

Diffusion Equation with Finite Difference Method

TF4062

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1 Initial-boundary value problem for 1d diffusion

1d diffusion equation:

$$\frac{\partial u}{\partial t} = \alpha \frac{\partial^2 u}{\partial x^2} + f(x, t) \quad (1)$$

Initial condition:

$$u(x, 0) = I(x), \quad x \in [0, L] \quad (2)$$

Boundary condition:

$$u(0, t) = 0, \quad u(L, t) = 0, \quad t > 0 \quad (3)$$

Spatial grid:

$$x_i = (i - 1)\Delta x, \quad i = 1, \dots, N_x \quad (4)$$

Temporal grid:

$$t_n = (n - 1)\Delta t, \quad n = 1, \dots, N_t \quad (5)$$

2 Forward Euler scheme

$$\frac{u_i^{n+1} - u_i^n}{\Delta t} = \alpha \frac{u_{i+1}^n - 2u_i^n + u_{i-1}^n}{\Delta x^2} + f_i^n \quad (6)$$

By using the following definition of *mesh Fourier number*:

$$F = \alpha \frac{\Delta t}{\Delta x^2} \quad (7)$$

we can rearrange the equation (6) to:

$$u_i^{n+1} = u_i^n + F (u_{i+1}^n - 2u_i^n + u_{i-1}^n) + f_i^n \Delta t \quad (8)$$

The equation (8) can be used

3 Backward Euler scheme

$$\frac{u_i^n - u_i^{n-1}}{\Delta t} = \alpha \frac{u_{i+1}^n - 2u_i^n + u_{i-1}^n}{\Delta x^2} + f_i^n \quad (9)$$

$$-Fu_{i-1}^n + (1 + 2F)u_i^n - Fu_{i+1}^n = u_i^{n-1} + f_i^n \Delta t \quad (10)$$

$$\mathbf{A}\mathbf{u} = \mathbf{b} \quad (11)$$

$$\begin{bmatrix}
A_{1,1} & A_{1,2} & 0 & \cdots & \cdots & \cdots & \cdots & \cdots & \cdots \\
A_{1,2} & A_{2,2} & A_{2,3} & \cdots & \cdots & \cdots & & & \vdots \\
0 & A_{3,2} & A_{3,3} & A_{3,4} & \cdots & \cdots & & & \vdots \\
\vdots & \ddots & & \ddots & & 0 & & & \vdots \\
\vdots & & & \ddots & \ddots & \ddots & \ddots & & \vdots \\
\vdots & & & 0 & A_{i,j-1} & A_{i,j} & A_{i,j+1} & \ddots & \vdots \\
\vdots & & & & \ddots & \ddots & \ddots & \ddots & 0 \\
\vdots & & & & & \ddots & \ddots & \ddots & A_{N_x-1,N_x} \\
0 & \cdots & \cdots & \cdots & \cdots & \cdots & \cdots & A_{N_x,N_x-1} & A_{N_x,N_x}
\end{bmatrix} \quad (12)$$

$$\begin{aligned}
A_{i,i-1} &= -F \\
A_{i,i} &= 1 + 2F \\
A_{i,i+1} &= -F
\end{aligned}$$

$$\begin{aligned}
A_{1,1} &= 1 \\
A_{1,2} &= 0 \\
A_{N_x-1,N_x-1} &= 0 \\
A_{N_x,N_x} &= 1
\end{aligned}$$

$$\mathbf{b} = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_i \\ \vdots \\ b_{N_x} \end{bmatrix} \quad (13)$$

Right-hand side $b_1 = 0$ and $b_{N_x} = 0$

$$b_i = u_i^{n-1} + f_i^{n-1} \Delta t, \quad i = 2, \dots, N_x - 1 \quad (14)$$

4 Crank-Nicolson (CN) method

In the Crank-Nicolson method we require the PDE to be satisfied at the spatial mesh point x_i but midway between the points in the time mesh ($t_{n+\frac{1}{2}}$):

$$\frac{\partial}{\partial t} u_i^{n+\frac{1}{2}} = \alpha \frac{\partial^2}{\partial x^2} u_i^{n+\frac{1}{2}} + f_i^{n+\frac{1}{2}} \quad (15)$$

Using centered difference in space and time:

$$\frac{u_i^{n+1} - u_i^n}{\Delta t} = \frac{1}{\Delta x^2} \left(u_{i+1}^{n+\frac{1}{2}} - 2u_i^{n+\frac{1}{2}} + u_{i-1}^{n+\frac{1}{2}} \right) + f_i^{n+\frac{1}{2}} \quad (16)$$

Because $u_i^{n+\frac{1}{2}}$ is not the quantity that we want to calculate, we must approximate it. We can approximate it by an average between the value at t_n and t_{n+1} :

$$u_i^{n+\frac{1}{2}} \approx \frac{1}{2}(u_i^n + u_i^{n+1}) \quad (17)$$

We also can use the same approximation for $f_i^{n+\frac{1}{2}}$:

$$f_i^{n+\frac{1}{2}} \approx \frac{1}{2}(f_i^n + f_i^{n+1}) \quad (18)$$

Substituting these approximations we obtain:

$$u_i^{n+1} - \frac{1}{2}F(u_{i-1}^{n+1} - 2u_i^{n+1} + u_{i+1}^{n+1}) = u_i^n + \frac{1}{2}F(u_{i-1}^n - 2u_i^n + u_{i+1}^n) + \frac{1}{2}f_i^{n+1} + \frac{1}{2}f_i^n \quad (19)$$

We notice that the equation (19) has similar structure as the one we obtained for backward Euler method:

$$\mathbf{A}\mathbf{u} = \mathbf{b} \quad (20)$$

The element of the matrix \mathbf{A} are:

$$\begin{aligned} A_{i,i-1} &= -\frac{1}{2}F \\ A_{i,i} &= 1 + F \\ A_{i,i+1} &= -\frac{1}{2}F \end{aligned}$$

for internal points $i = 2, \dots, N_x - 1$. For boundary points we have:

$$\begin{aligned} A_{1,1} &= 1 \\ A_{1,2} &= 0 \\ A_{N_x, N_x-1} &= 0 \\ A_{N_x, N_x} &= 1 \end{aligned}$$

For the right-hand side vector \mathbf{b} we have $b_1 = 0$ and $b_{N_x} = 0$ and

$$b_i = u_i^n + \frac{1}{2}F(u_{i+1}^n - 2u_i^n + u_{i-1}^n) + \frac{1}{2}(f_i^{n+1} + f_i^n)\Delta t \quad (21)$$

for internal points $i = 2, \dots, N_x - 1$.

5 Implementation

```
function diffusion_1d_explicit(
    L::Float64, Nx::Int64, T::Float64, Nt::Int64,
    α::Float64, u0x, bx0, bxf, f
)

    Δx = L / (Nx-1)
    x = collect(range(0.0, stop=L, length=Nx))

    Δt = T / (Nt-1)
    t = collect(range(0.0, stop=T, length=Nt))

    u = zeros(Float64, Nx, Nt)

    for i in 1:Nx
        u[i,1] = u0x(x[i])
    end

    for k in 1:Nt
        u[1,k] = bx0(t[k])
        u[Nx,k] = bxf(t[k])
    end

    F = α*Δt/Δx^2

    if F >= 0.5
```

```

    @printf("diffusion_1d_explicit:\n")
    @printf("WARNING: F is greater than 0.5: %f\n", F)
    @printf("WARNING: The solution is not guaranteed to be stable !!\n")
else
    @printf("diffusion_1d_explicit:\n")
    @printf("INFO: F = %f >= 0.5\n", F)
    @printf("INFO: The solution should be stable\n")
end

for n in 1:Nt-1
    for i in 2:Nx-1
        u[i,n+1] = F*( u[i+1,n] + u[i-1,n] ) + (1 - 2*F)*u[i,n] + f(x[i],
            ↪ t[n])*Δt
    end
end

return u, x, t
end

```

```

function diffusion_1d_implicit(
    L::Float64, Nx::Int64, T::Float64, Nt::Int64,
    α::Float64, u0x, bx0, bxf, f
)
    Δx = L/(Nx-1)
    x = collect(range(0.0, stop=L, length=Nx))

    Δt = T/(Nt-1)
    t = collect(range(0.0, stop=T, length=Nt))

    u = zeros(Float64, Nx, Nt)

    for i in 1:Nx
        u[i,1] = u0x(x[i])
    end

    for k in 1:Nt
        u[1,k] = bx0(t[k])
        u[Nx,k] = bxf(t[k])
    end

    F = α*Δt/Δx^2

    A = zeros(Float64, Nx, Nx)
    b = zeros(Float64, Nx)
    for i in 2:Nx-1
        A[i,i] = 1 + 2*F
        A[i,i-1] = -F
        A[i,i+1] = -F
    end
    A[1,1] = 1.0
    A[Nx,Nx] = 1.0

    for n in 2:Nt
        for i in 2:Nx-1
            b[i] = u[i,n-1] + f(x[i],t[n])*Δt
        end
        b[1] = 0.0
        b[Nx] = 0.0
        u[:,n] = A\b    # Solve the linear equations
    end
    return u, x, t
end

```

end

```
function diffusion_1d_CN(
    L::Float64, Nx::Int64, T::Float64, Nt::Int64,
    α::Float64, u0x, bx0, bxf, f
)

    Δx = L / (Nx-1)
    x = collect(range(0.0, stop=L, length=Nx))

    Δt = T / (Nt-1)
    t = collect(range(0.0, stop=T, length=Nt))

    u = zeros(Float64, Nx, Nt)

    for i in 1:Nx
        u[i,1] = u0x(x[i])
    end

    for k in 1:Nt
        u[1,k] = bx0(t[k])
        u[Nx,k] = bxf(t[k])
    end

    F = α*Δt/Δx^2

    A = zeros(Float64, Nx, Nx)
    b = zeros(Float64, Nx)
    for i in 2:Nx-1
        A[i,i] = 1 + F
        A[i,i-1] = -0.5*F
        A[i,i+1] = -0.5*F
    end
    A[1,1] = 1.0
    A[Nx,Nx] = 1.0

    for n in 1:Nt-1
        for i in 2:Nx-1
            b[i] = u[i,n] + 0.5*F*( u[i-1,n] - 2*u[i,n] + u[i+1,n] ) +
                0.5*( f(x[i],t[n]) + f(x[i],t[n+1]) )*Δt
        end
        b[1] = 0.0
        b[Nx] = 0.0
        u[:,n+1] = A\b # Solve the linear equations
    end
    return u, x, t

end
```