10주차(1/3)

다층 신경망 모델링

파이썬으로배우는기계학습

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다층 신경망 모델링

- 학습 목표
 - 미분의 연쇄법칙을 학습한다.
 - 오차함수의 행렬 표기에서 미분하는 방법을 학습한다.
 - 다층 인공 신경망의 행렬 모델을 학습한다.
- 학습 내용
 - 미분의 연쇄법칙
 - 오차함수의 행렬 미분
 - 다층 인공 신경망 행렬 모델

1. 연쇄법칙: 연쇄법칙이란?

 어떤 변수의 변화가 매개변수의 변화를 일으키고 그 후 최종 함수 값의 변화를 유발하는 것

1. 연쇄법칙: 연쇄법칙의 예

$$F(x) = f(g(x))$$

$$F'(x) = f'(g(x))g'(x)$$

1. 연쇄법칙: 연쇄법칙의 예

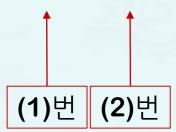
$$F(x) = f(g(x))$$

$$F'(x) = f'(g(x))g'(x)$$

라이프니츠 표기법

$$y = f(u), u = g(x)$$
 일 때,

$$\frac{dy}{dx} = \frac{dy}{du} \cdot \frac{du}{dx}$$



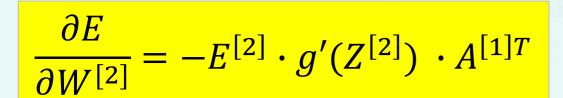
2. $W^{[2]}$ 의 오차함수 미분 : 복습

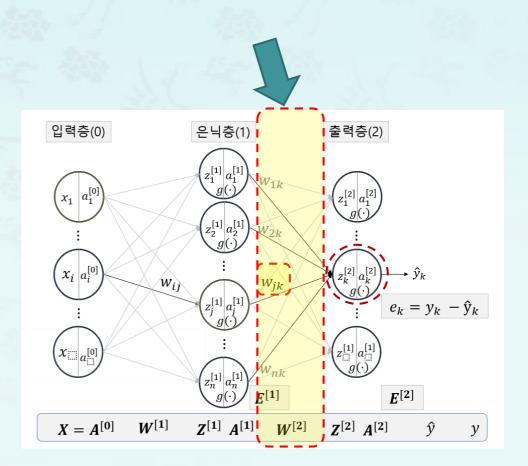
$$\frac{\partial E}{\partial w_{jk}} = -(y_k - \hat{y}_k) \cdot \frac{\partial}{\partial w_{jk}} g(z_k)$$

$$= -(y_k - \hat{y}_k) \cdot g'(z_k) \frac{\partial z_k}{\partial w_{jk}}$$

$$= -(y_k - \hat{y}_k) \cdot g'(z_k) \frac{\partial}{\partial w_{jk}} (\sum_j w_{jk} \cdot a_j)$$

$$= -(y_k - \hat{y}_k) \cdot g'(z_k) \cdot a_j$$





2. $W^{[2]}$ 의 오차함수 미분 : 복습

$$W^{[2]} := W^{[2]} - \alpha \Delta W^{[2]}$$
$$= W^{[2]} - \alpha \frac{\partial E}{\partial W^{[2]}}$$

• 2단계
$$w_{jk}^{[2]} \coloneqq w_{jk}^{[2]} - \alpha \Delta w_{jk}^{[2]}$$

$$= w_{jk}^{[2]} - \alpha \frac{\partial E}{\partial w_{jk}^{[2]}}$$
• 3단계

$$\frac{\partial E}{\partial w_{jk}} = -(y_k - \hat{y}_k) \cdot \frac{\partial}{\partial w_{jk}} g(z_k)$$

• 4단계
$$\Delta w_{jk}^{[2]} = \frac{\partial E}{\partial w_{jk}} = -(y_k - \hat{y}_k) \cdot g'(z_k) \cdot a_j$$

$$\Delta W^{[2]} = \frac{\partial E}{\partial W^{[2]}} = -E^{[2]} \cdot g'(Z^{[2]}) \cdot A^{[1]T}$$

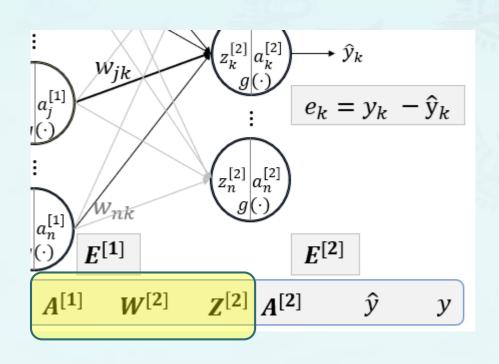
$$W^{[2]} := W^{[2]} - \alpha \Delta W^{[2]}$$

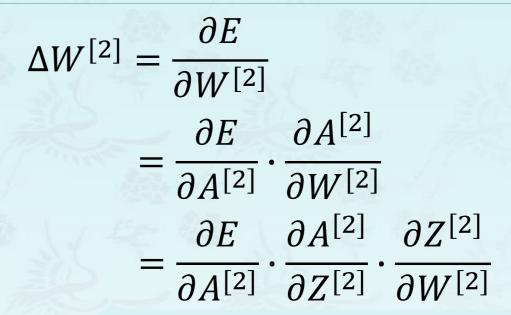
$$= W^{[2]} - \alpha \frac{\partial E}{\partial W^{[2]}}$$

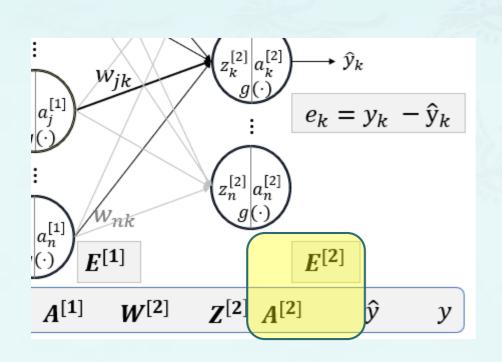
$$= W^{[2]} + E^{[2]} \cdot g'(Z^{[2]}) \cdot A^{[1]T}$$

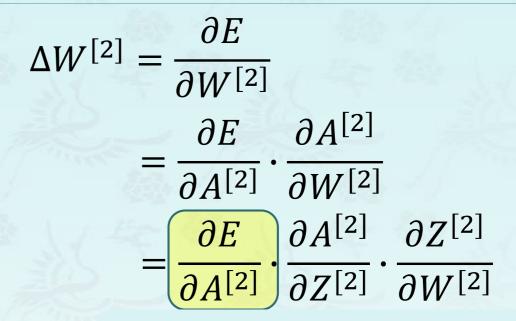
$$W^{[2]} := W^{[2]} - \alpha \Delta W^{[2]}$$
$$= W^{[2]} - \alpha \frac{\partial E}{\partial W^{[2]}}$$

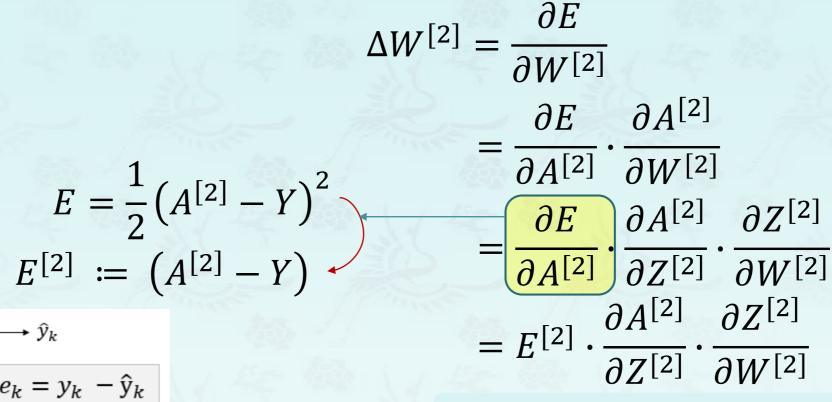
$$\Delta W^{[2]} = \frac{\partial E}{\partial W^{[2]}}$$

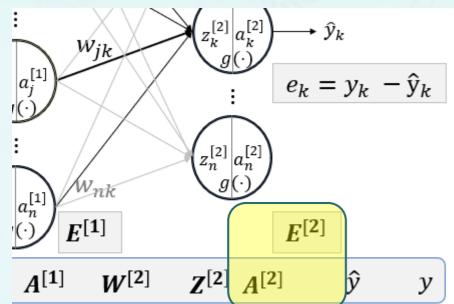


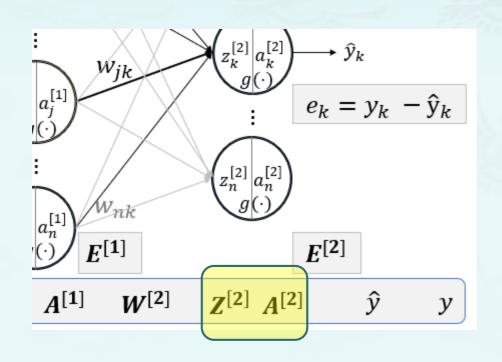


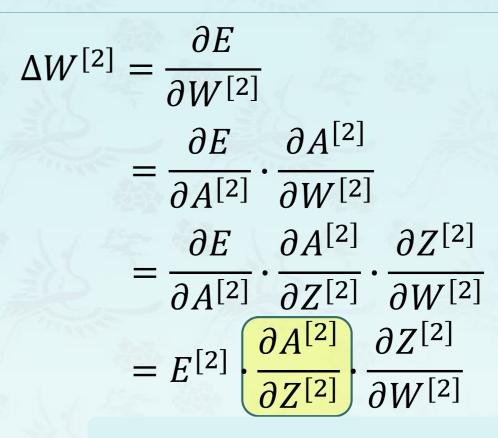












$$\Delta W^{[2]} = \frac{\partial E}{\partial W^{[2]}}$$

$$= \frac{\partial E}{\partial A^{[2]}} \cdot \frac{\partial A^{[2]}}{\partial W^{[2]}}$$

$$= \frac{\partial E}{\partial A^{[2]}} \cdot \frac{\partial A^{[2]}}{\partial Z^{[2]}} \cdot \frac{\partial Z^{[2]}}{\partial W^{[2]}}$$

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$$= E^{[2]} \cdot \frac{\partial A^{[2]}}{\partial Z^{[2]}} \cdot \frac{\partial Z^{[2]}}{\partial W^{[2]}}$$

$$= E^{[2]} \cdot g'(Z^{[2]}) \cdot \frac{\partial Z^{[2]}}{\partial W^{[2]}}$$

$$\Delta W^{[2]} = \frac{\partial E}{\partial W^{[2]}}$$

$$= \frac{\partial E}{\partial A^{[2]}} \cdot \frac{\partial A^{[2]}}{\partial W^{[2]}}$$

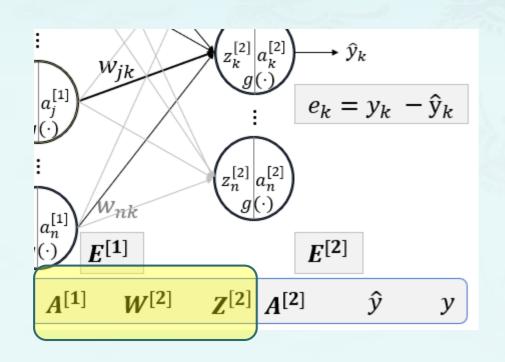
$$= E^{[2]} \cdot A^{[2]} \cdot A^{[2]} \cdot \frac{\partial Z^{[2]}}{\partial W^{[2]}}$$

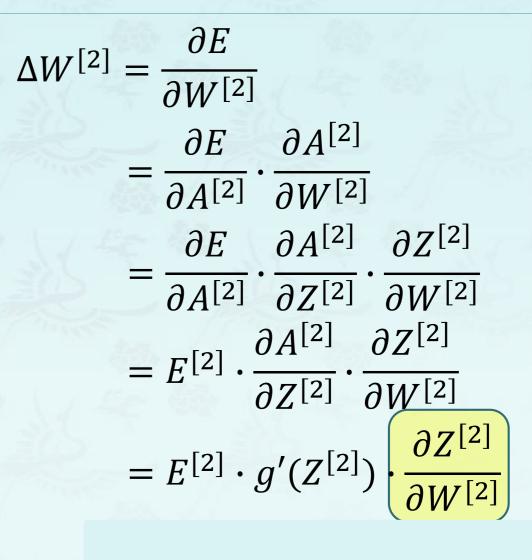
$$= \frac{\partial E}{\partial A^{[2]}} \cdot \frac{\partial A^{[2]}}{\partial Z^{[2]}} \cdot \frac{\partial Z^{[2]}}{\partial W^{[2]}}$$

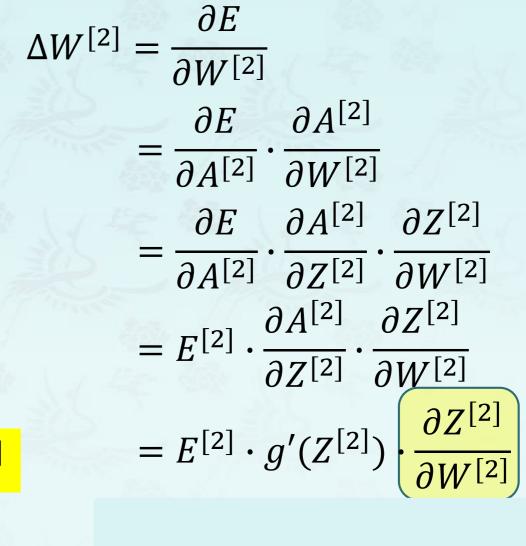
$$= \frac{\partial E}{\partial A^{[2]}} \cdot \frac{\partial A^{[2]}}{\partial Z^{[2]}} \cdot \frac{\partial Z^{[2]}}{\partial W^{[2]}}$$

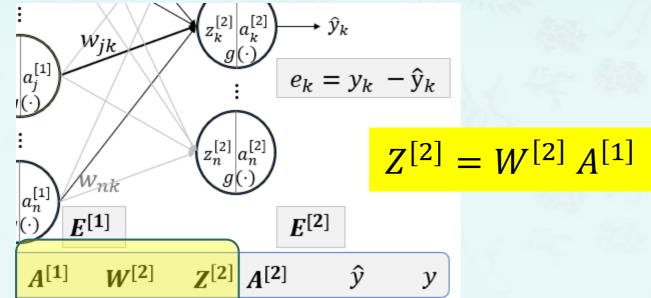
$$= E^{[2]} \cdot \frac{\partial A^{[2]}}{\partial Z^{[2]}} \cdot \frac{\partial Z^{[2]}}{\partial W^{[2]}}$$

$$= E^{[2]} \cdot \frac{\partial Z^{[2]}}{\partial W^{[2]}}$$









$$\Delta W^{[2]} = \frac{\partial E}{\partial W^{[2]}}$$

$$= \frac{\partial E}{\partial A^{[2]}} \cdot \frac{\partial A^{[2]}}{\partial W^{[2]}}$$

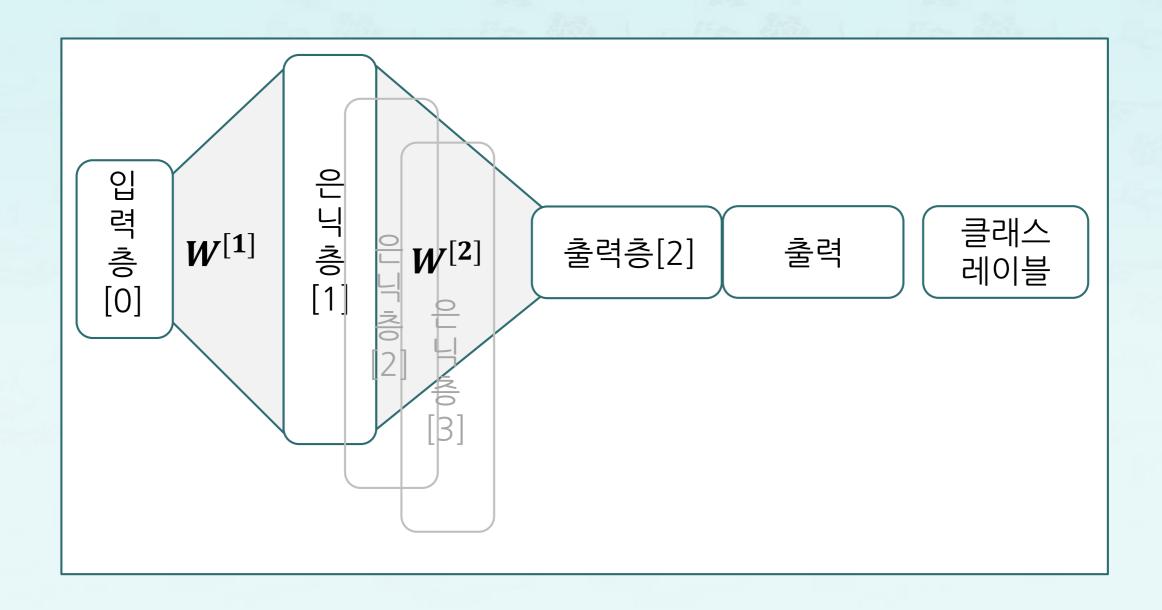
$$= \frac{\partial E}{\partial A^{[2]}} \cdot \frac{\partial A^{[2]}}{\partial Z^{[2]}} \cdot \frac{\partial Z^{[2]}}{\partial W^{[2]}}$$

$$= E^{[2]} \cdot \frac{\partial A^{[2]}}{\partial Z^{[2]}} \cdot \frac{\partial Z^{[2]}}{\partial W^{[2]}}$$

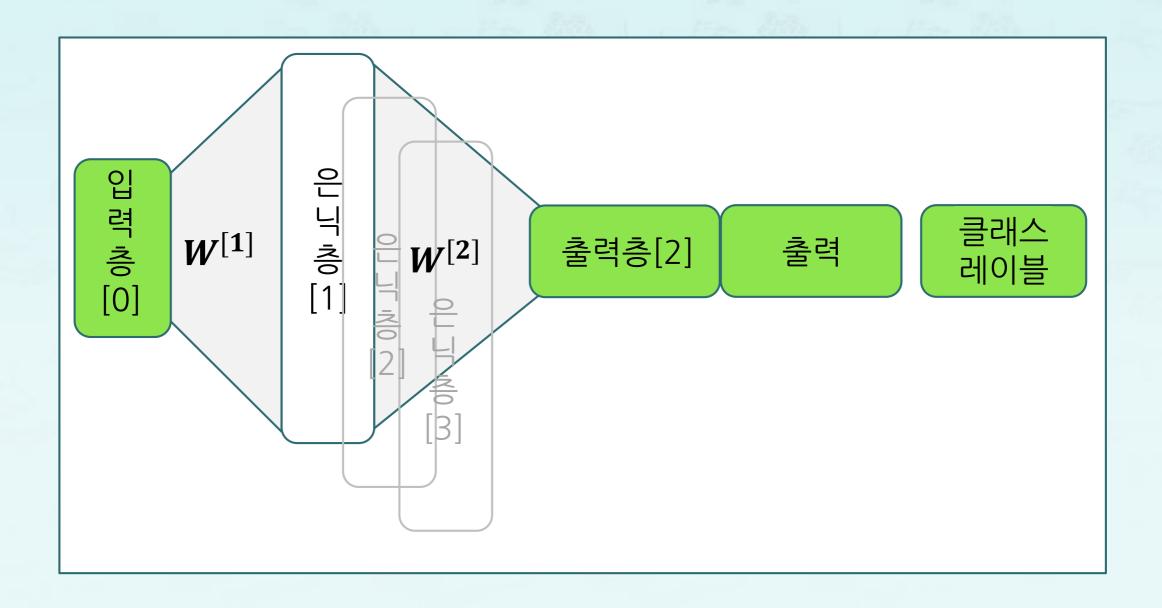
$$= E^{[2]} \cdot g'(Z^{[2]}) \cdot \frac{\partial Z^{[2]}}{\partial W^{[2]}}$$

$$= E^{[2]} \cdot g'(Z^{[2]}) \cdot A^{[1] \cdot T}$$

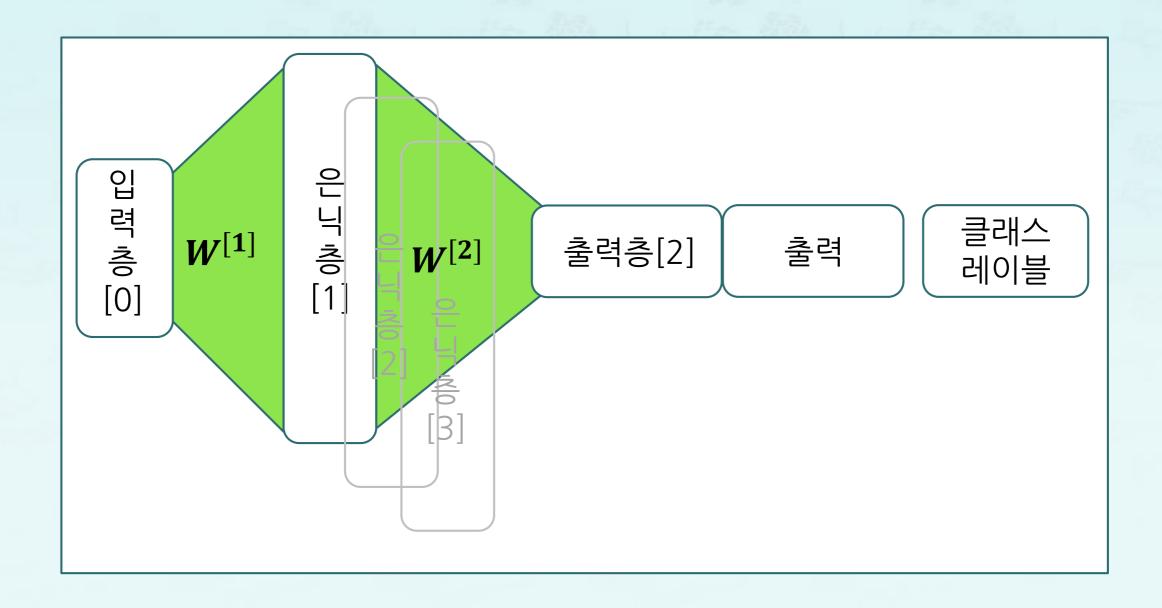
4. 다층 인공 신경망 행렬 모델: 다층 신경망의 구조



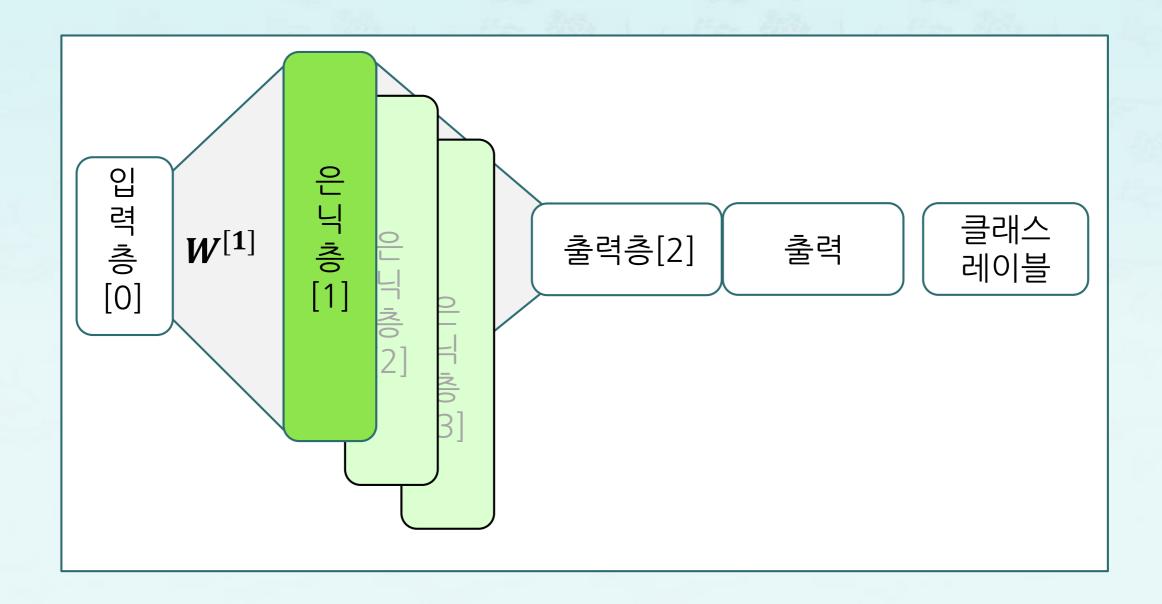
5. 다층 신경망의 구조: 입력층과 출력층



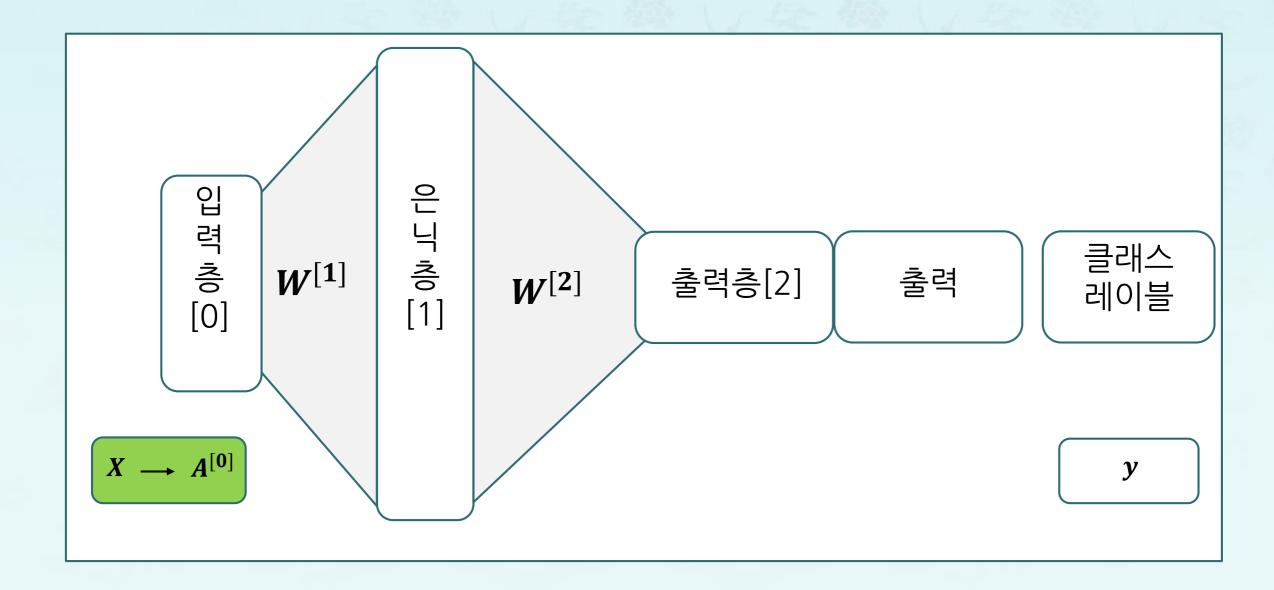
5. 다층 신경망의 구조: 가중치



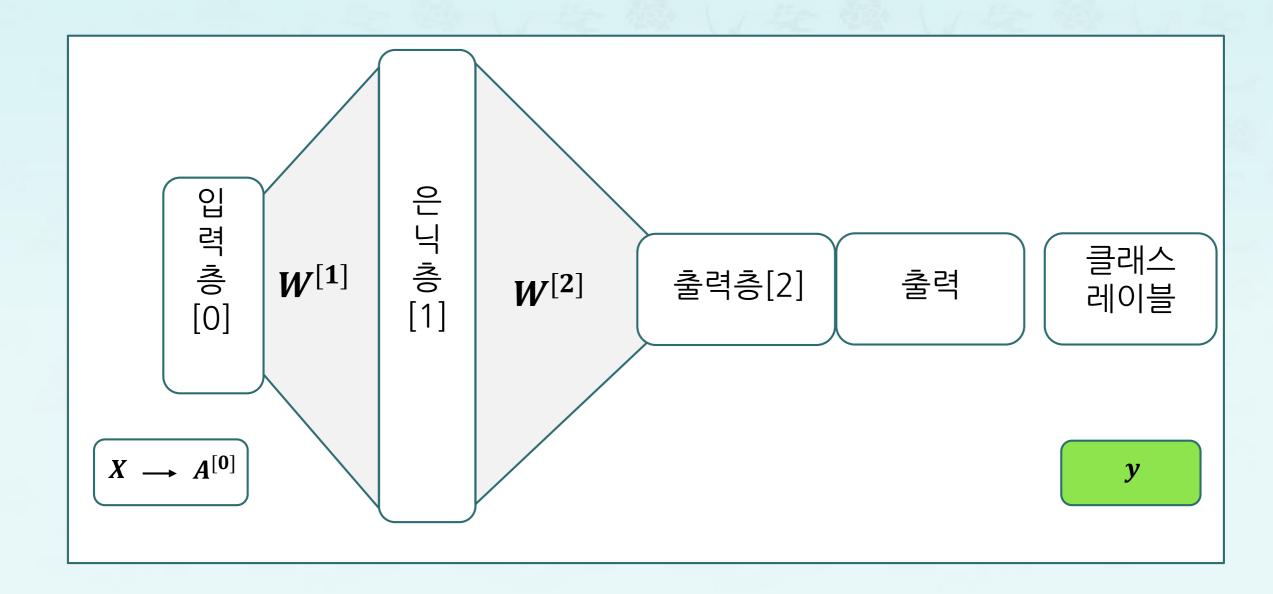
5. 다층 신경망의 구조: 은닉층



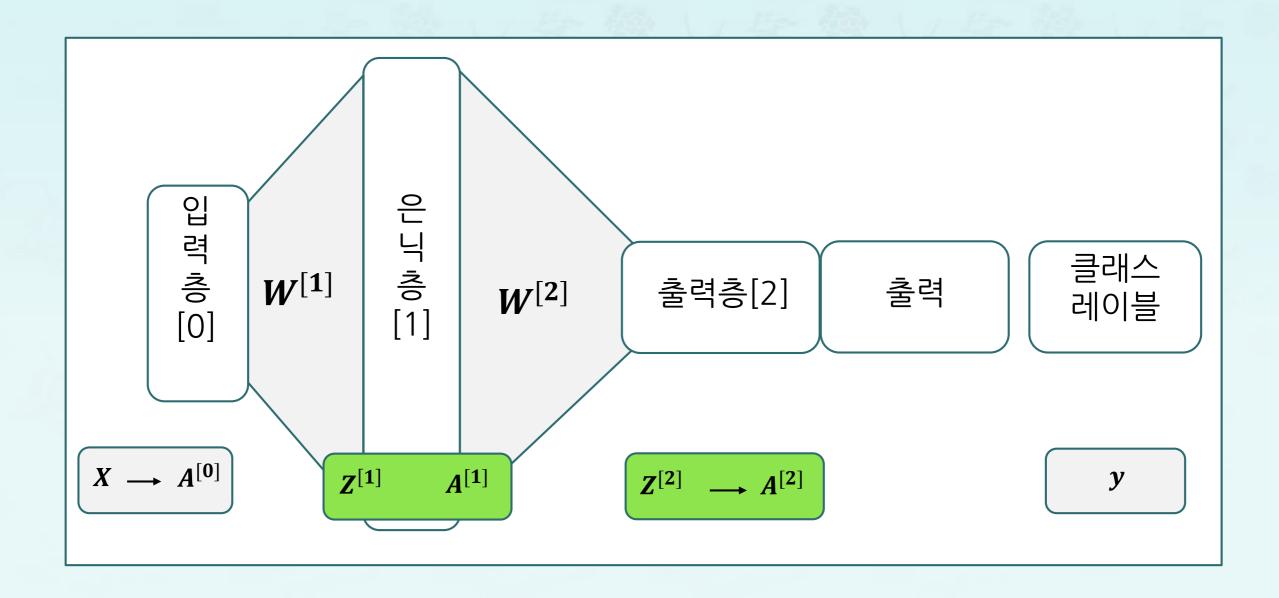
6. 다층 인공 신경망 행렬 모델: 입력



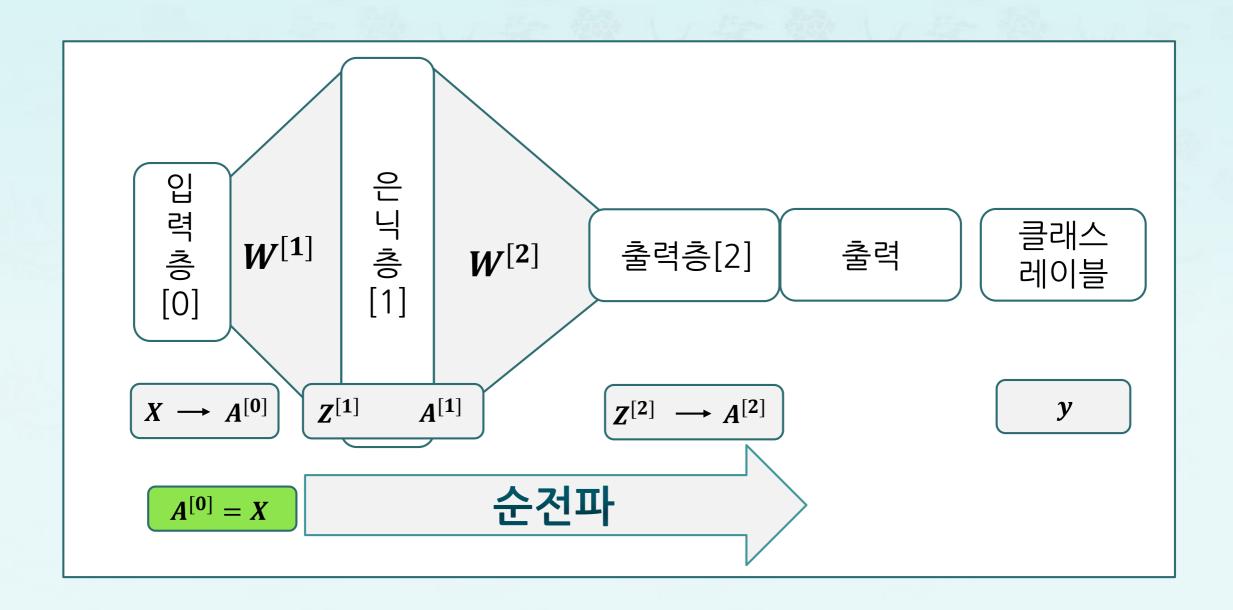
6. 다층 인공 신경망 행렬 모델: 레이블



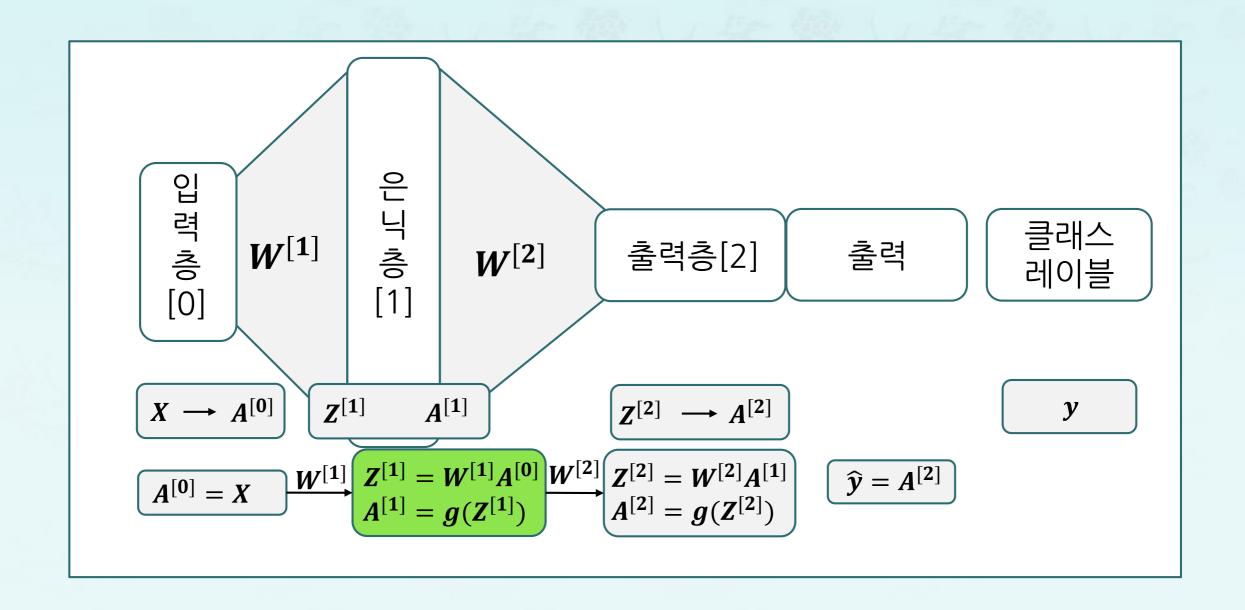
6. 다층 인공 신경망 행렬 모델: 입력과 출력



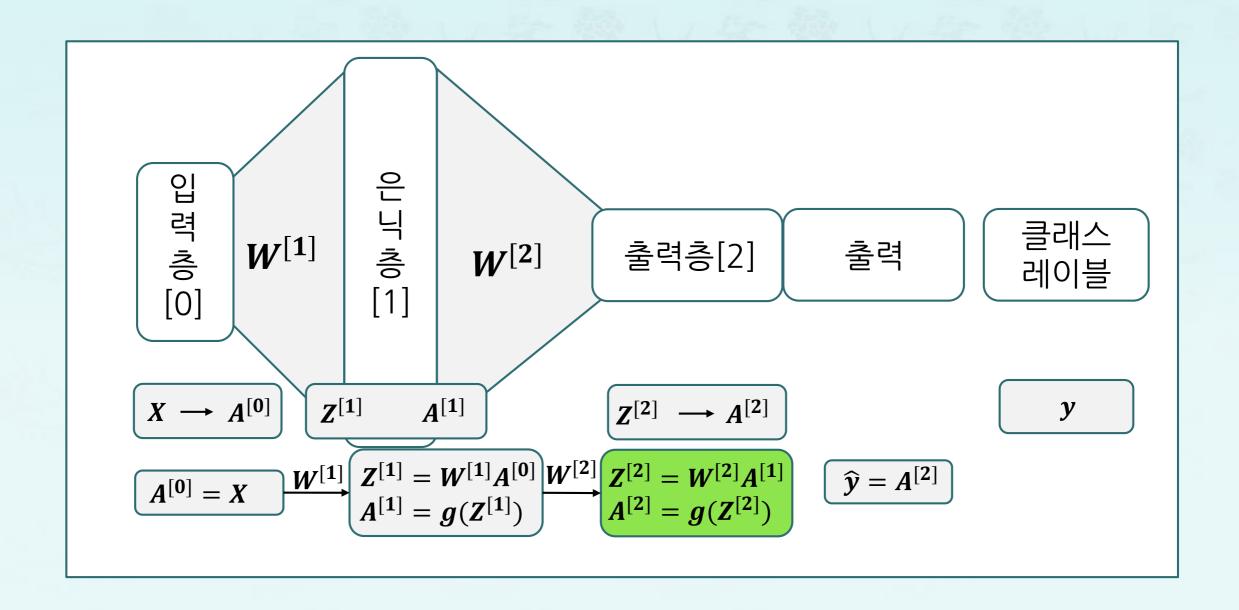
6. 다층 인공 신경망 행렬 모델: 순전파



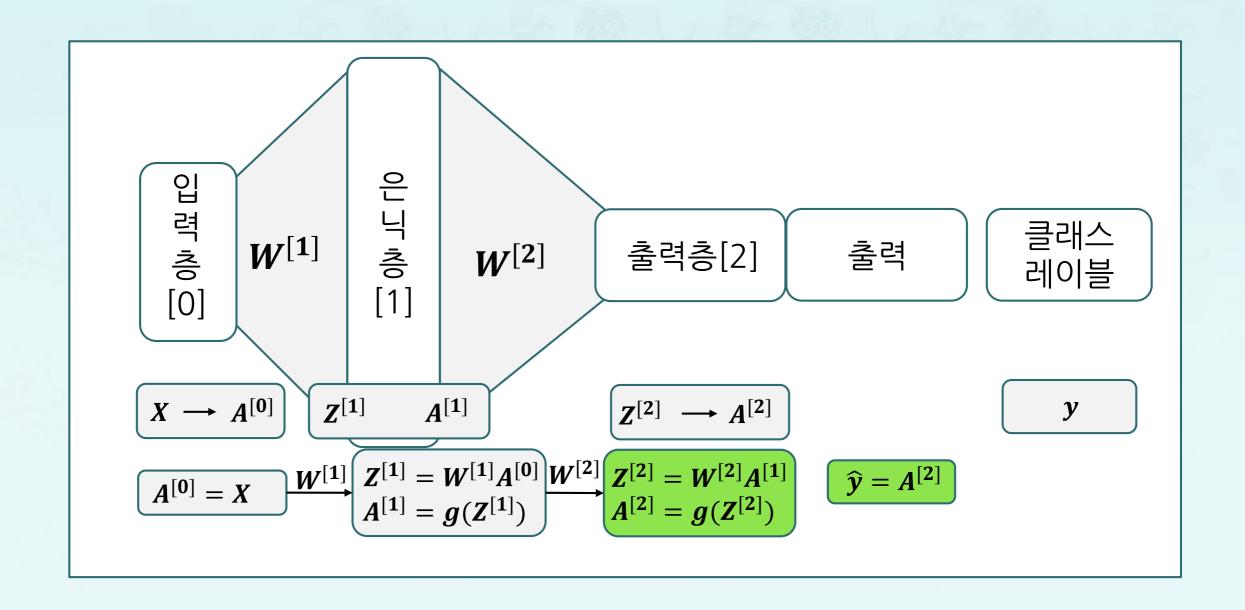
7. 순전파: 은닉층 계산



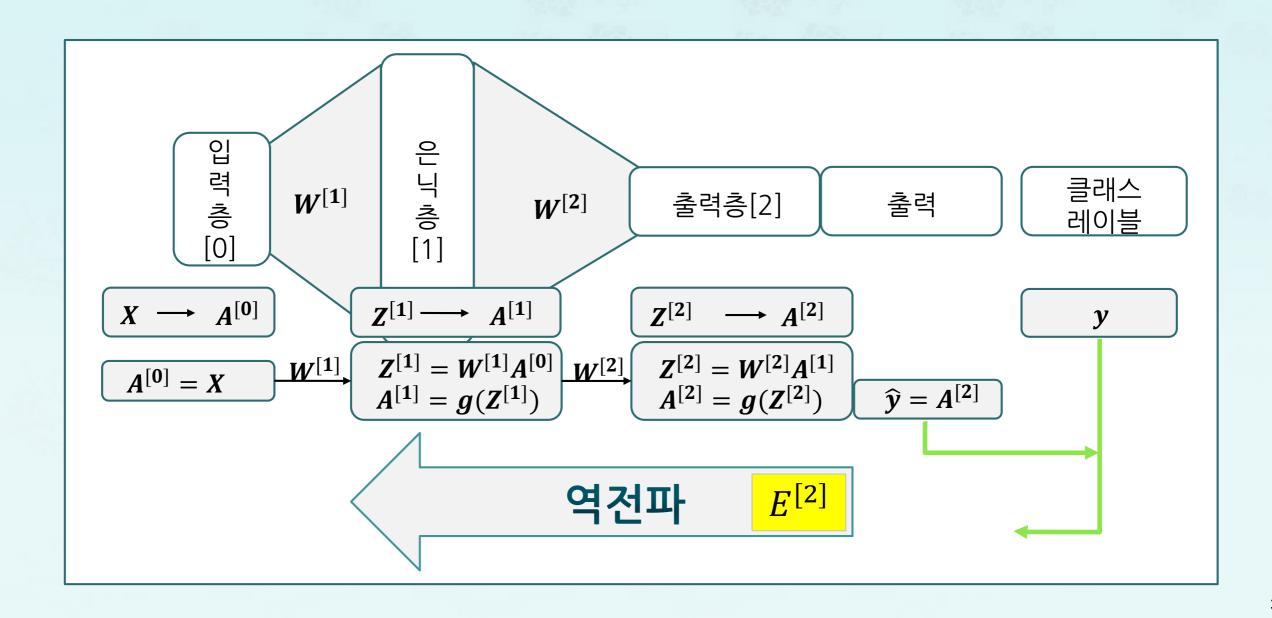
7. 순전파: 출력층 계산



7. 순전파: 출력층 계산



8. 역전파: 출력층 계산



8. 역전파: 가중치 조정

$$W^{[2]} := W^{[2]} - \alpha \Delta W^{[2]}$$

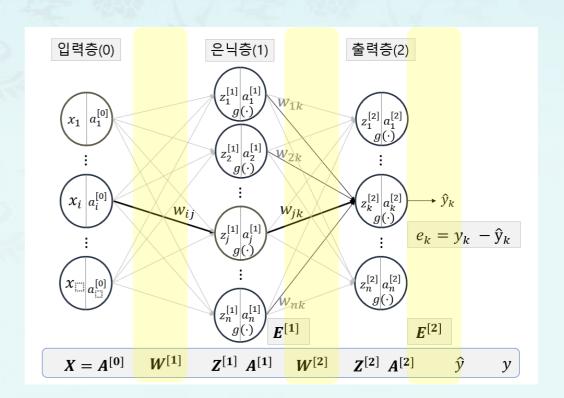
$$= W^{[2]} - \alpha \frac{\partial E}{\partial W^{[2]}}$$

$$= W^{[2]} + E^{[2]} \cdot g'(Z^{[2]}) \cdot A^{[1]T}$$

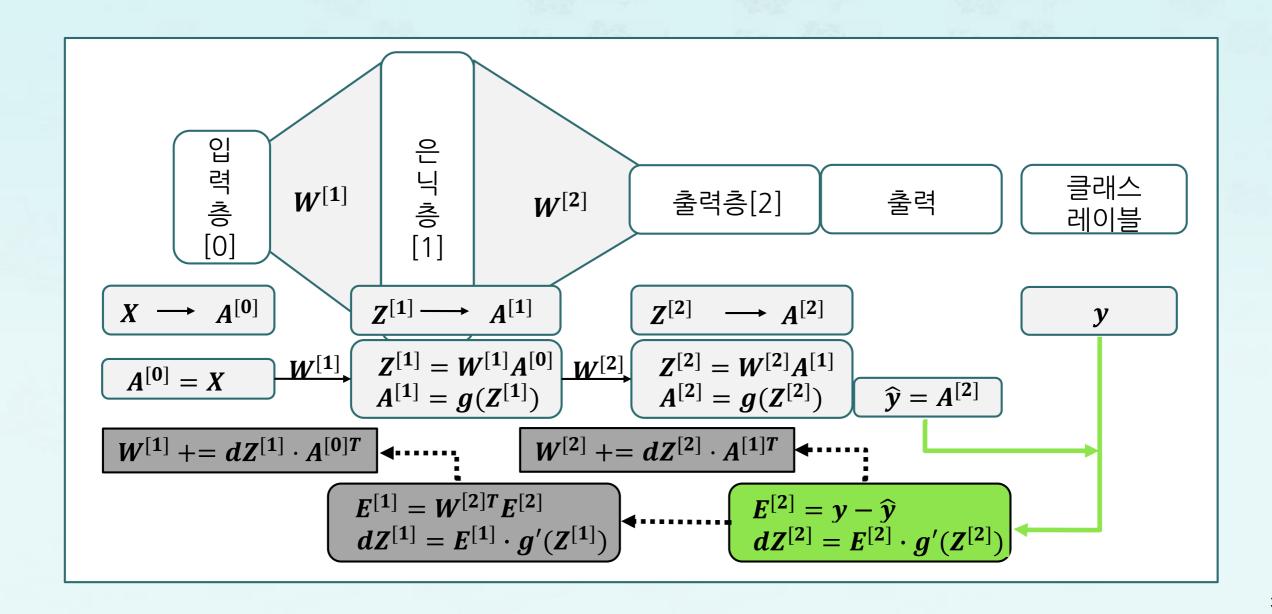
$$W^{[1]} := W^{[1]} - \alpha \Delta W^{[1]}$$

$$= W^{[1]} - \alpha \frac{\partial E}{\partial W^{[1]}}$$

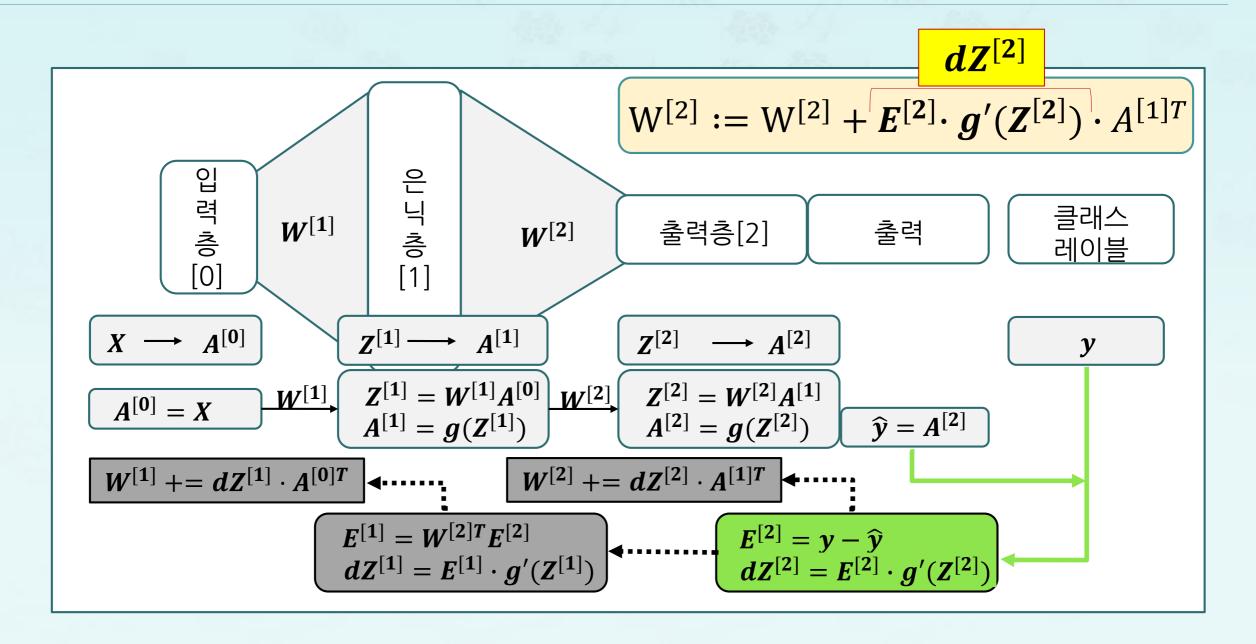
$$= W^{[1]} + E^{[1]} \cdot g'(Z^{[1]}) \cdot A^{[0]T}$$



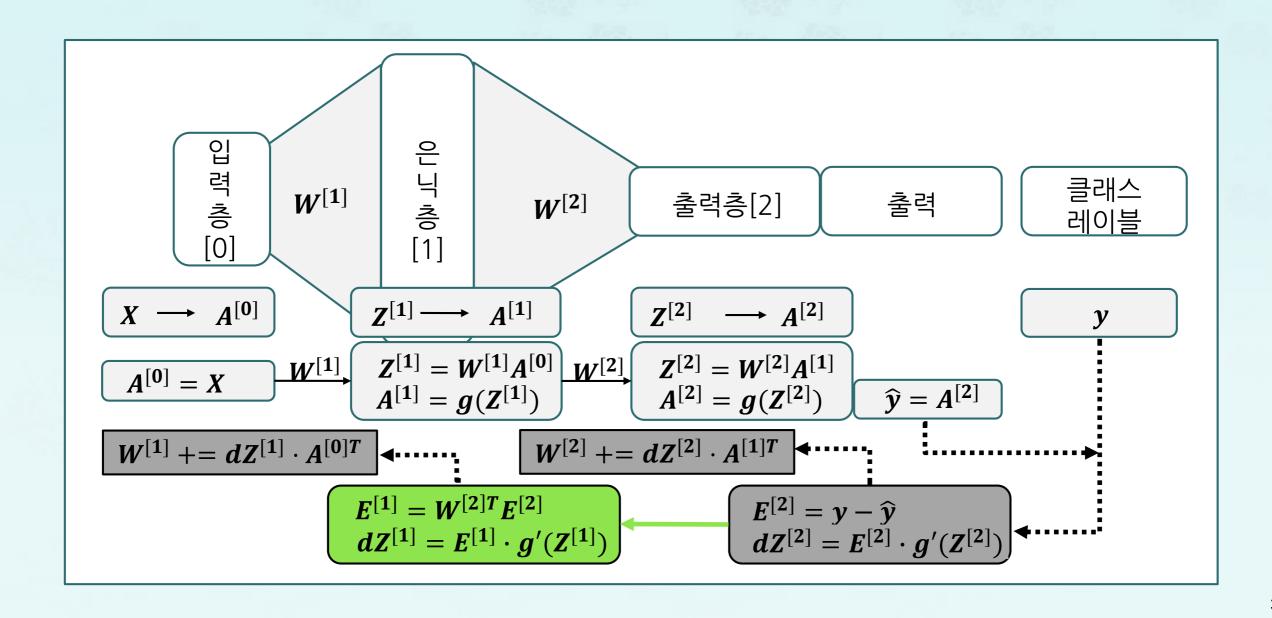
8. 역전파: E2 값 계산



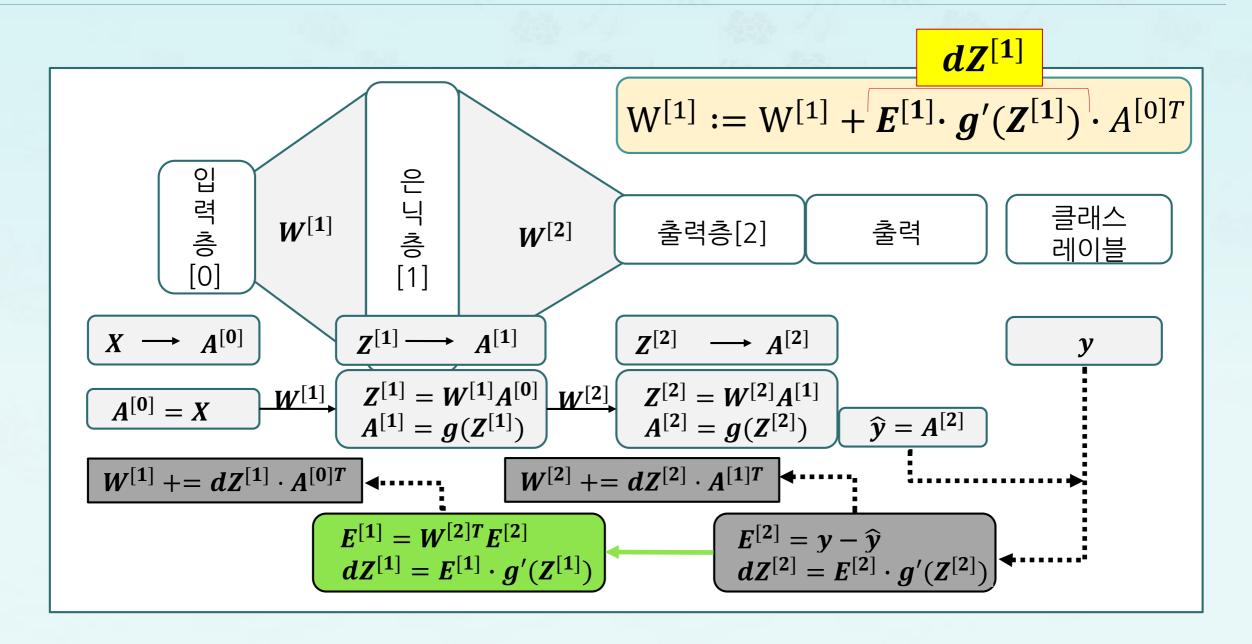
8. 역전파: dZ2 값 계산



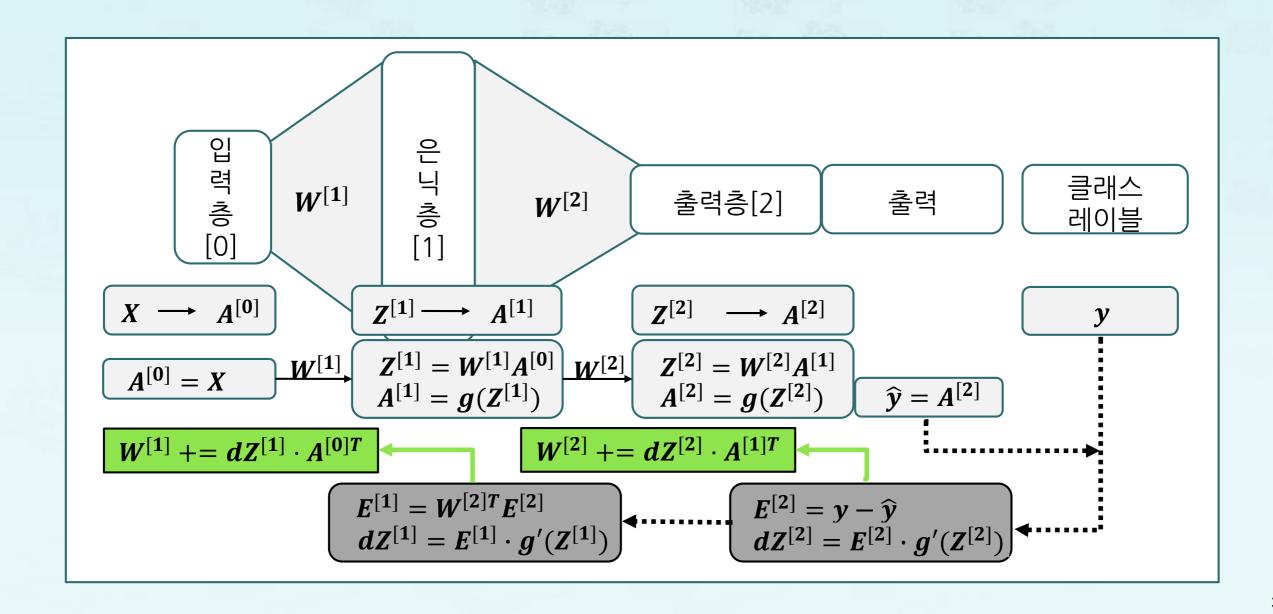
8. 역전파: E1 값 계산



8. 역전파: dZ1 값 계산



8. 역전파: 가중치 조정



다층 신경망 모델링

- 학습 정리
 - 미분에서의 연쇄법칙
 - 오차함수의 행렬 미분
 - 다층 인공 신경망의 행렬 모델링