

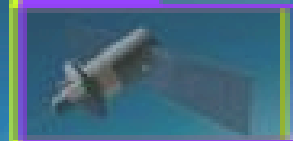
The YOLO WorkShop **Space Theme**

an introduction to Ultralytics and the YOLO models
Hamze Housam

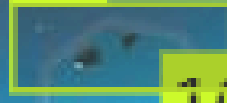
39%



12%



6%



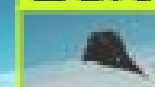
10%



19%



18%



8%



21%



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30%



19%



17%



10%



6%



13%



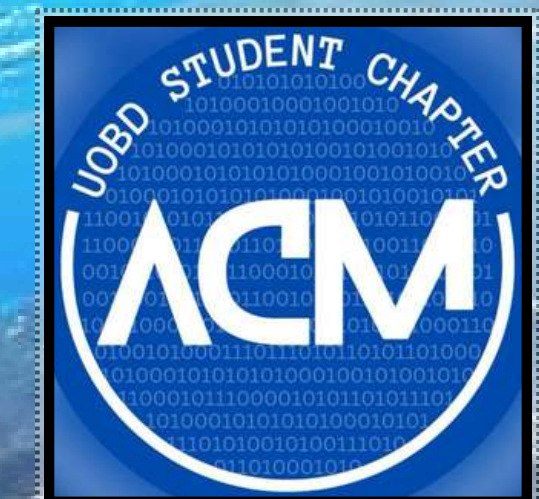
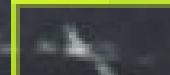
30%



23%



8%



About Me

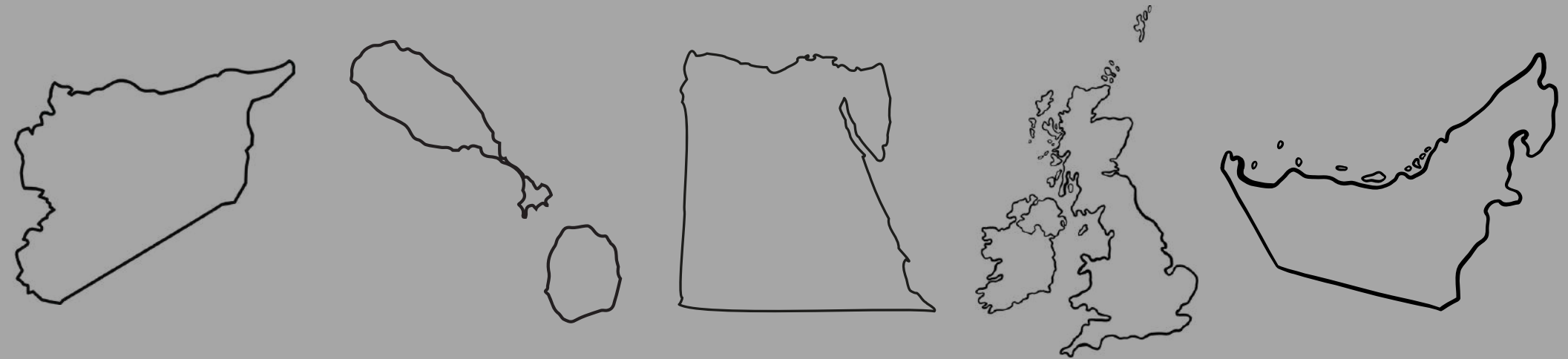
originally: from Syria

second nationality: Saint Kitts and Nevis

Lived in:

Syria (11 years), Egypt (9 years)

UK (4 years), UAE (1 year - present)



Work experience:

Embedded system and Machine learning engineer

Vee tech, Egypt, (9 month)

Teaching Assistant

Heriot-Watt University, UAE, (Present)



OUR CLIENTS

EMAAR



Education:

BEng Computer Systems Engineering (Hons), UOE, UK

MSc Robotics, HWU, UAE



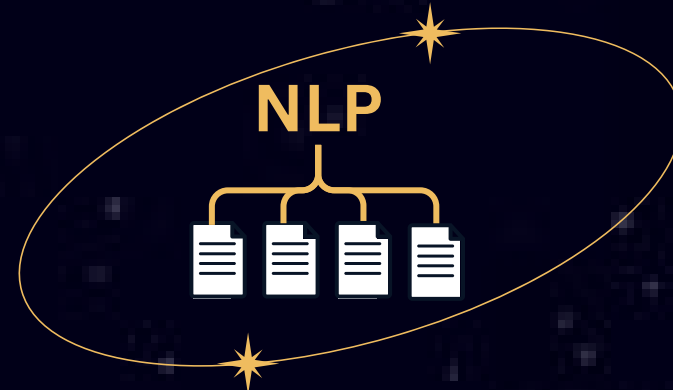
Galaxies 🌌

COMPUTER VISION (CV)



ANALYZING IMAGES AND
VIDEOS

NATURAL LANGUAGE PROCESSING (NLP)



PROCESS LANGUAGE

MACHINE LEARNING (ML)



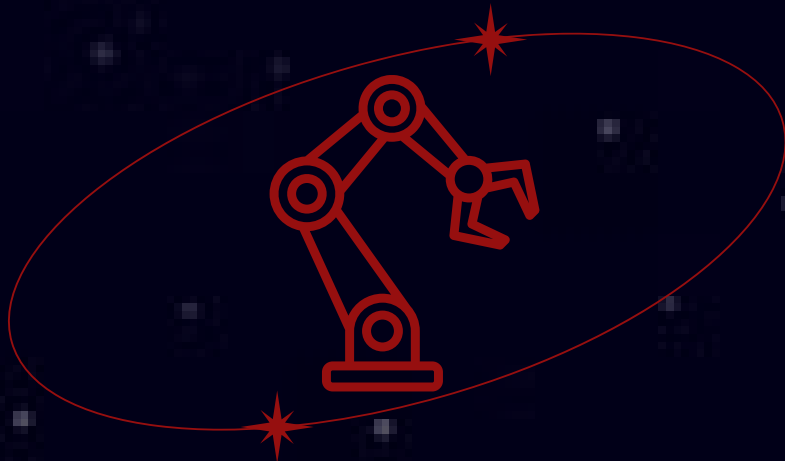
TEACH COMPUTERS TO LEARN

DEEP LEARNING



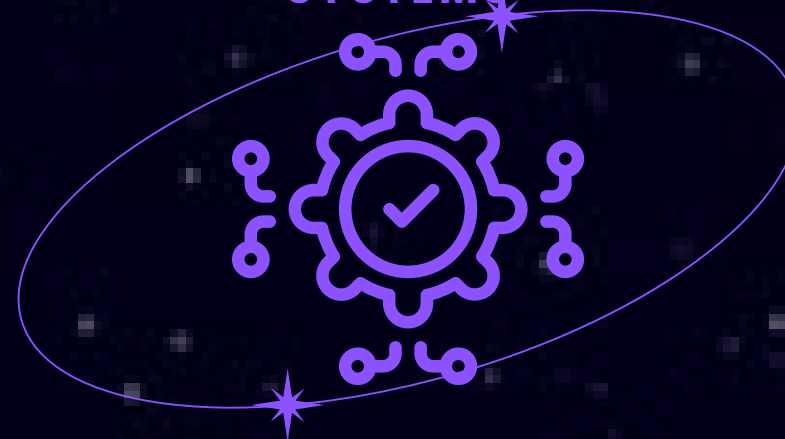
ANALYZES DATA WITH LAYERED
NETWORKS

ROBOTICS



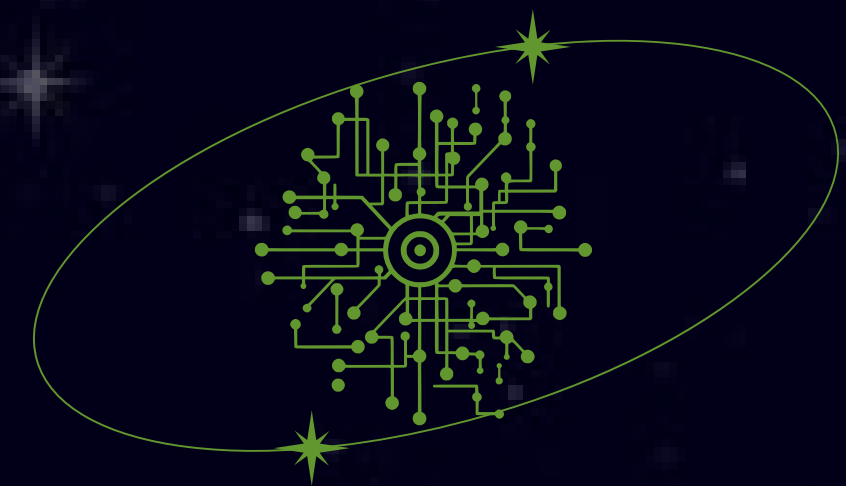
ROBOTS TO PERFORM PHYSICAL
ACTIONS

EXPERT SYSTEMS



SPECIALIZED KNOWLEDGE FOR
DECISIONS

FUZZY LOGIC



MANAGES UNCERTAINTY IN DECISION-
MAKING

SUNS☀️& STARS★

**GENRATIVE
AI**

**AUDIO
PROCESSING**

**REINFORCEMENT
LEARNING**

**AGENTIC
ML**



LARGE LANGUAGE
MODELS (LLMS)



VOICE SYNTHESIS

AUTONOMOUS VEHICLE
NAVIGATION



LLM AGENTS



GENERATIVE
ADVERSARIAL
NETWORKS (GANS)



AUDIO
CLASSIFICATION



CREATING GAME AGENTS



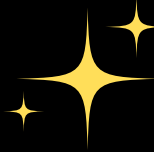
NETWORK SECURITY
AGENTS

VISUAL LANGUAGE
MODELS (VLMS)

AUTOMATIC SPEECH
RECOGNITION

SIM-TO-REAL ROBOTIC
TRANSFER LEARNING

MULTI-AGENT
SYSTEMS



NEBULA

XENOLINGUISTICS ??

ARTIFICIAL LIFE ??

SUPER INTELLIGENCE ??

GENERAL INTELLIGENCE ??

TOPOLOGICAL ??

QUANTUM INTELLIGENCE ??

EVOLUTIONARY ??

COGNITIVE ???

ORGANOID INTELLIGENCE ??

BIOACOUSTICS ??

Hands on activity

Start Training Object Detection model in 10 minutes:

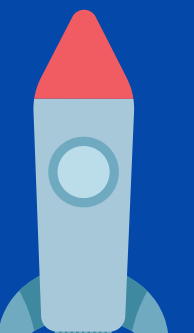
Use Roboflow Universe to Search for Dataset



Work on Google Colab to deploy the model
and retrieve data without downloading.



Ultralytics on colab and train with YOLOV8



Hands on activity

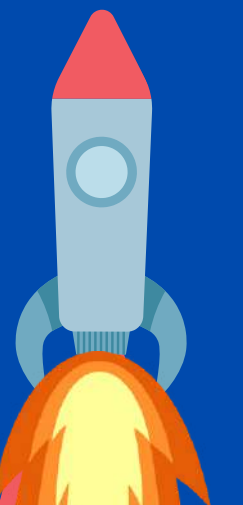
Task1 find the dataset:

- option 1 Use the same dataset
 - option 2 (recommended) Browse a desired dataset for your own unique detection model
- Creating a roboflow is required for this option

Task2 colab script:

use the command to load the dataset and start training the model per steps shown previously

Stand by, we are preparing for launch!



Hands on activity

Training Demo:

I will show the required steps to retrieve dataset and start training on collab.

Please follow along first and later will help anyone who needs support.

We've got lift-off!.....

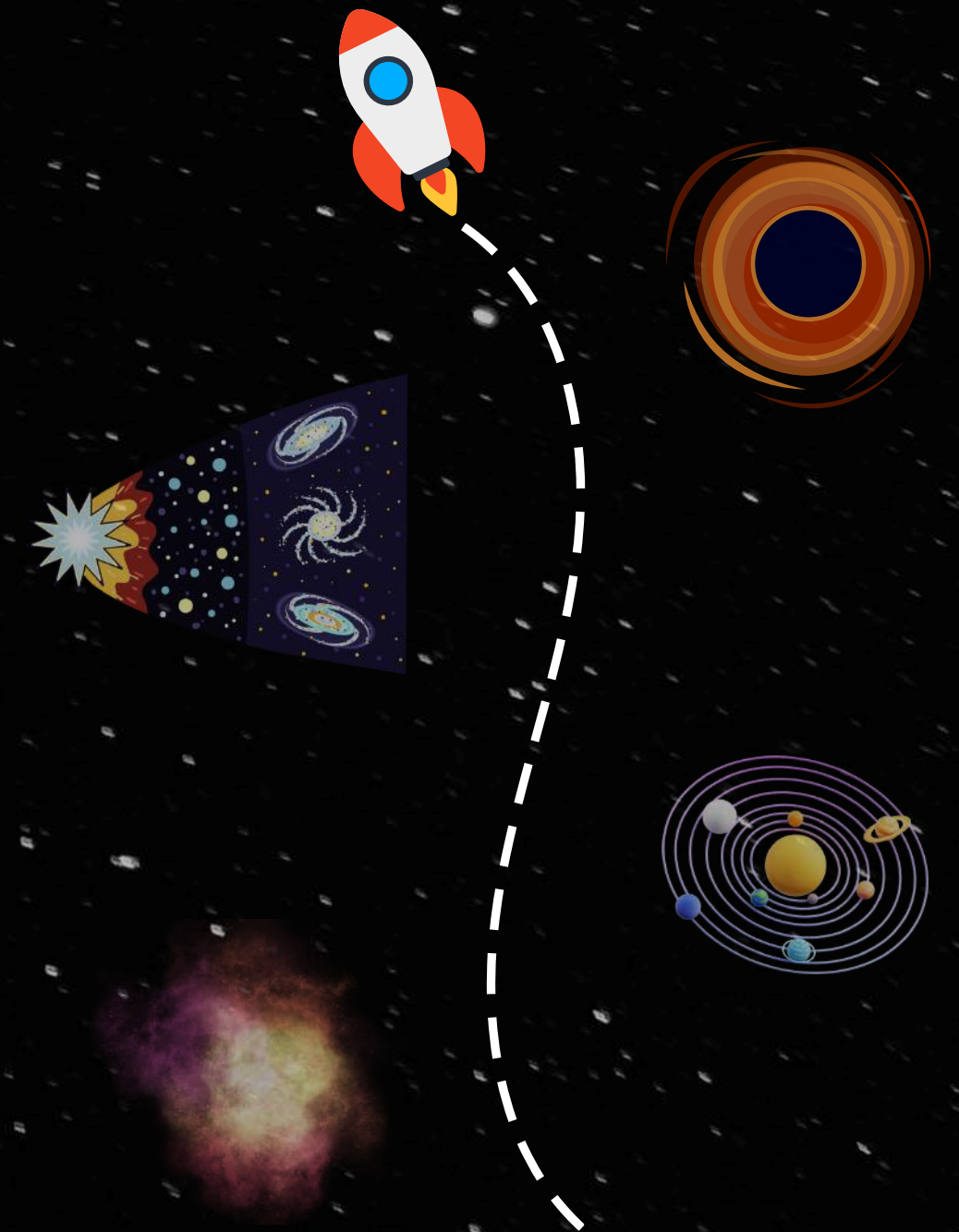


while we wait for touchdown, let's uncover the wonders of space

Bonus: **Space** Inspires 💡

In this bonus section, we will visualize four different optimization algorithms on four benchmark functions. This part of the field is known as Physics-Inspired Computation; however, we are focused on a space-themed.

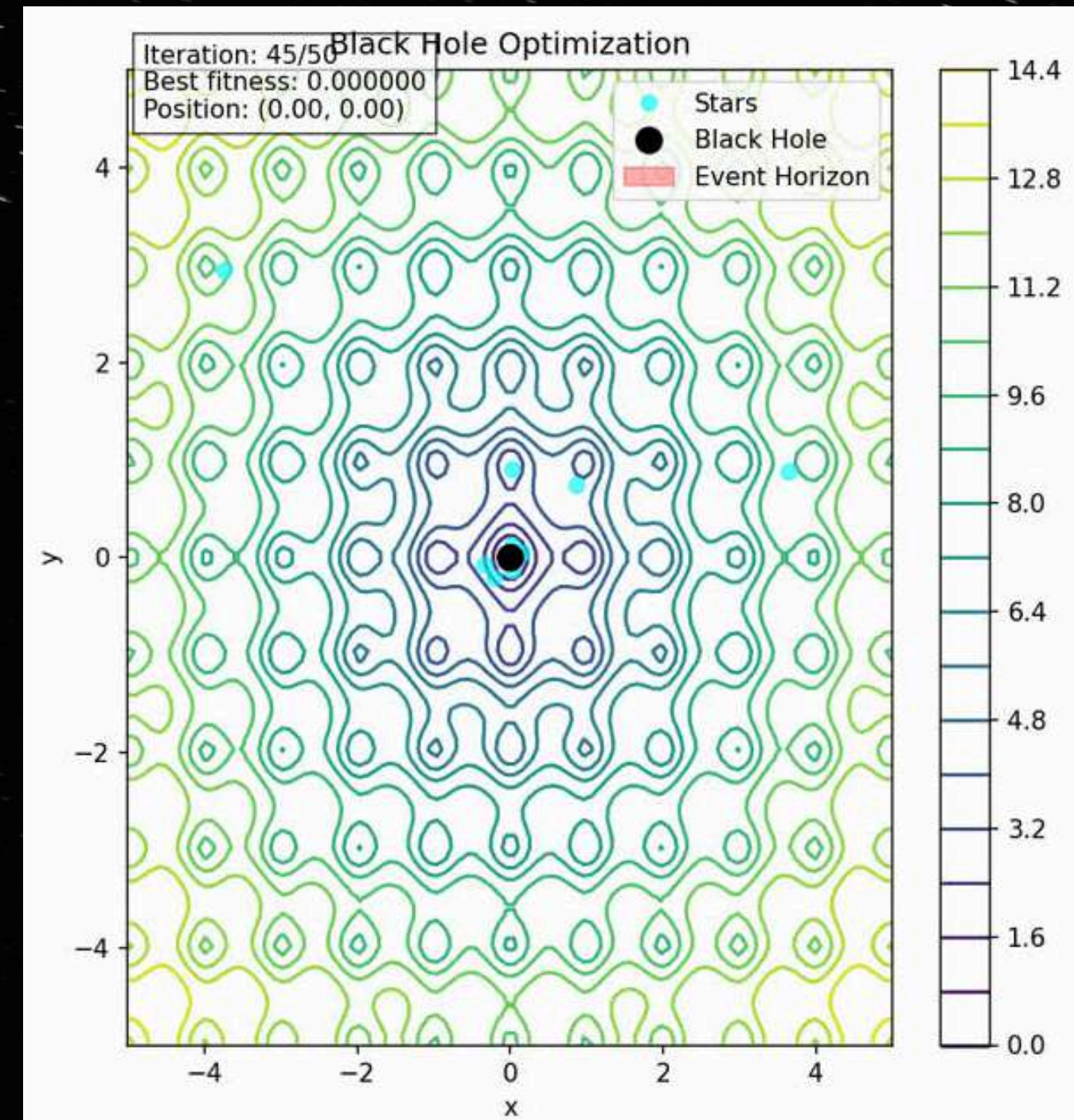
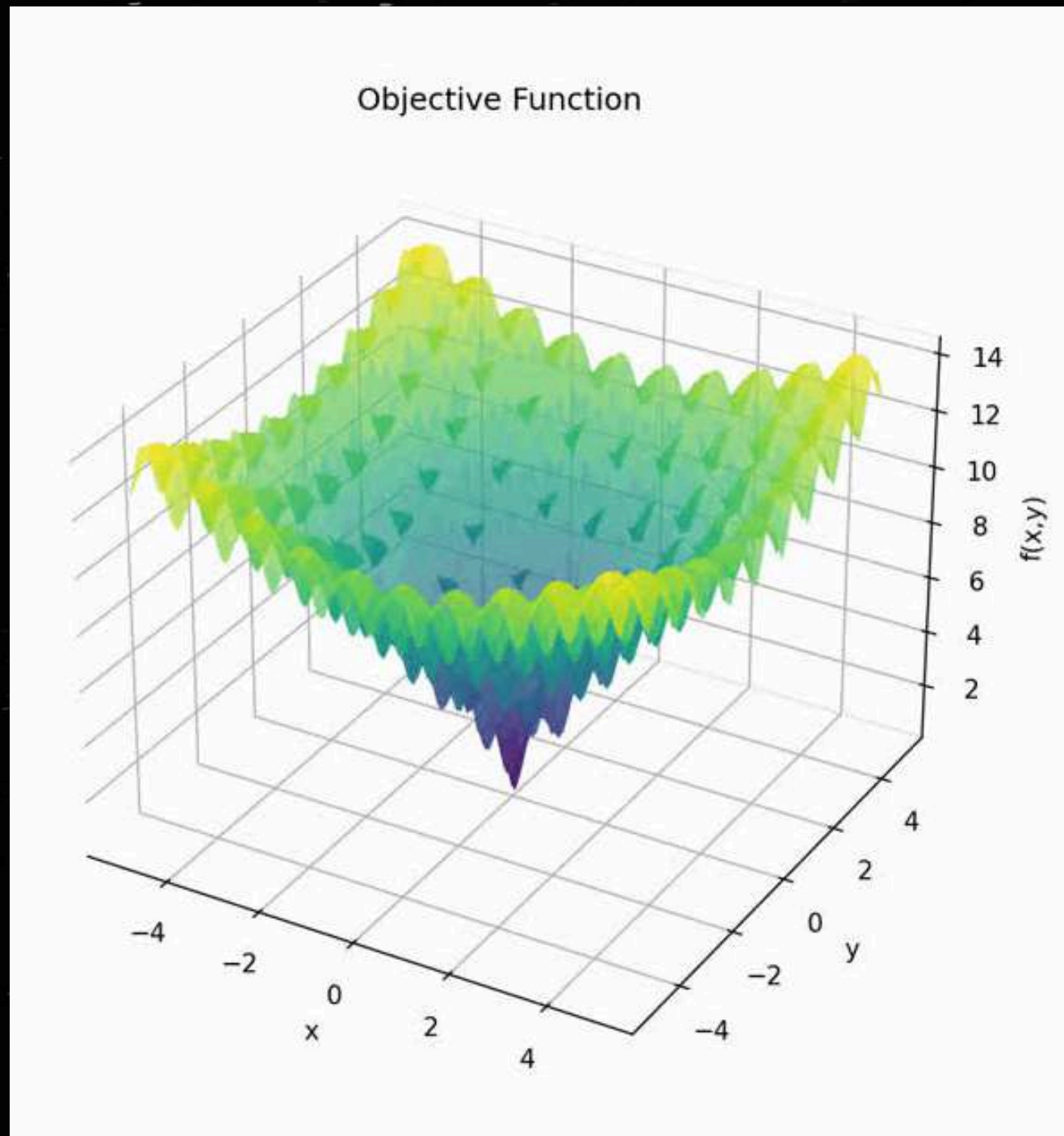
- 1:** ALGORITHM: [BLACK HOLE OPTIMIZATION]
FUNCTION: [ACKLEY FUNCTION]
- 2:** ALGORITHM : [BIG BANG CRUNSH OPTMIZATION]
FUNCTION: [RASTRIGIN FUNCTION]
- 3:** ALGORITHM: [SOLAR SYSTEM-BASED OPTIMIZATION]
FUNCTION: [ROSENBROCK FUNCTION]
- 4:** ALGORITHM: [SUPERNOVA OPTIMIZATION]
FUNCTION: [HIMMELBLAU FUNCTION]



there is more, but for this workshop will be briefly talking about these 4.

Bonus: **Space** Inspires

Black Hole Search Algorithm Benchmarked on the Ackley Function



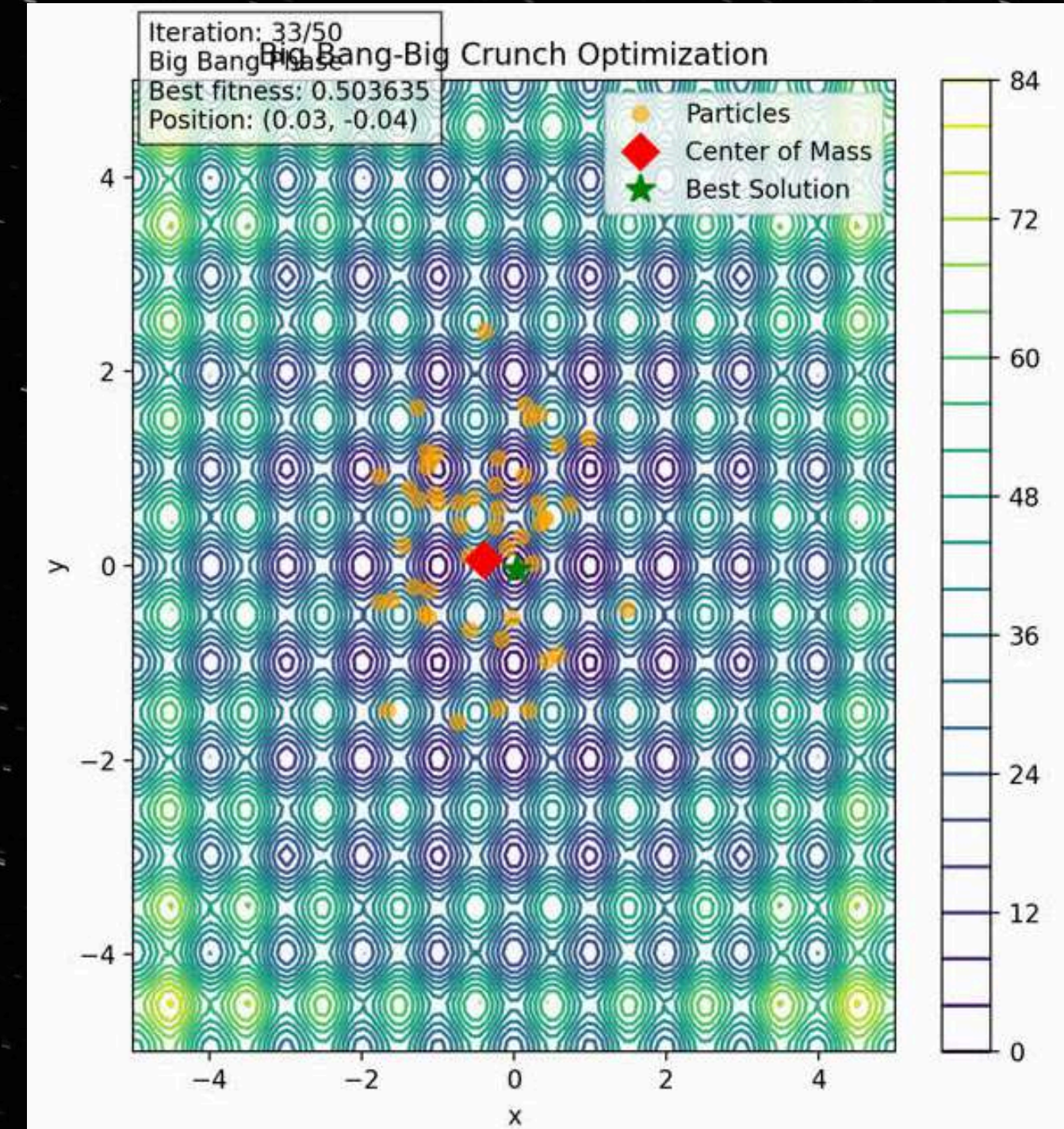
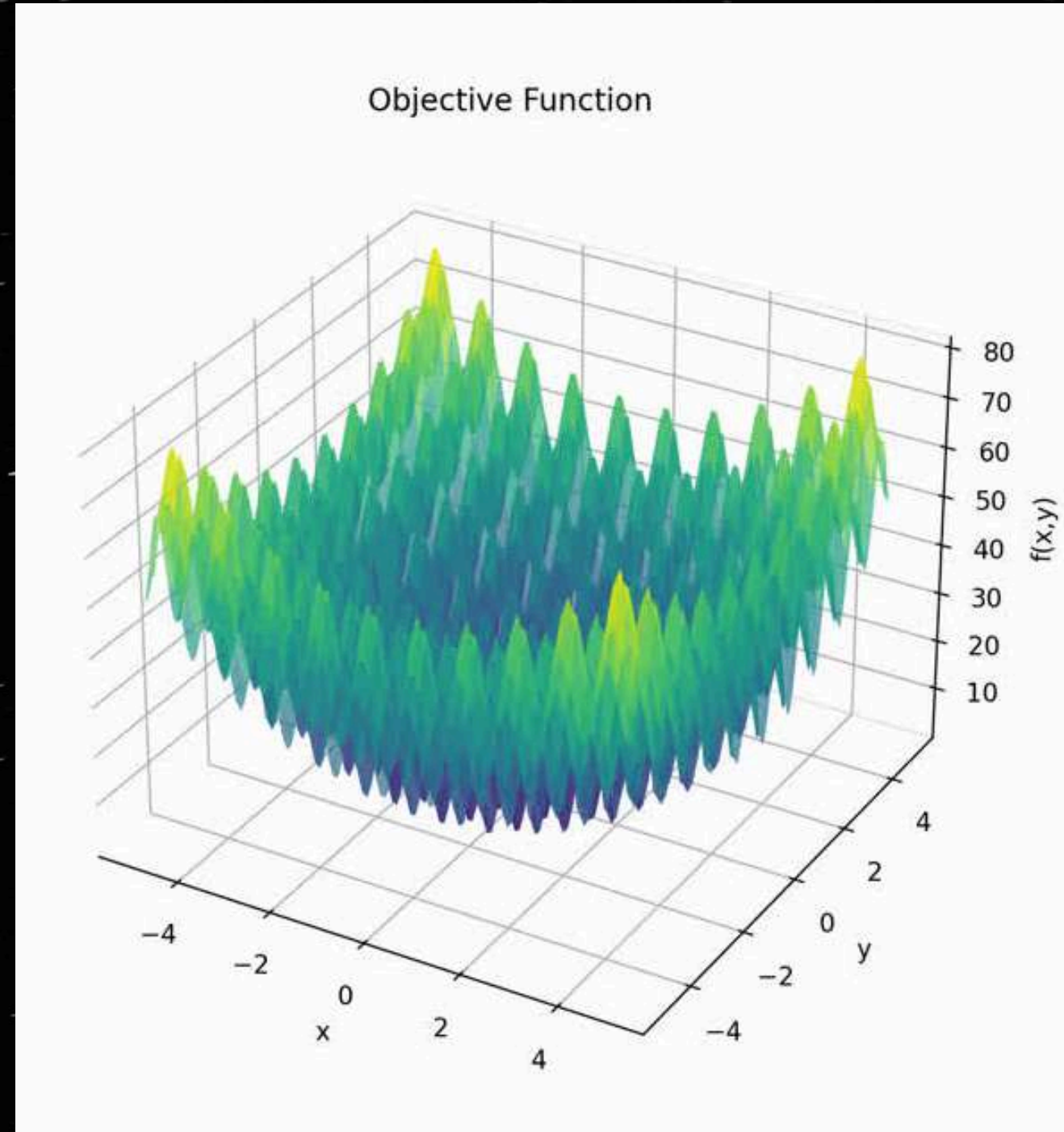
Bonus: Space Inspires



Big Bang Crunch Algorithm Benchmarked on the Rastrigin Function

Function

iterations

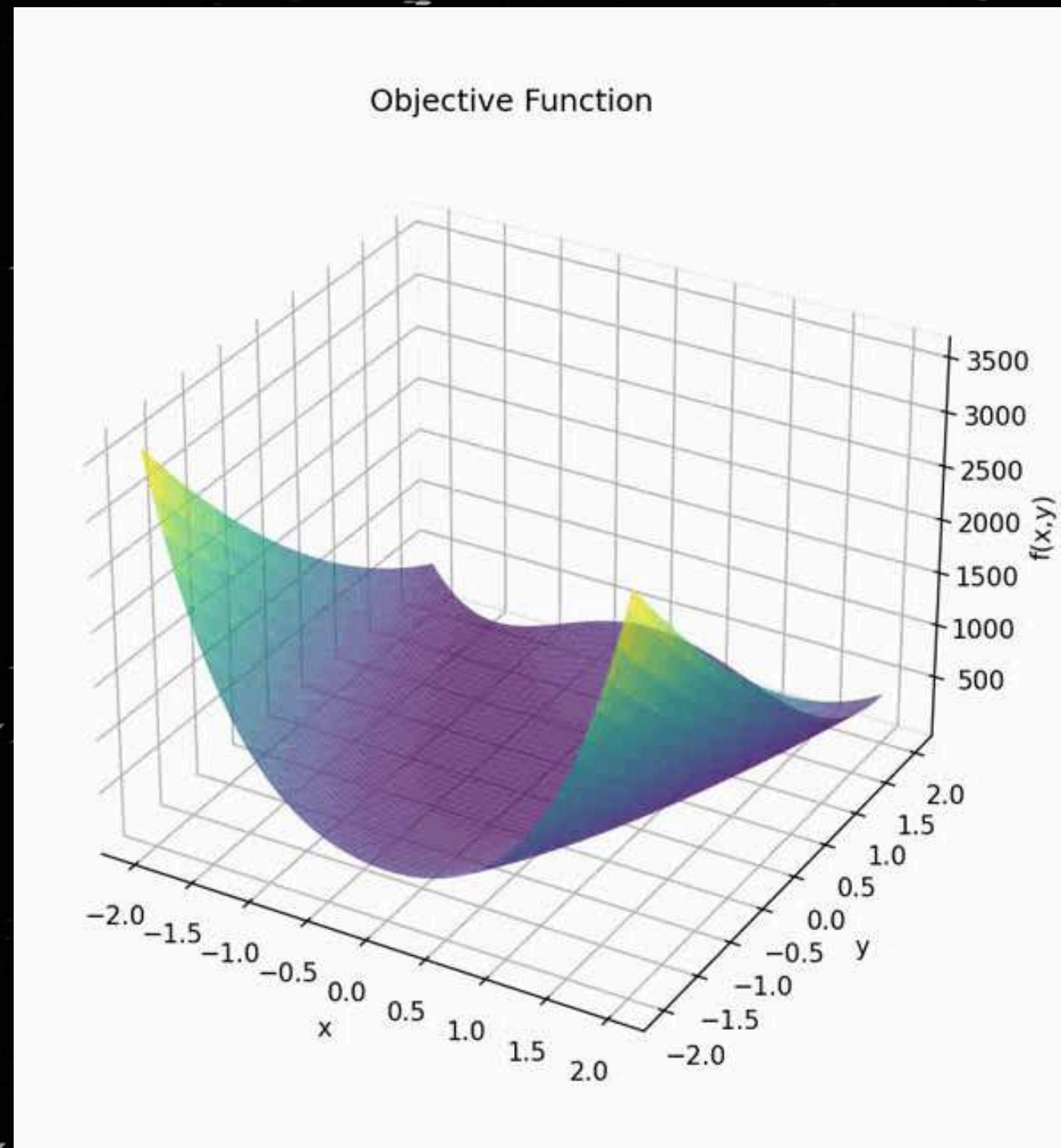


Bonus: **Space** Inspires

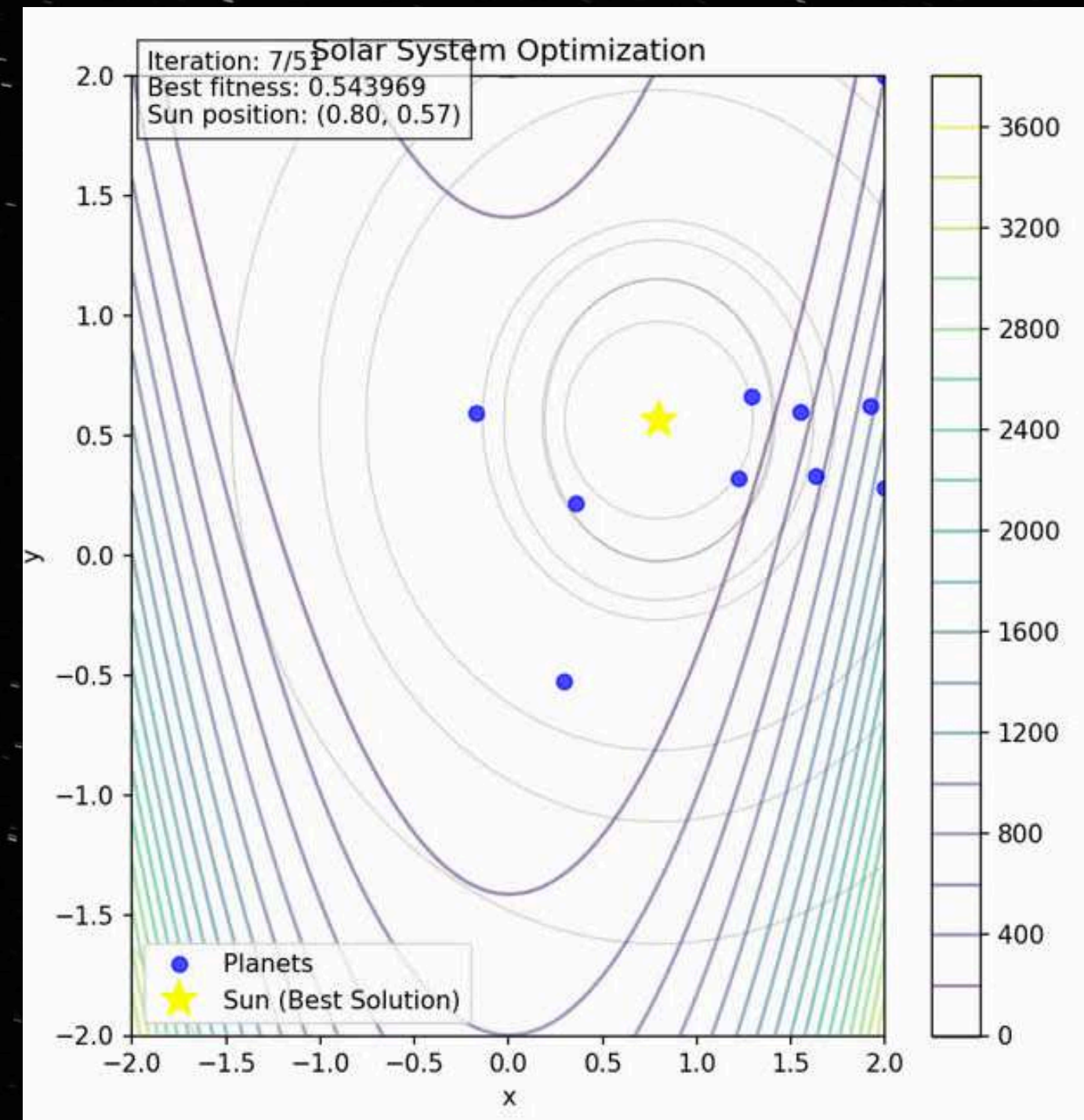


Solar System-Based Optimization Benchmarked on the Rosenbrock Function

Function



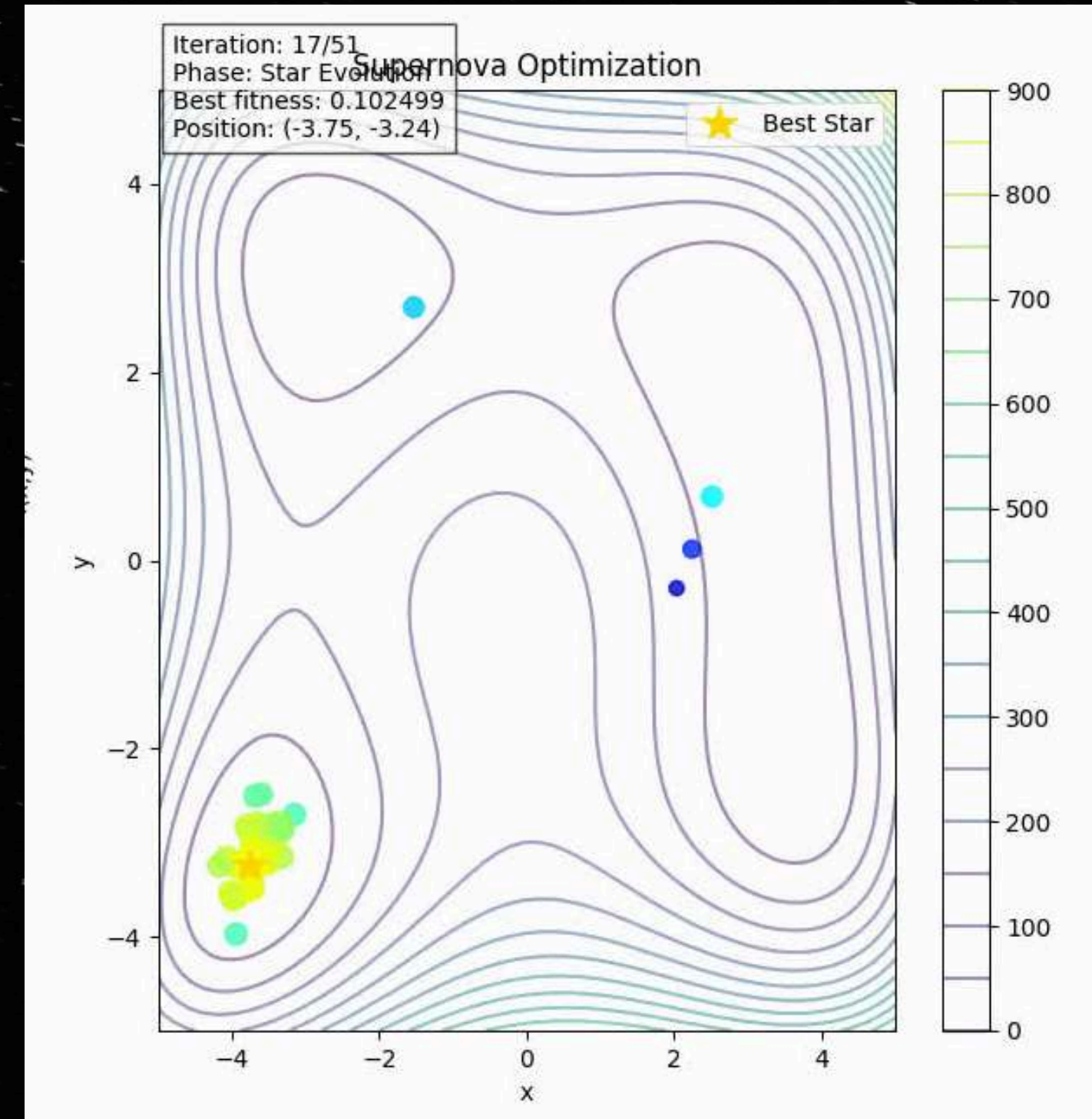
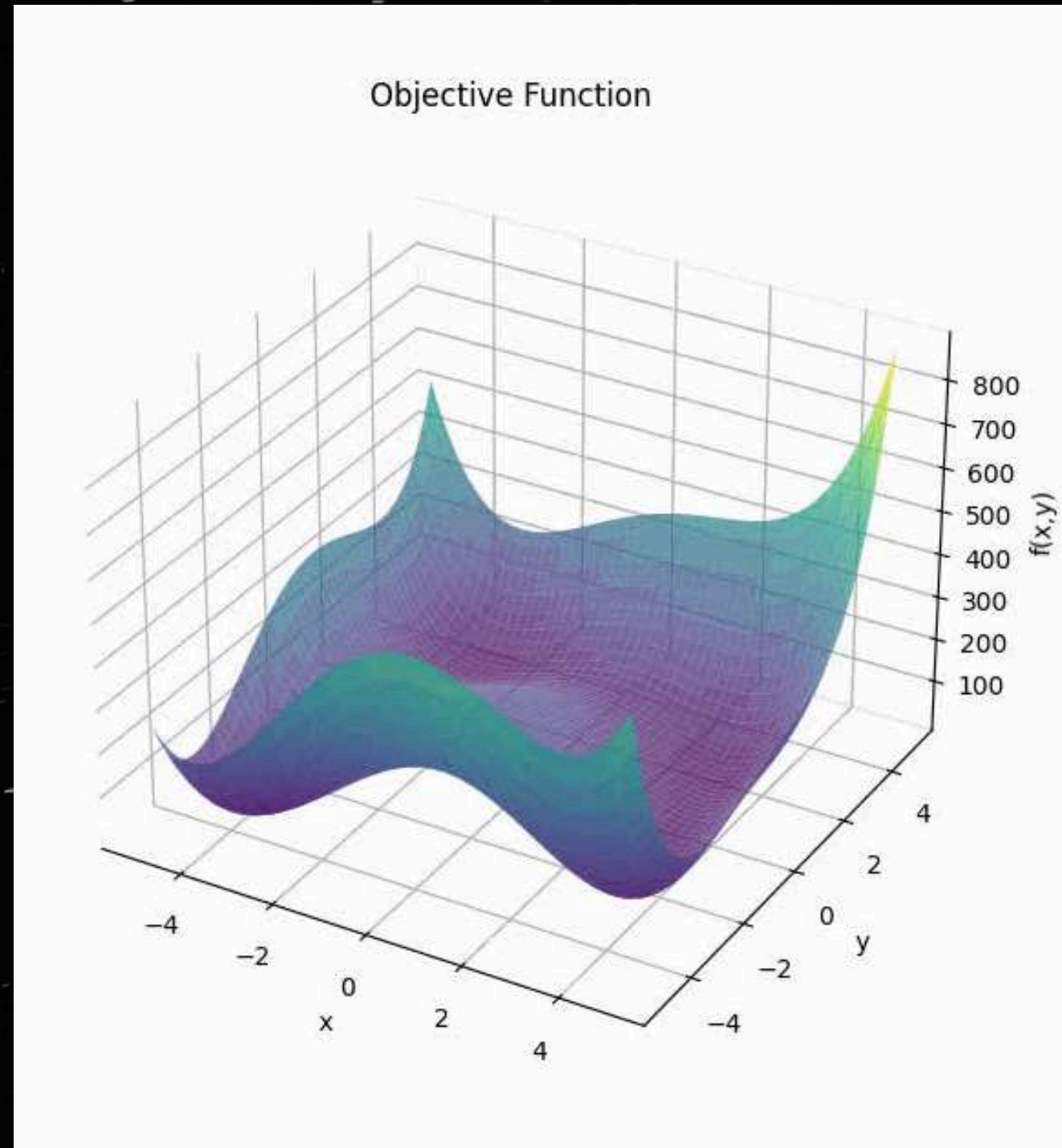
iterations



Bonus: **Space** Inspires

Supernova Optimization Benchmarked on the Himmelblau Function

iterations



<https://ccsenet.org/journal/index.php/mas/article/view/72215>

Hands on activity continued

We have Landed....

task 2.1

use test data to test your model and see how well it
performed, sometimes it is provided if not find some images

NOTE: DO NOT USE THE TRAINING IMAGES TO TEST HOW WELL YOUR MODEL IS

Task 3 Detect: now that your model is done training,
use provided script to test it

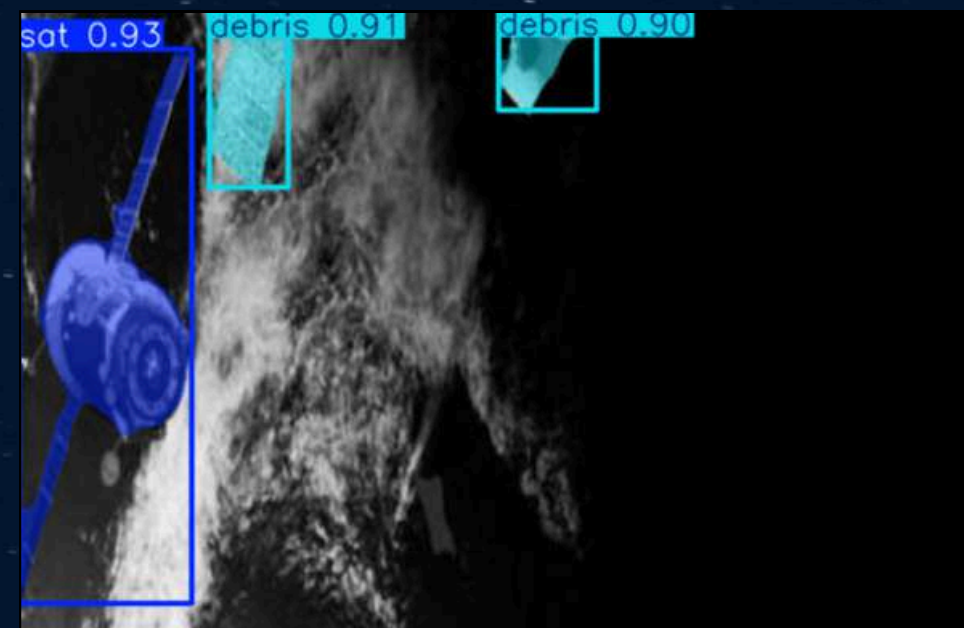
Output: get a similar if not identical results to images below



Debris (yolov8)



Debris and Sat(yolov8-seg)



sat images (yolov8-obb)



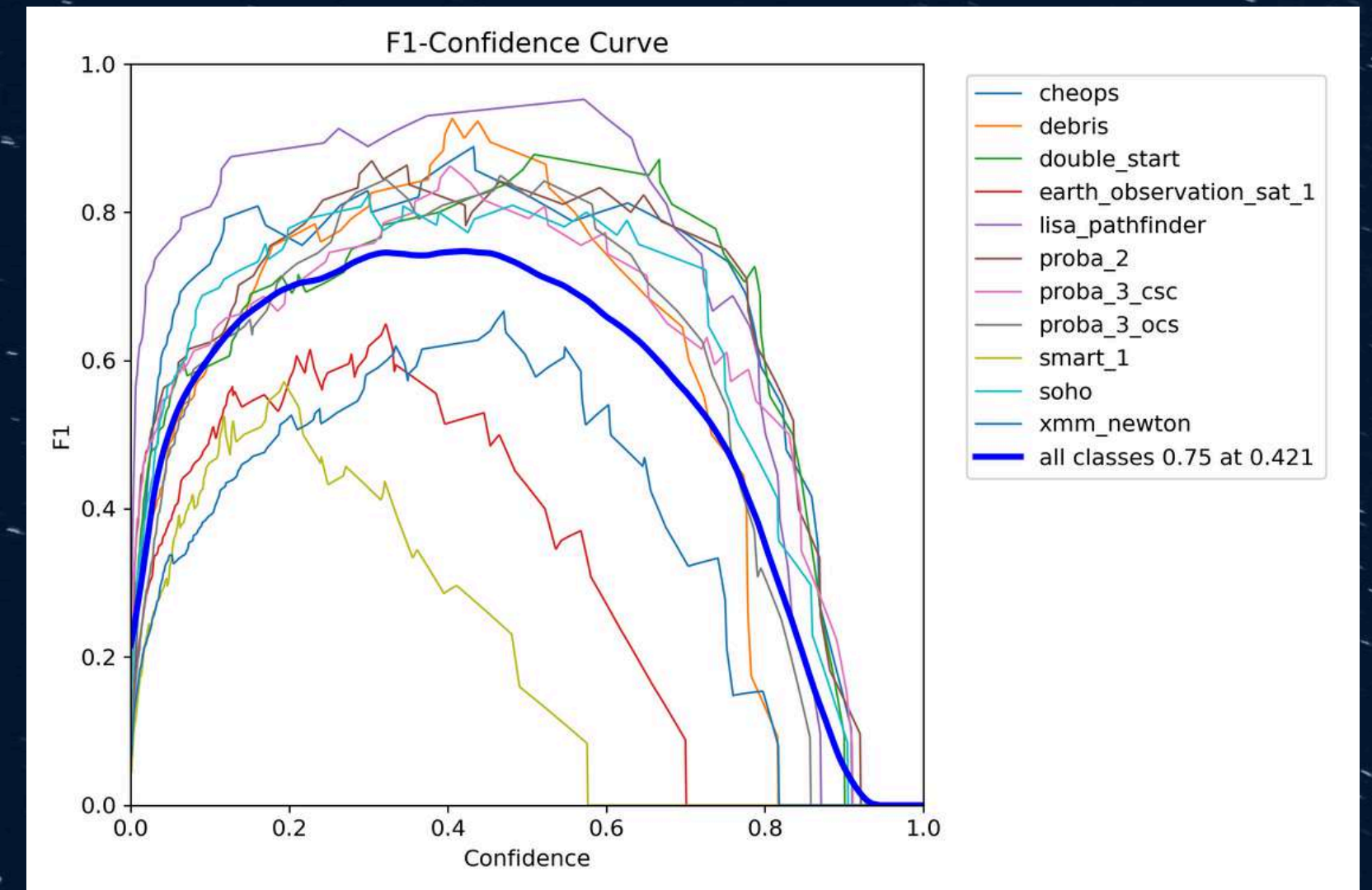
Hands on activity

Task 4 Evaluate model:

use the tables generated from framework to evaluate how well your model is

Test Models

Live Demo Testing on the YOLO and YOLO-seg pre-trained Models, on webcams.

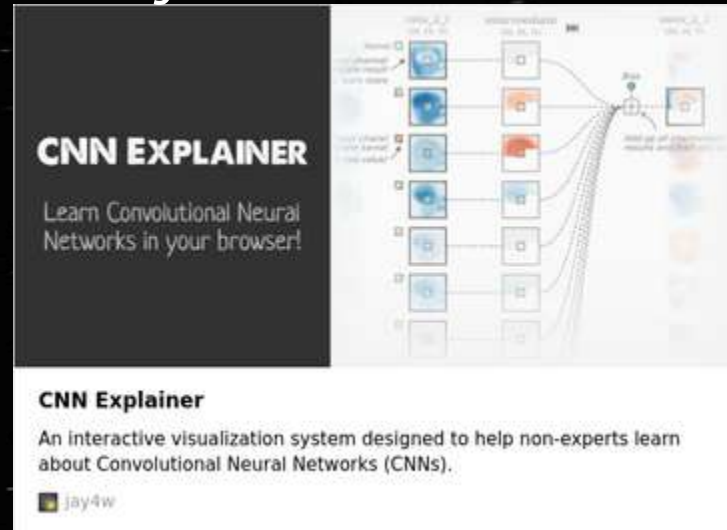


Landing Complete. Let's Explore!

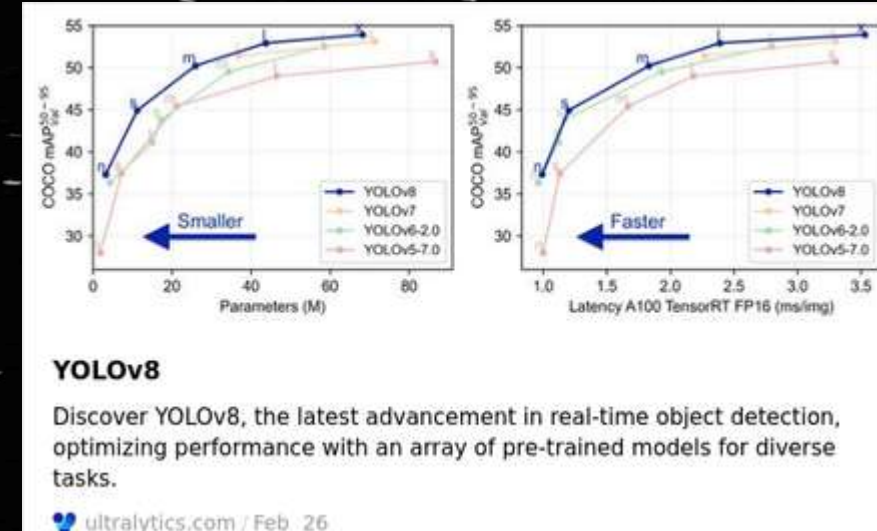


Bonus: Self Read Satalite stations

Study and visualise CNN



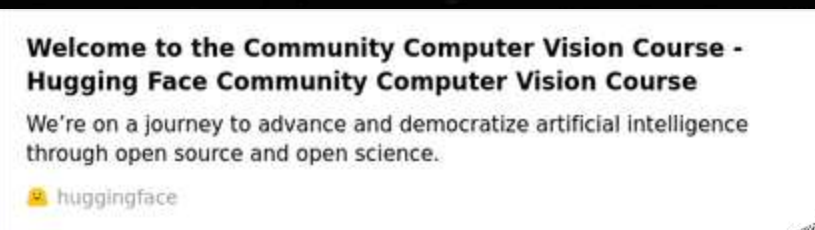
Yolov8 Docs



import Data roboflow universe



Hugging Face Computer Vision Course



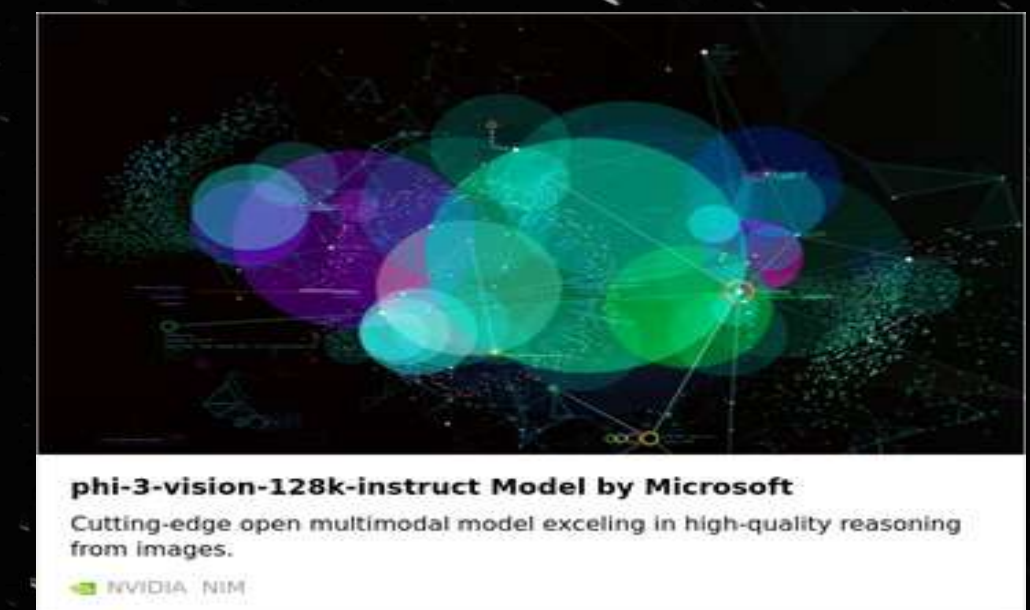
ML for robots course (paid)



meta's SAM Model tutorial



Try this Cool Model like phi-3 VLM on Nvidia NIM



Thank you for listening

happy Learning

any Further Qustions ?

