2016/11/19 Udacity Reviews





## **PROJECT**

## Train a Smartcab to Drive A part of the Machine Learning Engineer Nanodegree Program PROJECT REVIEW CODE REVIEW NOTES SHARE YOUR ACCOMPLISHMENT! 🏏 🖪 **Requires Changes** 3 SPECIFICATIONS REQUIRE CHANGES You have made great progress. Think through the questions I asked and put your thoughts in your report. I hope they are helpful for your understanding of the whole project. 实施基础驾驶智能体 学生能够实施智能体接受指定输入所需的接口。 驾驶智能体产生有效输出(one of None、'forward'、'left'、'right'),以响应输入。 驾驶智能体在模拟器中正常运行,未产生任何错误。奖励和惩罚没有必要——我们允许智能体出错。 确认并更新状态 $\mathbb{C}$ 学生确认了模拟驾驶智能体和环境的状态,并给出了合理的理由。 From your report, it is not clear what are included in the agent state. You mentioned about "Time Left", "Traffic state", "Next\_waypoint", and "Locations". Are they the states you are considering for agent states? In your code, you are using system "inputs" for the state. Could you please clearly explain what are the "factors" you are using for the agent state? Remember, agent uses the states to make decision for actions and learn from the result (action and reward). For Question 2, it is not still not clear what should be included and what should not. You have listed "location" and "deadline" in "factors of states", but in the next "states of numbers" part they are not in calculation. Are they in or out? Is there any confusion This is the core of Q-Learning and this whole project, so please make sure to address this clearly in your report to demonstrate you have thought it through. 驾驶智能体运行时会根据当前输入更新自己的状态。确切的状态并不重要,也无需与输入有关系,但应该在运行时进行相应更改。 实现 Q 学习

驾驶智能体会正确更新 Q 值的表/映射,从而实施 Q 学习算法。

上記書了名祭前所力変化、升展性了合理解導。  「登職能体不循膀珠之間開発 日前地、井田平弘前接為下草地  「のは your Queaming py and it runs greattle  「のは you have a good understanding of those parameters, you can do more combinations.  「 What spallow values you used for running those combinations (durn) are them in the combination table? You mentioned in your report 0.1 or 0.01. Are they good enough? Can you if yo.05.01, 0.15, and 0.2 to see whether epilion makes differences.  「 What spallow values you used for running those combinations (durn) are them in the combination table? You mentioned in your report 0.1 or 0.01. Are they good enough? Can you if yo.05.01, 0.15, and 0.2 to see whether epilion makes differences.  「 Whose pallow usexes vale, how many 100 can lay us have not long the trans in your combination values your report 0.1 or 0.01. Are they good enough? Can you if you were for the produce the randomness.  **Arameter tuning is very important step to improve agent performance. Make sure to do it thoroughly. Make sure to report and present it thoroughly to demonstrate you have mastered this part.  **ARE特別を維持与予測を定期的反応角度対応で接受性的対性。  The optimal polity is more related the ultimate good of this proget, what we want to active by training the agent.  **Belower matter that, agent in trained in a supplified simulation environment. All the conditions, ag, ment, asypoint, traffic lights, step remarks, and deadline, are all designed to help the agent to learn. Any charges of those conditions shall affect the agent performance.  ***What this mind, county on please use the performance of your agent and compare it to the optimal policy?  ** Is your agent learning the optimal policy wall?  ** anything that limits the agent to fully learn the optimal policy?  ** In the agent can achieve 100% success rate, is it good enough to run in the real world?  ** the main points for this question are:  **What is the optimal policy  ** If the agent can ha	ireat job!	
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課題教育部体  Page 12 を		<b>→</b>
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