HAN ZHANG

 $(+86)18826072909 \Leftrightarrow \text{hanz.enthe@gmail.com}$

EDUCATION

The Chinese University of Hong Kong, Hong Kong

Department of Mathematics

August 2018 - July 2020

Master of Philosophy

Sun Yat-Sen University, Guangzhou

School of Mathematics

August 2014 - June 2018 Bachelor of Science

RESEARCH INTEREST

Computational Geometry Scientific Computing

Geometry Processing

ACADEMIC EXPERIENCE

The Key Laboratory of Computational Science

of Guangdong Province

September 2016 - April 2018 Guangzhou, CHINA

Part-Time Research Assistant

· Research on medical images supervised by Prof.Ying JIANG. Especially on finding a new approach for CT reconstruction through wavelet basis.

Faculty of Mathematics,

The Chinese University of Hong Kong

August 2018 - July 2020 Hong Kong, CHINA

Teaching Assistant

· Research on computational geometry and deep learning. Supervised by Lok Ming LUI

Shenzhen University Research Assistant

Department of Computer Science,

July 2020 - June 2021 Shenzhen, CHINA

· Research on scene reconstruction and path planning. Work with Hui Huang

Faculty of Mathematics,

The Chinese University of Hong Kong

July 2021 - Present Hong Kong, CHINA

Research Assistant

· Research on computational geometry and medical image segmentation. Supervised by Lok Ming LUI

PROJECTS

Quasi-Conformal and Neural Network

October 2019 - Present

with Lok Ming LUI

The Chinese University of Hong Kong

Quasi-Conformal theory is a powerful tool to control the geometric deformation. Thus can control the degree of the deformation and preserve the topology of a spatial transformation in images. The project aim to introduce Quasi-Conformal into the neural network models to enable the convolution and the feature map deformable without destroying the topology of the original images.

Shape Signature and Its Application

July 2021 - Present

with Lok Ming LUI TBD

The Chinese University of Hong Kong

Continuous Path Planning for Reconstruction

July 2020 - June 2021 Shenzhen University

with Hui HUANG

We introduce the first path-oriented drone trajectory planning algorithm, which performs continuous (i.e., dense) image acquisition along an aerial path and explicitly factors path quality into an optimization along with scene reconstruction quality.

PUBLICATIONS

Topology-Preserving Segmentation Network: A Deep Learning Segmentation Framework with Topology Constraint. Han Zhang, Lok Ming Lui (manuscript).

Quasi-Conformal Transformer Network. Han Zhang, Qiguang Chen, Yuchen Guo, Lok Ming Lui (manuscript).

Continuous Aerial Path Planning for 3D Urban Scene Reconstruction. Han Zhang, Yucong Yao, Ke Xie, Chi-Wing Fu, Hao Zhang, Hui Huang. (Siggraph Asia 2021).

Quasi-Conformal Neural Network (QC-net) with Applications to Shape Matching. Han Zhang (MPhil thesis)

ACADEMIC ACHIEVEMENTS

Excellent Student Scholarship of Sun Yat-Sen University Excellent Thesis of Sun Yat-Sen University China Undergraduate Mathematical Contest in Modeling National High School Mathematics League

Outstanding Second Prize Second Prize

October 2017

First Class

EXTRA-CURRICULAR

Institute of Computing Technology,

Chinese Academy of Sciences July 2017 Outstanding Student of 'Computing Future' summer training class Beijing, CHINA

Department of Mathematics,

The Chinese University of Hong Kong

Visiting Student Hong Kong, CHINA

Department of Mathematics,

The Chinese University of Hong Kong August 2018 - August 2020 Teaching Assistant Hong Kong, CHINA

Programming Languages

TECHNICAL STRENGTHS

C++, MATLAB, PYTHON, CGAL...