MA50259: Statistical Design of Investigations

Dr. Sandipan Roy

Lecture 2

Our own randomised experiment, simulating the response

In order to understand statistical analysis later, we can think of how to simulate the response in our own randomised experiment.

- Let Y_{ij} be the response for the jth experimental unit subject to the ith level of the treatment factor, $i=1,\ldots,t$ and $j=1,\ldots,r_i$. Y_{ij} is treated as a **random variable**
- $ightharpoonup r_i$ is the number of replicates in ith level of the treatment factor. Note that $r_i = r$ for all i, if the design is balanced
- Let μ_i be the **mean response** [long-run average of all possible experiments] at the *i*th level of the treatment factor, then

$$Y_{ij} = \mu_i + \epsilon_{ij}$$
, where $E[Y_{ij}] = \mu_i$

 $ightharpoonup \epsilon_{ij}$ is the [additive] experimental error and is also treated as a random variable such that $E[\epsilon_{ij}] = 0$

Our own randomised experiment, simulating the response

- Let μ be either the overall response average when there is no treatment or simply a reference value of interest.
- ▶ **Linear model**: Let $\mu_i = \mu + \tau_i$ so that

$$Y_{ij} = \mu_i + \epsilon_{ij}$$
$$= \mu + \tau_i + \epsilon_{ij}$$

- ▶ The τ_i 's are called the **treatment effects**. τ_i represents the difference between the mean response at the *i*-th level of the treatment factor and the reference value μ
- **Assumption:** There is an additive effect of the treatment levels on the means, e.g. $\mu_i = \mu + \tau_i$
- Note the treatment effects model has t+1 unknown parameters and the means model only has t!

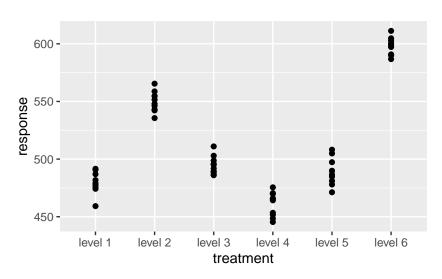
Our own CRD experiment, simulating the response

- Specifying the probability distribution of the experimental errors ϵ_{ij} determines uniquely the probability distribution of the responses Y_{ij} [and viceversa]
- ▶ Two sources of randomness: + Randomisation of units to treatement levels + Randomness in the response for different experimental units
- Due to the **randomisation** of units to treatement levels, the responses Y_{ij} (or the experimental errors ϵ_{ij}), are **mutually independent**
- ▶ **Assumption:** If the units are **homogeneous**, the probability distribution of the responses Y_{ij} (or the experimental errors ϵ_{ij}), under the same treatment level, is the **same**.
- ▶ **Assumption:** the probability distribution of the responses Y_{ij} (or the experimental errors ϵ_{ij}), is **Gaussian**.

Our own CRD experiment, simulating the response

Our own CRD experiment, simulating the response





We can use maximum likelihood, which is equivalent to the method of least squares with the above assumptions, the estimates of the means are found by minimising the error sum of squares

$$ssE := \sum_{i=1}^{t} \sum_{i=1}^{r_i} (y_{ij} - \mu_i)^2$$

Taking partial derivatives with respect to each μ_i and equating to zero we have

$$\frac{\partial ssE}{\partial \mu_i} = -2\sum_{i=1}^t \sum_{i=1}^{r_i} (y_{ij} - \mu_i) = 0$$

which results in the estimates

$$\hat{\mu}_i = \bar{y}_{i\cdot} = \frac{1}{r_i} \sum_{i=1}^{r_i} y_{ij}$$

Must check the Hessian is indeed positive definite!

Consider a CRD with t=3 levels and $r_i=4$ replicates. We can write the means model using matrix notation as:

$$extbf{ extit{y}} = extbf{ extit{Z}} \mu + \epsilon$$

where $\boldsymbol{\epsilon} \sim \textit{MVN}(\boldsymbol{0}, \sigma^2 \boldsymbol{I})$ and

$$\mathbf{y} = \begin{pmatrix} y_{11} \\ y_{12} \\ y_{13} \\ y_{14} \\ y_{21} \\ y_{22} \\ y_{23} \\ y_{24} \\ y_{31} \\ y_{32} \\ y_{33} \\ y_{33} \\ y_{33} \end{pmatrix}, \quad \mathbf{Z} = \begin{pmatrix} 1 & 0 & 0 \\ 1 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 1 \\ 0 & 0 & 1 \\ 0 & 0 & 1 \\ 0 & 0 & 1 \end{pmatrix}, \quad \boldsymbol{\mu} = \begin{pmatrix} \epsilon_{11} \\ \epsilon_{12} \\ \epsilon_{13} \\ \epsilon_{14} \\ \epsilon_{21} \\ \epsilon_{22} \\ \epsilon_{23} \\ \epsilon_{24} \\ \epsilon_{31} \\ \epsilon_{32} \\ \epsilon_{33} \\ \epsilon_{33} \\ \epsilon_{34} \end{pmatrix}$$

Consider a CRD with t=3 levels and $r_i=4$ replicates. We can write the treatment effects model using matrix notation as:

$$\mathbf{y} = \mathbf{X}eta + \mathbf{\epsilon}$$

where $\epsilon \sim MVN(\mathbf{0}, \sigma^2 \mathbf{I})$ and

$$\mathbf{y} = \begin{pmatrix} y_{11} \\ y_{12} \\ y_{13} \\ y_{14} \\ y_{21} \\ y_{22} \\ y_{23} \\ y_{24} \\ y_{31} \\ y_{32} \\ y_{33} \\ y_{34} \end{pmatrix}, \ \mathbf{X} = \begin{pmatrix} 1 & 1 & 0 & 0 \\ 1 & 1 & 0 & 0 \\ 1 & 1 & 0 & 0 \\ 1 & 0 & 1 & 0 \\ 1 & 0 & 1 & 0 \\ 1 & 0 & 1 & 0 \\ 1 & 0 & 0 & 1 \\ 1 & 0 & 0 & 1 \\ 1 & 0 & 0 & 1 \\ 1 & 0 & 0 & 1 \\ 1 & 0 & 0 & 1 \\ 1 & 0 & 0 & 1 \end{pmatrix}, \ \boldsymbol{\beta} = \begin{pmatrix} \epsilon_{11} \\ \epsilon_{12} \\ \epsilon_{13} \\ \epsilon_{14} \\ \epsilon_{21} \\ \epsilon_{22} \\ \epsilon_{23} \\ \epsilon_{24} \\ \epsilon_{31} \\ \epsilon_{32} \\ \epsilon_{33} \\ \epsilon_{34} \end{pmatrix}$$

Vector calculus recap

We will use the so-called denominator layout notation: \boldsymbol{u} is a column vector and \boldsymbol{u}^T is a row vector, g is a real function of \boldsymbol{u}

$$\frac{\partial \mathbf{g}}{\partial \mathbf{u}} = \begin{pmatrix} \frac{\partial \mathbf{g}}{\partial u_1} \\ \frac{\partial \mathbf{g}}{\partial u_2} \\ \vdots \\ \frac{\partial \mathbf{g}}{\partial u_p} \end{pmatrix}, \qquad \frac{\partial \mathbf{g}}{\partial \mathbf{u}^T} = \begin{pmatrix} \frac{\partial \mathbf{g}}{\partial u_1}, \frac{\partial \mathbf{g}}{\partial u_2}, \cdots, \frac{\partial \mathbf{g}}{\partial u_p} \end{pmatrix}$$

$$\frac{\partial^2 \mathbf{g}}{\partial \mathbf{u}^T \partial \mathbf{u}} = \begin{pmatrix} \frac{\partial^2 \mathbf{g}}{\partial u_1 \partial u_1} & \frac{\partial^2 \mathbf{g}}{\partial u_2 \partial u_1} & \cdots & \frac{\partial^2 \mathbf{g}}{\partial u_p \partial u_1} \\ \frac{\partial^2 \mathbf{g}}{\partial u_1 \partial u_2} & \frac{\partial^2 \mathbf{g}}{\partial u_2 \partial u_2} & \cdots & \frac{\partial^2 \mathbf{g}}{\partial u_p \partial u_2} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial^2 \mathbf{g}}{\partial u_1 \partial u_p} & \frac{\partial^2 \mathbf{g}}{\partial u_2 \partial u_p} & \cdots & \frac{\partial^2 \mathbf{g}}{\partial u_p \partial u_p} \end{pmatrix} = \frac{\partial^2 \mathbf{g}}{\partial \mathbf{u} \partial \mathbf{u}^T}$$

Vector calculus recap

Let $g(u) = a^T u$ for some constant vector a then

$$\frac{\partial (\mathbf{a}^{\mathsf{T}}\mathbf{u})}{\partial \mathbf{u}} = \frac{\partial (\mathbf{u}^{\mathsf{T}}\mathbf{a})}{\partial \mathbf{u}} = \mathbf{a}$$

Let g(u) = Au for some constant matrix A then

$$\frac{\partial(\mathbf{A}\mathbf{u})}{\partial\mathbf{u}}=\mathbf{A}^{T}$$

Let $g(u) = u^T A u$ for some constant matrix **A** then

$$\frac{\partial (\boldsymbol{u}^{\mathsf{T}} \boldsymbol{A} \boldsymbol{u})}{\partial \boldsymbol{u}} = 2 \boldsymbol{A} \boldsymbol{u}$$

The Least Squares (LS) estimator for μ is the one minimising the error sum of squares

$$ssE = \sum_{i=1}^{t} \sum_{i=1}^{r_i} (y_{ij} - \mu_i)^2 = \|\mathbf{y} - \mathbf{Z}\boldsymbol{\mu}\|^2 = (\mathbf{y} - \mathbf{Z}\boldsymbol{\mu})^T (\mathbf{y} - \mathbf{Z}\boldsymbol{\mu})$$

the solution is given by the so-called the *normal equations*:

$$Z^T Z \hat{\mu} = Z^T y$$

since Z^TZ is non-singular then we have

$$\hat{\boldsymbol{\mu}} = (\boldsymbol{Z}^{T}\boldsymbol{Z})^{-1}\boldsymbol{Z}^{T}\boldsymbol{y}$$

It is easy to verify that

$$\hat{\mu}_i = \bar{y}_{i.} = \frac{1}{r_i} \sum_{i=1}^{r_i} y_{ij}$$

as verified above! We say that the model is full rank

```
r<-4; t<-3; levels<-c("level 1", "level 2", "level 3");
fact <- rep(levels,each = r) %>% factor()
Z <- model.matrix(~ fact-1); Z</pre>
   factlevel 1 factlevel 2 factlevel 3
10
11
12
attr(,"assign")
[1] 1 1 1
attr(,"contrasts")
attr(,"contrasts") $fact
[1] "contr.treatment"
```

```
mod.crd.means<-lm(response~treatment-1,data=crd)</pre>
summary(mod.crd.means)
Call:
lm(formula = response ~ treatment - 1, data = crd)
Residuals:
    Min
           10 Median
                             30
                                    Max
-21.6029 -6.9514 0.5019 6.4716 19.0177
Coefficients:
               Estimate Std. Error t value Pr(>|t|)
treatmentlevel 1 480.800
                            3.015 159.5 <2e-16 ***
treatmentlevel 2 550.033 3.015 182.4 <2e-16 ***
treatmentlevel 3 494.618 3.015 164.0 <2e-16 ***
treatmentlevel 4 461.012 3.015 152.9 <2e-16 ***
treatmentlevel 5 489.149 3.015 162.2 <2e-16 ***
treatmentlevel 6 597.342 3.015 198.1 <2e-16 ***
Signif. codes: 0 '*** 0.001 '** 0.01 '* 0.05 '.' 0.1 ' 1
Residual standard error: 9.535 on 54 degrees of freedom
Multiple R-squared: 0.9997, Adjusted R-squared: 0.9997
F-statistic: 2.909e+04 on 6 and 54 DF, p-value: < 2.2e-16
```

The LS estimator for β minimises the error sum of squares

$$ssE = \sum_{i=1}^{t} \sum_{j=1}^{r_i} (y_{ij} - \mu - \tau_i)^2 = \|\mathbf{y} - \mathbf{X}\boldsymbol{\beta}\|^2 = (\mathbf{y} - \mathbf{X}\boldsymbol{\beta})^T (\mathbf{y} - \mathbf{X}\boldsymbol{\beta})$$

with corresponding normal equations:

$$X^T X \widehat{\beta} = X^T y$$

The problem now is that X^TX is singular and cannot be inverted!

- Note **X** has t+1 columns!
- First column of **X** is the sum of the rest of the columns.
- ➤ X'X has rank=t
- ▶ We say that the treatment effects model is **not full rank**

By default, R makes the matrix \boldsymbol{X} to have have full rank by dropping the column that corresponds to the first level of the factor

```
r<-4; t<-3; levels<-c("level 1", "level 2", "level 3");
fact <- rep(levels,each = r) %>% factor()
X <- model.matrix(~ fact); X</pre>
   (Intercept) factlevel 2 factlevel 3
10
11
12
attr(, "assign")
[1] 0 1 1
attr(,"contrasts")
attr(,"contrasts")$fact
[1] "contr.treatment"
```

```
mod.crd<-lm(response~treatment,data=crd)</pre>
summary(mod.crd)
Call:
lm(formula = response ~ treatment, data = crd)
Residuals:
    Min
             10 Median
                              30
                                     Max
-21.6029 -6.9514 0.5019 6.4716 19.0177
Coefficients:
               Estimate Std. Error t value Pr(>|t|)
(Intercept) 480.800
                            3.015 159.463 < 2e-16 ***
treatmentlevel 2 69.233 4.264 16.237 < 2e-16 ***
treatmentlevel 3 13.818 4.264 3.241 0.00204 **
treatmentlevel 4 -19.788 4.264 -4.641 2.25e-05 ***
treatmentlevel 5 8.349 4.264 1.958 0.05540.
treatmentlevel 6 116.542 4.264 27.332 < 2e-16 ***
Signif. codes: 0 '*** 0.001 '** 0.01 '* 0.05 '.' 0.1 ' 1
Residual standard error: 9.535 on 54 degrees of freedom
Multiple R-squared: 0.964, Adjusted R-squared: 0.9606
F-statistic: 288.8 on 5 and 54 DF, p-value: < 2.2e-16
```

Statistical analysis of plywood experiment: linear model

```
mod.plywood<-lm(strength~glue,data=plywood)</pre>
summary(mod.plywood)
Call:
lm(formula = strength ~ glue, data = plywood)
Residuals:
  Min
         10 Median 30 Max
-44.40 -17.82 -5.00 14.45 59.40
Coefficients:
          Estimate Std. Error t value Pr(>|t|)
(Intercept) 478.800 8.107 59.063 < 2e-16 ***
glueB
     13.600 11.464 1.186 0.2407
glueC 24.600 11.464 2.146 0.0364 *
glueD 50.000 11.464 4.361 5.86e-05 ***
glueE 99.800 11.464 8.705 7.30e-12 ***
glueF 117.700 11.464 10.267 2.67e-14 ***
Signif. codes: 0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
Residual standard error: 25.64 on 54 degrees of freedom
Multiple R-squared: 0.7646, Adjusted R-squared: 0.7428
F-statistic: 35.08 on 5 and 54 DF, p-value: 8.37e-16
```

Statistical analysis of plywood experiment: linear model

```
coefs<-coef(mod.plywood) # extracts coefficient values only</pre>
# reconstruct means from coefficients
taus<-c(0,coefs[2:length(coefs)])</pre>
means2<-coefs[1]+taus
means2
      glueB glueC glueD glueE glueF
478.8 492.4 503.4 528.8 578.6 596.5
# compute means from original data
by_group <- group_by(plywood, glue)</pre>
summaries.plywood<-summarize(by_group, means = mean(strength))</pre>
glimpse(summaries.plywood)
Rows: 6
Columns: 2
$ glue <chr> "A", "B", "C", "D", "E", "F"
$ means <dbl> 478.8, 492.4, 503.4, 528.8, 578.6, 596.5
```

Estimability in the treatment effects model

► Theory says that normal equations:

$$X^T X \widehat{\beta} = X^T y$$

maybe have infinite number of solutions for $\widehat{eta}!!!$

- lacktriangle Theory says any solution \widehat{eta} will be a linear function of $m{y}$
- ▶ We can focus on unbiased solutions!
- We will focus on finding unbiased estimators of linear combinations of the form

$$\boldsymbol{\lambda}^{T}\boldsymbol{\beta} = \lambda_0 \, \mu + \sum_{i=1}^{t} \lambda_i \tau_i$$

Note we write $\lambda^T = (\lambda_0, \lambda_1, \dots, \lambda_t)$

Estimability in the treatment effects model

A linear combination of the parameters $\lambda^T \beta$ is called **estimable** if

$$\boldsymbol{\lambda}^T \boldsymbol{\beta} = E\left[\sum_{i=1}^t \sum_{j=1}^{r_i} a_{ij} Y_{ij}\right] = E[\boldsymbol{a}^T \boldsymbol{Y}], \qquad \text{for all } \boldsymbol{\beta}$$

- ▶ Equivalently, a linear combination $\lambda^T \beta$ is **estimable** if there exists an unbiased estimator of the form $a^T Y$
- Note that if $\lambda^T \beta$ is estimable then

$$\lambda^T \beta = a^T E[Y] = a^T X \beta$$
, for all β

which implies that

$$\lambda = X^T a$$

which means λ belongs to the space generated by the rows of X!

Estimability in the treatment effects model

Useful results for the CRD design

1. A linear combination $\lambda^T \beta$ is **estimable** if and only if ther exists a solution R to the system

$$X^TXr=\lambda$$

- 2. Both $E(Y) = X\beta$ and $X^TX\beta$ are estimable
- 3. There are exactly t linearly independent estimable linear combinations $\lambda_1^T \beta, \dots, \lambda_t^T \beta$
- 4. **Great Result!!** Let α be a vector of t linearly independent estimable combinations of β in the treatement effects model $\mathbf{Y} = \mathbf{X}\beta + \epsilon$. Then there exists a reparametrization to the full rank model $\mathbf{Y} = \mathbf{Z}\alpha + \epsilon$. Furthermore,
- ▶ any full rank reparametrization will give the same estimate of any estimable combination $\lambda^T \beta$
- \triangleright a full rank reparametrization requires Z^TZ is diagonal!

Estimability: Examples for the CRD design

- ▶ The means $\mu_i = \mu + \tau_i$ for i = 1, ..., t are estimable!
- ▶ Any difference $\tau_i \tau_j$ for $i \neq j$ is estimable!
- ▶ **Definition**: Let *c* be known constant vector. A **contrast** is a linear combination

$$oldsymbol{c^T}eta = c_0 \mu + \sum_{i=1}^t c_i au_i$$
 , where $\sum_{i=0}^t c_i = 0$

Contrasts are always estimable!

▶ The treatement effects themselves τ_i for i = 1, ..., t are not estimable!

Variances and covariances of estimable functions

Let $\lambda_1^T \beta$ and $\lambda_2^T \beta$ be two estimable linear combinations in the treatment effects (non full rank) model

$$\mathbf{Y} = \mathbf{X}\boldsymbol{\beta} + \boldsymbol{\epsilon}, \qquad \boldsymbol{\epsilon} \sim MVN_n(\mathbf{0}, \sigma^2 \mathbf{I})$$

The corresponding variances and covariances are given by:

- $ightharpoonup Var(a_1^T Y) = \sigma^2 r_1 X^T X r_1$ where $X^T X r_1 = \lambda 1$
- $ightharpoonup Var(\mathbf{a_2^TY}) = \sigma^2 \mathbf{r_2X^TXr_2}$ where $\mathbf{X^TXr_2} = \lambda 2$
- $\mathsf{Cov}(\mathbf{a_1^TY}, \mathbf{a_2^TY}) = \sigma^2 \mathbf{r_1X^TXr_2}$

Maximum Likelihood Theory

Consider the treatment effects (non full rank) model

$$\mathbf{Y} = \mathbf{X}\boldsymbol{\beta} + \boldsymbol{\epsilon}, \qquad \boldsymbol{\epsilon} \sim MVN_n(\mathbf{0}, \sigma^2 \mathbf{I})$$

Then the MLE of any estimable linear combination of β is the best possible unbiased estiamte with minimum variance where

$$\widehat{\sigma^2} = \frac{1}{n-t} (\mathbf{Y} - \mathbf{Z}\alpha)^T (\mathbf{Y} - \mathbf{Z}\alpha)$$

where $oldsymbol{Y} = oldsymbol{Z} lpha + \epsilon$ is a estimable reparametrization