# Chapter 2: Operating-System Structures

### **Chapter 2: Operating-System Structures**

**Operating System Services** 

User and Operating-System Interface

System Calls

System Services

**Linkers and Loaders** 

Why Applications Are Operating-System Specific

Operating-System Design and Implementation

**Operating-System Structure** 

Building and Booting an operating System

Operating-System Debugging

### **Objectives**

Identify services provided by an operating system

Illustrate how system calls are used to provided operating system services.

Compare and contrast monolithic, layered, microkernel, modular, and hybrid strategies for designing operating systems.

Illustrate the process for booting an operating system.

Apply tools for monitoring operating system performance.

Design and implement kernel modules for interacting with a Linux kernel.

### 2.1 Operating-System Services

Operating systems provide an environment for execution of programs and services to programs and users

One set of operating-system services provides functions that are helpful to the user:

**User interface** - Almost all operating systems have a user interface (UI).

 Varies between Command-Line Interpreter (CLI), Graphics User Interface (GUI), Batch

**Program execution** - The system must be able to load a program into memory and to run that program, end execution, either normally or abnormally (indicating error)

I/O operations - A running program may require I/O, which may involve a file or an I/O device

# **Operating System Services (Cont.)**

One set of operating-system services provides functions that are helpful to the user (Cont.):

**File-system manipulation** - The file system is of particular interest. Programs need to read and write files and directories, create and delete them, search them, list file Information, permission management.

**Communications** – Processes may exchange information, on the same computer or between computers over a network

 Communications may be via shared memory or through message passing (packets moved by the OS)

**Error detection** – OS needs to be constantly aware of possible errors

- May occur in the CPU and memory hardware, in I/O devices, in user program
- For each type of error, OS should take the appropriate action to ensure correct and consistent computing
- Debugging facilities can greatly enhance the user's and programmer's abilities to efficiently use the system

# **Operating System Services (Cont.)**

Another set of OS functions exists for ensuring the efficient operation of the system itself via resource sharing

**Resource allocation -** When multiple users or multiple jobs running concurrently, resources must be allocated to each of them

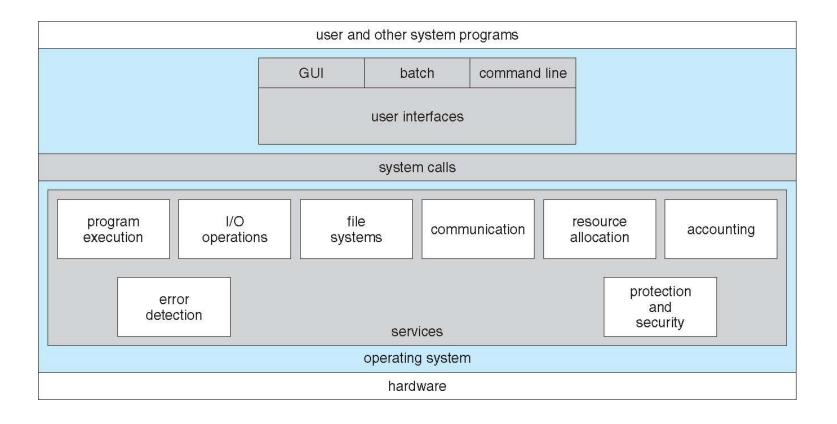
Many types of resources - CPU cycles, main memory, file storage, I/O devices.

**Logging -** To keep track of which users use how much and what kinds of computer resources

**Protection and security -** The owners of information stored in a multiuser or networked computer system may want to control use of that information, concurrent processes should not interfere with each other

- Protection involves ensuring that all access to system resources is controlled
- Security of the system from outsiders requires user authentication, extends to defending external I/O devices from invalid access attempts

# A View of Operating System Services



### 2.2 User Operating-System Interface

CLI or command interpreter allows direct command entry

Sometimes implemented in kernel, sometimes by systems program

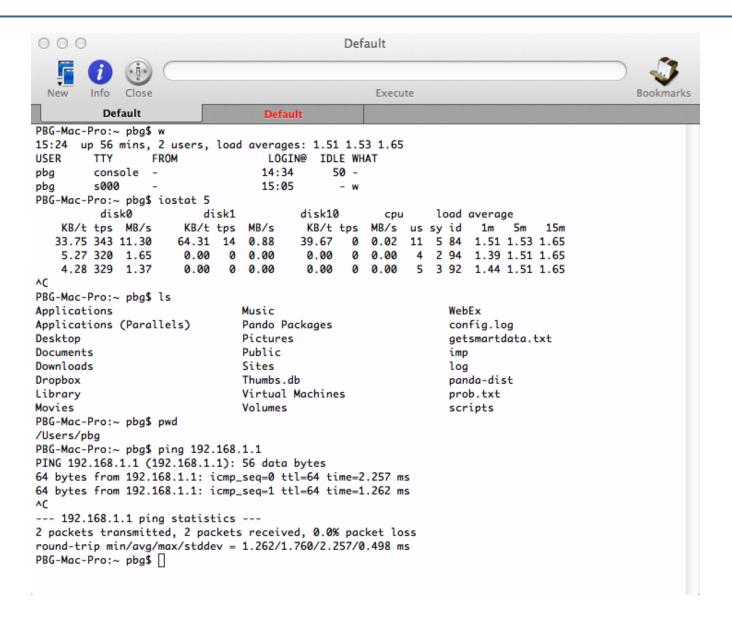
Sometimes multiple flavors implemented – **shells** 

Primarily fetches a command from user and executes it

Sometimes commands built-in, sometimes just names of programs

If the latter, adding new features doesn't require shell modification

### **Bourne Shell Command Interpreter**



### **User Operating-System Interface - GUI**

#### Graphical User Interface (GUI)

User-friendly desktop metaphor interface

Usually mouse, keyboard, and monitor

lcons represent files, programs, actions, etc

Various mouse buttons over objects in the interface cause various actions (provide information, options, execute function, open directory (known as a folder)

Invented at Xerox PARC

Many systems now include both CLI and GUI interfaces

Microsoft Windows is GUI with CLI "command" shell

Apple Mac OS X is "Aqua" GUI interface with UNIX kernel underneath and shells available

Unix and Linux have CLI with optional GUI interfaces (CDE, KDE, GNOME)

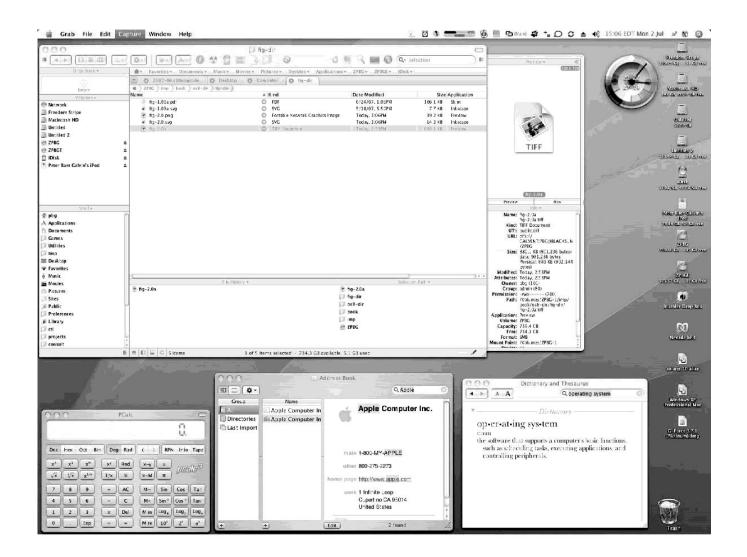
### **Touchscreen Interfaces**

- Touchscreen devices require new interfaces
  - Mouse not possible or not desired
  - Actions and selection based on gestures
  - Virtual keyboard for text entry

Voice commands.



### The Mac OS X GUI



### 2.3 System Calls

Programming interface to the services provided by the OS

Typically written in a high-level language (C or C++)

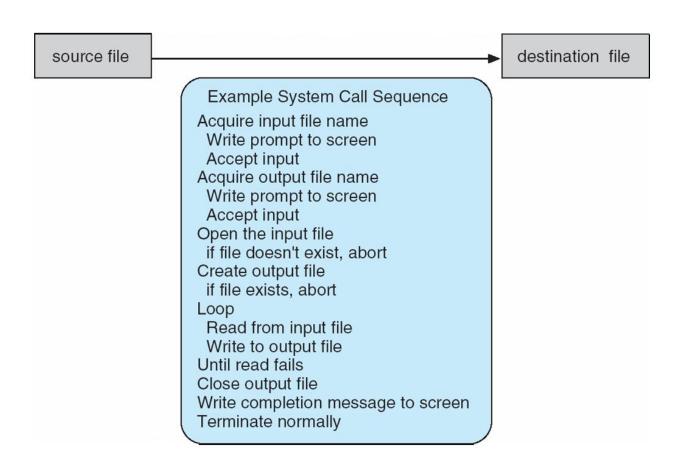
Mostly accessed by programs via a high-level **Application Programming Interface (API)** rather than direct system call use

Three most common APIs are Win32 API for Windows, POSIX API for POSIX-based systems (including virtually all versions of UNIX, Linux, and Mac OS X), and Java API for the Java virtual machine (JVM)

Note that the system-call names used throughout this text are generic

### **Example of System Calls**

System call sequence to copy the contents of one file to another file



### **Example of Standard API**

#### EXAMPLE OF STANDARD API

As an example of a standard API, consider the read() function that is available in UNIX and Linux systems. The API for this function is obtained from the man page by invoking the command

#### man read

on the command line. A description of this API appears below:

```
#include <unistd.h>
ssize_t read(int fd, void *buf, size_t count)

return function parameters
value name
```

A program that uses the read() function must include the unistd.h header file, as this file defines the ssize\_t and size\_t data types (among other things). The parameters passed to read() are as follows:

- int fd—the file descriptor to be read
- void \*buf—a buffer where the data will be read into
- size\_t count—the maximum number of bytes to be read into the buffer

On a successful read, the number of bytes read is returned. A return value of 0 indicates end of file. If an error occurs, read() returns -1.

### **System Call Implementation**

Typically, a number associated with each system call

System-call interface maintains a table indexed according to these numbers

The system call interface invokes the intended system call in OS kernel and returns status of the system call and any return values

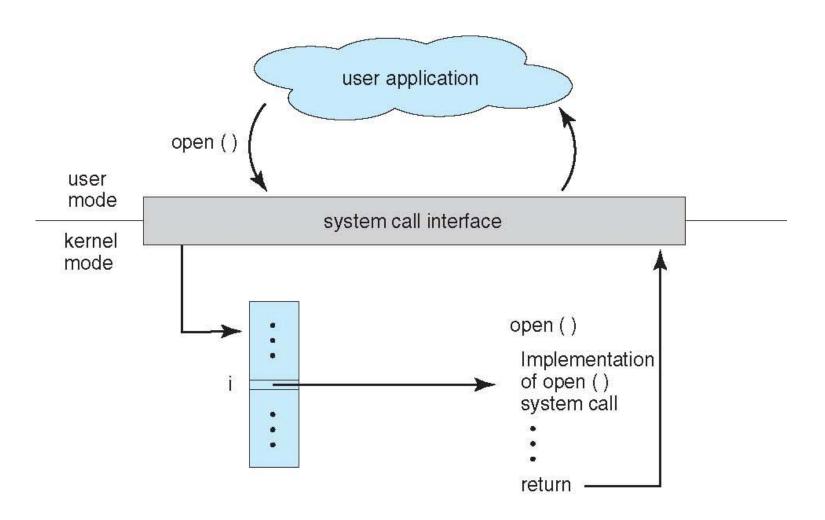
The caller need know nothing about how the system call is implemented

Just needs to obey API and understand what OS will do as a result call

Most details of OS interface hidden from programmer by API

 Managed by run-time support library (set of functions built into libraries included with compiler)

# API – System Call – OS Relationship



# **System Call Parameter Passing**

Often, more information is required than simply identity of desired system call

Exact type and amount of information vary according to OS and call

Three general methods used to pass parameters to the OS

Simplest: pass the parameters in registers

In some cases, may be more parameters than registers

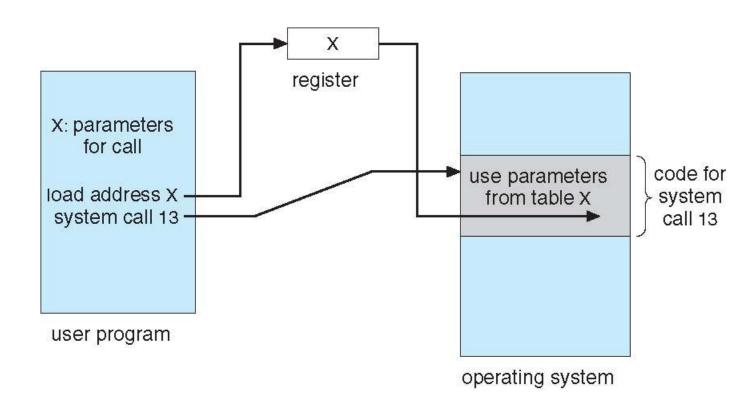
Parameters stored in a block, or table, in memory, and address of block passed as a parameter in a register

This approach taken by Linux and Solaris

Parameters placed, or **pushed**, onto the **stack** by the program and **popped** off the stack by the operating system

Block and stack methods do not limit the number or length of parameters being passed

### **Parameter Passing via Table**



### **Types of System Calls**

#### **Process control**

create process, terminate process

end, abort

load, execute

get process attributes, set process attributes

wait for time

wait event, signal event

allocate and free memory

Dump memory if error

Debugger for determining bugs, single step execution

Locks for managing access to shared data between processes

# **Types of System Calls**

#### File management

create file, delete file
open, close file
read, write, reposition
get and set file attributes

#### **Device management**

request device, release device read, write, reposition get device attributes, set device attributes logically attach or detach devices

# Types of System Calls (Cont.)

#### Information maintenance

get time or date, set time or date get system data, set system data get and set process, file, or device attributes

#### **Communications**

create, delete communication connection
send, receive messages if message passing model to host
name or process name

From client to server

Shared-memory model create and gain access to memory regions

transfer status information attach and detach remote devices

# Types of System Calls (Cont.)

#### **Protection**

Control access to resources

Get and set permissions

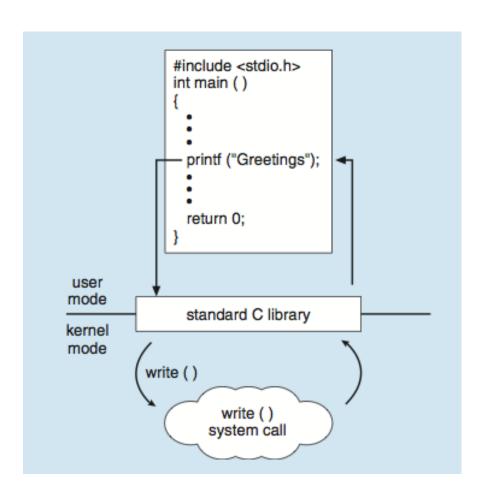
Allow and deny user access

### **Examples of Windows and Unix System Calls**

	Windows	Unix
Process Control	<pre>CreateProcess() ExitProcess() WaitForSingleObject()</pre>	<pre>fork() exit() wait()</pre>
File Manipulation	<pre>CreateFile() ReadFile() WriteFile() CloseHandle()</pre>	<pre>open() read() write() close()</pre>
Device Manipulation	SetConsoleMode() ReadConsole() WriteConsole()	ioctl() read() write()
Information Maintenance	<pre>GetCurrentProcessID() SetTimer() Sleep()</pre>	<pre>getpid() alarm() sleep()</pre>
Communication	<pre>CreatePipe() CreateFileMapping() MapViewOfFile()</pre>	<pre>pipe() shmget() mmap()</pre>
Protection	SetFileSecurity() InitlializeSecurityDescriptor() SetSecurityDescriptorGroup()	<pre>chmod() umask() chown()</pre>

### **Standard C Library Example**

C program invoking printf() library call, which calls write() system call



### **Three Examples**

There are so many facets of and variations in process control that we use three examples to clarify these concepts.

### **Example: Arduino**

P74 (Figure 2.9)

Single-tasking

No Shell but boot loader only

Simple method to run program

No process created

Single memory space

Provides no user interface beyond hardware input sensors

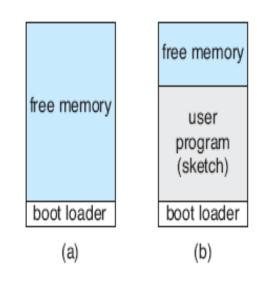


Figure 2.9 Arduino execution. (a) At system startup. (b) Running a sketch.

### **Example: MS-DOS**

#### Single-tasking

Shell invoked when system booted

Simple method to run program

No process created

Single memory space

Loads program into memory, overwriting all but the kernel

Program exit -> shell reloaded

free memory command interpreter kernel (a)

At system startup

process

command interpreter

kernel

running a program

### **Example: FreeBSD**

١t	arian	V2	IX	n	U
	ulal	Va	IX	'	u

low memory

high memory

#### Multitasking

User login -> invoke user's choice of shell

Shell executes fork() system call to create process

Executes exec() to load program into process

Shell waits for process to terminate (with no user interface) or continues with user commands

Process exits with:

code = 0 - no error

code > 0 - error code

free memory

process D

process C

interpreter

process B

kernel

# 2.4 System Services

System programs (or services) provide a convenient environment for program development and execution. They can be divided into:

File management

Status information

File modification

Programming-language support

Program loading and execution

Communications

Background services

Application programs

Most users' view of the operation system is defined by system programs, not the actual system calls

### **System Programs**

Provide a convenient environment for program development and execution

Some of them are simply user interfaces to system calls; others are considerably more complex

**File management** - Create, delete, copy, rename, print, dump, list, and generally manipulate files and directories

#### Status information

Some ask the system for info - date, time, amount of available memory, disk space, number of users

Others provide detailed performance, logging, and debugging information

Typically, these programs format and print the output to the terminal or other output devices

Some systems implement a registry - used to store and retrieve configuration information

# **System Programs (Cont.)**

#### File modification

Text editors to create and modify files

Special commands to search contents of files or perform transformations of the text

**Programming-language support** - Compilers, assemblers, debuggers and interpreters sometimes provided

Program loading and execution- Absolute loaders, relocatable loaders, linkage editors, and overlay-loaders, debugging systems for higher-level and machine language

**Communications** - Provide the mechanism for creating virtual connections among processes, users, and computer systems

Allow users to send messages to one another's screens, browse web pages, send electronic-mail messages, log in remotely, transfer files from one machine to another

# **System Programs (Cont.)**

#### **Background Services**

Launch at boot time

- Some for system startup, then terminate
- Some from system boot to shutdown

Provide facilities like disk checking, process scheduling, error logging, printing

Run in user context not kernel context

Known as services, subsystems, daemons

#### **Application programs**

Don't pertain to system

Run by users

Not typically considered part of OS

Launched by command line, mouse click, finger poke

### 2.5 Linkers and Loaders

Source files are compiled into object files (in relocatable format)

The **linker** combines relocatable object files into a single binary executable file

A loader is used to load the binary executable file into memory, where it is eligible to run on a CPU core

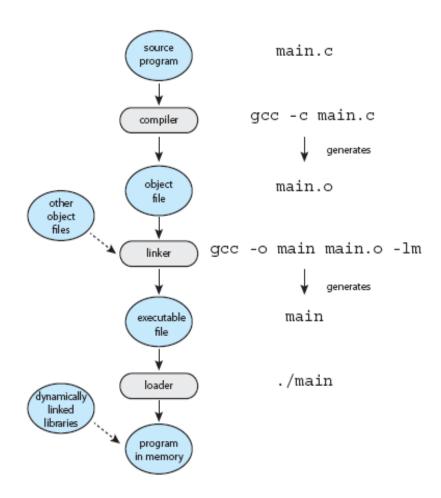


Figure 2.11 The role of the linker and loader.

### 2.6 Why Applications Are Operating-System Specific

Fundamentally, applications compiled on one operating system are not executable on other operating system.

Binary format

CPU instruction set

System calls or API

Unless an interpreter, full run time environment(RTE), or binary executable file is written for and compiled on a specific operating system on a specific CPU type, the application will fail to run.

### 2.7 Operating System Design and Implementation

Design and Implementation of OS **not "solvable"**, but some approaches have proven successful

Internal structure of different Operating Systems can vary widely

Start the design by defining goals and specifications

Affected by choice of hardware, type of system

#### User goals and System goals

User goals – operating system should be convenient to use, easy to learn, reliable, safe, and fast

System goals – operating system should be easy to design, implement, and maintain, as well as flexible, reliable, error-free, and efficient

### **Operating System Design and Implementation (Cont.)**

Important principle to separate

**Policy:** What will be done? Mechanism: How to do it?

Mechanisms determine how to do something, policies decide what will be done

The separation of policy from mechanism is a very important principle, it allows maximum flexibility if policy decisions are to be changed later (example – timer)

Specifying and designing an OS is highly creative task of software engineering

### **Implementation**

Much variation

Early OSes in assembly language

Then system programming languages like Algol, PL/1

Now C, C++

Actually usually a mix of languages

Lowest levels in assembly

Main body in C

Systems programs in C, C++, scripting languages like PERL, Python, shell scripts

More high-level language easier to **port** to other hardware But slower

**Emulation** can allow an OS to run on non-native hardware

## 2.8 Operating System Structure

General-purpose OS is very large program

Various ways to structure ones

Simple structure – MS-DOS

Monolithic structure -- UNIX

Layered – an abstraction

Microkernel –Mach

Modules

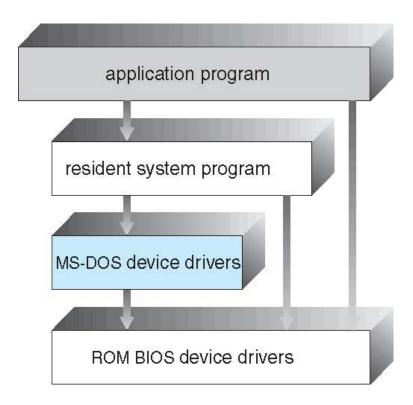
Hybrid

### Simple Structure -- MS-DOS

MS-DOS – written to provide the most functionality in the least space (no structure)

Not divided into modules

Although MS-DOS has some structure, its interfaces and levels of functionality are not well separated



### **Monolithic Structure -- UNIX**

UNIX – limited by hardware functionality, the original UNIX operating system had limited structuring. The UNIX OS consists of two separable parts

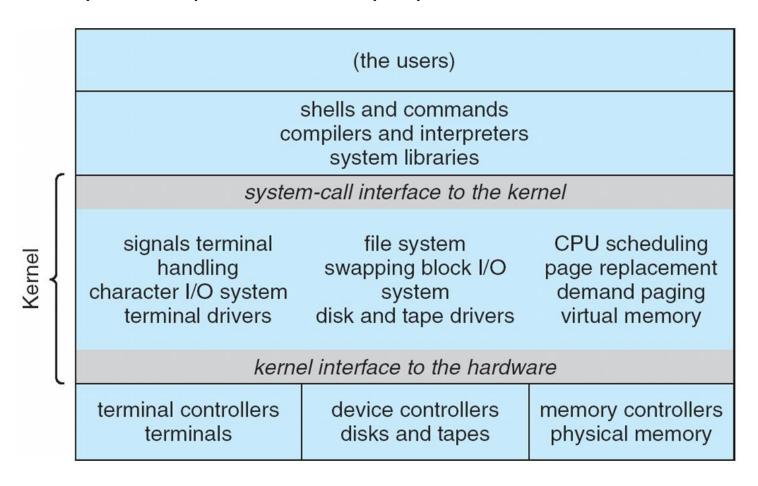
#### Systems programs

#### The kernel

- Consists of everything below the system-call interface and above the physical hardware
- Provides the file system, CPU scheduling, memory management, and other operating-system functions; a large number of functions for one level

## **Traditional UNIX System Structure**

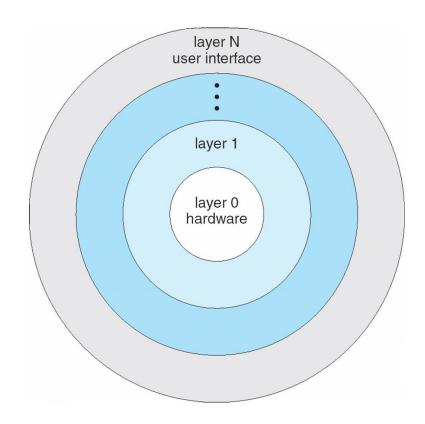
#### Beyond simple but not fully layered



### Layered Approach

The operating system is divided into a number of layers (levels), each built on top of lower layers. The bottom layer (layer 0), is the hardware; the highest (layer N) is the user interface.

With modularity, layers are selected such that each uses functions (operations) and services of only lower-level layers



## Microkernel System Structure

Moves as much from the kernel into user space

Mach example of microkernel

Mac OS X kernel (Darwin) partly based on Mach

Communication takes place between user modules using message passing

#### Benefits:

Easier to extend a microkernel

Easier to port the operating system to new architectures

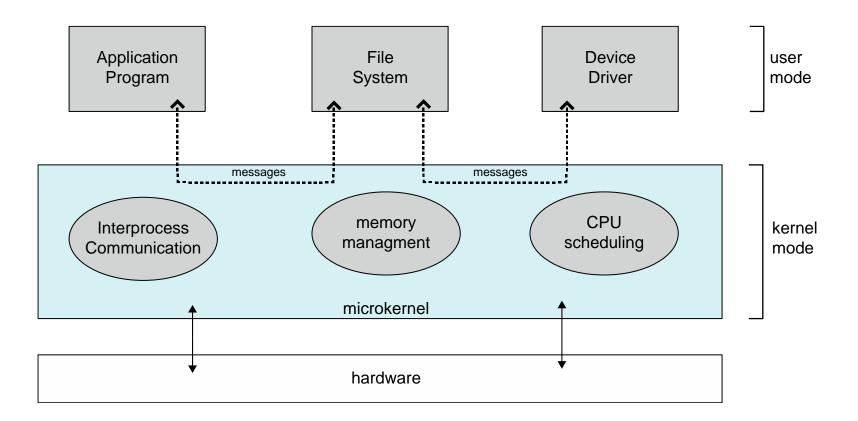
More reliable (less code is running in kernel mode)

More secure

#### **Detriments:**

Performance overhead of user space to kernel space communication

## Microkernel System Structure



### **Modules**

Many modern operating systems implement loadable kernel modules

Uses object-oriented approach

Each core component is separate

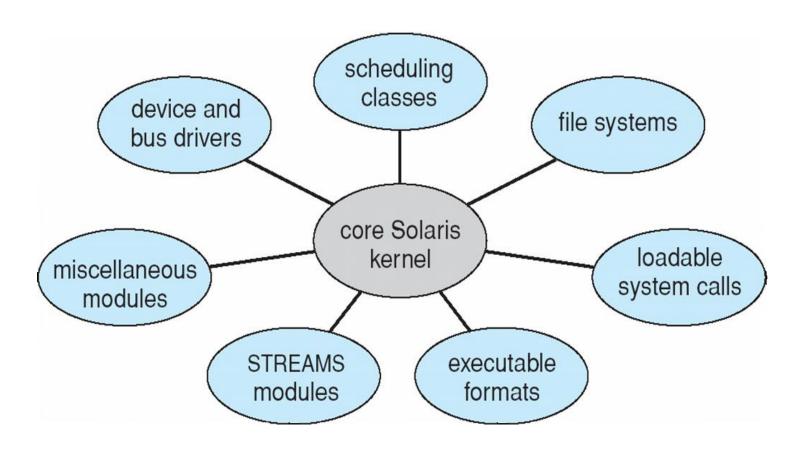
Each talks to the others over known interfaces

Each is loadable as needed within the kernel

Overall, similar to layers but with more flexible

Linux, Solaris, etc

## **Solaris Modular Approach**



Most modern operating systems are actually not one pure model

Hybrid combines multiple approaches to address performance, security, usability needs

Linux and Solaris kernels in a kernel address space (for providing very efficient performance), so monolithic, plus modular for dynamic loading of functionality

Windows is largely monolithic as well, but it retains some behavior typical of microkernel system, including providing support for separate subsystems (known as operating-system *personalities*) that run as user-mode process.

The general architecture of Mac OS and iOS systems is shown in Figure 2.16.

#### User experience layer

- Mac OS (Aqua)
- iOS (Springboard)

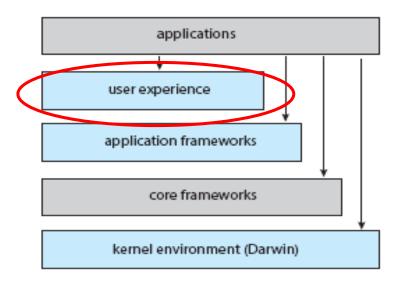


Figure 2.16 Architecture of Apple's macOS and iOS operating systems.

The general architecture of Mac OS and iOS systems is shown in Figure 2.16.

#### Application frameworks layer

- Mac OS (Cocoa)
- iOS (Cocoa touch)

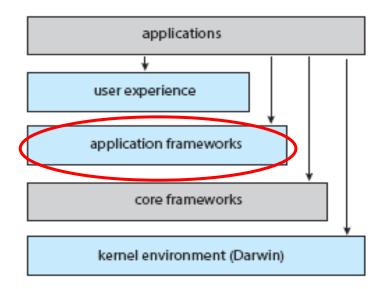


Figure 2.16 Architecture of Apple's macOS and iOS operating systems.

The general architecture of Mac OS and iOS systems is shown in Figure 2.16.

Core frameworks: This layer defines frameworks that support graphics and media including, Quicktime and OpenGL.

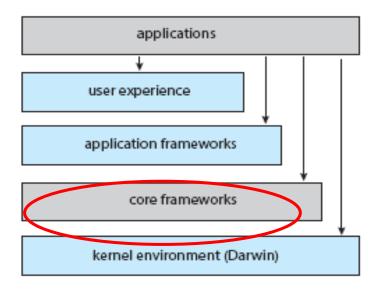


Figure 2.16 Architecture of Apple's macOS and iOS operating systems.

The general architecture of Mac OS and iOS systems is shown in Figure 2.16.

Kernel environment (Darwin) : Mach microkernel + BSD UNIX kernel

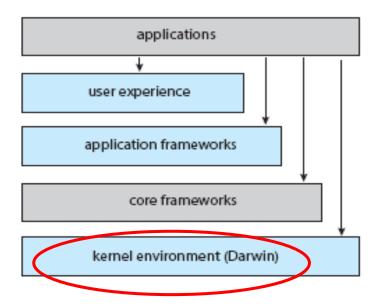
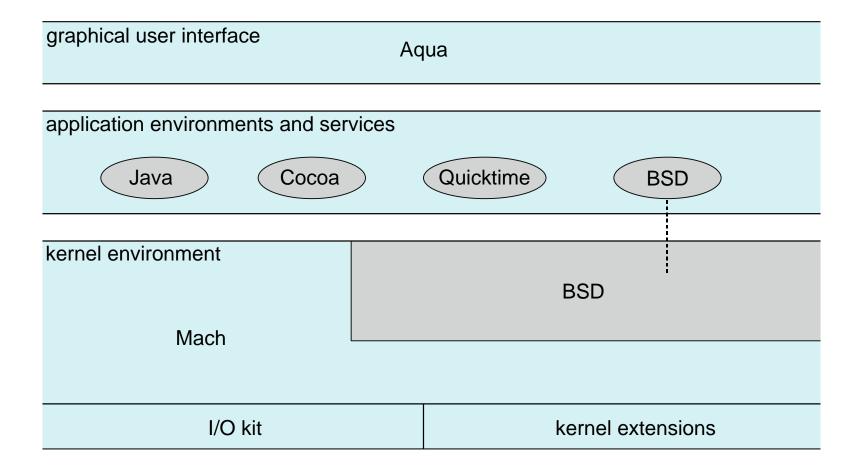


Figure 2.16 Architecture of Apple's macOS and iOS operating systems.

Apple Mac OS X hybrid, layered, Aqua UI plus Cocoa programming environment

Below is kernel consisting of Mach microkernel and BSD Unix parts, plus I/O kit and dynamically loadable modules (called kernel extensions)

### **Mac OS X Structure**



### The Structure of Darwin

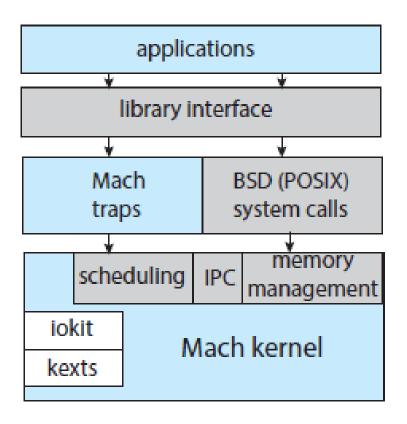


Figure 2.17 The structure of Darwin.

### iOS

Apple mobile OS for *iPhone*, *iPad* 

Structured on Mac OS X, added functionality

Does not run OS X applications natively

 Also runs on different CPU architecture (ARM vs. Intel)

Cocoa Touch Objective-C API for developing apps

**Media services** layer for graphics, audio, video

**Core services** provides cloud computing, databases

**Core operating system**, based on Mac OS X kernel

Cocoa Touch

Media Services

**Core Services** 

Core OS

### **Android**

Developed by Open Handset Alliance (mostly Google)

**Open Source** 

Similar stack to iOS

Based on Linux kernel but modified

Provides process, memory, device-driver management

Adds power management

Runtime environment includes core set of libraries and Dalvik virtual machine

Apps developed in Java plus Android API

 Java class files compiled to Java bytecode then translated to executable than runs in Dalvik VM

Libraries include frameworks for web browser (webkit), database (SQLite), multimedia, smaller libc

### **Android Architecture**

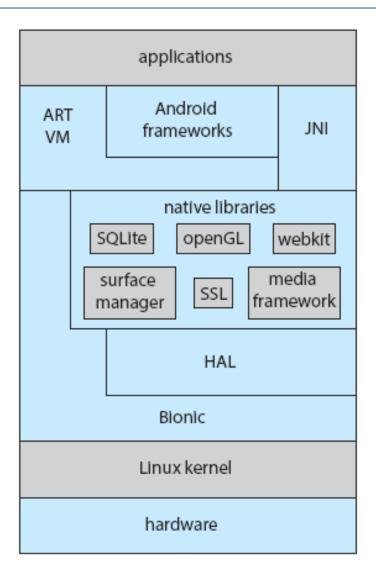


Figure 2.18 Architecture of Google's Android.

### 2.9 Building and Booting an Operating System

#### Operating system generation

Operating systems are designed to run on any of a class of machines; the system must be configured for each specific computer site

SYSGEN program obtains information concerning the specific configuration of the hardware system

- a. The operating system is tailored to the system described.
- b. Link compiled modules
- c. All the code is always part of the system and selection occurs at execution time. (table driven)

## **System Boot**

When power initialized on system, execution starts at a fixed memory location

Firmware ROM used to hold initial boot code

Operating system must be made available to hardware so hardware can start it

Small piece of code – **bootstrap loader**, stored in **ROM** or **EEPROM** locates the kernel, loads it into memory, and starts it

Sometimes two-step process where **boot block** at fixed location loaded by ROM code, which loads bootstrap loader from disk

Common bootstrap loader, **GRUB** (open-source bootstrap program for Linux and UNIX), allows selection of kernel from multiple disks, versions, kernel options

Kernel loads and system is then running

## 2.10 Operating-System Debugging

**Debugging** is finding and fixing errors, or bugs

OS generate log files containing error information

Failure of an application can generate **core dump** file capturing memory of the process

Operating system failure can generate **crash dump** file containing kernel memory

Beyond crashes, performance tuning can optimize system performance Sometimes using *trace listings* of activities, recorded for analysis **Profiling** is periodic sampling of instruction pointer to look for statistical trends

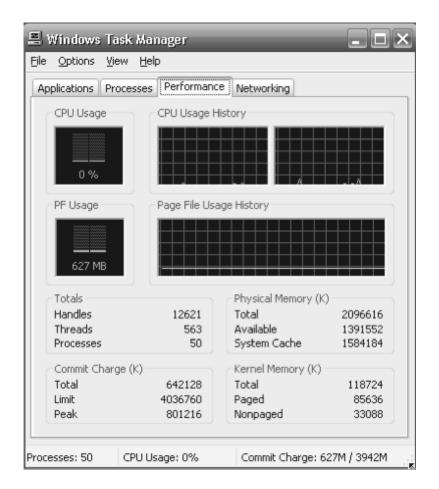
Kernighan's Law: "Debugging is twice as hard as writing the code in the first place. Therefore, if you write the code as cleverly as possible, you are, by definition, not smart enough to debug it."

## **Performance Tuning**

Improve performance by removing bottlenecks

OS must provide means of computing and displaying measures of system behavior

For example, "top" program or Windows Task Manager



### **DTrace**

DTrace tool in Solaris, FreeBSD, Mac OS X allows live instrumentation on production systems

Probes fire when code is executed within a provider, capturing state data and sending it to consumers of those probes

Example of following XEventsQueued system call move from libc library to kernel and back

```
# ./all.d 'pgrep xclock' XEventsQueued
dtrace: script './all.d' matched 52377 probes
CPU FUNCTION
  0 -> XEventsQueued
                                         U
      -> XEventsQueued
                                         U
        -> X11TransBytesReadable
                                         U
        <- X11TransBytesReadable
                                         U
        -> X11TransSocketBytesReadable U
        <- X11TransSocketBytesreadable U
        -> ioctl
                                         U
          -> ioctl
                                         K
            -> getf
              -> set active fd
              <- set active fd
                                         Κ
            <- getf
                                         Κ
            -> get udatamodel
                                         Κ
            <- get udatamodel
                                         Κ
            -> releasef
              -> clear active fd
                                         K
              <- clear active fd
              -> cv broadcast
              <- cv broadcast
            <- releasef
                                         K
          <- ioctl
                                         Κ
        <- ioctl
                                         U
      <- XEventsQueued
                                         U
  0 <- XEventsQueued
```

### **Dtrace (Cont.)**

DTrace code to record amount of time each process with UserID 101 is in running mode (on CPU) in nanoseconds

```
sched:::on-cpu
uid == 101
{
    self->ts = timestamp;
}
sched:::off-cpu
self->ts
{
    @time[execname] = sum(timestamp - self->ts);
    self->ts = 0;
}
```

```
# dtrace -s sched.d
dtrace: script 'sched.d' matched 6 probes
^C
   gnome-settings-d
                                 142354
   gnome-vfs-daemon
                                 158243
   dsdm
                                 189804
                                 200030
   wnck-applet
   gnome-panel
                                 277864
   clock-applet
                                 374916
   mapping-daemon
                                 385475
                                 514177
   xscreensaver
   metacity
                                 539281
                                2579646
   Xorg
                                5007269
   gnome-terminal
   mixer_applet2
                                7388447
                               10769137
   java
```

Figure 2.21 Output of the D code.

# **End of Chapter 2**