## EM Algorithm for Gaussian Mixture Model

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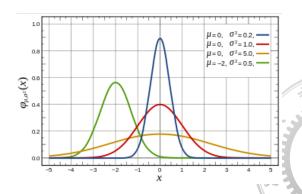
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Recap: The Guassian distribution

The Guassian distribution:

$$\mathcal{N}(x|\mu, \Sigma) = \frac{1}{(2\pi)^{D/2}} \frac{1}{|\Sigma|^{1/2}} exp\{-\frac{1}{2}(x-\mu)^T \Sigma^{-1}(x-\mu)\}$$
 (1)



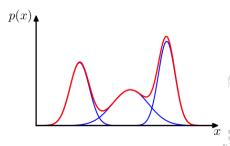
#### The Guassian Mixture distribution

The Guassian Mixture distribution is a linear superposition of Guassians:

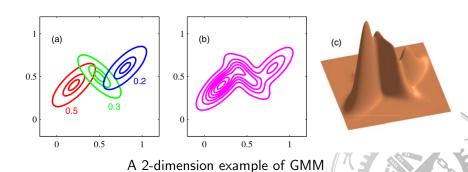
$$p(x) = \sum_{k=1}^{K} \pi_k \mathcal{N}(x|\mu_k, \Sigma_k)$$
 (2)

Subject to:

$$\sum_{k=1}^{K} \pi_k = 1 \tag{3}$$

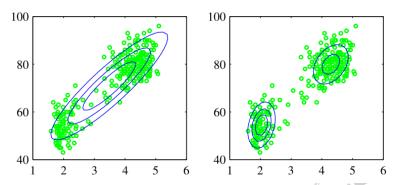


#### The Guassian Mixture distribution



Now, for a Guassian Mixture Model, given the parameters: k, the number of Guassian components  $\pi_1...\pi_k$ , the mixture weights of the components  $\mu_1...\mu_k$ , the mean of each component  $\Sigma_1...\Sigma_k$ , the variance of each component We can generate samples  $s_1, s_2...s_n$  from the distribution.

## Why do we need Guassian Mixture



In this example, we see that Guassian Mixture describes the data better a single Guassian.

Given a Guassian Mixture model, we introduce K-dimensional binary random variable z which only one element  $z_k$  is eugal to 1 and the others are all 0.

$$z = (0, 0, ..., 1, 0, ..0) (4)$$

So there are K possible states for z.And we let

$$p(z_k = 1) = \pi_k \tag{5}$$

That is to say,

$$p(z) = \prod_{k=1}^K \pi_k^{z_k}$$



Then, we define the conditional distribution of x given a particular z:

$$p(x|z_k = 1) = \mathcal{N}(x|\mu_k, \Sigma_k) \tag{7}$$

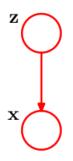
which can also be written as:

$$p(x|z) = \prod_{k=1}^{K} \mathcal{N}(x|\mu_k, \Sigma_k)^{z_k}$$
(8)

Now we can easily compute the marginal distribution of x

$$p(x) = \Sigma_z p(x|z) p(z) = \Sigma_z \prod_{k=1}^K \mathcal{N}(x|\mu_k, \Sigma_k)^{z_k} \prod_{k=1}^K \pi_k^{z_k}$$
$$= \Sigma_{k=1}^K \pi_k \mathcal{N}(x|\mu_k, \Sigma_k)$$

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Now, instead of working with p(x) we can work with p(x,z)=p(x|z)p(z), which will lead to significant simplification when we are introducing the EM algorithm.

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Another quantity p(z|x) will also be very important. We use  $\gamma(z_k)$  to denote  $p(z_k=1|x)$ , and we can use Bayes' theorem to deride its value.

$$\gamma(z_k) = p(z_k = 1|x) = \frac{p(x|z_k = 1)p(z_k = 1)}{p(x)}$$

$$= \frac{\mathcal{N}(x|\mu_k, \Sigma_k)}{\Sigma_{k=1}^K \pi_k \mathcal{N}(x|\mu_k, \Sigma_k)}$$
(9)

We usually say  $\gamma(z_{nk})$  is the responsibility of component k for  $x_n$ .

### Maximum likelihood

Suppose we have a data set of observations  $\{x_1,...,x_N\}$ . And we wish to model this data set using Guassian Mixture model. We could represent this data set as an N\*D matrix  $\mathbf{X}$ , where N is the number of data vectors and D is the dimension of the vector. Then the log likelihood function is given by

$$lnp(X|\pi,\mu,\Sigma) = \sum_{n=1}^{N} ln\{\sum_{k=1}^{K} \pi_k \mathcal{N}(x_n|\mu_k,\Sigma_k)\}$$
 (10)

The expectation-maximization algorithm is an elegant and powerful method for finding maximum likelihood solutions for models with latent variables.

First, we set the derivatives of  $lnp(X|\pi,\mu,\Sigma)$  in equation 10 with repect to  $\mu_k$  to zero.

$$0 = -\sum_{n=1}^{N} \frac{\pi_k \mathcal{N}(x_n | \mu_k, \Sigma_k)}{\sum_{j=1}^{K} \pi_j \mathcal{N}(x_n | \mu_j, \Sigma_j)} \Sigma_k(x_n - \mu_k)$$

$$= -\sum_{n=1}^{N} \gamma(z_{nk}) \Sigma_k(x_n - \mu_k)$$
(11)

If we assume  $\Sigma_k$  to be nonsingular, we obtain

$$\mu_k = \frac{\sum_{n=1}^{N} \gamma(z_{nk}) x_n}{\sum_{n=1}^{N} \gamma(z_{nk})}$$

(12)

We set  $N_k=\Sigma_{n=1}^N\gamma(z_{nk}),$  as the effective number of points assigned to cluster k.

If we set the derivative of  $lnp(X|\pi,\mu,\Sigma)$  with respect to  $\Sigma_k$  to zero,we get

$$\Sigma_k = \frac{1}{N_k} \gamma_k(z_{nk}) (x_n - \mu_k) (x_n - \mu_k)^T$$
 (13)

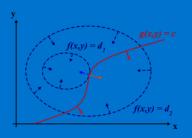


Finally, when we maximize the log likelihood with respect to  $\pi$ , we need to take the constraint  $\Sigma_{k=1}^K \pi_k = 1$  into consideration. This is done by using the Lagrange multiplier.



### The Lagrange Multiplier

We want to maximize f(x,y) subject g(x,y)=c. Let  $\Lambda(x,y\lambda)=f(x,y)+\lambda(g(x,y)-c)$ . Then if  $(x_0,y_0)$  is a maximum of the original f, there exists  $(x_0,y_0,\lambda_0)$  is a stationary point for the  $\Lambda$  function.



The contour lines of f and g touch when the tangent vectors of the contour lines are parallel. Since the gradient of a function is perpendicular to the contour lines, this is the same as saying that the gradients of f and g are parallel.

### The Lagrange Multiplier

So 
$$\nabla_{x,y}f=-\lambda\nabla_{x,y}g.$$
 Combining with the constraint, we get  $\nabla_{x,y,\lambda}\Lambda=0$ 

Now, we apply the Lagrange Multiplier to maximize with respect to  $\pi$ . We will be maximizing

$$lnp(x|\pi,\mu,\Sigma) + \lambda(\Sigma_{k=1}^K \pi_k - 1)$$
(14)

By maximizing it we will get

$$\pi_k = \frac{N_k}{N}$$



We have to note that the solutions 12, 13, 15 are not closed. Because the responsibilities  $\gamma(z_{nk})$  depend on the parameters. However, they suggest a iterative scheme for finding a solution to the maximum likelihood problem.



**Initialize** Initialize the parameters  $\mu_k$ ,  $\Sigma_k$ , and  $\pi_k$  **E-step** Evaluate the responsibilities using the current parameter values.

$$\gamma(z_{nk}) = \frac{\mathcal{N}(x_n | \mu_k, \Sigma_k)}{\sum_{k=1}^K \pi_k \mathcal{N}(x_n | \mu_k, \Sigma_k)}$$
(16)



**M-step** Re-estimate the parameters using the current responsibilities.

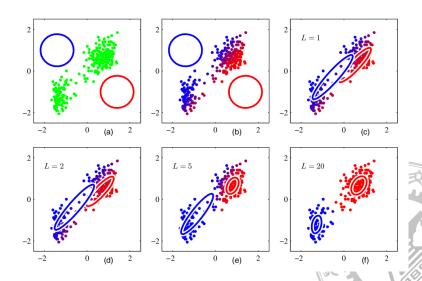
$$\mu_k^{new} = \frac{1}{N_k} \sum_{n=1}^N \gamma(z_{nk}) x_n$$

$$\sum_k^{new} = \frac{1}{N_k} \gamma_k(z_{nk}) (x_n - \mu_k) (x_n - \mu_k)^T$$

$$\pi_k^{new} = \frac{N_k}{N}$$
(17)

**Likelihood** Recalculate the log likelihood function to see if it converges, if not, go to step 1 again.

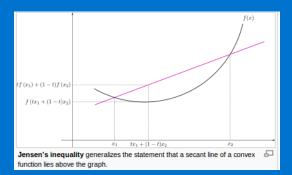
## An Example



Now we've know the inituition of the EM algorithm, and we are going to proof its property. We will need the Jensen Inequality.

### Jensen's Inequality

If X is a random variable and  $\varphi$  is a convex function. Then  $\varphi(E[X]) \leq E[\varphi(X)].$ 



### The General EM

#### Theorem

In each iteration, the E-M algorithm gives a solution that gives higher likelihood.

*Proof:*For simplicity, we denote all parameters as  $\theta$ . Remembering the latent variable Z, we can now write the log likelihood as

$$lnp(X|\theta) = ln\{\Sigma_z p(X, z|\theta)\}$$
(18)

In the E-step, we are are actually forming an ancillary function(go back to 12, 13, 15 and check it):

$$Q(\theta, \theta^{old}) = \Sigma_z p(z|X, \theta^{old}) lnp(X, z|\theta)$$
(19)

Then, in the M-step, we are maximizing  $Q(\theta, \theta^{old})$ , and get the  $\rho new$ 

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### The General EM

Now we use Jensen's inequality to transform the log likelihood function.

$$lnp(X|\theta) = ln\{\Sigma_z \frac{q(z)p(X,z|\theta)}{q(z)}\}$$

$$\geq \Sigma_z q(z) ln(\frac{p(X,z|\theta)}{q(z)})$$

$$= \Sigma_z q(z) ln(p(X,z|\theta)) - \Sigma_z q(z) ln(q(z))$$
(20)

To continue we need to prove a lemma first.



#### lemma

If  $q(z) = p(z|\theta, X)$ , equation 20 becomes an equality. *Proof:* 

$$\begin{split} lnp(X|\theta) - \Sigma_z q(z) ln(\frac{p(X,z|\theta)}{q(z)}) \\ = \Sigma_z q(z) \{ ln(p(X|\theta)) - ln(\frac{p(X,z|\theta)}{q(z)}) \} \\ = \Sigma_z q(z) \{ ln(\frac{q(z)}{p(z|\theta,X)}) \} \end{split}$$

 $= \sum_{z} q(z) \ln(1) = 0$   $= \sum_{z} q(z) \ln(1) = 0$ 

(21)

### The General EM

completing the proof

Now we let  $q(z) = p(z|X, \theta^{old})$ , then we can complete our proof.

$$ln(p(X|\theta^{new}) \ge \Sigma_z q(z) ln(p(X, z|\theta^{new})) - \Sigma_z q(z) ln(q(z))$$

$$= \mathcal{Q}(\theta^{new}, \theta^{old}) - \Sigma_z q(z) ln(q(z))$$

$$\ge \mathcal{Q}(\theta^{old}, \theta^{old}) - \Sigma_z q(z) ln(q(z))$$

$$= ln(p(X|\theta^{old}))$$
(22)

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# Bibliography

► Some pictures are from Wiki or PRML

