12주차(2/2)

심층 신경망 1

파이썬으로배우는기계학습

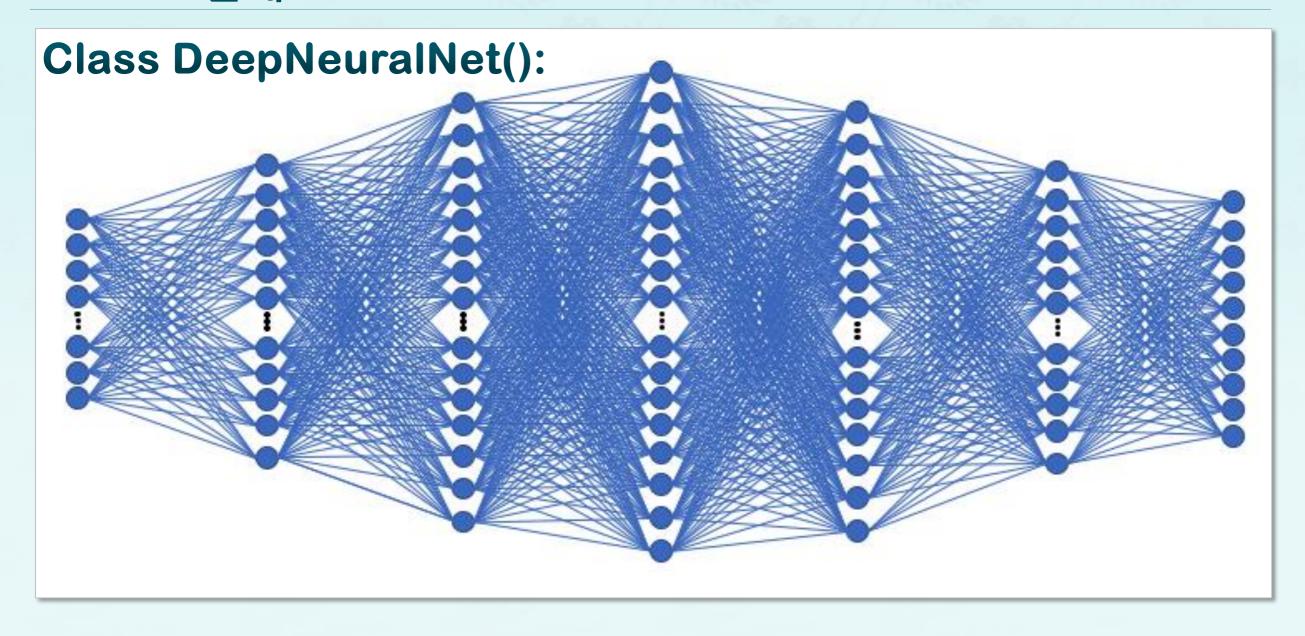
한동대학교 김영섭교수

심층 신경망 1

- 학습 목표
 - 심층 신경망을 학습한다.
 - 은닉층의 개수에 따른 성능을 확인한다.

- 학습 내용
 - 심층 신경망 이해하기
 - 심층 신경망 구현하기
 - 심층 신경망 성능 확인하기

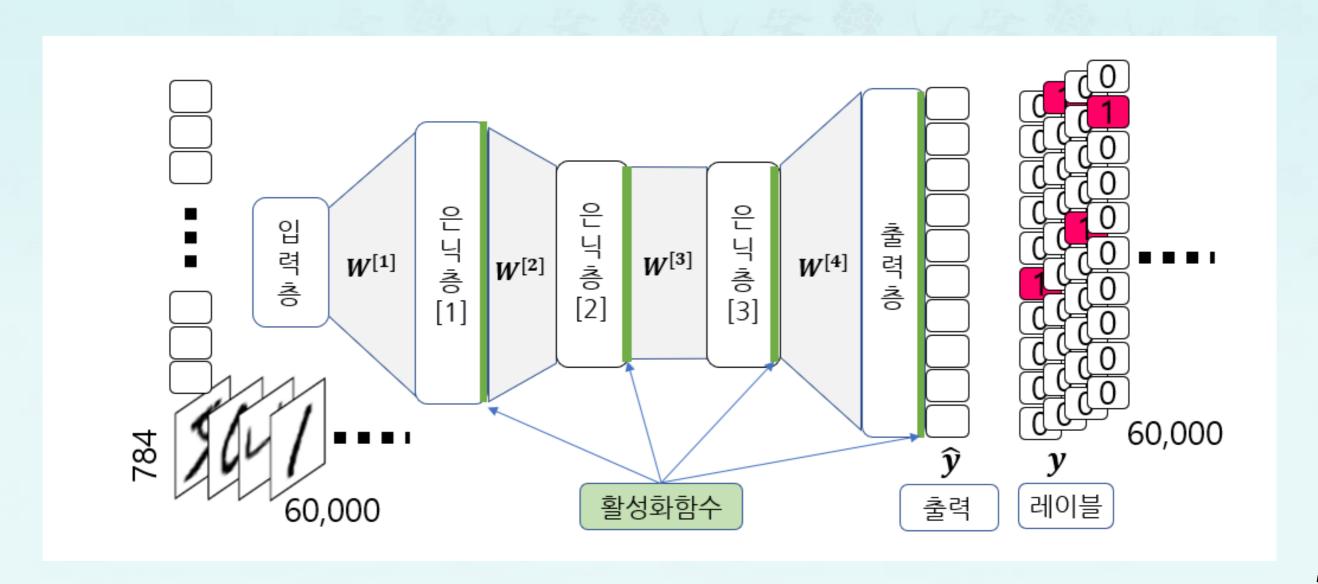
1. DNN 클래스



1. DNN 클래스 : 코드 개요

```
class DeepNeuralNet():
        """ implements a deep neural net.
            Users may specify any number of layers.
            net arch -- consists of a number of neurons in each layer
 4
 5
        def __init__(self, net_arch, activate = None,
 6
                     eta = 1.0, epochs = 100, random seed = 1):
 8
            pass
 9
10
        def forpass(self, A0):
11
            pass
12
13
        def backprop(self, Z, A, Y):
14
            pass
15
16
        def fit(self, X, y):
17
            pass
18
        def predict(self, X):
19
20
            pass
21
22
        def evaluate(self, Xtest, ytest):
23
            pass
```

2. DNN 활성화 함수 : 구조



2. DNN 활성화 함수: tanh

$$tanh(x) = \frac{e^x - e^{-x}}{e^x + e^{-x}} = \frac{1 - e^{-2x}}{1 + e^{-2x}}$$

```
def tanh(x):
        return (1.0 - np.exp(-2 * x))/(
               1.0 + np.exp(-2 * x))
   def tanh d(x):
        return (1 + tanh(x)) * (1 - tanh(x))
 6
   def sigmoid(x):
       \#x = np.clip(x, -500, 500)
    return 1 / (1 + np.exp((-x)))
10
11
12
   def sigmoid d(x):
        return sigmoid(x) * (1 - sigmoid(x))
13
14
15
   def relu(x):
        return np.maximum(x, 0)
16
17
18
   def relu_d(x):
19
      x[x<=0] = 0
      x[x>0] = 1
20
21
        return x
```

2. DNN 활성화 함수: tanh

$$tanh(x) = \frac{e^x - e^{-x}}{e^x + e^{-x}} = \frac{1 - e^{-2x}}{1 + e^{-2x}}$$

$$\frac{d}{dx} \tanh(x) = 1 - \left(\frac{2}{1 + e^{-2x}} - 1\right)^2$$
= 1 - \tanh^2(x)

```
1 def tanh(x):
       return (1.0 - np.exp(-2 * x))/(
               1.0 + np.exp(-2 * x))
5 def tanh_d(x):
       return (1 + tanh(x)) * (1 - tanh(x))
   def sigmoid(x):
       \#x = np.clip(x, -500, 500)
10
       return 1 / (1 + np.exp((-x)))
11
12
   def sigmoid d(x):
       return sigmoid(x) * (1 - sigmoid(x))
13
14
   def relu(x):
15
16
       return np.maximum(x, 0)
17
18
   def relu_d(x):
19
    x[x<=0] = 0
      x[x>0] = 1
20
21
       return x
```

2. DNN 활성화 함수: sigmoid

$$\sigma(x) = \frac{1}{1 + e^{-x}} = \frac{1}{1 + \frac{1}{e^x}}$$

```
def tanh(x):
        return (1.0 - np.exp(-2 * x))/(
                1.0 + np.exp(-2 * x))
 4
   def tanh_d(x):
        return (1 + tanh(x)) * (1 - tanh(x))
 8 def sigmoid(x):
       #x = np.clip(x, -500, 500)
10
      return 1 / (1 + np.exp((-x)))
12
    def sigmoid d(x):
        return sigmoid(x) * (1 - sigmoid(x))
13
14
15
   def relu(x):
        return np.maximum(x, 0)
16
17
18
   def relu_d(x):
       x[x<=0] = 0
19
       x[x>0] = 1
20
21
        return x
```

2. DNN 활성화 함수: sigmoid

$$\sigma(x) = \frac{1}{1 + e^{-x}} = \frac{1}{1 + \frac{1}{e^x}}$$

$$\frac{d}{dx}\sigma(x) = \frac{1}{1 + e^{-x}} (1 - \frac{1}{1 + e^{-x}})$$
$$= \sigma(x)(1 - \sigma(x))$$

```
def tanh(x):
        return (1.0 - np.exp(-2 * x))/(
               1.0 + np.exp(-2 * x))
 4
   def tanh_d(x):
        return (1 + tanh(x)) * (1 - tanh(x))
8 def sigmoid(x):
       \#x = np.clip(x, -500, 500)
10
       return 1 / (1 + np.exp((-x)))
12 def sigmoid_d(x):
       return sigmoid(x) * (1 - sigmoid(x))
13
   def relu(x):
16
        return np.maximum(x, 0)
17
18
   def relu_d(x):
19
       x[x<=0] = 0
      x[x>0] = 1
20
21
        return x
```

2. DNN 활성화 함수: ReLU

$$Relu(x) = \begin{cases} x & if \ x \ge 0 \\ 0 & otherwise \end{cases}$$

```
def tanh(x):
        return (1.0 - np.exp(-2 * x))/(
                1.0 + np.exp(-2 * x))
 4
   def tanh_d(x):
        return (1 + tanh(x)) * (1 - tanh(x))
 6
   def sigmoid(x):
       \#x = np.clip(x, -500, 500)
10
        return 1 / (1 + np.exp((-x)))
11
12
   def sigmoid_d(x):
        return sigmoid(x) * (1 - sigmoid(x))
13
15 def relu(x):
16
        return np.maximum(x, 0)
18
   def relu_d(x):
        x[x<=0] = 0
19
        x[x>0] = 1
20
21
        return x
```

2. DNN 활성화 함수: ReLU

$$Relu(x) = \begin{cases} x & if \ x \ge 0 \\ 0 & otherwise \end{cases}$$

$$\frac{d}{dx}Relu(x) = \begin{cases} 1 & if \ x \ge 0 \\ 0 & otherwise \end{cases}$$

```
def tanh(x):
        return (1.0 - np.exp(-2 * x))/(
                1.0 + np.exp(-2 * x))
 4
   def tanh_d(x):
        return (1 + tanh(x)) * (1 - tanh(x))
 6
   def sigmoid(x):
       \#x = np.clip(x, -500, 500)
        return 1 / (1 + np.exp((-x)))
10
11
   def sigmoid_d(x):
12
        return sigmoid(x) * (1 - sigmoid(x))
13
14
15
   def relu(x):
16
        return np.maximum(x, 0)
18 def relu_d(x):
       x[x<=0] = 0
19
20
       x[x>0] = 1
        return x
```

2. DNN 활성화 함수

```
def tanh(x):
        return (1.0 - np.exp(-2 * x))/(
               1.0 + np.exp(-2 * x))
 3
   def tanh_d(x):
        return (1 + tanh(x)) * (1 - tanh(x))
 6
   def sigmoid(x):
       #x = np.clip(x, -500, 500)
       return 1 / (1 + np.exp((-x)))
10
11
   def sigmoid_d(x):
        return sigmoid(x) * (1 - sigmoid(x))
13
14
   def relu(x):
        return np.maximum(x, 0)
16
17
18
   def relu_d(x):
    x[x<=0] = 0
19
    x[x>0] = 1
20
       return x
21
```

3. DNN 구현: 생성자

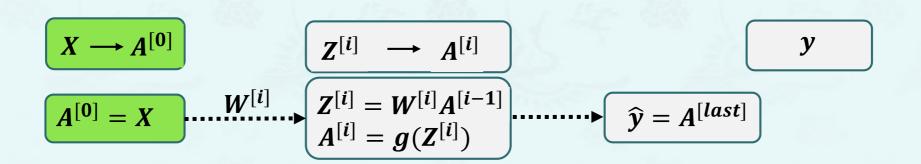
```
def init (self, net arch, activate = None,
            eta = 1.0, epochs = 100, random seed = 1):
    self.eta = eta
   self.epochs = epochs
   self.net arch = net arch
   self.layers = len(net arch)
   self.W = []
   self.g = [lambda x: sigmoid(x) for _ in range(self.layers)]
   self.g prime = [lambda x: sigmoid d(x) for in range(self.layers)]
   if activate is not None:
       for i, (g, g_prime) in enumerate(zip(activate[::2], activate[1::2])):
           self.g[i+1] = g
           self.g prime[i+1] = g prime
   np.random.seed(random seed)
   self.W = [[None]] ## the first W0 is not used.
   for layer in range(self.layers - 1):
       w = 2 * np.random.rand(self.net_arch[layer+1],
                              self.net arch[layer]) - 1
       self.W.append(w)
```

3. DNN 구현: 생성자

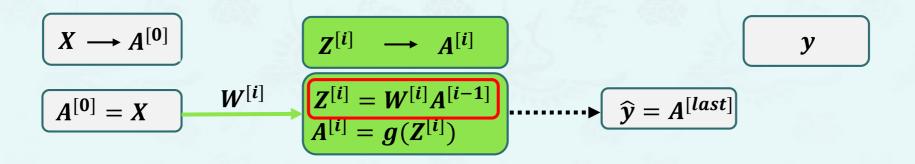
```
def init (self, net arch, activate = None,
                                     eta = 1.0, epochs = 100, random_seed = 1):
                             self.eta = eta
                             self.epochs = epochs
                            self.net arch = net arch
                             self.layers = len(net arch)
                            self.W = []
                            self.g = [lambda x: sigmoid(x) for _ in range(self.layers)]
                             self.g prime = [lambda x: sigmoid d(x) for in range(self.layers)]
                            if activate is not None:
                                for i, (g, g_prime) in enumerate(zip(activate[::2], activate[1::2])):
                                    self.g[i+1] = g
                                    self.g prime[i+1] = g prime
                            np.random.seed(random seed)
                            self.W = [[None]] ## the first W0 is not used.
                            for layer in range(self.layers - 1):
                                w = 2 * np.random.rand(self.net_arch[layer+1],
(뒷층 노드 수, 앞층 노드 수)
                                                       self.net arch[layer]) - 1
                                self.W.append(w)
```

3. DNN 구현: fit() 메소드

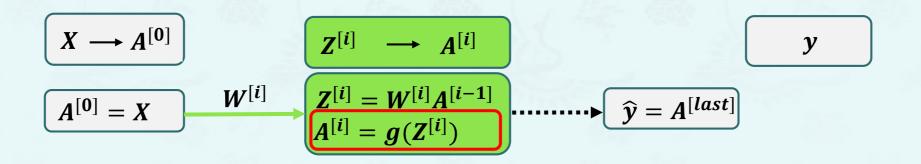
```
def forpass(self, A0):
    Z = [[None]] # Z0 is not used.
    A = [] # A0 = X0 is used.
    A.append(A0)
    for i in range(1, len(self.W)):
        z = np.dot(self.W[i], A[i-1])
        Z.append(z)
        a = self.g[i](z)
        A.append(a)
    return Z, A
```



```
def forpass(self, A0):
    Z = [[None]] # Z0 is not used.
    A = [] # A0 = X0 is used.
    A.append(A0)
    for i in range(1, len(self.W)):
        z = np.dot(self.W[i], A[i-1])
        Z.append(z)
        a = self.g[i](z)
        A.append(a)
    return Z, A
```



```
def forpass(self, A0):
    Z = [[None]] # Z0 is not used.
    A = [] # A0 = X0 is used.
    A.append(A0)
    for i in range(1, len(self.W)):
        z = np.dot(self.W[i], A[i-1])
        Z.append(z)
        a = self.g[i](z)
        A.append(a)
    return Z, A
```



```
1 def fit(self, X, y):
    def backprop(self, Z, A, Y):
                                                                             self.cost = []
         E = [None for x in range(self.layers)]
                                                                             for epoch in range(self.epochs):
        dZ = [None for x in range(self.layers)]
                                                                                 Z, A = self.forpass(X)
                                                                               cost = self.backprop(Z, A, y)
        11 = self.layers - 1
                                                                                 self.cost .append(np.sqrt(np.sum(cost * cost)))
        error = Y - A[11]
                                                                            return self
        E[11] = error
        dZ[11] = error * self.g_prime[11](Z[11])
 9
                                                                           X \longrightarrow A^{[0]}
        for i in range(self.layers-2, 0, -1):
10
             E[i] = np.dot(self.W[i+1].T, E[i+1])
11
12
             dZ[i] = E[i] * self.g prime[i](Z[i])
                                                                           A^{[0]} = X
13
        m = Y.shape[0] # number of samples
14
                                                                               W^{[i]}
                                                                                                                                   y
        for i in range(ll, 0, -1):
15
             self.W[i] += self.eta * np.dot(dZ[i], A[i-1].T) / m
16
17
         return error
                                                                           Z^{[i]} = W^{[i]}A^{[i-1]}
                                                                                                          \widehat{y} = A^{[last]}
                                                                           A^{[i]} = g(Z^{[i]})
                                                                      W^{[last]} += dZ^{[last]} \cdot A^{[last-1]T}
                            W^{[i]} += dZ^{[i]} \cdot A^{[i-1]T} \mid \bullet \cdots 
                                                                                                  E^{[last]} = y - \widehat{y}
                                                   E^{[i]} = W^{[i+1]T}E^{[i+1]}
                                                   dZ^{[i]} = E^{[i]}g'(Z^{[i]})
                                                                                           dZ^{[last]} = E^{[last]}g'(Z^{[last]})
```

```
def backprop(self, Z, A, Y):
         E = [None for x in range(self.layers)]
         dZ = [None for x in range(self.layers)]
         11 = self.layers - 1
         error = Y - A[11]
         E[11] = error
         dZ[11] = error * self.g_prime[11](Z[11])
 9
                                                                               X \longrightarrow A^{[0]}
         for i in range(self.layers-2, 0, -1):
10
              E[i] = np.dot(self.W[i+1].T, E[i+1])
11
12
              dZ[i] = E[i] * self.g prime[i](Z[i])
                                                                               A^{[0]} = X
13
14
         m = Y.shape[0] # number of samples
                                                                                   W^{[i]}
                                                                                                                                          y
         for i in range(ll, 0, -1):
15
              self.W[i] += self.eta * np.dot(dZ[i], A[i-1].T) / m
16
17
         return error
                                                                               Z^{[i]} = W^{[i]}A^{[i-1]}
                                                                                                                   \widehat{y} = A^{[last]}
                                                                               A^{[i]} = g(\mathbf{Z}^{[i]})
                                                                          W^{[last]} += dZ^{[last]} \cdot A^{[last-1]T}
                              W^{[i]} += dZ^{[i]} \cdot A^{[i-1]T} \mid \bullet \cdots
                                                                                                       E^{[last]} = y - \widehat{y}
                                                      E^{[i]} = W^{[i+1]T}E^{[i+1]}
                                                      dZ^{[i]} = E^{[i]}g'(Z^{[i]})
                                                                                                dZ^{[last]} = E^{[last]}g'(Z^{[last]})
```

```
def backprop(self, Z, A, Y):
         E = [None for x in range(self.layers)]
         dZ = [None for x in range(self.layers)]
         11 = self.layers - 1
         error = Y - A[11]
         E[11] = error
         dZ[11] = error * self.g_prime[11](Z[11])
                                                                               X \longrightarrow A^{[0]}
         for i in range(self.layers-2, 0, -1):
              E[i] = np.dot(self.W[i+1].T, E[i+1])
12
              dZ[i] = E[i] * self.g prime[i](Z[i])
                                                                              A^{[0]} = X
13
         m = Y.shape[0] # number of samples
14
                                                                                  W^{[i]}
                                                                                                                                        y
         for i in range(ll, 0, -1):
15
              self.W[i] += self.eta * np.dot(dZ[i], A[i-1].T) / m
16
17
         return error
                                                                              Z^{[i]} = W^{[i]}A^{[i-1]}
                                                                                                                 \widehat{y} = A^{[last]}
                                                                              A^{[i]} = g(Z^{[i]})
                                                                         W^{[last]} += dZ^{[last]} \cdot A^{[last-1]T}
                              W^{[i]} += dZ^{[i]} \cdot A^{[i-1]T} \mid \bullet \cdots
                                                                                                      E^{[last]} = y - \widehat{y}
                                                      E^{[i]} = W^{[i+1]T}E^{[i+1]}
                                                     dZ^{[i]} = E^{[i]}g'(Z^{[i]})
                                                                                               dZ^{[last]} = E^{[last]}g'(Z^{[last]})
```

```
def backprop(self, Z, A, Y):
         E = [None for x in range(self.layers)]
         dZ = [None for x in range(self.layers)]
        11 = self.layers - 1
         error = Y - A[11]
         E[11] = error
         dZ[11] = error * self.g_prime[11](Z[11])
 9
                                                                             X \longrightarrow A^{[0]}
         for i in range(self.layers-2, 0, -1):
10
             E[i] = np.dot(self.W[i+1].T, E[i+1])
11
12
             dZ[i] = E[i] * self.g prime[i](Z[i])
                                                                             A^{[0]} = X
13
         m = Y.shape[0] # number of samples
14
                                                                                W^{[i]}
                                                                                                                                      y
15
         for i in range(ll, 0, -1):
             self.W[i] += self.eta * np.dot(dZ[i], A[i-1].T) / m
16
                                                                             Z^{[i]} = W^{[i]}A^{[i-1]}
17
         return error
                                                                                                             \widehat{y} = A^{[last]}
                                                                            A^{[i]} = g(Z^{[i]})
                                                                        W^{[last]} += dZ^{[last]} \cdot A^{[last-1]T}
                             W^{[i]} += dZ^{[i]} \cdot A^{[i-1]T}
                                                                                                    E^{[last]} = y - \widehat{y}
                                                    E^{[i]} = W^{[i+1]T}E^{[i+1]}
                                                    dZ^{[i]} = E^{[i]}g'(Z^{[i]})
                                                                                             dZ^{[last]} = E^{[last]}g'(Z^{[last]})
```

4. fit() 메소드: 오차 계산

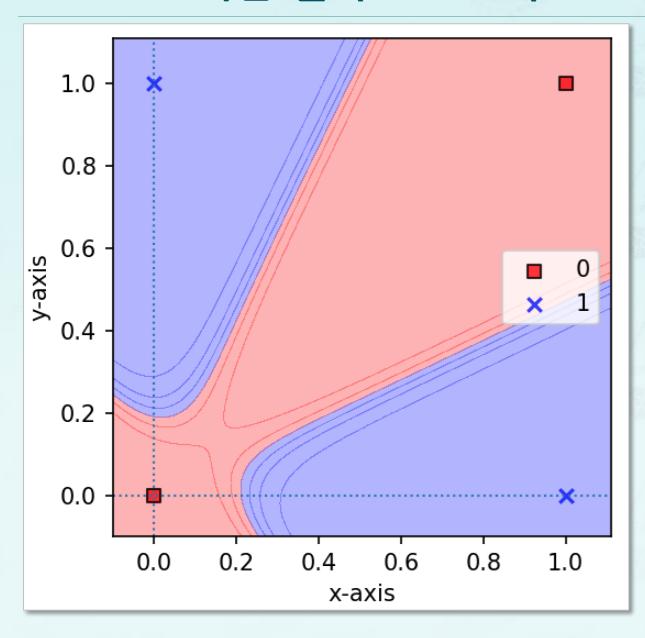
5. DNN 학습 결과: XOR 테스트

```
import joy
X = np.array([[0, 0, 1, 1], [0, 1, 0, 1]])
y = np.array([0, 1, 1, 0])
dnn = DeepNeuralNet([2, 4, 2, 1], eta = 0.5, epochs = 5000).fit(X, y)

joy.plot_decision_regions(X.T, y, dnn)
plt.xlabel('x-axis')
plt.ylabel('y-axis')
plt.legend(loc='best')
plt.show()
```

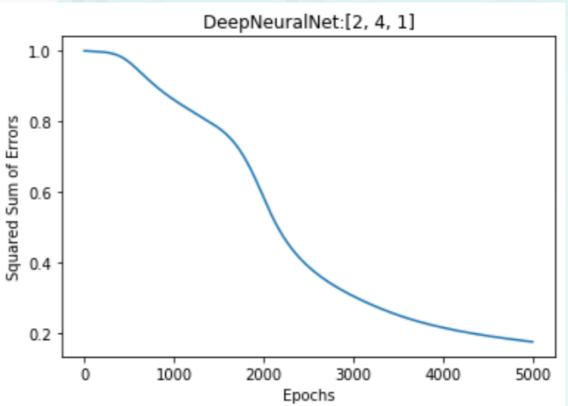
[입력층, 은닉층, 은닉층, 출력층]의 노드 수

5. DNN 학습 결과: XOR 테스트



5. DNN 학습 결과: XOR 테스트

은닉층 1개



5. DNN 학습 결과: 비교를 위한 학습 코딩

```
dnn1 = DeepNeuralNet([2,4,1], eta = 0.5, epochs = 5000).fit(X, y)
g = [sigmoid, sigmoid_d, sigmoid_d, sigmoid_d, sigmoid_d]
dnn2 = DeepNeuralNet([2,4,2,1], activate=g, eta = 0.5, epochs = 5000).fit(X, y)
plt.plot(range(len(dnn1.cost_)), dnn1.cost_, label='{}'.format(dnn1.net_arch))
plt.plot(range(len(dnn2.cost_)), dnn2.cost_, label='{}'.format(dnn2.net_arch))
plt.title('DeepNeuralNet:{} vs {}'.format(dnn1.net_arch, dnn2.net_arch))
plt.xlabel('Epochs')
plt.ylabel('Squared Sum of Errors')
plt.legend(loc='best')
plt.show()
```

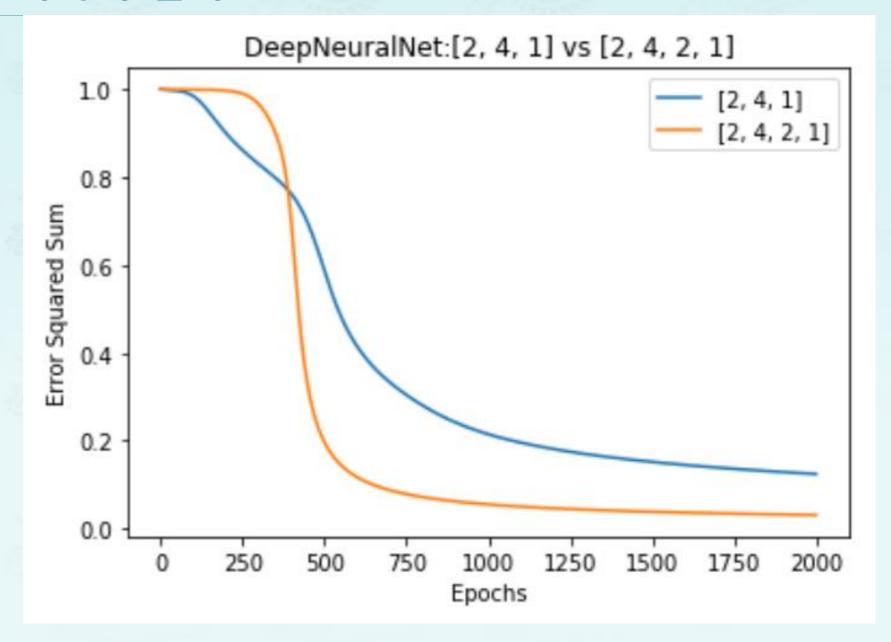
5. DNN 학습 결과: 비교를 위한 학습 코딩

```
dnn1 = DeepNeuralNet([2,4,1], eta = 0.5, epochs = 5000).fit(X, y)
g = [sigmoid, sigmoid_d, sigmoid_d, sigmoid_d]
dnn2 = DeepNeuralNet([2,4,2,1], activate=g, eta = 0.5, epochs = 5000).fit(X, y)
plt.plot(range(len(dnn1.cdst_)), dnn1.cost_, label='{}'.format(dnn1.net_arch))
plt.plot(range(len(dnn2.cdst_)), dnn2.cost_, label='{}'.format(dnn2.net_arch))
plt.title('DeepNeuralNet:{} vs {}'.format(dnn1.net_arch, dnn2.net_arch))
plt.xlabel('Epochs')
plt.ylabel('Squared Sum of Errors')
plt.legend(loc='best')
plt.show()
으닉층 2개
```

5. DNN 학습 결과: 비교를 위한 학습 코딩

```
dnn1 = DeepNeuralNet([2,4,1], eta = 0.5, epochs = 5000).fit(X, y)
g = [sigmoid, sigmoid_d, sigmoid_d, sigmoid_d, sigmoid_d]
dnn2 = DeepNeuralNet([2,4,2,1], activate=g, eta = 0.5, epochs = 5000).fit(X, y)
plt.plot(range(len(dnn1.cost_)), dnn1.cost_, label='{}'.format(dnn1.net_arch))
plt.plot(range(len(dnn2.cost_)), dnn2.cost_, label='{}'.format(dnn2.net_arch))
plt.title('DeepNeuralNet:{} vs {}'.format(dnn1.net_arch, dnn2.net_arch))
plt.xlabel('Epochs')
plt.ylabel('Squared Sum of Errors')
plt.legend(loc='best')
plt.show()
```

5. DNN 학습 결과: 시각화 결과



6. DNN 학습: 각 층별로 활성화 함수 지정

```
g1 = [tanh, tanh_d, sigmoid, sigmoid_d, sigmoid_d]
dnn1 = DeepNeuralNet([2,4,2,1], activate=g1, eta = 0.5, epochs = 5000).fit(X, y)
g2 = [sigmoid, sigmoid_d, sigmoid_d, sigmoid_d, sigmoid_d]
dnn2 = DeepNeuralNet([2,4,2,1], activate=g2, eta = 0.5, epochs = 5000).fit(X, y)
plt.plot(range(len(dnn1.cost_)), dnn1.cost_, label='[tanh, sigmoid, sigmoid]')
plt.plot(range(len(dnn2.cost_)), dnn2.cost_, label='[sigmoid, sigmoid, sigmoid]')
plt.title('DeepNeuralNet: tanh vs sigmoid')
plt.xlabel('Epochs')
plt.ylabel('Squared Sum of Errors')
plt.legend(loc='best')
plt.show()
```

6. DNN 학습: 각 층별로 활성화 함수 지정

```
g1 = [tanh, tanh_d, sigmoid, sigmoid_d, sigmoid, sigmoid_d]
dnn1 = DeepNeuralNet([2,4,2,1], activate=g1, eta = 0.5, epochs = 5000).fit(X, y)
g2 = [sigmoid, sigmoid_d, sigmoid_d, sigmoid_d, sigmoid_d]
dnn2 = DeepNeuralNet([2,4,2,1], activ
                                                         DeepNeuralNet: tanh vs sigmoid
plt.plot(range(len(dnn1.cost_)), dnn1
                                             1.0
                                                                        [tanh, sigmoid, sigmoid]
plt.plot(range(len(dnn2.cost_)), dnn2
                                                                        [sigmoid, sigmoid, sigmoid]
plt.title('DeepNeuralNet: tanh vs sig
                                             0.8
plt.xlabel('Epochs')
                                           Sum
plt.ylabel('Squared Sum of Errors')
                                           Error Squared
                                             0.6
plt.legend(loc='best')
plt.show()
                                             0.4
                                             0.2
                                             0.0
                                                      250
                                                           500
                                                                750
                                                                    1000
                                                                         1250
                                                                              1500
                                                                                  1750
                                                                                       2000
                                                                   Epochs
```

심층 신경망 1

- 학습 정리
 - 심층 신경망인 DeepNeuralNet 클래스 구현
 - 심층 신경망의 은닉층 갯수에 따른 성능 확인