COMPSCI 762 Tutorial 9

Tutorial on Unsupervised Learning

Luke Chang

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The University of Auckland

Unsupervised Learning - Cluster Analysis

- Cluster analysis is an unsupervised learning task.
- The task of clustering is to partition a set of objects such that objects in the same group are more similar to each other than those in other groups.
- Evaluation metrics:
- Sum of Squared Error (SSE)
 - Sum of Squared Between(SSB)
- Algorithms we will cover:
 - K-means
 - · Hierarchical clustering
 - DBSCAN: Density-based clustering

K-means

- Partition the data into clusters
- Hyperparameter: the number of clusters, *K*
- Each cluster is associated with a centroid
- Each point is assigned to the cluster with the closest centroid
- Iterative method: Update centroids in each iteration, converge until the centroids don't change

Limitations:

- When clusters have:
 - Different sizes
 - Different densities
 - Non-globular shapes (hypersphere)
- · When data contains outliers

K-means Pseudocode

Select *K* points as the initial centroids **repeat:**

For each point:

Assign the point to the closest centroid

For $i \in \{1, ..., K\}$:

Update the *i* centroid

until The centroids (or points) don't change

Evaluation Metric: Sum of Squared Error (SSE)

- No true labels are available in the unsupervised learning
- Use sum of the squared errors to evaluate the performance

$$SSE = \sum_{i=1}^{K} \sum_{x \in C_i} dist^2(m_i, x)$$

- SSE highly depends on **K** and the **initial centroids**
- Depends on the initial K-centroids, the K-means clusters with same the K value may not have the same SSE

Solve the Initial Centroids Problem

Problem:

Stuck in the local minimal

Example

Demonstration of k-means assumptions from *sklearn*

Solution:

- Multiple runs
- Use hierarchical clustering to determine the initial centroids
- Define more than *K* initial centroids and then select among these initial centroids
- Postprocessing:
 - · Remove empty clusters and small cluster
 - Split "loose" clusters High SSE
 - Merge clusters when they are "close" Low SSE
 - Apply these steps multiple times and use the pruned centroids as new initial centroids
- Improved k-means algorithms: Bisecting K-means, Mini Batch K-Means

Hierarchical Clustering

- Produces a set of nested clusters organized as a hierarchical tree
- · Can be visualized as a dendrogram
- No assumption on the number of clusters
- Two main types:
 - Agglomerative: Start from each data point, merge the closest pair of clusters
 - $\bullet\,$ Divisive: Start with one big cluster which contains all data, split at each step

Agglomerative Clustering Algorithm Pseudocode

Compute the proximity matrix Let each point be a cluster repeat:

Merge the two closest clusters Update the proximity matrix until only a single cluster remains

Proximity Matrix

The linkage criteria determines the metric used for the merge strategy:

- **Min Single-linkage:** uses the minimum of the distances between all observations of the two sets
 - Can handle non-elliptical shapes
 - Sensitive to noise and outliers
- Max Complete-linkage: uses the maximum distances between all observations of the two sets
 - · Less susceptible to noise and outliers
 - Tends to break large clusters
 - Biased towards globular clusters
- Group average Average-linkage: The average of the distances between all observations of pairs of clusters
 - · Less susceptible to noise and outliers
 - Biased towards globular clusters

$$\frac{1}{|C_i|\cdot|C_j|}\sum_{i\in C_i}\sum_{j\in C_j}d(i,j)$$

Proximity Matrix (continue)

- Distance Between Centroids Centroid-linkage: Distance between the centroids of two clusters
- Ward's minimum variance method Ward's linkage: Minimizes the sum of squared differences of the clusters being merged

$$SSE(C_i, C_j) - [SSE(C_i) + SSE(C_j)]$$

where $SSE(C_i, C_j)$ is the SSE of the union of the cluster i and the cluster j.

- · Less susceptible to noise and outliers
- Biased towards globular clusters
- Hierarchical analogue of K-means; Can be used to initialize K-means

Example

Hierarchical clustering from *sklearn*

DBSCAN: Density-based Clustering

- DBSCAN: Density-Based Spatial Clustering of Applications with Noise
- **Density:** The number of points within a specified radius (ε)
- MinPts (min_samples)): A point is a core point if it has at least MinPts within ε .
- A **border point** is not a **core point**, but is in the neighborhood of a core point.
- A **noise point** is any point that is not a core point or a border point.

Limitations:

- Clusters with varied densities
- High dimensional data

DBSCAN Pseudocode

```
DBSCAN(DB, distFunc, eps, minPts) {
   C := 0
                                                          /* Cluster counter */
   for each point P in database DB {
       if label(P) ≠ undefined then continue
                                                        /* Previously processed in inner loop */
       Neighbors N := RangeOuerv(DB, distFunc, P, eps)
                                                        /* Find neighbors */
       if |N| < minPts then {</pre>
                                                         /* Density check */
           label(P) := Noise
                                                          /* Label as Noise */
           continue
       C := C + 1
                                                         /* next cluster Label */
       label(P) := C
                                                          /* Label initial point */
                                                         /* Neiahbors to expand */
       SeedSet S := N \ {P}
       for each point 0 in S {
                                                        /* Process every seed point 0 */
           if label(0) = Noise then label(0) := C  /* Change Noise to border point */
           if label(Q) # undefined then continue /* Previously processed (e.g., border point) */
           label(0) := C
                                                         /* Label neighbor */
           Neighbors N := RangeOuerv(DB. distFunc. O. eps) /* Find neighbors */
           if |N| \ge minPts then {
                                                       /* Density check (if Q is a core point) */
               S := S U N
                                                         /* Add new neighbors to seed set */
```

Cluster Cohesion and Separation

Cluster Cohesion

- Measures how closely related are data points in a cluster
- Within Cluster Sum of Squares (WCSS) = Sum of Squared Error (SSE)

$$SSE = \sum_{i=1}^{K} \sum_{x \in C_i} ||x - m_i||^2$$

Cluster Separation

- Measure how distinct or well-separated a cluster is from other clusters
- Between cluster Sum of Squares (BSS) a.k.a. Sum of Squared Between (SSB)

$$SSB = \sum_{i=1}^{K} |C_{i}| (m - m_{i})^{2}$$

where $|C_i|$ is the size of cluster i, m is the grand mean, m_i is the mean for the cluster i.

Cluster Cohesion and Separation

• *Sum of Squares Total* (SST): The sum of squares between the n data points and the grand mean

$$SST = SSB + SSE$$

- SST is a constant based on the observed data points.
- $\bullet\,$ The same terminologies are used in the one-way analysis of variance (ANOVA) test.

Sums of Squares (SS) Example

Example

Divide 1D data points $\{1,2,3,6,7\}$ into 2 clusters: $\{1,2,3\}$ and $\{6,7\}$.

- n = 5, $|C_1| = 3$, and $|C_2| = 2$
- m = (1+2+3+6+7)/5 = 3.8
- $m_1 = (1+2+3)/3 = 2$
- $m_2 = (6+7)/2 = 6.5$

SSB =
$$3(3.8-2)^2 + 2(3.8-6.5)^2 = 24.3$$

SSE = $(1-2)^2 + (2-2)^2 + (3-2)^2 + (6-6.5)^2 + (7-6.5)^2 = 2.5$
SST = $SSB + SSE = 24.3 + 2.5 = 26.8$

The alternative way to compute SST:

SST =
$$(1-3.8)^2 + (2-3.8)^2 + (3-3.8)^2 + (6-3.8)^2 + (7-3.8)^2 = 26.8$$

Silhouette Coefficient

Silhouette coefficient combines ideas of both cohesion and separation, but for individual points.

For each data point, *i*:

a: The mean distance between a sample and all other points in the same class

$$a(i) = \frac{1}{|C_i| - 1} \sum_{j \in C_i, y \neq i} d(i, j)$$

b: The mean distance between a sample and all other points in the next nearest cluster

$$b(i) = \min_{k \neq i} \frac{1}{|C_k|} \sum_{j \in C_k} d(i,j)$$

Silhouette Coefficient for the Entire Dataset

The Silhouette Coefficient for a single sample s(i) is then given as:

$$s(i) = \begin{cases} 1 - a(i)/b(i) & \text{, if } a(i) < b(i) \\ b(i)/a(i) - 1 & \text{, if } a(i) \le b(i) \end{cases}$$

- The Silhouette Coefficient for a set of samples is given as the mean of the Silhouette Coefficient for each sample.
- The range is in [0,1], the **larger** the better.

Example

An example from *sklearn*

Overview of Clustering Methods From *sklearn*

Example

The sklearn Documentation for Clustering