

Course Number	532
Course Title	Signal and Systems I
Semester/Year	F2021

Instructor	Soosan Beheshti
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ASSIGNMENT No.	3
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Assignment Title	Fourier Series Analysis Using Matlab
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www.ryerson.ca/senate/current/pol60.pdf.

A.1 and A.2:

ELE 532 LAB 3

A.1 $x_1(t) = \cos \frac{3\pi}{10} t + \frac{1}{2} \cos \frac{\pi}{10} t$

$$x_1(t) = \frac{1}{2} e^{j3\pi/10 t} + \frac{1}{2} e^{-j3\pi/10 t} + \frac{1}{2} \left(\frac{1}{2} e^{j\pi/10 t} + \frac{1}{2} e^{-j\pi/10 t} \right)$$

$$x_1(t) = \frac{1}{2} e^{j3\pi/10 t} + \frac{1}{2} e^{-j3\pi/10 t} + \frac{1}{4} e^{j\pi/10 t} + \frac{1}{4} e^{-j\pi/10 t}$$

Fundamental Frequency:

$$W_{01} = \frac{3\pi}{10} \quad W_{02} = \frac{\pi}{10} \quad T_0 = \frac{2\pi}{\left(\frac{\pi}{10}\right)} = \frac{2\pi \cdot 10}{\pi} = 20$$

$$\frac{3\pi}{10} \cdot \frac{10}{\pi} = 3$$

$$\frac{GCE}{LCM} = \frac{\pi}{10}$$

$$jn \frac{\pi}{10} t = j \frac{3\pi}{10} t$$

$$n = 3$$

$$n = -3$$

$$jn \frac{\pi}{10} t = j \frac{\pi}{10} t$$

$$n = 1$$

$$n = -1$$

$$D_3 = \frac{1}{2}$$

$$D_{-3} = \frac{1}{2}$$

$$D_1 = \frac{1}{4}$$

$$D_{-1} = \frac{1}{4}$$

$$D_n = \frac{1}{20} \int_{-10}^{10} \left[\frac{1}{2} e^{j3\pi/10 t} + \frac{1}{2} e^{-j3\pi/10 t} + \frac{1}{4} e^{j\pi/10 t} + \frac{1}{4} e^{-j\pi/10 t} \right] e^{-jn\pi/10 t} dt$$

A.1 (continued)

$$D_n = \frac{1}{20} \left[\frac{e^{j(3-n)\pi} - e^{-j(3-n)\pi}}{2j(3-n)\pi/10} + \frac{e^{j(3+n)\pi} - e^{-j(3+n)\pi}}{2j(3+n)\pi/10} + \frac{e^{j(1+n)\pi} - e^{-j(1+n)\pi}}{4j(1+n)\pi/10} + \frac{e^{j(1-n)\pi} - e^{-j(1-n)\pi}}{4j(1-n)\pi/10} \right]$$

$$= D_n = \frac{1}{\pi} \left[\text{Sinc}[(3-n)\pi] + \text{Sinc}[(3+n)\pi] \right] + \frac{1}{2} \text{Sinc}[(1+n)\pi] + \frac{1}{2} \text{Sinc}[(1-n)\pi]$$

A.2 $x_2(t)$: $\omega_0 = \frac{2\pi}{T_0}$ where $T_0 = 20$, $\omega_0 = \frac{2\pi}{20} = \frac{\pi}{10}$

$$D_n = \frac{1}{20} \left[\int_{-5}^5 (1) e^{-jn\pi/10t} dt \right] = \frac{1}{20} \left[\frac{1}{-jn\pi/10} e^{-jn\pi/10t} \right]_{-5}^5$$

$$D_n = \frac{1}{20} \left[\frac{-10}{jn\pi} e^{-jn\pi/2} + \frac{10}{jn\pi} e^{jn\pi/2} \right] = \frac{1}{n\pi} \sin\left(\frac{n\pi}{2}\right)$$

$$D_n = \frac{1}{n\pi} \sin\left(\frac{n\pi}{2}\right)$$

$x_3(t)$: $T_0 = 40$ $\omega_0 = \frac{2\pi}{40} = \frac{\pi}{20}$ | $D_n = \frac{1}{40} \int_{-5}^5$

$$(1) e^{-jn\pi/20t} dt \rightarrow D_n = \frac{1}{40} \left[\frac{1}{-jn\pi/20} e^{-jn\pi/20t} \right]_{-5}^5$$

$$D_n = \frac{1}{40} \left[\frac{-20}{jn\pi} e^{-jn\pi/4} + \frac{20}{jn\pi} e^{jn\pi/4} \right]$$

$$\therefore D_n = \frac{1}{n\pi} \sin\left(\frac{n\pi}{4}\right)$$

A.3:

```
%A.3:
function [D1,D2,D3]=Lab3(d,n)

D1 = (1/2)*(abs(n)==3)+(1/4)*(abs(n)==1);
D2 = (1/n*pi).*(sin(pi*n/2));
D3 = (1/n*pi).*(sin(pi*n/4));

if (d == 1)
D1 = (1/2)*(abs(n)==3)+(1/4)*(abs(n)==1);
end

if (d == 2)
D2 = (1/n*pi).*(sin(pi*n/2));
end

if (d == 3)
D3 = (1/n*pi).*(sin(pi*n/4));
end

end
```

A.4 (a):

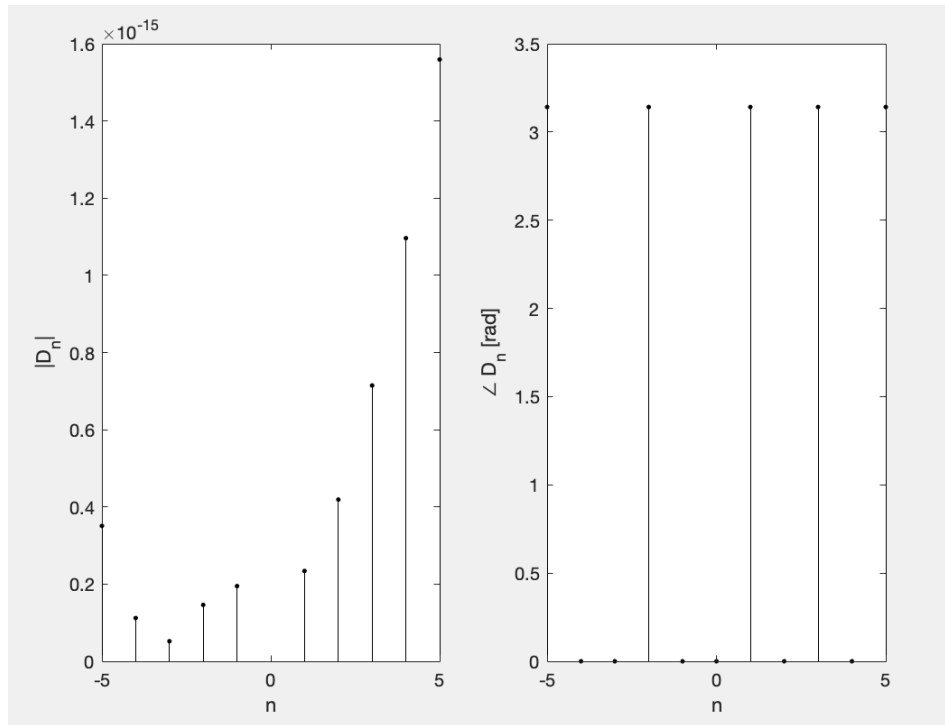
```
% A.4: (a)
% x1(t)
clf;
n = (-5:5);

D_n = 1./2.*((1./(pi.*n)).*sin((3-n).*pi))+(1./pi.*n).*sin((3+n).*pi)+(1./(2.*n.*pi)).*sin((1+n).*pi)+(1./(2.*n.*pi)).*sin((1-n).*pi);

subplot(1,2,1);
stem(n,abs(D_n),'k');
xlabel('n');
ylabel('|D_n|');

subplot(1,2,2);
stem(n,angle(D_n),'k');
xlabel('n');
ylabel("\angle D_n [rad]");
```

$x_1(t)$:



`%x2(t)`

```
clf;
n = (-5:5);
```

```
D_n = (1 ./ (n.*pi)).*sin((n.*pi)./2);
```

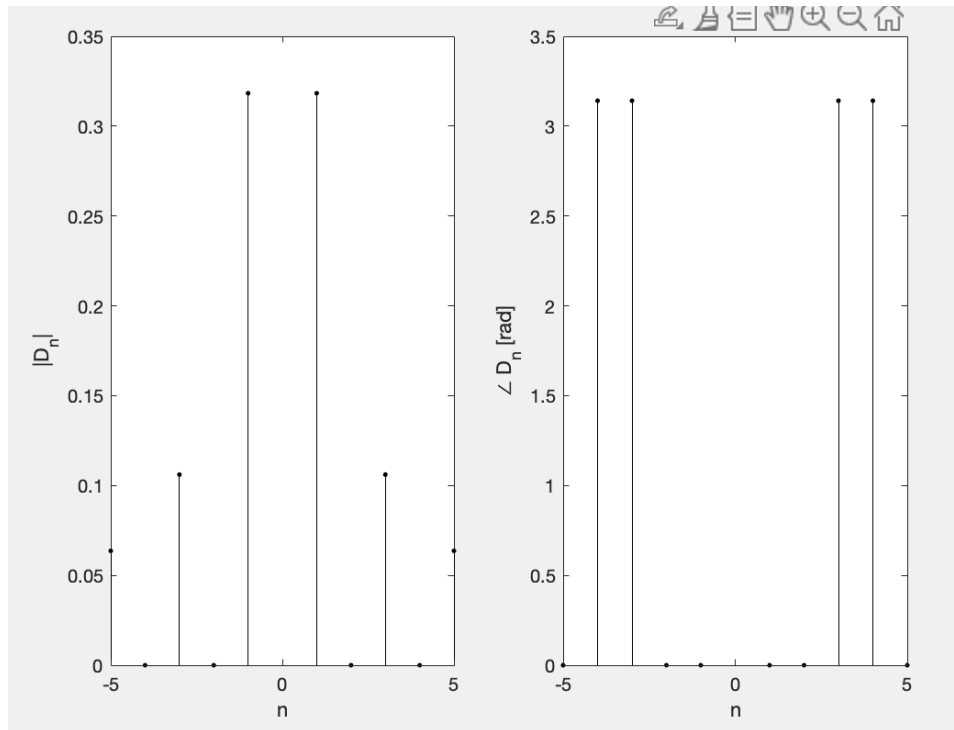
```
subplot(1,2,1); stem(n,abs(D_n),'k');
```

```
xlabel('n'); ylabel('|D_n|');
```

```
subplot(1,2,2); stem(n,angle(D_n),'k');
```

```
xlabel('n'); ylabel('\angle D_n [rad]');
```

$x_2(t)$:

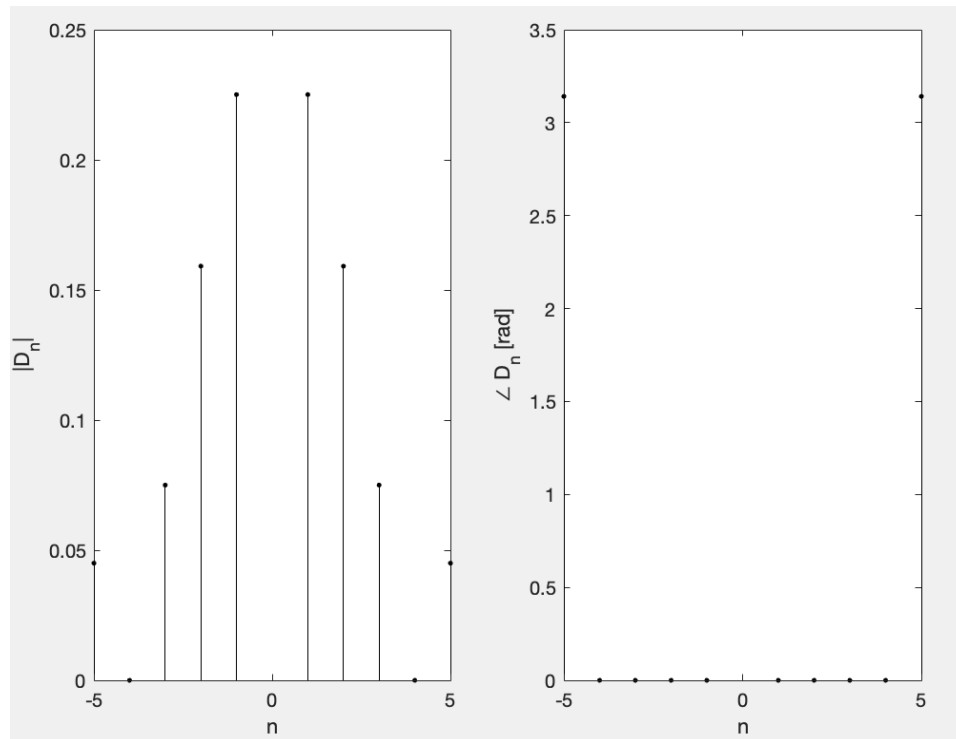


```
%x3(t)
clf;
n = (-5:5);

D_n = (1./(n.*pi)).*sin((n.*pi)./4);

subplot(1,2,1); stem(n,abs(D_n),'k');
xlabel('n'); ylabel('|D_n|');
subplot(1,2,2); stem(n,angle(D_n),'k');
xlabel('n'); ylabel('\angle D_n [rad]');
```

$x_3(t)$:



A.4 (b):

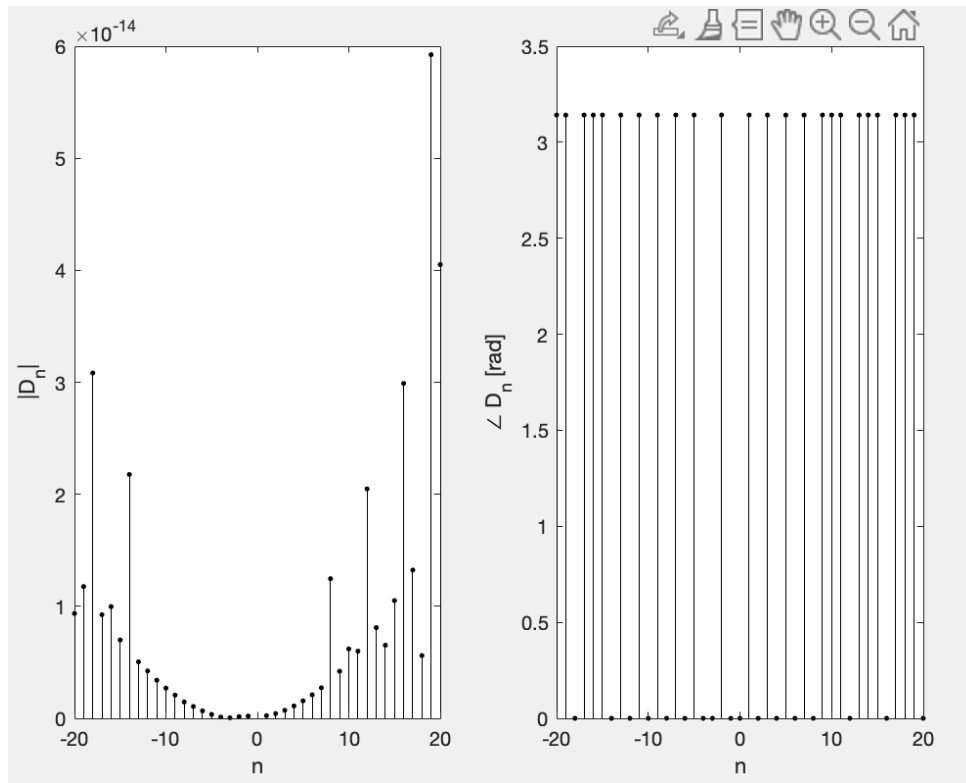
```
%x1(t)
clf;
n = (-20:20);

D_n = 1./2.*((1./(pi.*n)).*sin((3-n).*pi))+(1./pi.*n).*sin((3+n).*pi)+(1./(2.*n.*pi)).*sin((1+n).*pi)+(1./(2.*n.*pi)).*sin((1-n).*pi));

subplot(1,2,1);
stem(n,abs(D_n),'k');
xlabel('n');
ylabel('|D_n|');

subplot(1,2,2);
stem(n,angle(D_n),'k');
xlabel('n');
ylabel('\angle D_n [rad]');
```

$x_1(t)$:

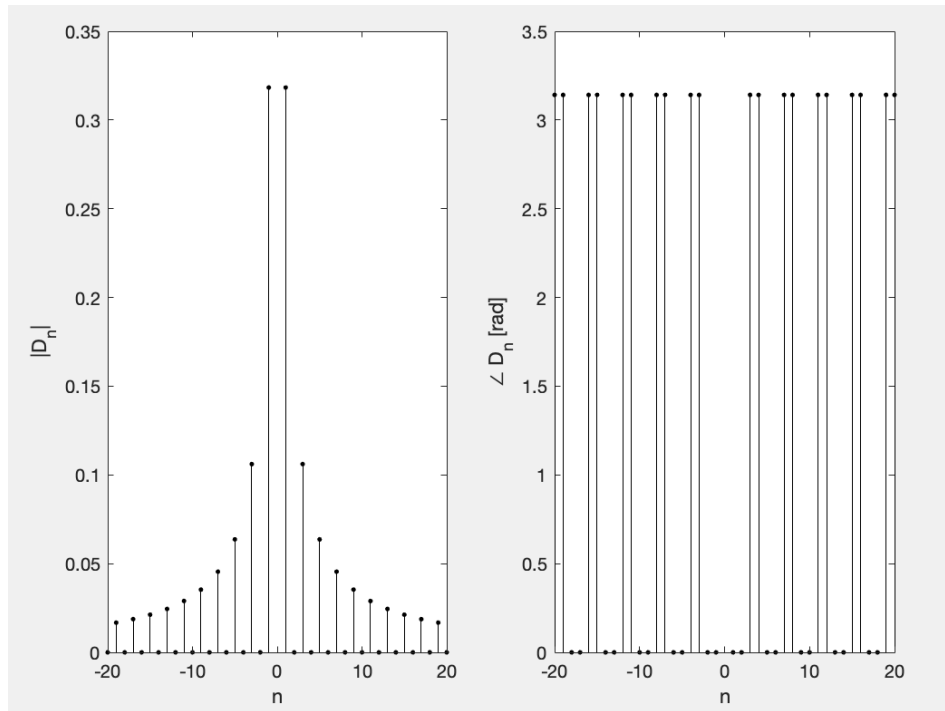


```
%x2(t)
clf;
n = (-20:20);

D_n = (1 ./ (n.*pi)).*sin((n.*pi)./2);

subplot(1,2,1); stem(n,abs(D_n),'k');
xlabel('n'); ylabel('|D_n|');
subplot(1,2,2); stem(n,angle(D_n),'k');
xlabel('n'); ylabel('\angle D_n [rad]');
```


$x_2(t)$:

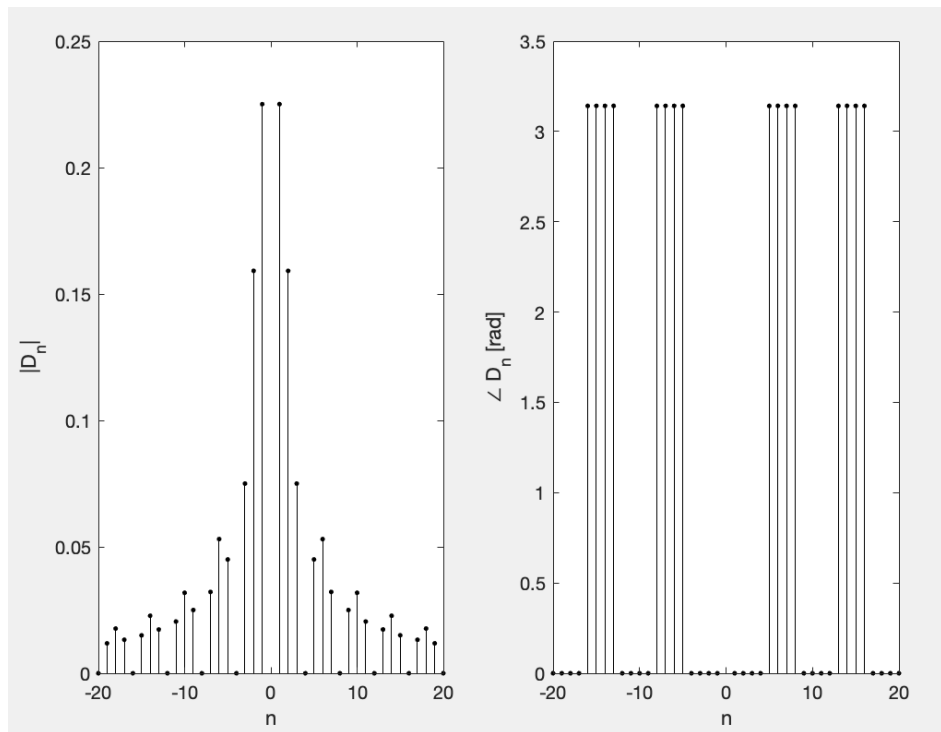


```
%x3(t)
clf;
n = (-20:20);

D_n = (1./(n.*pi)).*sin((n.*pi)./4);

subplot(1,2,1); stem(n,abs(D_n),'.k');
xlabel('n'); ylabel('|D_n|');
subplot(1,2,2); stem(n,angle(D_n),'.k');
xlabel('n'); ylabel('angle D_n [rad]');
```

$x_3(t)$:



A.4 (c):

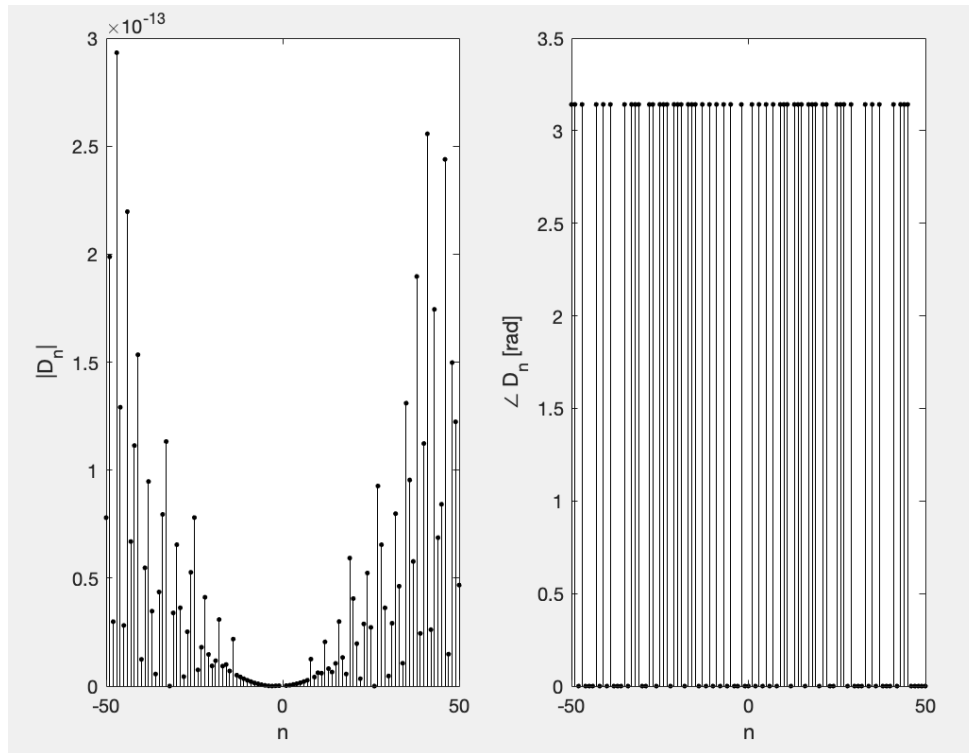
```
%x1(t)
clf;
n = (-50:50);

D_n = 1./2.*((1./(pi.*n)).*sin((3-n).*pi))+(1./pi.*n).*sin((3+n).*pi)+(1./(2.*n.*pi)).*sin((1+n).*pi)+(1./(2.*n.*pi)).*sin((1-n).*pi));

subplot(1,2,1);
stem(n,abs(D_n),'.k');
xlabel('n');
ylabel('|D_n|');

subplot(1,2,2);
stem(n,angle(D_n),'.k');
xlabel('n');
ylabel('\angle D_n [rad]');
```

$x_1(t)$:

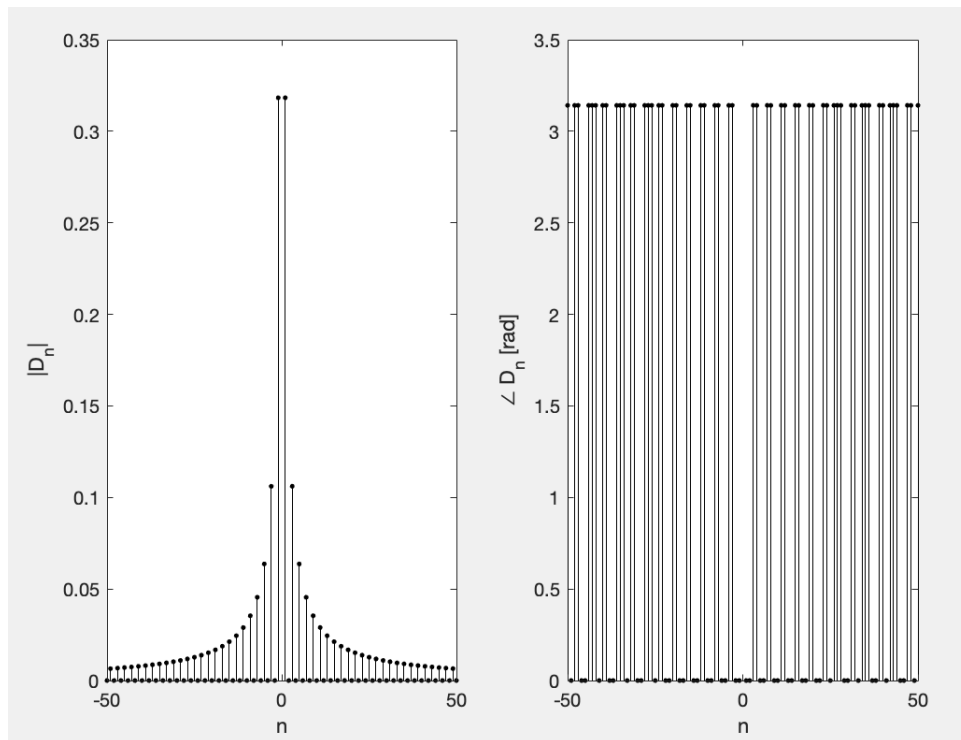


```
% %x2(t)
clf;
n = (-50:50);

D_n = (1 ./ (n.*pi)).*sin((n.*pi)./2);

subplot(1,2,1); stem(n,abs(D_n),'k');
xlabel('n'); ylabel('|D_n|');
subplot(1,2,2); stem(n,angle(D_n),'k');
xlabel('n'); ylabel('angle D_n [rad]');
```

x2(t):

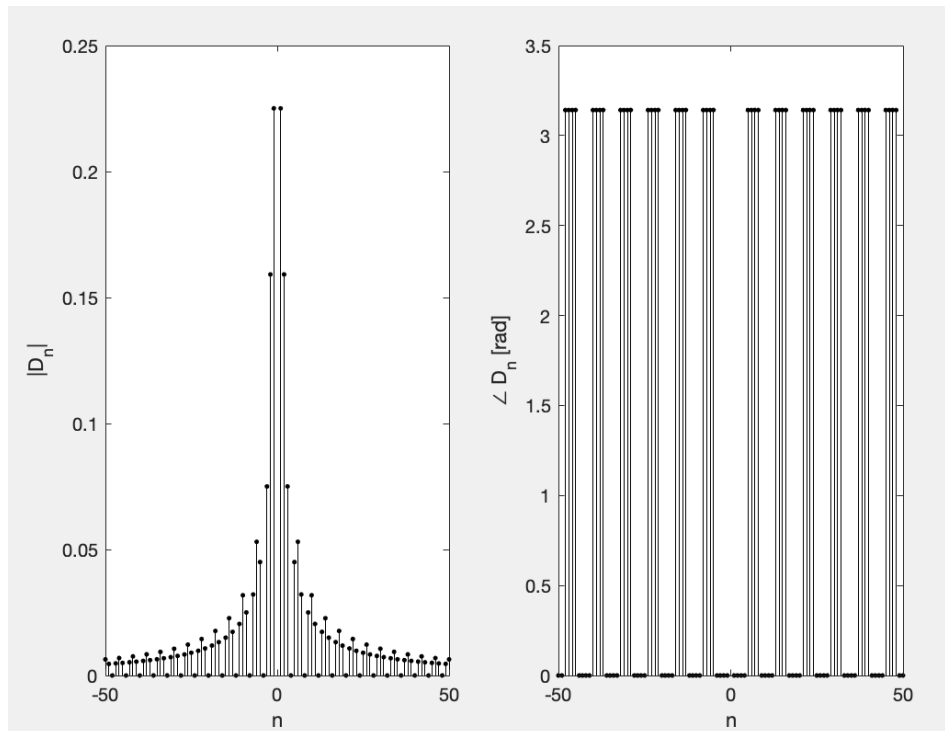


```
%x3(t)
clf;
n = (-50:50);

D_n = (1./(n.*pi)).*sin((n.*pi)./4);

subplot(1,2,1); stem(n,abs(D_n),'.k');
xlabel('n'); ylabel('|D_n|');
subplot(1,2,2); stem(n,angle(D_n),'.k');
xlabel('n'); ylabel('\angle D_n [rad]');
```

x3(t):



A.4 (d):

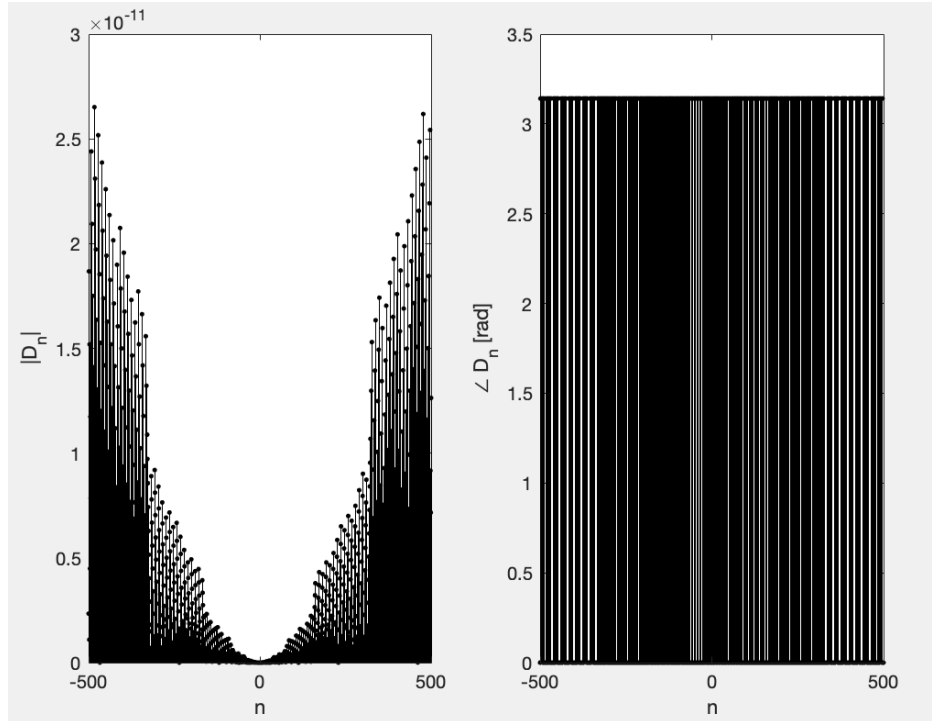
```
%x1(t)
clf;
n = (-500:500);

D_n = 1./2.*((1./(pi.*n)).*sin((3-n).*pi))+(1./pi.*n).*sin((3+n).*pi)+(1./(2.*n.*pi)).*sin((1+n).*pi)+(1./(2.*n.*pi)).*sin((1-n).*pi));

subplot(1,2,1);
stem(n,abs(D_n),'k');
xlabel('n');
ylabel('|D_n|');

subplot(1,2,2);
stem(n,angle(D_n),'k');
xlabel('n');
ylabel('\angle D_n [rad]');
```

$x_1(t)$:

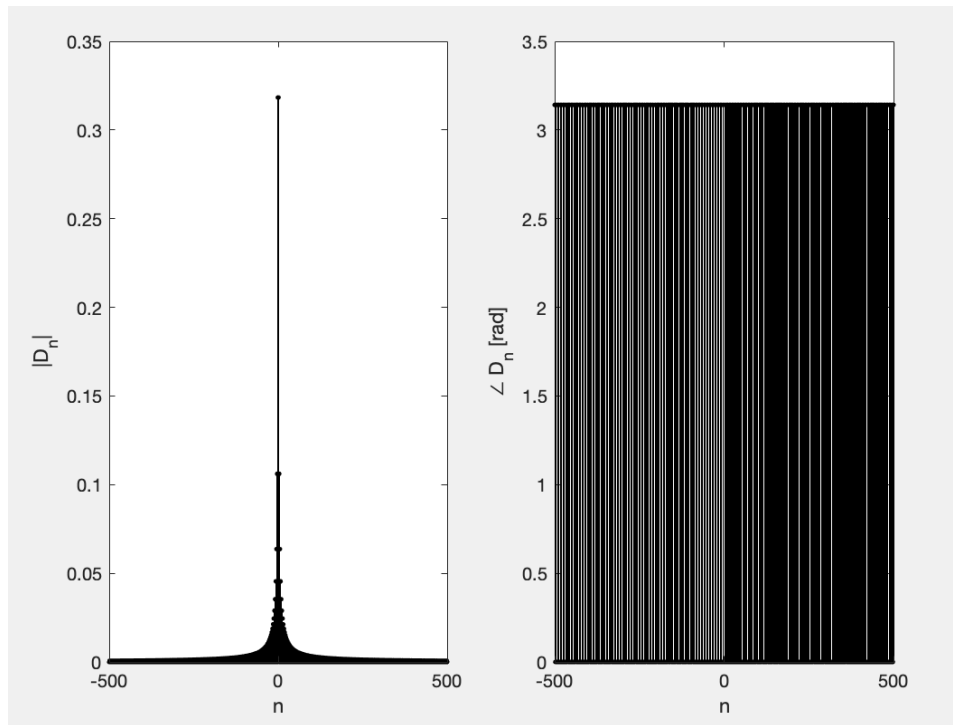


```
%x2(t)
clf;
n = (-500:500);

D_n = (1 ./ (n.*pi)).*sin((n.*pi)./2);

subplot(1,2,1); stem(n,abs(D_n),'k');
xlabel('n'); ylabel('|D_n|');
subplot(1,2,2); stem(n,angle(D_n),'k');
xlabel('n'); ylabel('\angle D_n [rad]');
```

$x_2(t)$:

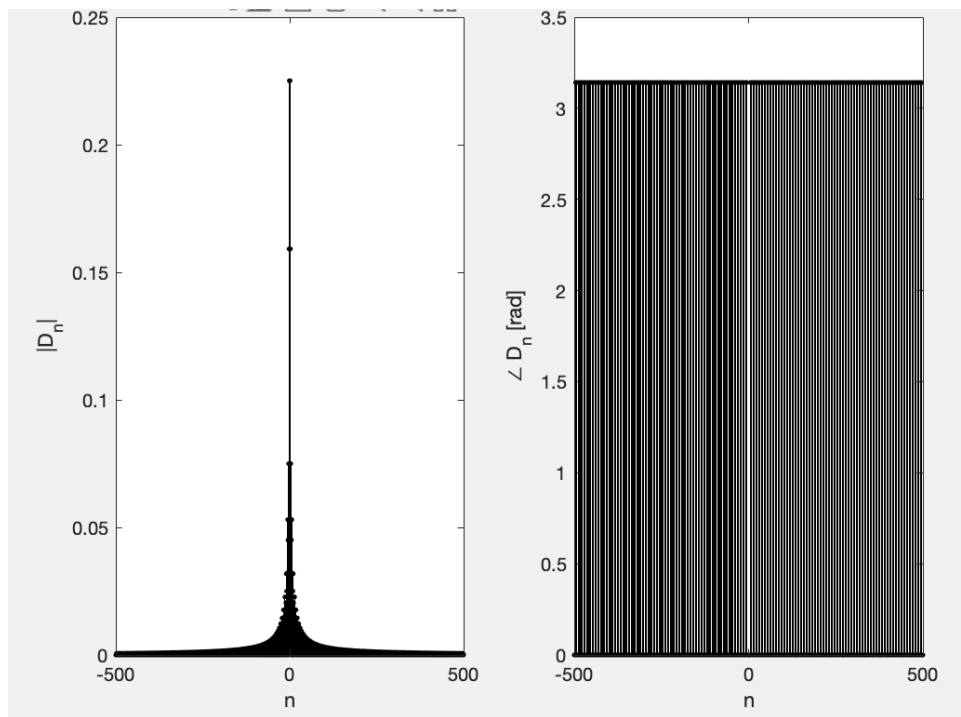


```
%x3(t)
clf;
n = (-500:500);

D_n = (1./(n.*pi)).*sin((n.*pi)./4));

subplot(1,2,1); stem(n,abs(D_n),'.k');
xlabel('n'); ylabel('|D_n|');
subplot(1,2,2); stem(n,angle(D_n),'.k');
xlabel('n'); ylabel("\angle D_n [rad]");
```

$x_3(t)$:



A.5:

$x_1(t)$

```
%A5 (x1):
function [D] = Lab3(Dn)
n=-500:500;
D=(1/2)*(abs(n)==3)+(1/4)*(abs(n)==1);
t=[-300:1:300];
w=pi*0.1;
x=zeros(size(t));
for i = 1:length(n)
    x=x+D(i)*exp(j*n(i)*w*t);
end

figure(5);
plot(t,x,'k')
xlabel('t(sec)');
ylabel('x(t)');
axis([-300 300 -1 2]);
title('Fourier Coefficients Reconstructed');
grid;
```

$x_2(t)$


```

%A5 (x2):
function [D] = lab3(Dn)
n=-500:500;
D=0.5*sinc(n/2);
t=[-300:1:300];
w=pi*0.1;
x=zeros(size(t));
for i = 1:length(n)
    x=x+D(i)*exp(j*n(i)*w*t);
    't'
end

figure(5);
plot(t,x,'k')
xlabel('t(sec)');
ylabel('x(t)');
axis([-300 300 -1 2]);
title('Fourier Coefficients Reconstructed');
grid;

```

x3(t)

```

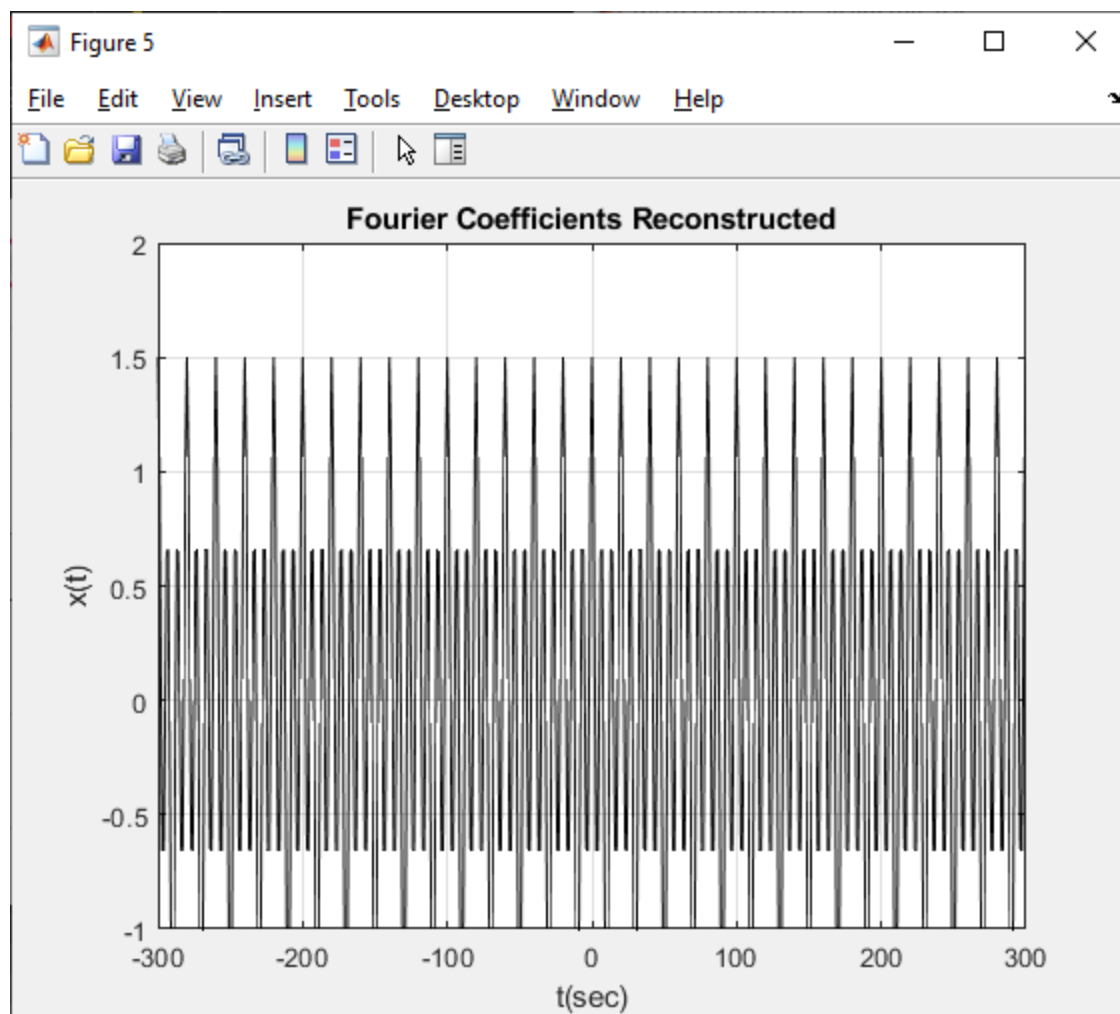
%A5 (x3):
function [D] = Lab3(Dn)
n=-500:500;
D=0.25.*(sinc(n/4));
t=[-300:1:300];
w=pi*0.1;
x=zeros(size(t));
for i = 1:length(n)
    x=x+D(i)*exp(j*n(i)*w*t);
    't'
end

figure(5);
plot(t,x,'k')
xlabel('t(sec)');
ylabel('x(t)');
axis([-300 300 -1 2]);
title('Fourier Coefficients Reconstructed');
grid;

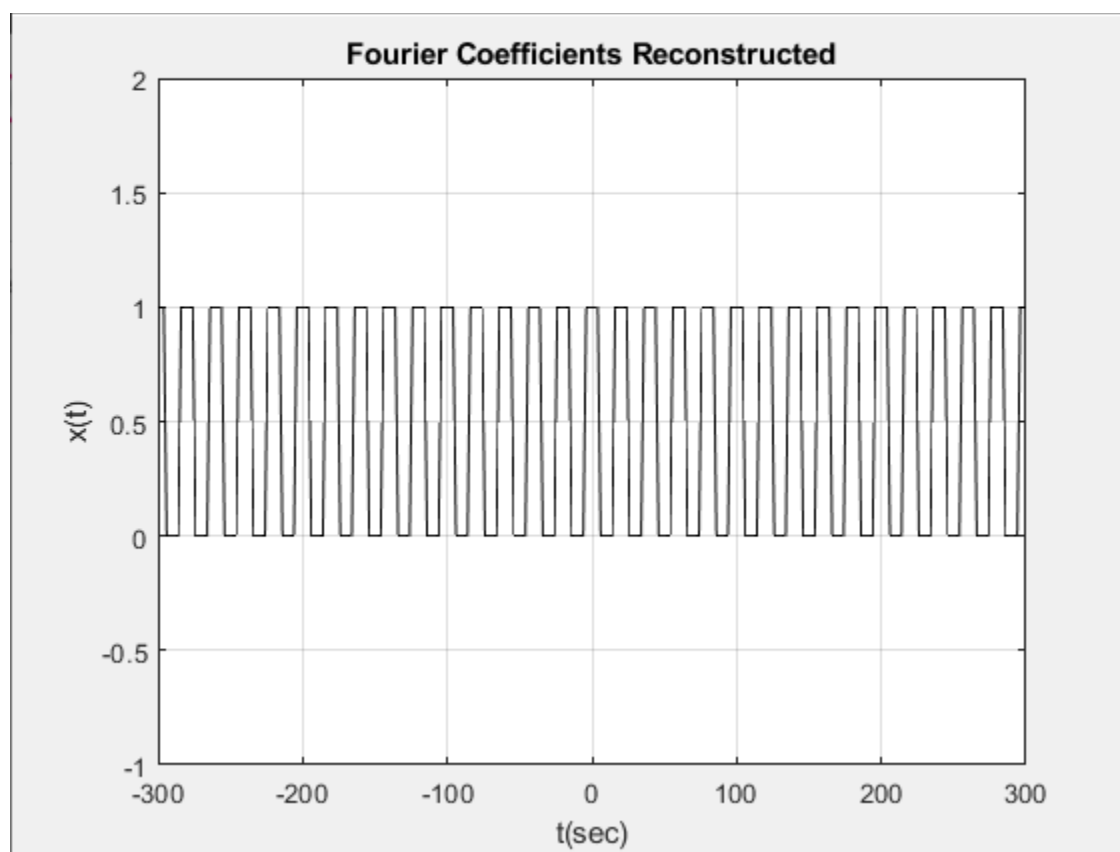
```

A.6:

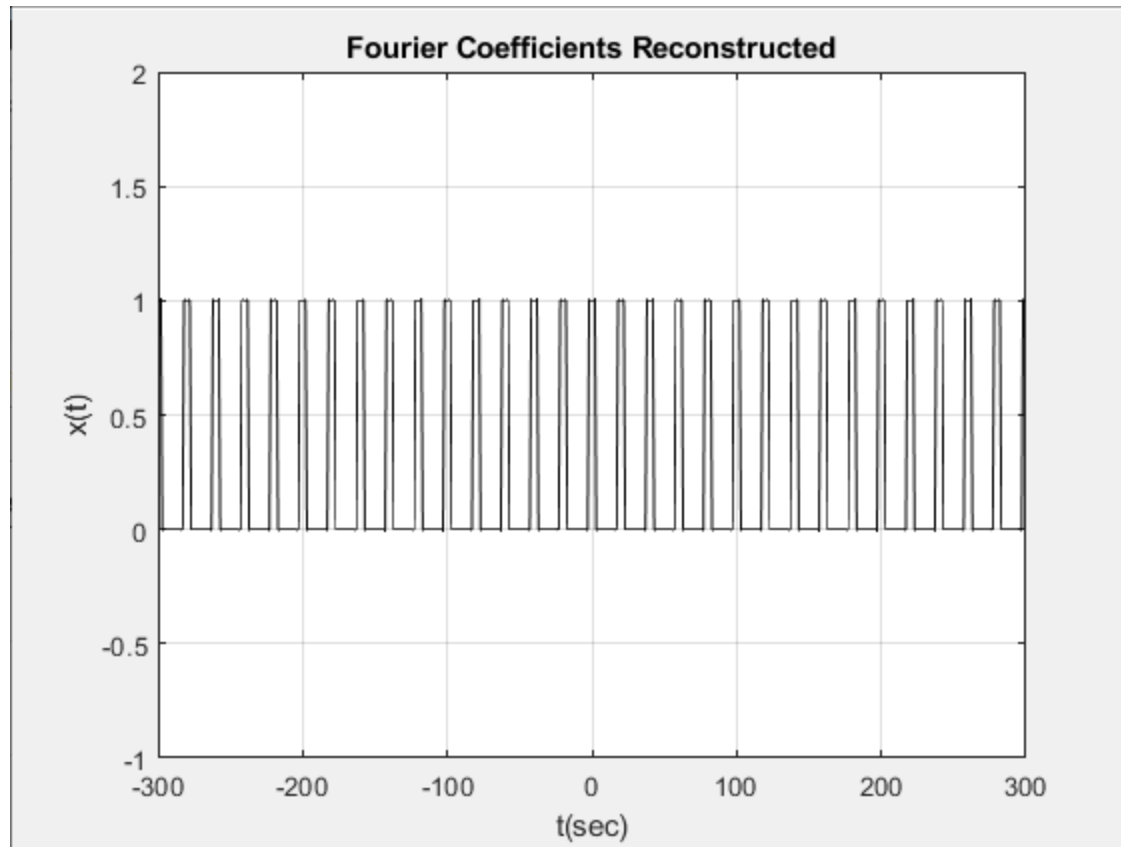
x1(t):



$x_2(t)$:



$x_3(t)$:



B.1:

$$x_1(t) = \cos(3\pi/10)t + \frac{1}{2} \cos(\pi/10)t,$$

$$w_{01} = 3\pi/10$$

$$w_{02} = \pi/10$$

$$\text{GCF/LCM: } w_0 = \pi/10 = 0.314 \text{ rad/s}$$

For $x_2(t)$

$$T_0 = 20 \text{ s}$$

$$T_0 = 2\pi/w_0$$

$$\omega_0 = \pi/10 = 0.314 \text{ rad/s}$$

For $x_3(t)$

$$T_0 = 40 \text{ s}$$

$$T_0 = 2\pi/\omega_0$$

$$\omega_0 = \pi/20 = 0.157 \text{ rad/s}$$

B.2:

The main difference between the fourier coefficients of $x_1(t)$ and $x_2(t)$ is that $x_1(t)$ has four distinct fourier series coefficients, while $x_2(t)$ has infinite fourier series coefficients for D_n . Additionally, one of them consists of $\sin(x_2(t))$ function while the other consists of $\text{sinc}(x_1(t))$.

B.3:

The characteristics of the signals $x_2(t)$ and $x_3(t)$ having the same rectangular pulse shape, but different periods is reflected in their respective Fourier coefficients through the signal $x_3(t)$ having a smaller fundamental frequency value when compared to $x_2(t)$ for its Fourier coefficients.

B.4:

To derive D_0 of $x_4(t)$ from D_0 of $x_2(t)$ by letting $D_0 = 0.5$ for signal $x_4(t)$ derived from $x_2(t)$.

B.5:

The reconstructed signals for $x_1(t)$ and $x_2(t)$ change as we increase the number of fourier coefficients, because $x_1(t)$ has a finite number of D_n values, nothing will change if the fourier coefficients are increased. Contrastingly, for $x_2(t)$ and $x_3(t)$, increasing values of D_n results in a higher accuracy.

B.6:

4 fourier coefficients are needed to perfectly reconstruct the periodic waveforms due to $x_1(t)$ having a finite range of D_n values. For $x_2(t)$ & $x_3(t)$, an infinite number of D_n would be required for perfect reconstruction.

B.7:

We know that a periodic signal has an infinite amount of D_n values so this is not viable. But, if it is finite such as $x_1(t)$, then the values of D_n can be stored. Although this also would not be efficient as you would end up wasting space for signals which have large amounts of finite D_n values.