

Process Description:

“**Sub-Resolution Object Detection**” identifies sub-resolution objects in the images and returns their sub-pixel positions and intensities. For a description of how the algorithm works, please see **Jaqaman et al., Nature Methods 5: 695-702 (2008), Supplementary Note 2.**

Parameter Descriptions:

Gaussian Standard Deviation: The standard deviation of the point spread function, defined as $0.21 * (\text{emission wavelength}) / (\text{numerical aperture})$. To get value in pixels, divide by pixel size. This field is automatically filled using the movie information supplied when movieData is set up.

Camera Bit Depth: This field is also automatically filled using the movie information supplied when movieData is set up.

Local Maxima Detection:

Alpha-value for Local Maxima Detection: This value is used in the hypothesis test to decide whether a local maximum is significantly brighter than what is expected from background and noise fluctuations. The smaller the alpha-value, the more strict the selection.

Check “**Use Rolling Window Time-Averaging**” to average consecutive frames using a rolling window prior to searching for local maxima. This option can help in the case of low signal-to-noise ratio if objects do not move much from one frame to the next. This averaging is used **ONLY** for local maxima detection, and not for any of the consecutive steps.

If option is checked, define “**Window Size**”: 1 means no averaging, 3 means you average 3 frames at a time (i.e. 1, 2 and 3; 2, 3 and 4; etc.), and so on.

Check “**Use Absolute Background**” to use absolute background information (in addition to local background information) for local maxima detection.

If option is checked, define an **alpha-value** to compare the brightness of local maxima to the absolute background. This alpha-value is usually stricter than that used for comparing to local background, as defined above.

Click “**Open**” if you already have background images that you can supply.

Click “**New**” if you want to crop background images out of the images used for detection.

Gaussian Fitting at Local Maxima

Choose “**Iterate to estimate Gaussian Standard Deviation**” to estimate the Gaussian standard deviation from the data, instead of using the theoretical one defined above.

If chosen, enter the “**Maximum Number of Iterations**” used to determine the Gaussian standard deviation.

Choose “**Do Iterative Gaussian Mixture-Model Fitting**” to attempt to iteratively fit multiple Gaussians at each local maximum, as described in the paper.
For the fitting, define the following hypothesis test alpha-values:

Residuals: Alpha-value to decide whether $n+1$ Gaussians fit the image significantly better than n Gaussians. Needed only if “Do Iterative Gaussians Mixture-Model Fitting” is checked.

Amplitude: Alpha-value for testing whether the amplitude of the fitted Gaussian (reflecting object intensity) is significantly different from zero, given the uncertainty in the amplitude.

Distance: Alpha-value for testing whether the distance between two fitted Gaussian centers (reflecting the underlying object positions) is significantly different from zero, given the uncertainty in the positions.

Final: This test is disabled, and there is nothing to define.

Input and Output

Define frame range to analyze.

Define name and location of file where results will be saved.

Check “**View results immediately frame by frame**” to view results as movie is being analyzed. Recommended only when analyzing a small number of frames for parameter testing. When whole movie is analyzed, it is more efficient to view results *after* the analysis is finished (by clicking on the “Result” button in the U-Track package control panel.