Mass properties of ERP03D LINK5 Configuration: Default Coordinate system: -- default --Density = 2000 kilograms per cubic meter Mass = 1.417 kilograms Volume = 0.0007 cubic meters Surface area = 0.057 square meters Center of mass: (meters) X = 0Y = 0.0023Z = 0.0506Principal axes of inertia and principal moments of inertia: (kilograms * square meters) Taken at the center of mass. Ix = (0, -0.0184, 0.9998)Px = 0.0014ly = (0, -0.9998, -0.0184)Py = 0.0023Iz = (1, 0, 0)Pz = 0.0023Moments of inertia: (kilograms * square meters) Taken at the center of mass and aligned with the output coordinate system. Lxx = 0.0023Lxy = 0 Lxz = 0Lyy = 0.0023Lyx = 0Lyz = 0Lzz = 0.0014Lzx = 0Lzy = 0Moments of inertia: (kilograms * square meters) Taken at the output coordinate system.

Ixy = 0

lyy = 0.0059

Izy = 0.0002

Ixz = 0

lyz = 0.0002lzz = 0.0014

Ixx = 0.0059

lyx = 0

Izx = 0