



# Butterfly: Environment-Independent Physical-Layer Authentication for Passive RFID

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▶ Tag Seal



▶ Entrance check



▶ Logistic and warehousing

**RFID Authentication is a crucial task for many applications!**

## Prior authentication methods



Tag counterfeiting?

✗ E1G2 Protocol

✓ Cryptology method

✓ Physical-layer

✓ Butterfly

Don't need Modification?

✓ E1G2 Protocol

✗ Cryptology method

✓ Physical-layer

✓ Butterfly

Tag mobility?

✓ E1G2 Protocol

✓ Cryptology method

✗ Physical-layer

✓ Butterfly

# Outline

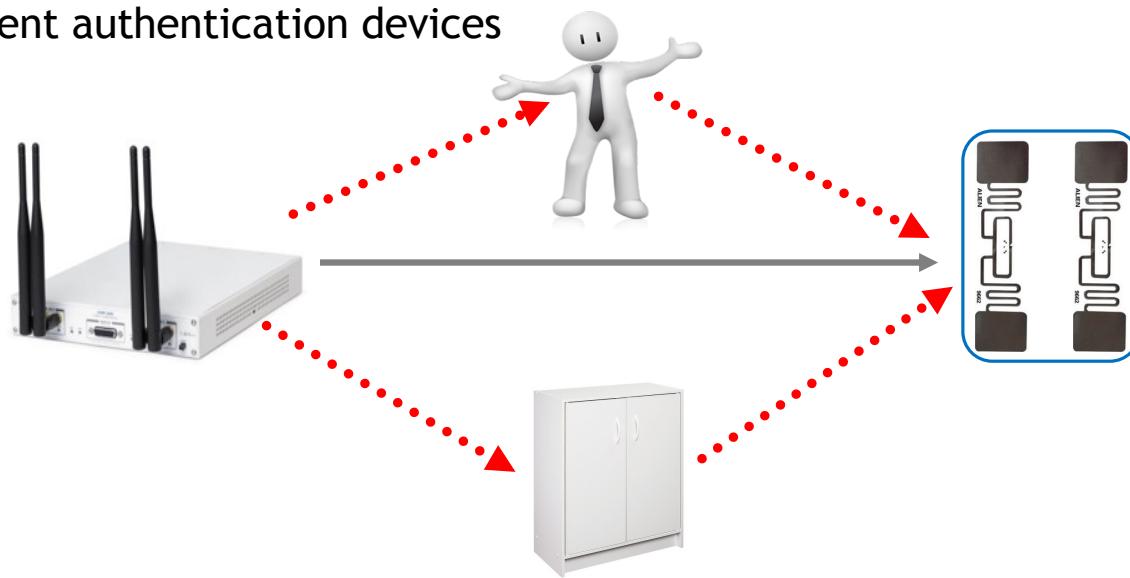
- ▶ Basic Idea
- ▶ System Design
- ▶ Experiments and Evaluation
- ▶ Conclusion



## Problem Statement

Some practical factors introduce unpredictable errors in physical-layer signals:

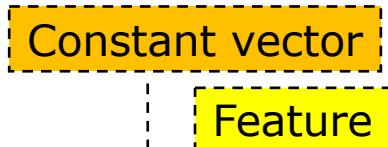
- Position of the tag
- Surrounding environments
- Different authentication devices



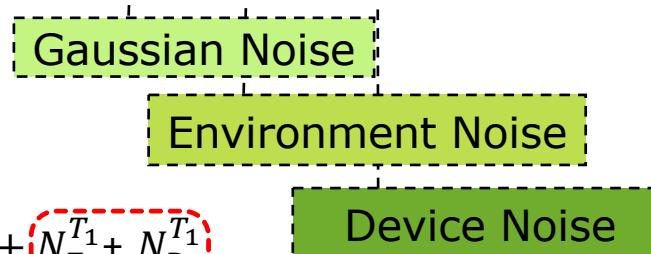


## Basic Idea

Our solution: employ two adjacent tags as an unit.



$$\text{Received signal: } P = C^T + F^T + N_G + N_E + N_D$$



Tag 1

$$P^{T_1} = C^{T_1} + F^{T_1} + N_G^{T_1} + N_E^{T_1} + N_D^{T_1}$$

Tag 2

$$P^{T_2} = C^{T_2} + F^{T_2} + N_G^{T_2} + N_E^{T_2} + N_D^{T_2}$$

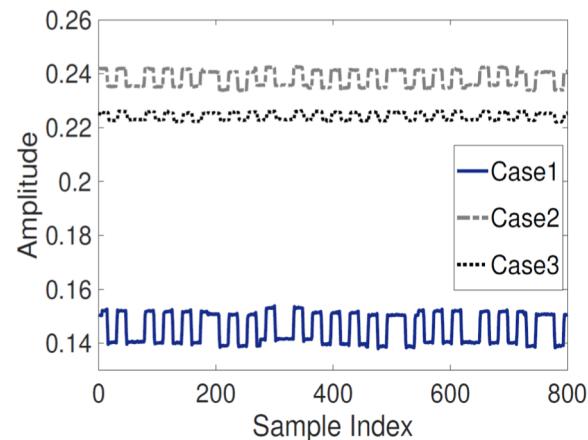
$$P^{T_1} - P^{T_2} \approx (C^{T_1} - C^{T_2}) + (F^{T_1} - F^{T_2})$$



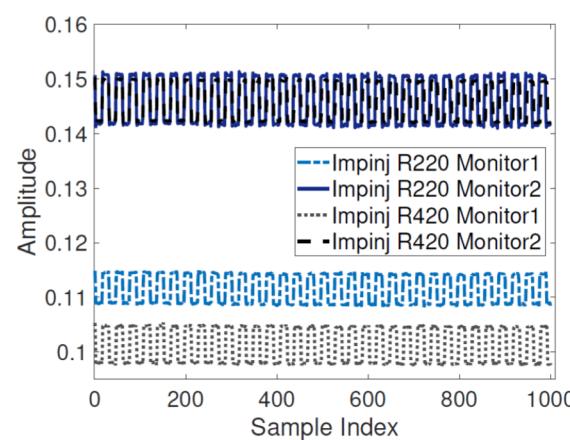
## Basic Idea

### Performance of noise elimination:

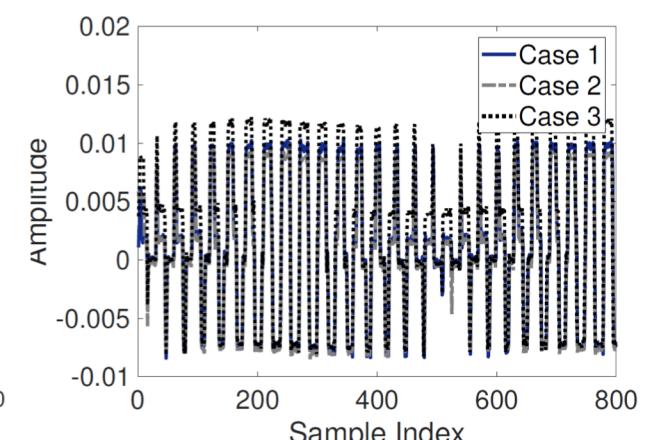
- Our method can effectively eliminate the environment and device noises!



► Signals in different environments



► Signals of different devices



► Signals after elimination

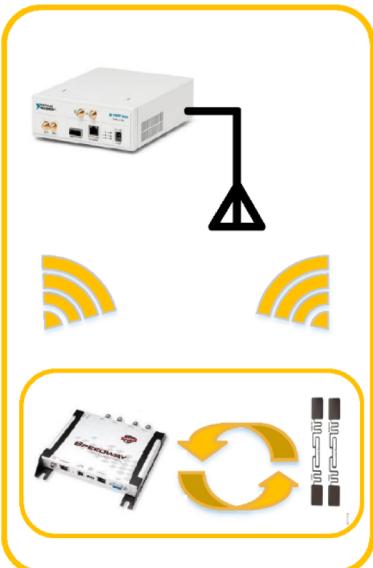
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# System Design

## Signal Collection



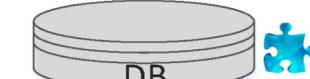
## Signal Preprocessing

Cut EPC

Categorization

Noise  
Elimination

## Feature Extraction



FFT - Normalization

## Matching

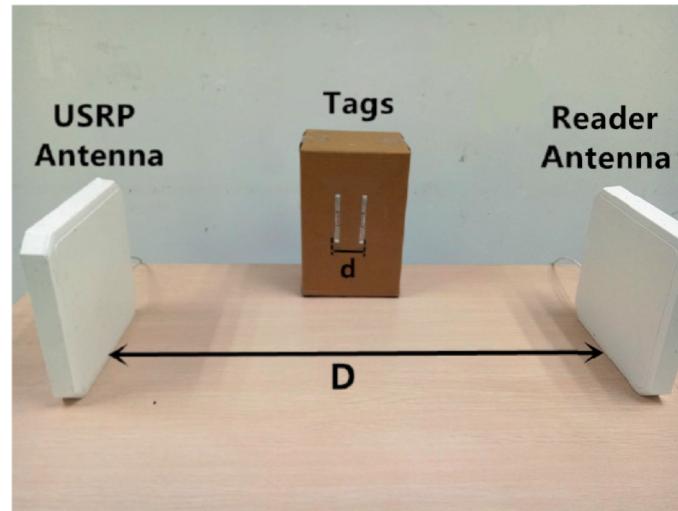




## System Design: Signal collection

### System deployment:

- USRP N210-based Monitor
- ImpinJ R220 Reader
- Two tags



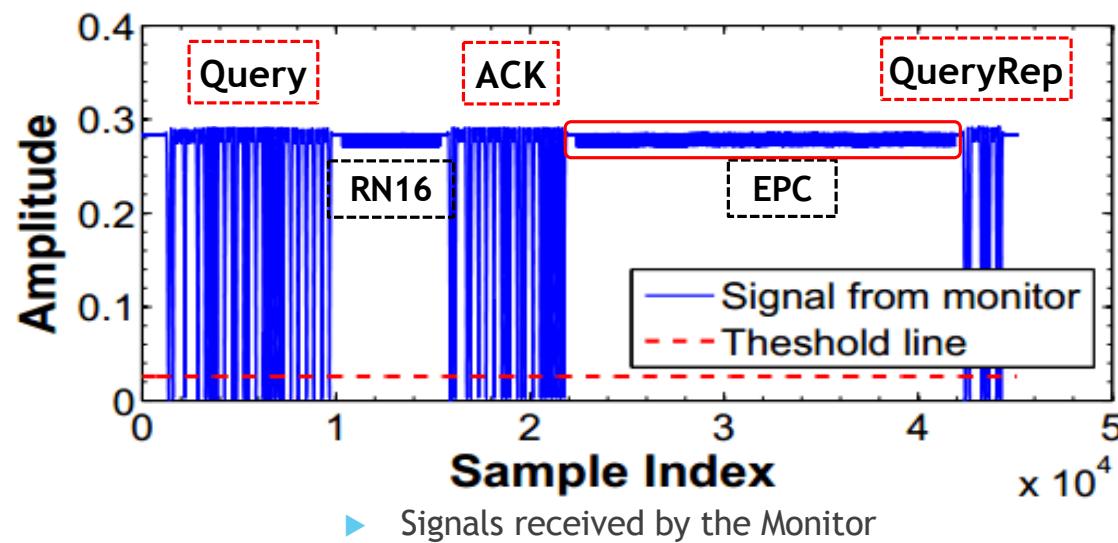
► System deployment



# System Design: Signal preprocessing

## Signal preprocessing:

- Cut EPC segment
- Tag categorization
- Noise elimination

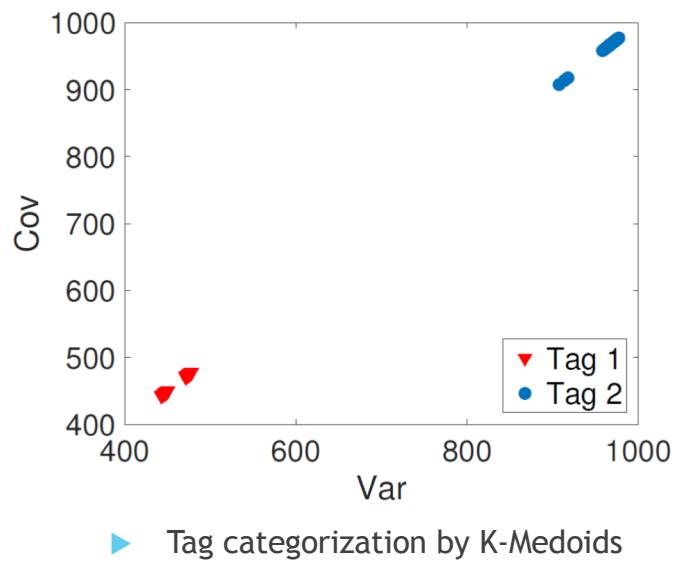




# System Design: Signal preprocessing

## Signal preprocessing:

- Cut EPC segment
- Tag categorization
- Noise elimination

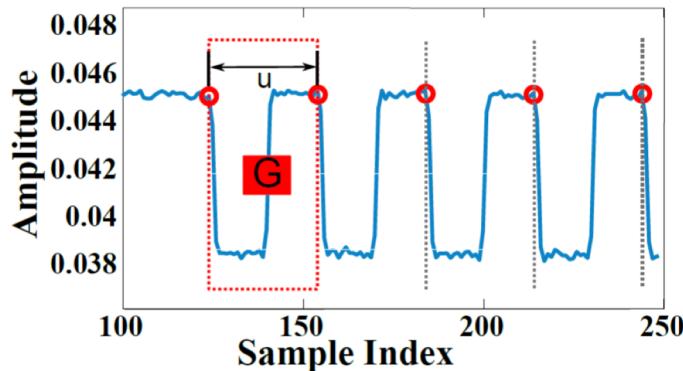




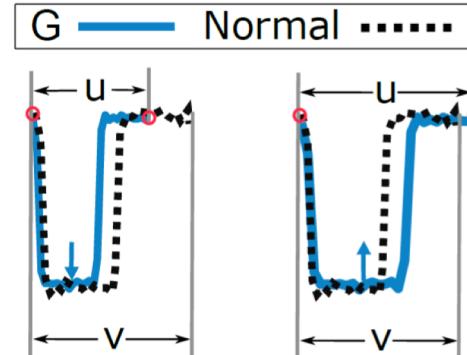
# System Design: Signal preprocessing

## Signal preprocessing:

- Cut EPC segment
- Tag categorization
- Noise elimination      **ASP: Align Sample Point algorithm.**



(a) segment



(b) abnormal waveforms

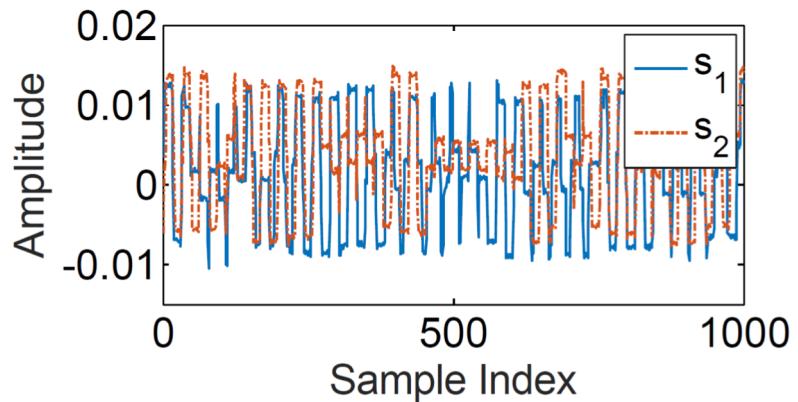
► Inconsistent signal caused by hardware



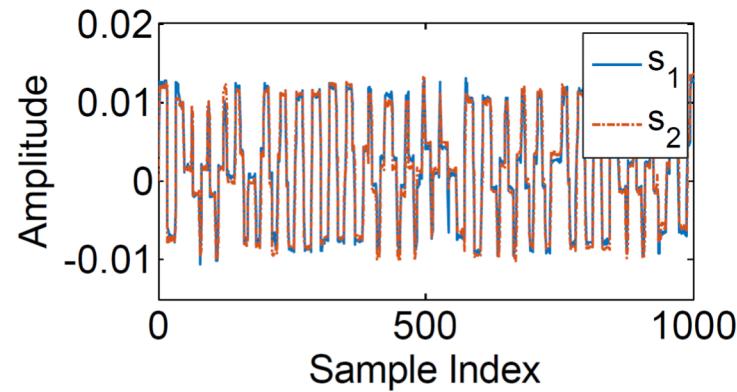
## System Design: Signal preprocessing

### Signal preprocessing:

- Cut EPC segment
- Tag categorization
- Noise elimination



(a) Before performing ASP



(b) After performing ASP

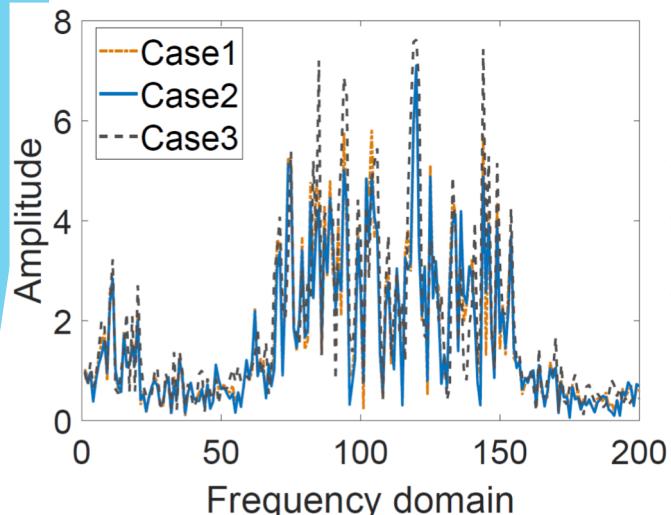
► Effectiveness of ASP



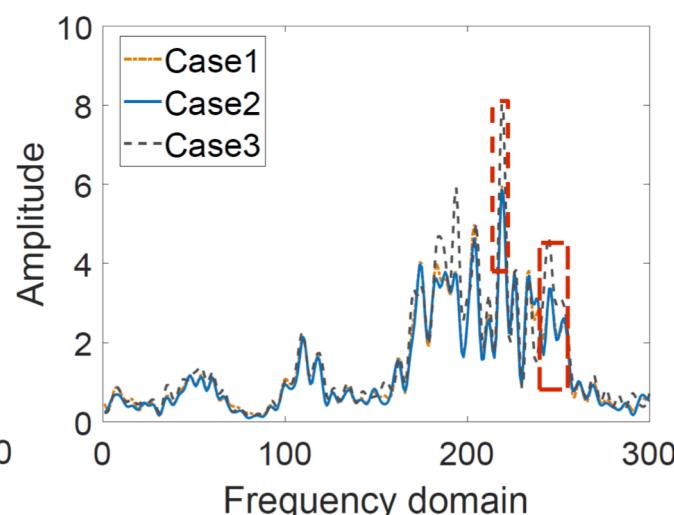
# System Design: Feature extraction

## Feature extraction:

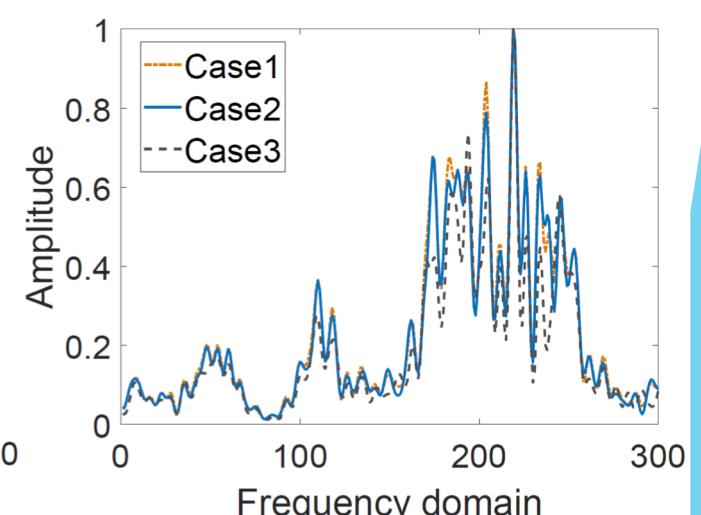
- FFT
- Low-pass filter
- Normalization



► After FFT



► After Low-pass Filter



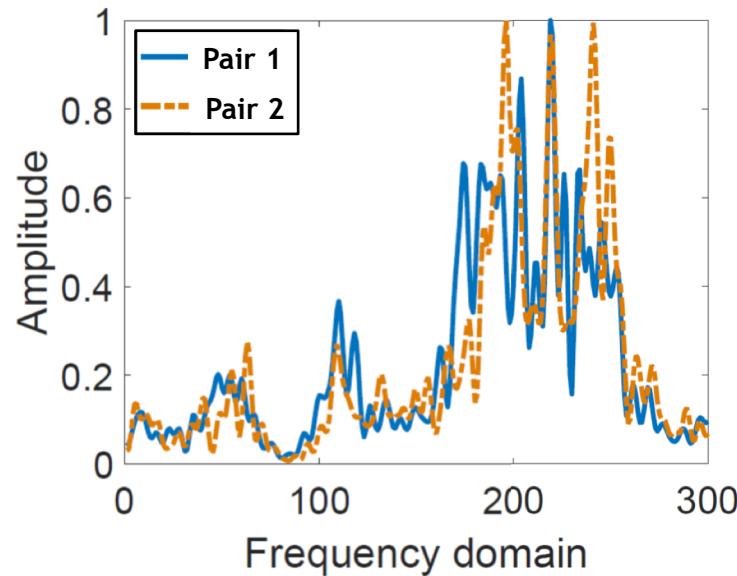
► After normalization



## System Design: Feature matching

### Feature extraction:

- Overlapped rate  $R$ : 
$$R = \frac{\varphi(F_c) \cap \varphi(F_t)}{\varphi(F_c) \cup \varphi(F_t)}$$



- ▶ The features of different tag pairs

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# Experiments and Evaluation

## Hardware:

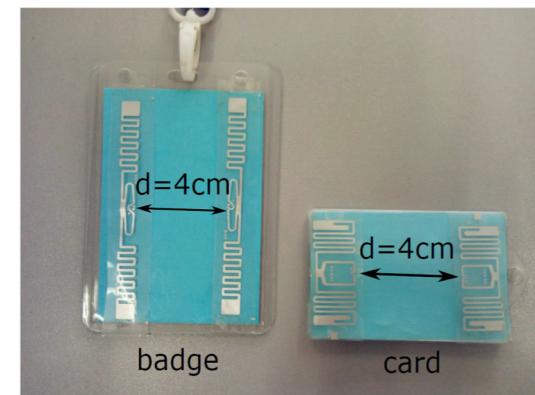
- Impinj R220 Reader
- USRP N210 plus SBX daughterboard
- 3 types of tags:Impinj E41-B, E41-C, Alien-9640

## Deployment:

- The distance between the reader antenna and the monitor antenna:  $D=0.5\text{m} \sim 1.5\text{m}$
- The distance between two tags: 4cm

## Metrics:

- False accept rate (FAR)
- False reject rate (FRR)
- Accuracy



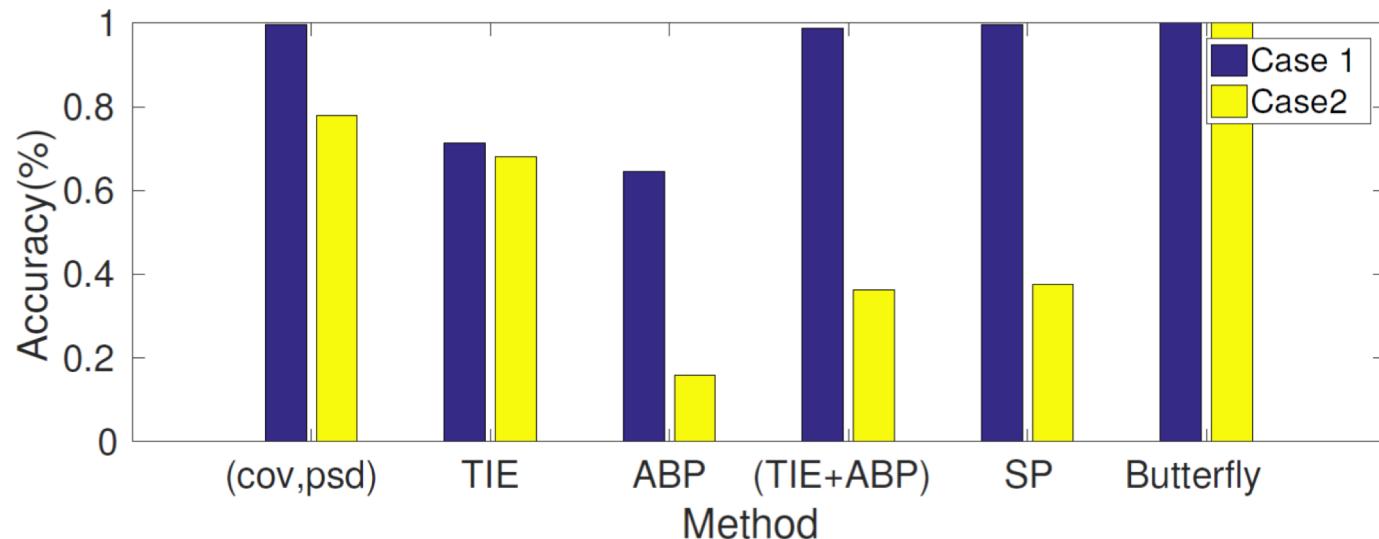


## Experiments and Evaluation

Case 1: The **same** authentication position.

Case 2: **Different** authentication position in the **same** room.

Case 3: **Different** authentication position in the **different** room.



- ▶ Comparison between Butterfly and prior solutions in two cases



## Experiments and Evaluation

**Changing the authentication devices:**

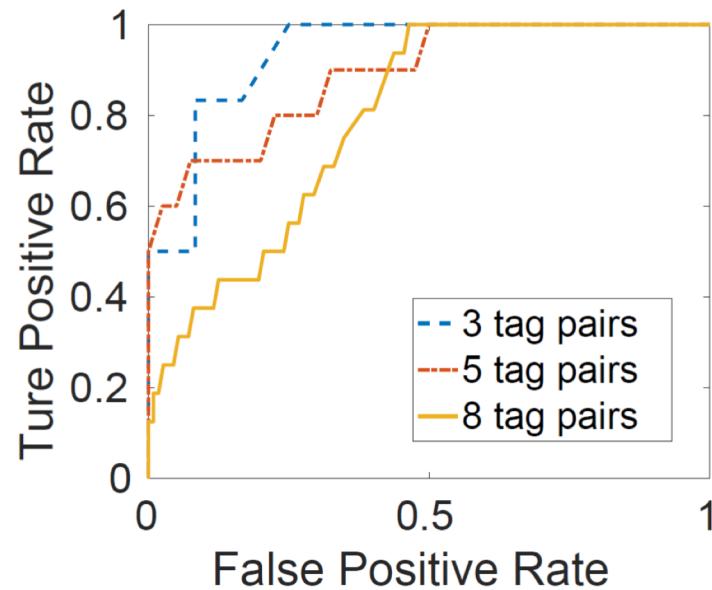
Table 2. Accuracy after changing devices

|          | Room 2 | Room 3 | Room 4 |
|----------|--------|--------|--------|
| Accuracy | 98.5%  | 93.3%  | 91.5%  |



## Experiments and Evaluation

**Authenticate multiple tags:**

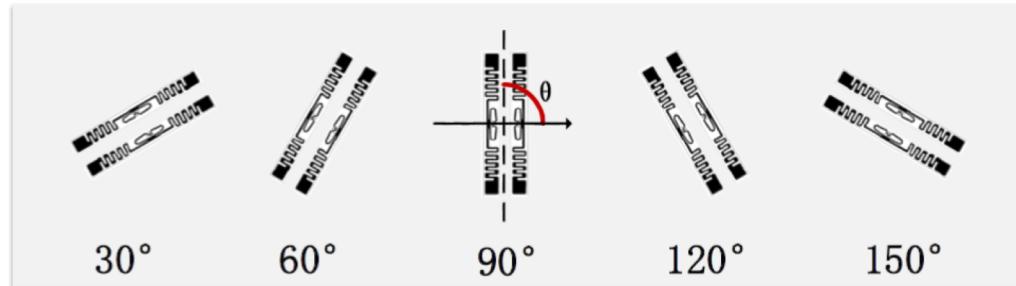


► The ROC curve of multiple pairs



## Experiments and Evaluation

### Other factors: Tag rotation



► Rotations of tag pairs

Table 3. The accuracy when tag pairs rotate

| Angle(°)    | 30   | 60   | 90  | 120 | 150  |
|-------------|------|------|-----|-----|------|
| Accuracy(%) | 91.7 | 96.7 | 100 | 95  | 93.3 |

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## Conclusion

- In this paper, we present an **environment-independent** physical layer authentication scheme for passive RFID tags, called Butterfly.
- The main advantage of Butterfly is the **resilience to environments, locations, and device changes**, which are major problems in prior solutions.
- We implement a prototype Butterfly and conduct extensive experiments for evaluation. The results show that Butterfly is very effective and accurate in authentication (up to 96.7%).



**Thank you!**

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