Mass properties of LINK3
    Configuration: Default
    Coordinate system: -- default --

Mass (user-overridden) = 3.88 kilograms

Volume = 0.0019 cubic meters

Surface area = 0.159 square meters

Center of mass: (meters)
        X = 0.0052
        Y = 0.0037
        Z = 0

Principal axes of inertia and principal moments of inertia: (kilograms * square meters)
Taken at the center of mass.
        Ix = (1, -0.0048, 0)   Px = 0.0048
        Iy = (0.0048, 1, 0.0001)   Py = 0.0445
        Iz = (0, -0.0001, 1)   Pz = 0.0455

Moments of inertia: (kilograms * square meters)
Taken at the center of mass and aligned with the output coordinate system.
        Lxx = 0.0048   Lxy = -0.0002   Lxz = 0
        Lyx = -0.0002   Lyy = 0.0445   Lyz = 0
        Lzx = 0   Lzy = 0   Lzz = 0.0455

Moments of inertia: (kilograms * square meters)
Taken at the output coordinate system.
        Ixx = 0.0049   Ixy = -0.0001   Ixz = 0
        Iyx = -0.0001   Iyy = 0.0446   Iyz = 0
        Izx = 0   Izy = 0   Izz = 0.0456