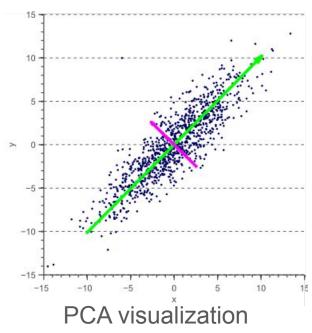
Chapter 5. dimension reduction

Principal component analysis

Dimension reduction method (unsupervised feature extraction)



(blue dot: origin data, arrow: output vector)

PCA algorithm

- 1. Data pre-processing
- 2. create covariance matrix
- 3. eigen decomposition (covariance matrix)
- 4. select eigenvector (standard: eigen value)
- 5. space projection

Data pre-processing

Data mean -> 0

Data variance -> 1

sklearn.preprocessing.StandardScaler

class sklearn.preprocessing.StandardScaler(copy=True, with_mean=True, with_std=True)

[source]

Standardize features by removing the mean and scaling to unit variance

The standard score of a sample x is calculated as:

z = (x - u) / s

where u is the mean of the training samples or zero if with_mean=False, and s is the standard deviation of the training samples or one if with std=False.

```
from sklearn.preprocessing import StandardScaler
data1 = [[-9, 100], [2, 100]]
scaler = StandardScaler()
print(scaler.fit(data1))
print(scaler.transform(data1))
```

```
StandardScaler(copy=True, with_mean=True, with_std=True)
[[-1. 0.]
[ 1. 0.]
```

```
from sklearn.preprocessing import StandardScaler
data2 = [[-9, 100], [9, -100]]
scaler = StandardScaler()
print(scaler.fit(data2))
print(scale|r.transform(data2))
```

```
StandardScaler(copy=True, with_mean=True, with_std=True)
[[-1. 1.]
[1. -1.]]
```

Create covariance matrix

covariance $- cov(x,y) = E[(x-m_x)(y-m_y)]$

Eigen decomposition

A (non-zero) vector \mathbf{v} of dimension N is an **eigenvector** of a square $N \times N$ matrix \mathbf{A} if it satisfies the linear equation

$$\mathbf{A}\mathbf{v} = \lambda \mathbf{v}$$

The decomposition can be derived from the fundamental property of eigenvectors:

$$\mathbf{A}\mathbf{v} = \lambda \mathbf{v}$$

$$\mathbf{A}\mathbf{Q} = \mathbf{Q}\boldsymbol{\Lambda}$$

$$\mathbf{A} = \mathbf{Q}\boldsymbol{\Lambda}\mathbf{Q}^{-1}.$$

$$= \begin{bmatrix} v_1 & v_2 & \cdots & v_n \end{bmatrix} \begin{bmatrix} \lambda_1 & 0 & 0 & 0 \\ 0 & \lambda_2 & 0 & 0 \\ 0 & 0 & \ddots & \vdots \\ 0 & 0 & \cdots & \lambda_n \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{bmatrix}$$

$$= \begin{bmatrix} \lambda_1 v_1 & \lambda_2 v_2 & \cdots & \lambda_n v_n \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{bmatrix}$$

$$= \lambda_1 v_1 v_1^T + \lambda_2 v_2 v_2^T + \cdots + \lambda_n v_n v_n^T$$