

Hooking-Up: ANCHOR POINT

Wireless direct link to your Handibot

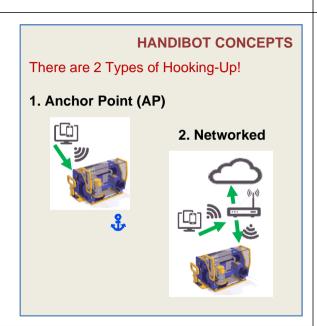


HANDIBOT CONCEPTS

There are 2 Types of Hooking-Up!

- Two ways you can wirelessly link your Handibot to vour device -- smart-phone, tablet, PC, Mac (these methods make different use of Wi-Fi technology).
- 1. Anchor Point (AP) mode provides a direct wireless link
 - it's off-line, no network or router needed
 - always available to you
 - used in setting up a network connection
 - IP address is defined (192.168.42.1)
- 2. Networked mode wirelessly links over vour local network.
 - lets your device access other resources
 - allows internet access, FabMo updates
 - IP address must be determined





These instructions are for Method 1, Hooking-up in ANCHOR POINT (AP) Mode

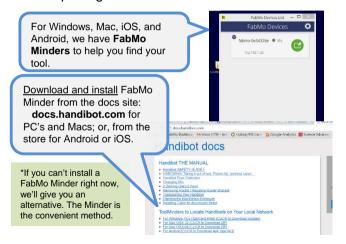
- For a lot of Handibot work you will only need to be directly linked to your your Handibot from your device.
- Anchor Point mode provides a direct connection you can use anywhere, even when no network or Internet is available -- such as on a jobsite.
- And, Anchor Point mode is used to put your Handibot on a network.
- SO. ANCHOR POINT here we come ...

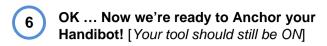


There is one thing that will be helpful in preparation for Anchor Point and will be even more useful later for Networked mode linking.

1. It is a method to identify your tool's IP address and open the its software, once you've made a link. Let's get what you need...

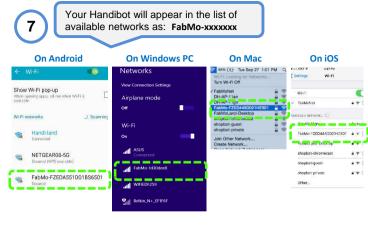
A FabMo Minder App for your device will give you a method for identifying your Handibot and opening the software.*





Open the **WiFi manager** or **Network manager** on <u>your computer or device</u>.

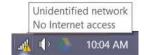




<u>Link into your Handibot's AP mode</u> as you would to a Wi-Fi network.

Use the password: go2fabmo

After your device's network manager connects to your Handibot it will probably say something like: Unidentified network, No Internet Acess".



That's OK because we took your device off the internet to give **you a direct link** right into your Handibot – Anchor Point (AP) mode access.

AP mode is the linkage that we will use to set-up and test your tool. Your tool can always fall back to AP mode (good for job sites, etc...). You also will put your tool on a network from AP Mode.

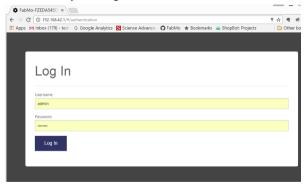
9 Start your **Tool Minder** and in a minute or so, your tool's software interface should appear.



[ALTERNATIVELY you can get to your tool's software by entering "192.168.42.1" in the address bar of your internet browser*.]



At the beginning of any new session, you will be asked for your log-on credentials to the tool.



Initially log in with:

Username: admin Password: go2fabmo



FabMo Dashboard

We call the software platform on which your Handibot runs. **FabMo.**

{It's short for digital Fabrication and Motion platform.}

And we call the software interface in the browser that you are now viewing, the **Dashboard**.





At this point you could continue to the instructions for putting your tool onto a network if you have grown anxious about being off the internet for so long ...

- However, we'd like to first explore the Dashboard, do a quick trial run of your tool, making a test cut -- before getting distracted with the neat network capabilities of your Handibot.
- * Please go to the <u>next section</u> of the manual for the **Quick Start and Test Cut**.