can be distinguished:

- A model: B ist set to I_K (minimum number of restrictions for identification is K(K-1)/2).
- B model: A ist set to I_K (minimum number of restrictions to be imposed for identification is the same as for A model).
- AB model: restrictions can be placed on both matrices (minimum number of restrictions for identification is $K^2 + K(K-1)/2$).

3.2 Estimation

A SVAR model is estimated with the function SVAR(). Its arguments are shown in the R-code example below. An object with class attribute varest has to be provided as argument x. Whether an A-, B- or AB-model will be estimated, is dependent on the setting for Amat and Bmat. If a restriction matrix for Amat with dimension $(K \times K)$ is provided and the argument Bmat is left NULL, an A-model be estimated. In this case Bmat is set to an identity matrix I_K . Alternatively, if only a matrix object for Bmat is provided and Amat left unchanged, then a B-model will be estimated and internally Amat is set to an identity matrix I_K . Finally, if matrix objects for both arguments are provided, then an AB-model will be estimated. In all cases, the matrix elements to be estimated are marked by NA entries at the relevant positions.

> args(SVAR)

```
function (x, estmethod = c("scoring", "logLik"), Amat = NULL,
    Bmat = NULL, Ra = NULL, Rb = NULL, ra = NULL, rb = NULL,
    start = NULL, max.iter = 100, conv.crit = 1e-07, maxls = 1,
    lrtest = TRUE, ...)
NULL
```

⁴The following exhibition uses the estimation method logLik for directly minimising the negative log-likelihood function. It also possible to use a scoring algorithm. Hereby, the restrictions have to be provided in a different form (see example(SVAR) for further details.

```
> amat <- diag(4)
> diag(amat) <- NA
> amat[1, 2] <- NA
> amat[1, 3] <- NA
> amat[3, 2] <- NA
> amat[4, 1] <- NA
> amat
     [,1] [,2] [,3] [,4]
[1,]
            NA
                        0
[2,]
            NA
                  0
        0
[3,]
                        0
        0
            NA
                 NA
[4,]
       NA
                   0
                       NA
```

In the example above, an expository object amat has been set up. The next function's argument is start. This argument expects a vector of starting values, hence, the user has one handle at hand for controlling the optimisation process in case one encounters convergence problems. If left NULL, then starting values are set to 0.1 for all coefficients to be optimised. Finally, the ... argument in SVAR() is parsed to the optim() function. Therefore, it is possible to choose the numerical optimisation method and set hessian = TRUE to obtain the numerical standard errors, for instance.

The parameters are estimated by minimising the negative of the concentrated log-likelihood function:

$$\ln L_c(A, B) = -\frac{KT}{2} \ln(2\pi) + \frac{T}{2} \ln|A|^2 - \frac{T}{2} \ln|B|^2 - \frac{T}{2} tr(A'B'^{-1}B^{-1}A\tilde{\Sigma}_u),$$
(26)

by utilising optim.

> args(optim)

```
> svar2c.A <- SVAR(var.2c, estmethod = "logLik", Amat = amat, Bmat = NULL,
+ hessian = TRUE, method = "BFGS")
> svar2c.A
```


LR overidentification test:

LR overidentification

```
data: Canada
Chi^2 = 0.8252, df = 2, p-value = 0.6619
```

Estimated A matrix:

```
        e
        prod
        rw
        U

        e
        2.787720
        0.01998724
        0.1906375
        0.000000

        prod
        0.000000
        1.53260287
        0.000000
        0.000000

        rw
        0.000000
        -0.19609242
        1.2920240
        0.000000

        U
        2.562603
        0.00000000
        0.0000000
        4.882572
```

Estimated standard errors for A matrix:

	е	prod	rw	U
е	0.2176737	0.1706396	0.1434537	0.000000
prod	0.0000000	0.1196780	0.0000000	0.000000
rw	0.0000000	0.1699440	0.1008898	0.000000
U	0.3642575	0.0000000	0.0000000	0.381258

Estimated B matrix:

Estimated standard errors for B matrix:

e prod rw U
e 0 0 0 0
prod 0 0 0 0
rw 0 0 0 0
U 0 0 0

The returned object of function SVAR() is a list with class attribute svarest.

> class(svar2c.A)

[1] "svarest"

> names(svar2c.A)

Dependent on the choosen model and if the argument hessian = TRUE has been set, the list elements A, Ase, B, Bse contain the estimated coefficient matrices with the numerical standard errors, if applicable. The element LRIM does contain the long-run impact matrix in case a SVAR of type Blanchard & Quah is estimated, otherwise this element is NULL (see below for more details). The list element Sigma.U is the variance-covariance matrix of the reduced form residuals times 100, i.e., $\Sigma_U = A^{-1}BB'A^{-1'} \times 100$. The list element LR is an object with class attribute htest, holding the Likelihood ratio overidentification test, whereby the test statistic is defined as:

$$LR = T(\log \det(\tilde{\Sigma}_{\mathbf{u}}^r) - \log \det(\tilde{\Sigma}_{\mathbf{u}})) \tag{27}$$

with $\tilde{\Sigma}_{\mathbf{u}}$ being the ML estimator of the reduced form variance-covariance matrix and $\tilde{\Sigma}_{\mathbf{u}}^{r}$ is the corresponding estimator obtained from the restricted structural form estimation. The element opt is the returned object from function optim. The remaining four list items are the vector of starting values, the SVAR model type, the varest object and the call to SVAR().

Finally, it should be noted that the model proposed by Blanchard & Quah [1989] can be considered as a particular SVAR-model of type B. The matrix A is equal to I_K and the matrix of the long-run effects is lower-triangular and defined as:

$$(I_K - A_1 - \dots - A_P)^{-1}B$$
 (28)

Hence, the residual of the second equation cannot exert a long-run influence on the first variable and likewise the third residual cannot impact the first and second variable. The estimation of the Blanchard & Quah model is achieved by a Choleski decomposition of:

$$(I_K - \hat{A}_1 - \dots - \hat{A}_p)^{-1} \hat{\Sigma}_u (I_K - \hat{A}_1' - \dots - \hat{A}_p')^{-1} \quad . \tag{29}$$

The matrices \hat{A}_i for $i=1,\ldots,p$ assign the reduced form estimates. The long-run impact matrix is the lower-triangular Choleski decomposition of this matrix and the contemporaneous impact matrix is equal to:

$$(I_K - A_1 - \dots - A_p)Q \quad , \tag{30}$$

where Q assigns the lower-trinagular Choleski decomposition. It should be noted that a re-ordering of the VAR might become necessary due to the recursive nature of the model.

The Blanchard & Quah model is implemented as function BQ(). It has one argument x, which is an object with class attribute varest. The function does return a list object with class attribute svarest. Below is a trivial example of applying a Blanchard & Quah [1989]-type SVAR to the already available VAR var.2c.

> BQ(var.2c)

Estimated contemporaneous impact matrix:

```
prod
               е
                                      rw
     -0.00764432 -0.28469582
                             0.07374319 -0.21233590
prod
     0.54366334
                  0.21657828 -0.03379321 -0.28651841
rw
      0.08211181
                  0.28588183 0.71874239
                                          0.06161939
U
      0.12945102
                 0.05667792 -0.01039129
                                          0.24110588
```

Estimated identified long run impact matrix:

```
e prod rw U
e 104.37389 0.0000000 0.000000 0.0000000
prod 45.35215 5.1971134 0.000000 0.0000000
rw 168.40969 -2.1144696 10.719506 0.0000000
U -19.25842 -0.4561694 1.410200 0.5331401
```

The contemporaneous impact matrix is stored as list-element B and the long-run impact matrix as list-element LRIM in the returned object.

3.3 Impulse response analysis

Like impulse response analysis can be conducted for objects with class attribute varest it can be done so for objects with class attribute svarest

(see section 2.7 on page 19 following). In fact, the irf-methods for classes varest and svarest are at hand with the same set of arguments; except ortho is missing for objects of class svarest due to the nature and interpretation of the error terms in a SVAR. The impulse response coefficients for a SVAR are calculated as $\Theta_i = \Phi_i A^{-1}B$ for $i = 1, \ldots, n$.

In the code snippet below, an example of an IRA is exhibited for the estimated SVAR from the previous section.

```
> svar2cA.ira <- irf(svar2c.A, impulse = "rw", response = c("e",
+ "U"), boot = FALSE)
> svar2cA.ira
```

Impulse response coefficients
\$rw

```
e U
[1,] -0.05292837 0.02777929
[2,] -0.12816194 0.06237647
[3,] -0.19908356 0.13215216
[4,] -0.26547797 0.18578989
[5,] -0.32043081 0.22492294
[6,] -0.35743849 0.24753946
[7,] -0.37478736 0.25405194
[8,] -0.37389275 0.24686257
[9,] -0.35784064 0.22915640
[10,] -0.33036781 0.20422207
[11,] -0.29519673 0.17504960
```

3.4 Forecast error variance decomposition

A forecast error variance decomposition can be applied likewise to objects of class swarest. Here, the forecast errors of $y_{T+h|T}$ are derived from the impulse responses of a SVAR and the derivation to the forecast error variance decomposition is similar to the one outlined for VARs (see section 2.8 on page 21 following).

An application is provided in the code snippet below and a plot for the real wage equation is exhibited in figure 14 on page 29.

```
> svar2cA.fevd <- fevd(svar2c.A, n.ahead = 8)
> plot(svar2cA.fevd)
```

4 VECM to VAR

Reconsider the VAR presentation from equation 1 on page 2:

$$\mathbf{y}_t = A_1 \mathbf{y}_{t-1} + \ldots + A_p \mathbf{y}_{t-p} + \mathbf{u}_t \quad , \tag{31}$$

The following vector error correction specifications do exist, which can be estimated with function ca.jo() contained in urca:

$$\Delta \mathbf{y}_t = \Pi \mathbf{y}_{t-p} + \Gamma_1 \Delta \mathbf{y}_{t-1} + \ldots + \Gamma_{p-1} \mathbf{y}_{t-p+1} + \mathbf{u}_t \quad , \tag{32}$$

with

$$\Gamma_i = -(I - A_1 - \dots - A_i), \quad i = 1, \dots, p - 1.$$
 (33)

and

$$\Pi = -(I - A_1 - \dots - A_p) \quad . \tag{34}$$

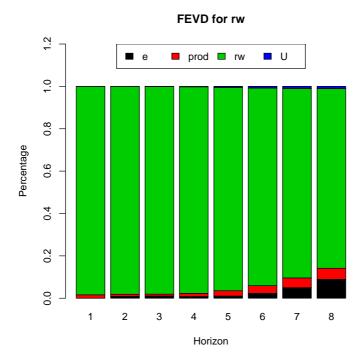


Figure 14: SVAR: FEVD for real wage

The Γ_i matrices contain the cumulative long-run impacts, hence this VECM specification is signified by longrun form. The other specification is given as follows:

$$\Delta \mathbf{y}_t = \Pi \mathbf{y}_{t-1} + \Gamma_1 \Delta \mathbf{y}_{t-1} + \ldots + \Gamma_{p-1} \mathbf{y}_{t-p+1} + \mathbf{u}_t \quad , \tag{35}$$

with

$$\Gamma_i = -(A_{i+1} + \dots + A_p) \quad i = 1, \dots, p-1.$$
 (36)

Equation 34 applies to this specification too. Hence, the Π matrix is the same as in the first specification. However, the Γ_i matrices now differ, in the sense that they measure transitory effects. Therefore this specification is signified by transitory form.

With function vec2var() a VECM (*i.e* an object of formal class ca.jo, generated by ca.jo()) is transormed into its level VAR representation. For illustration purposes, an example taken from Johansen & Juselius [1990] is used in the following.

```
> library(urca)
> data(finland)
> sjf <- finland
> sjf.vecm <- ca.jo(sjf, constant = FALSE, type = "eigen", K = 2,
+     spec = "longrun", season = 4, ctable = "A2")</pre>
```


> summary(sjf.vecm)

Johansen-Procedure


```
Test type: maximal eigenvalue statistic (lambda max) , with linear trend
Eigenvalues (lambda):
[1] 0.30932660 0.22599561 0.07308056 0.02946699
Values of teststatistic and critical values of test:
          test 10pct 5pct 1pct
r <= 3 | 3.11 6.69 8.08 11.58
r <= 2 | 7.89 12.78 14.60 18.78
r <= 1 | 26.64 18.96 21.28 26.15
r = 0 \mid 38.49 \ 24.92 \ 27.34 \ 32.62
Eigenvectors, normalised to first column:
(These are the cointegration relations)
           1rm1.12
                      lny.12
                                lnmr.12
                                           difp.12
lrm1.12 1.0000000 1.000000 1.0000000
                                          1.000000
lny.12 -0.9763252 -1.323191 -0.9199865
                                         1.608739
lnmr.12 -7.0910749 -2.016033 0.2691516 -1.375342
difp.12 -7.0191097 22.740851 -1.8223931 -15.686927
Weights W:
(This is the loading matrix)
           1rm1.12
                         lny.12
                                     lnmr.12
lrm1.d 0.033342108 -0.020280528 -0.129947614 -0.002561906
lny.d 0.022544782 -0.005717446 0.012949130 -0.006265406
lnmr.d 0.053505000 0.046876449 -0.007367715 0.002173242
difp.d 0.005554849 -0.017353903 0.014561151 0.001531004
One can conclude that two cointegration relationships do exist. The
cointegrating rank is needed for the above transformation with function
vec2var. Given the object sjf.vecm of class ca.jo with r=2, one can
now swiftly proceed:
> args(vec2var)
function (z, r = 1)
NULL
> sjf.var \leftarrow vec2var(sjf.vecm, r = 2)
> sjf.var
Coefficient matrix of lagged endogenous variables:
A1:
          1rm1.11
                       lny.11
                                  lnmr.l1
                                             difp.11
lrm1 0.855185363 -0.28226832 -0.09298924 -0.1750511
lny 0.036993826 0.33057494 -0.06731145 -0.1946863
```

A2:

lnmr -0.156875074 -0.01067717 0.76861874 0.4247362 difp 0.001331951 0.02850137 0.02361709 0.2063468

```
lrm1.12 lny.12 lnmr.12 difp.12 lrm1 0.15787622 0.27655060 -0.10255593 -0.52017728 lny -0.02016649 0.65497929 -0.08102873 -0.09357761 lnmr 0.25725652 -0.10358761 -0.24253117 0.26571672 difp -0.01313100 -0.01096218 -0.02802090 0.36002057
```

Coefficient matrix of deterministic regressor(s).

```
    constant
    sd1
    sd2
    sd3

    lrm1
    0.03454360
    0.039660747
    0.037177941
    0.10095683

    lny
    0.05021877
    0.043686282
    0.082751819
    0.09559270

    lnmr
    0.22729778
    0.008791390
    0.012456612
    0.02011396

    difp
    -0.03055891
    0.001723883
    -0.007525805
    -0.00835411
```

The print method does return the coefficient values, first for the lagged endogenous variables, next for the deterministic regressors. The returned object is of class vec2var and this list has the following elements:

> names(sjf.var)

```
[1] "deterministic" "A" "p" "K"
[5] "y" "obs" "totobs" "call"
[9] "vecm" "datamat" "resid" "r"
```

> class(sjf.var)

[1] "vec2var"

> methods(class = "vec2var")

```
[1] fevd.vec2var* fitted.vec2var* irf.vec2var* logLik.vec2var*
[5] Phi.vec2var* plot.vec2var* predict.vec2var* print.vec2var*
[9] Psi.vec2var* residuals.vec2var*
```

Non-visible functions are asterisked

The object has assigned class attribute vec2var and a print-, irf-, fevd-, predict-, Phi and Psi-method do exist. Furthermore, the functions arch(), normality(), serial() and fanchart() can be employed for further analysis too.⁵

Finally, structural vector error correction models can be estimated with the function SVEC(). Likewise to the function SVAR2() a scoring algorithm is utilised for determining the coefficients of the long run and contemporaneous impact matrices. The estimated standard errors of these parameters can be calculated by a bootstrapping procedure. The latter is controlled by the functional argument boot in SVEC; its default value is FALSE.

 $^{^5{}m The}$ reader is referred to the previous sections in which these methods and functions are outlined.

List	of Tables
1 2 3 4	Regression result for employment equation 5 Regression result for productivity equation 7 Regression result for real wage equation 7 Regression result for unemployment equation 10
List	of Figures
1	Canada: Macroeconomic series
2	Employment equation: Diagram of fit, residuals with ACF
3	and PACF
	and PACF
4	Real wage equation: Diagram of fit, residuals with ACF and PACF
5	Unemployment equation: Diagram of fit, residuals with ACF and PACF
6	Employment equation: OLS-Cusum test
7	Productivity equation: OLS-Cusum test 16
8	Real wage equation: OLS-Cusum test
9	Unemployment equation: OLS-Cusum test 18
10	Employment: 10-step ahead forecasts with 95% confidence . 19
11	Unemployment: Fan chart with default settings 20
12	Orthogonal impulse responses from real wage to employ-
	ment and unemployment (95% confidence bands, boots trapped
	with 100 replications)
13	Forecast error variance decomposition for employment 23
14	SVAR: FEVD for real wage
Refe	erences
In	ee, A., Dolado, J., Galbraith, J. & Hendry, D. [1993], Co- tegration, Error-Correction, and the Econometric Analysis of Non- ationary Data, Oxford University Press.
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