

# HAN ZHANG

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## EDUCATION

<b>The Chinese University of Hong Kong, Hong Kong</b> Department of Mathematics	<i>July 2020</i> M.Phil in Applied Mathematics
<b>Sun Yat-Sen University, Guangzhou</b> School of Mathematics	<i>June 2018</i> B.Sc in Computational Science

## RESEARCH INTEREST

Computer Graphics      Geometry Processing      Medical Image

## ACADEMIC EXPERIENCE

- The Key Laboratory of Computational Science of Guangdong Province**  
*Part-Time Research Assistant*

*September 2016 - April 2018*  
*Guangzhou, CHINA*

  - Research on medical images supervised by Prof.Ying JIANG. Especially on finding a new approach for CT reconstruction through wavelet basis.
- Faculty of Mathematics, The Chinese University of Hong Kong**  
*Teaching Assistant*

*August 2018 - July 2020*  
*Hong Kong, CHINA*

  - Research on computational geometry and deep learning. Supervised by [Lok Ming LUI](#)
- Department of Computer Science, Shenzhen University**  
*Research Assistant*

*July 2020 - June 2021*  
*Shenzhen, CHINA*

  - Research on scene reconstruction and path planning. Work with [Hui Huang](#)
- Faculty of Mathematics, The Chinese University of Hong Kong**  
*Research Assistant*

*July 2021 - Present*  
*Hong Kong, CHINA*

  - Research on computational geometry and medical image analysis. Supervised by [Lok Ming LUI](#)

## PROJECTS

- Quasi-Conformal and Neural Network**  
*with* Lok Ming LUI

*October 2019 - Present*  
The Chinese University of Hong Kong

Quasi-Conformal theory is a powerful tool to control the geometric deformation. Thus can control the degree of the deformation and preserve the topology of a spatial transformation in images. The project aim to introduce Quasi-Conformal into the neural network models to enable the convolution and the feature map deformable without destroying the topology of the original images.
- Continuous Path Planning for Reconstruction**  
*with* Hui HUANG

*July 2020 - June 2021*  
Shenzhen University

We introduce the first path-oriented drone trajectory planning algorithm, which performs continuous (i.e., dense) image acquisition along an aerial path and explicitly factors path quality into an optimization along with scene reconstruction quality.

## PUBLICATIONS

- Nondeterministic Deformation analysis using Quasiconformal Geometry.  
**Han Zhang**, Lok Ming Lui  
(submitted).
- Topology-Preserving Segmentation Network: A Deep Learning Segmentation Framework for Connected Component.  
**Han Zhang**, Lok Ming Lui  
(submitted).
- Quasi-Conformal Transformer Network.  
**Han Zhang**, Qiguang Chen, Yuchen Guo, Lok Ming Lui  
(manuscript).
- Continuous Aerial Path Planning for 3D Urban Scene Reconstruction.  
**Han Zhang**, Yucong Yao, Ke Xie, Chi-Wing Fu, Hao Zhang, Hui Huang.  
(*Siggraph Asia 2021*).
- Quasi-Conformal Neural Network (QC-net) with Applications to Shape Matching.  
**Han Zhang**  
(*MPhil thesis*)

## ACADEMIC ACHIEVEMENTS

<b>Research Postgraduate Scholarship</b>	<i>First Class</i>
<b>Excellent Student Scholarship of Sun Yat-Sen University</b>	<i>Outstanding</i>
<b>Excellent Thesis of Sun Yat-Sen University</b>	<i>Second Prize</i>
<b>China Undergraduate Mathematical Contest in Modeling</b>	<i>Second Prize</i>
<b>National High School Mathematics League</b>	<i>Second Prize</i>

## TEACHING

Calculus for Engineering(MATH1510)	2018-2019 FALL, at CUHK
Game Theory(MATH4250)	2018-2019 SPRING, at CUHK
Foundation of Modern Mathematics(MATH1050)	2019-2020 FALL, at CUHK

## TECHNICAL STRENGTHS

**Programming Languages**      C++, MATLAB, PYTHON, CGAL...