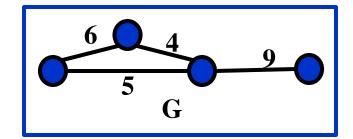
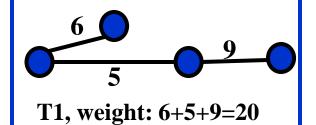
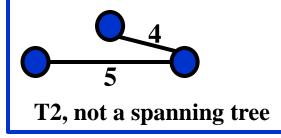
# Lecture 10: Minimum Spanning Tree (MST)

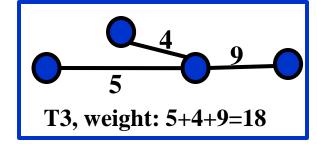
#### Spanning Tree and Minimum Spanning Tree

- **Spanning tree** of a connected graph: A tree that connects *all* nodes of the graph.
- Minimum Spanning tree of a connected weighted graph: A tree that connects all nodes of the graph with total edge weight lowest possible.
- **Example:** For the graph G,
  - T1, T3 are spanning trees
  - T2 is not a spanning tree, because it does not connect all nodes of G
  - T1 is not minimum, because its total weight is 20
  - T2 is minimum with lowest possible total weight 19



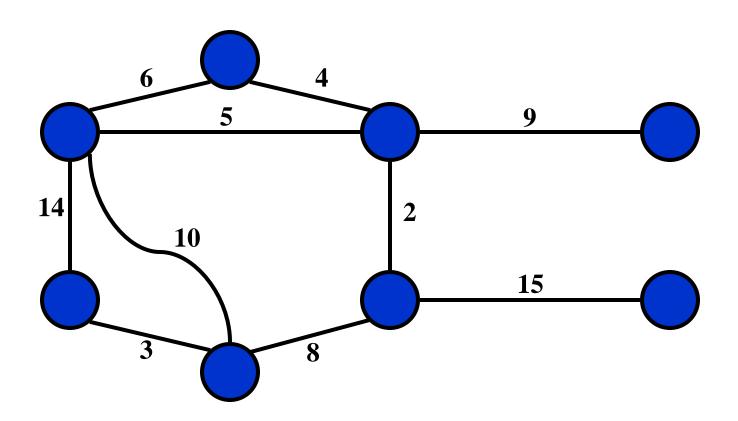




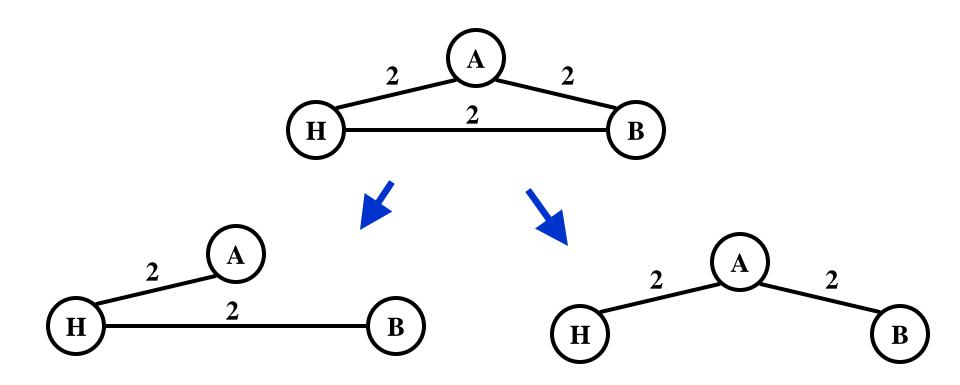


#### Minimum Spanning Tree

• Problem: given a connected, undirected, weighted graph, find a *minimum spanning tree* 

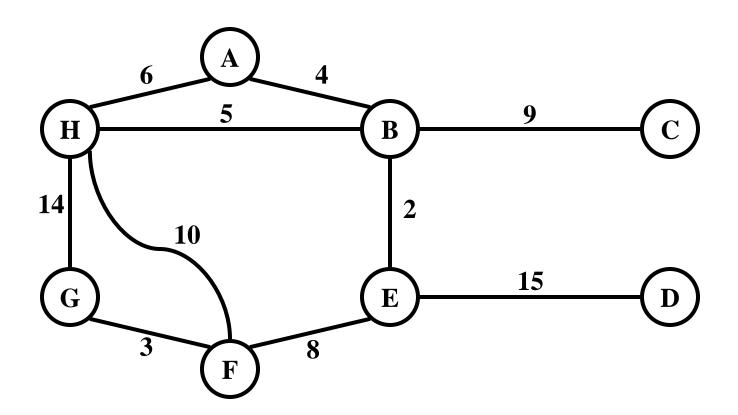


## Mora Than One Minimum Spanning Tree Possible



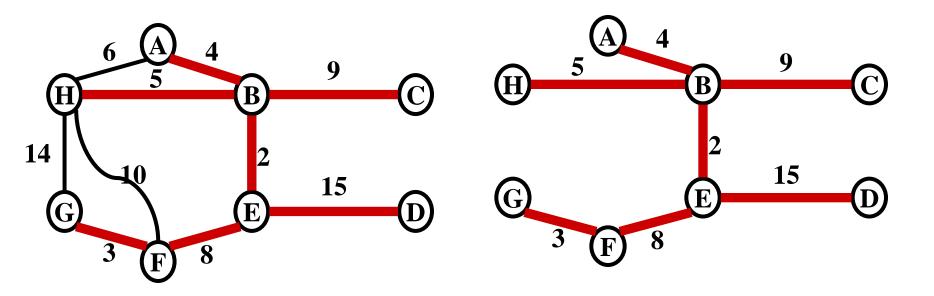
### Minimum Spanning Tree

• Which edges form the minimum spanning tree (MST) of the graph below?



#### Minimum Spanning Tree

• Answer:



• Total weight: 3+8+4+5+2+9+15=46. This is smallest total weight.

#### Two Algorithm

- Krushkal's algorithm
- Prim's algorithm

- Take the minimum weight edge one after another if there is no cycle
- Use disjoint set data structure
- MakeSet() for each element
- Maintain two sets:
  - tree edges
  - other remaining edges
- Use FindSet() to check for cycle (If same set, then must be cycle, because if you connect any two vertices of one set, then it makes a cycle.)

#### Symbols used:

E: Edge set, V: Vertex set, T: Resulting tree, n: number of vertices

```
Run the algorithm:
Kruskal()
                                      19
   T = \emptyset;
                                  25
                                             5
   for each v \in V
                                       13
                          21
      MakeSet(v);
   sort E by increasing edge weight w
   for each (u,v) \in E (in sorted order)
       if FindSet(u) \( \neq \) FindSet(v) //no cycle
          T = T \cup \{\{u,v\}\};
          Union(FindSet(u), FindSet(v));
```

```
Run the algorithm:
Kruskal()
                                       19
   T = \emptyset;
                                   25
                                               5
   \quad \text{for each } v \ \in \ V
                                         13
                           21
       MakeSet(v);
   sort E by increasing edge weight w
   for each (u,v) \in E (in sorted order)
       if FindSet(u) ≠ FindSet(v) //no cycle
           T = T \cup \{\{u,v\}\};
           Union(FindSet(u), FindSet(v));
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Kruskal()
                                     19
   T = \emptyset;
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                                            5
   for each v \in V
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                         21
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Kruskal()
                                     19
   T = \emptyset;
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   for each v \in V
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      if FindSet(u) ≠ FindSet(v) //no cycle
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```

```
Run the algorithm:
Kruskal()
                           2?
                                      19
   T = \emptyset;
                                  25
                                             5
   for each v \in V
                                       13
                          21
       MakeSet(v);
   sort E by increasing edge weight w
   for each (u,v) \in E (in sorted order)
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   T = \emptyset;
                                  25
                                             5?
   for each v \in V
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```

```
Run the algorithm:
Kruskal()
                                      19
   T = \emptyset;
                    8?
                                  25
   for each v \in V
                                       13
                          21
      MakeSet(v);
   sort E by increasing edge weight w
   for each (u,v) \in E (in sorted order)
       if FindSet(u) \( \neq \) FindSet(v) //no cycle
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   T = \emptyset;
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Kruskal()
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   T = \emptyset;
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   for each v \in V
                                     13?
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                                      17?
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                                       13
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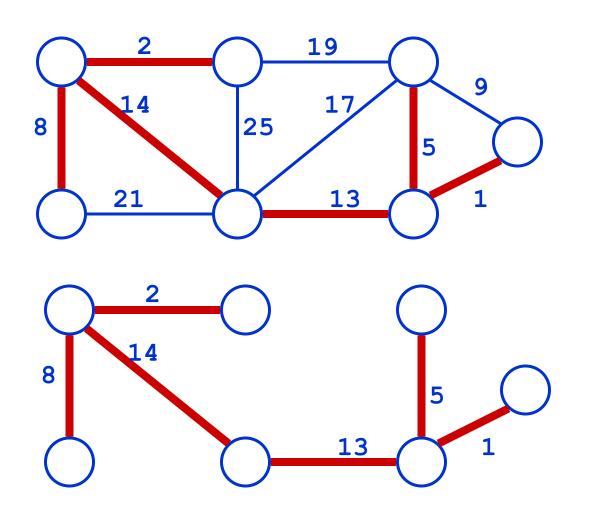
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Run the algorithm:
Kruskal()
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   T = \emptyset;
                                  25
   for each v \in V
                                       13
                          21
      MakeSet(v);
   sort E by increasing edge weight w
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Kruskal()
                                      19
   T = \emptyset;
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                         21?
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   for each (u,v) \in E (in sorted order)
       if FindSet(u) \( \neq \) FindSet(v) //no cycle
          T = T \cup \{\{u,v\}\};
          Union(FindSet(u), FindSet(v));
```

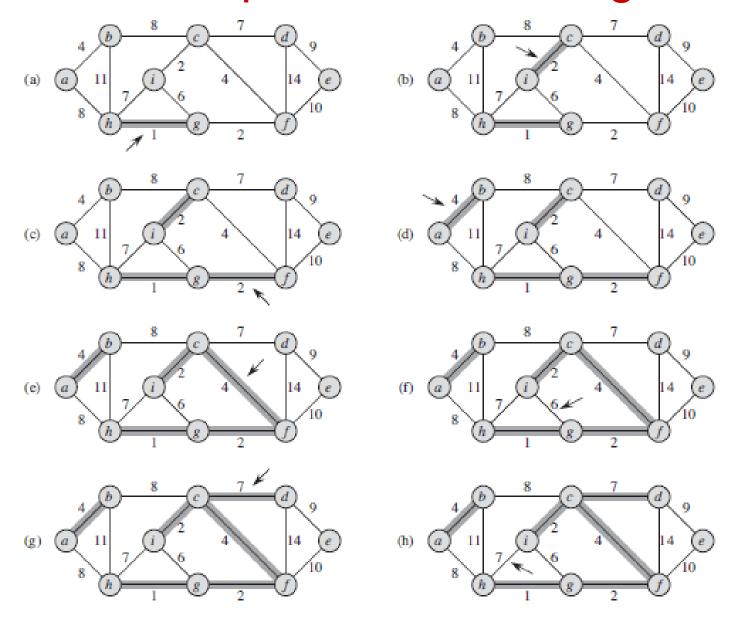
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Run the algorithm:
Kruskal()
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   T = \emptyset;
                                  25?
   for each v \in V
                                       13
                          21
      MakeSet(v);
   sort E by increasing edge weight w
   for each (u,v) \in E (in sorted order)
       if FindSet(u) \( \neq \) FindSet(v) //no cycle
          T = T \cup \{\{u,v\}\};
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Run the algorithm:
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   T = \emptyset;
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   for each v \in V
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      MakeSet(v);
   sort E by increasing edge weight w
   for each (u,v) \in E (in sorted order)
       if FindSet(u) \( \neq \) FindSet(v) //no cycle
          T = T \cup \{\{u,v\}\};
          Union(FindSet(u), FindSet(v));
```

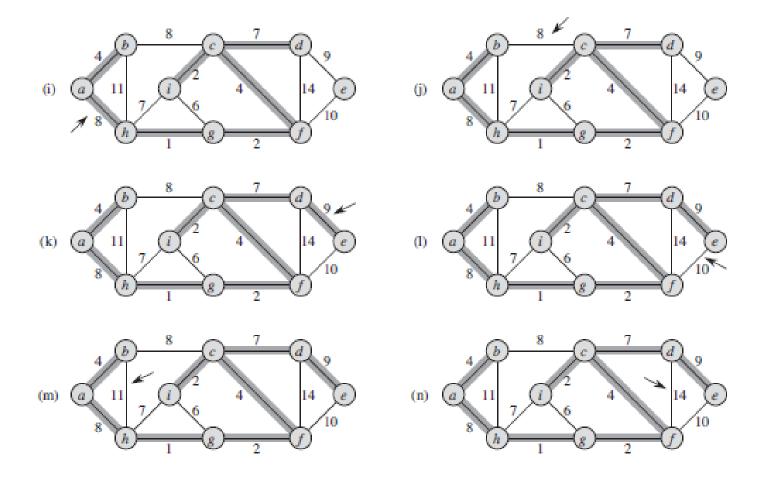
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Run the algorithm:
Kruskal()
                                     19
   T = \emptyset;
                                 25
   for each v \in V
                         21
                                      13
      MakeSet(v);
   sort E by increasing edge weight w
   for each (u,v) \in E (in sorted order)
      if FindSet(u) ≠ FindSet(v) //no cycle
          T = T \cup \{\{u,v\}\};
          Union(FindSet(u), FindSet(v));
```



#### Another Example: Krushkal's Algorithm



#### Another Example: Krushkal's Algorithm



#### Cost of Kruskal's Algorithm

```
Kruskal()
   T = \emptyset;
   for each v \in V
                                            O(E log E)
       MakeSet(v);
   sort E by increasing edge weight w
   for each (u,v) \in E (in sorted order)
       if FindSet(u) \neq FindSet(v) \leftarrow O(1)
          T = T U \{\{u,v\}\};
           Union(FindSet(u), FindSet(v));
  Total E Union(): O(E log E)
```

```
Total Cost: O(n) + O(E \log E) + O(E \log E) = O(E \log E)
E: Number of edges, and E > = n
```

#### Prim's Algorithm

- 1. Initially, all node have weight ∞
- 2. Keep all of them in a queue (heap)
- 3. Take minimum node from heap (ExtractMin())
- 4. For each neighbor of this node, if edge weight from this node is smaller than current weight, then update weight (DecreaseKey()) and add that edge in the tree.
- 5. Repeat step 3, 4 until finished.

n: number of vertex

```
MST-Prim
    for all node u
         weight[u] = \infty;
                          14
    Q = all node;
                                  10
                                                    15
    weight[root] = 0;
    p[root] = NULL;
    while (Q not empty)
                                  Run on example graph
         u = ExtractMin(Q);
         for each v \in Adjacent[u]
              if (v \in Q \text{ and } w(u,v) < weight[v])
                  p[v] = u;
                  weight[v] = w(u,v);
```

```
MST-Prim
     for all node u
         weight[u] = \infty; <sub>14</sub>
                                     10
     Q = all node;
                                                        15
                              \infty
     weight[root] = 0;
    p[root] = NULL;
                                       \infty
     while (Q not empty)
                                     Run on example graph
         u = ExtractMin(Q);
          for each v \in Adjacent[u]
               if (v \in Q \text{ and } w(u,v) < weight[v])
                   p[v] = u;
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```

```
MST-Prim
    for all node u
         weight[u] = \infty;
                             14
                                     10
     Q = all node;
                                                        15
     weight[root] = 0;
    p[root] = NULL;
                                        \infty
    while (Q not empty)
                                       Pick a start vertex r
         u = ExtractMin(Q);
         for each v \in Adjacent[u]
              if (v \in Q \text{ and } w(u,v) < weight[v])
                  p[v] = u;
                   weight[v] = w(u,v);
```

```
Q: heap, V: vertex set, E: Edge set, p: parent, w: edge weight
MST-Prim
     for all node u
                             14
                                     10
         weight[u] = \infty;
                                                        15
     Q = all node;
     weight[root] = 0;
                                        \infty
    p[root] = NULL;
                                  Red vertices have been removed from Q
    while (Q not empty)
         u = ExtractMin(Q);
          for each v \in Adjacent[u]
              if (v \in Q \text{ and } w(u,v) < weight[v])
                   p[v] = u;
                   weight[v] = w(u,v);
```

```
MST-Prim
    for all node u
         weight[u] = \infty;
                             14
                                     10
    Q = all node;
                                                       15
    weight[root] = 0; u
    p[root] = NULL;
    while (Q not empty)
                                   Red arrows indicate parent pointers
         u = ExtractMin(Q);
         for each v \in Adjacent[u]
              if (v \in Q \text{ and } w(u,v) < weight[v])
                  p[v] = u;
                  weight[v] = w(u,v);
```

```
MST-Prim
    for all node u
         weight[u] = \infty;
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                                    10
    Q = all node;
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    weight[root] = 0; u
    p[root] = NULL;
    while (Q not empty)
         u = ExtractMin(Q);
         for each v \in Adjacent[u]
             if (v \in Q \text{ and } w(u,v) < weight[v])
                  p[v] = u;
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    for all node u
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                  p[v] = u;
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MST-Prim
    for all node u
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    Q = all node;
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MST-Prim
    for all node u
         weight[u] = \infty;
                            14
                                   10
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```

```
MST-Prim
                             10
    for all node u
         weight[u] = \infty;
                            14
                                    10
    Q = all node;
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    weight[root] = 0;
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MST-Prim
    for all node u
         weight[u] = \infty;
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    while (Q not empty)
         u = ExtractMin(Q);
         for each v \in Adjacent[u]
             if (v \in Q \text{ and } w(u,v) < weight[v])
                  p[v] = u;
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```

```
MST-Prim
                                                       9
    for all node u
         weight[u] = \infty;
                             14
                                     10
    Q = all node;
                                                      15
    weight[root] = 0;
    p[root] = NULL;
    while (Q not empty)
         u = ExtractMin(Q);
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                                                      9
    for all node u
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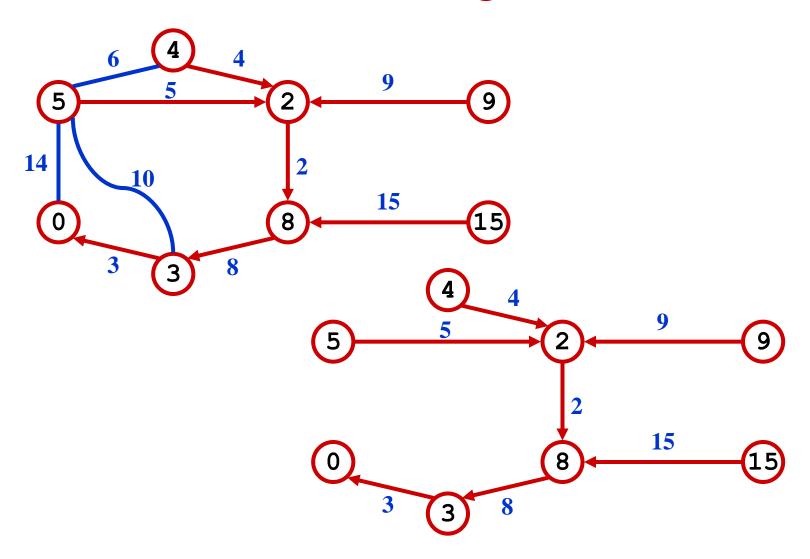
```
MST-Prim
                                                     9
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         weight[u] = \infty;
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MST-Prim
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MST-Prim
    for all node u
         weight[u] = \infty;
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                                   10
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    p[root] = NULL;
    while (Q not empty)
         u = ExtractMin(Q);
         for each v \in Adjacent[u]
             if (v \in Q \text{ and } w(u,v) < weight[v])
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```
MST-Prim
    for all node u
         weight[u] = \infty;
                            14
                                    10
    Q = all node;
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    while (Q not empty)
         u = ExtractMin(Q);
         for each v \in Adjacent[u]
             if (v \in Q \text{ and } w(u,v) < weight[v])
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MST-Prim
    for all node u
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         u = ExtractMin(Q);
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             if (v \in Q \text{ and } w(u,v) < weight[v])
                  p[v] = u;
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```



#### Cost of Prim's Algorithm

```
MST-Prim
    for each node u 🕜
        weight[u] = \infty;
                                    BuildHeap = O(n log n)
    weight[root] = 0;
   p[root] = NULL;
                                n times
    while (Q not empty) ←
        for each v \in Adjacent[u] Total for all nodes =
                                                  E times
            if (v \in Q \text{ and } w(u, v) < \text{weight}[v])
                p[v] = u;
                weight[v] = w(u,v);
                                       HeapDecreaseKey
                                           O(log n)
     Worst Case Total for this part: n*(O(log n)+E*O(log n)) =
     O(n \log n) + O(nE \log n) = O(nE \log n)
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   while (Q not empty) ← n times
      for each v \in Adjacent[u] Total for all nodes =
                                           E times
          if (v \in Q \text{ and } w(u,v) < weight[v])
             p[v] = u;
             weight[v] = w(u,v); HeapDecreaseKey
                                   = O(\log n)
       1
```

But, amortized cost (agreegate method): How many total ExractMin()? **Answer:** n. How many total DecreaseKey()? **Answer:** E.

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   while (Q not empty) ← n times
      for each v \in Adjacent[u] Total for all nodes =
                                           E times
          if (v \in Q \text{ and } w(u,v) < weight[v])
             p[v] = u;
             weight[v] = w(u,v); HeapDecreaseKey
                                   = O(\log n)
```

So, total cost: BuildHeap() + n ExtractMin + E DecreaseKey = n\*O(log n) + E\*O(n log n) = O(n log n) + O(E log n) = O(E log n), because E >= n\*O(log n)