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### Overview of TensorFlowLiteSwift

- Swift library to run TensorFlowLite models on an iOS device.
- Current version is 0.2.0

https://github.com/tensorflow/tensorflow/tree/master/tensorflow/lite/experimental/swift















#### WHAT IS COCOAPODS

CocoaPods is a dependency manager for Swift and Objective-C Cocoa projects. It has over 64 thousand libraries and is used in over 3 million apps. CocoaPods can help you scale your projects elegantly.

#### INSTALL

**GET STARTED** 

CREATE A POD

CocoaPods is built with Ruby and is installable with the default Ruby available on macOS. We recommend you use the default ruby.

Using the default Ruby install can require you to use sudo when installing gems. Further installation instructions are in the guides.

\$ sudo gem install cocoapods

We also have a Mac app for CocoaPods. It only gets major releases ATM though.

#### CONTRIBUTE

We're developing CocoaPods on GitHub. There's a guide for getting started on the CocoaPods tool. It's easy and really gratifying to contribute patches! - for a lot of people it's their first foray into Open Source. We have some easy tickets to look at

#### Podfile |

```
# Pods for 'Your Project'
pod 'TensorFlowLiteSwift'
```

#### Install Command

```
$> cd /path/to/directory/containing/podfile
$> pod install
```

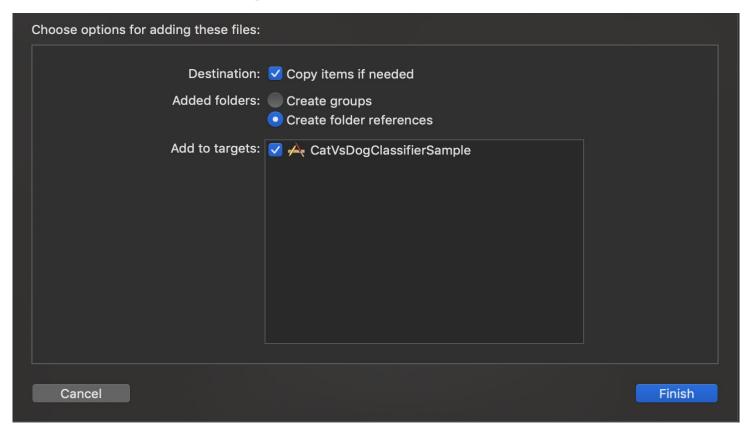
### **Getting the Model**

Python notebook to train the model:

bit.ly/makecatsdogs

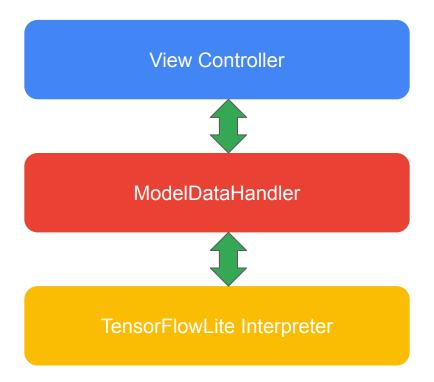
After running all the cells, you get model(.tflite) and labels(.txt) files

### **Adding Model and Labels**





### **App Architecture**



### Interpreter

- Performs the inference using the Tflite model
- Input is passed into the input tensors
- Resulting inferences are available in the output tensors

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# Initialize the Interpreter

Model is loaded in the interpreter at this stage

#### Preparing the Image Input

Input image pixel buffer is converted to the format recognized by the model

## Perform Inference

Pass input to the Interpreter and Invoke the Interpreter

# Obtain and Map Results

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## Initialize the Interpreter

Model is loaded in the interpreter at this stage

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## Perform Inference

Pass input to the Interpreter and Invoke the Interpreter

# Obtain and Map Results

```
let modelPath = Bundle.main.path(
    forResource: modelFilename, ofType: modelFileInfo.extension)
```

```
var options = InterpreterOptions()
options.threadCount = threadCount
```

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let modelPath = Bundle.main.path(
    forResource: modelFilename, ofType: modelFileInfo.extension)
```

```
var options = InterpreterOptions()
options.threadCount = threadCount
```

```
do {
    try interpreter.allocateTensors()
}
catch let error {
}
```

1 - 2 - 3 -

# Initialize the Interpreter

Model is loaded in the interpreter at this stage

#### Preparing the Image Input

Input image pixel buffer is converted to the format recognized by the model

## Perform Inference

Pass input to the Interpreter and Invoke the Interpreter

# Obtain and Map Results

- Model Expects pixel buffer of size 224 x 224 x 3
- iOS uses CVPixelBuffer to represent images in memory
- CVPixelBuffer has Alpha as well as RGB
- Need to extract R, G, B from CVPixelBuffer and normalize
- Final output has to be of type 'Data'

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- iOS uses CVPixelBuffer to represent images in memory
- CVPixelBuffer has Alpha as /ill as RGB
- Need to extract R,

Final output

CVPixelBuffer and normalize

'Data'

https://developer.apple.com/documentation/corevideo/cvpixelbuffer-q2e

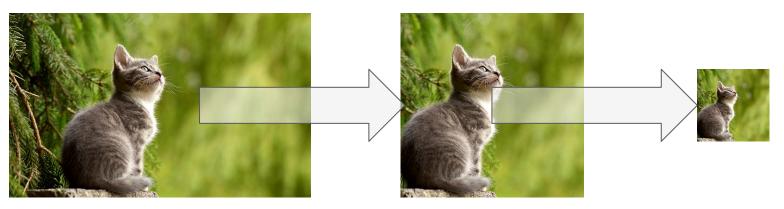
- Model Expects pixel buffer of size 224 x 224 x 3
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- iOS uses CVPixelBuffer to represent images in memory
- CVPixelBuffer has Alpha as well as RGB
- Need to extract R, G, B from CVPixelBuffer and normalize
- Final output has to be of type 'Data'

### Scaling and Cropping the CVPixelBuffer

Crop the biggest square and scale down to 224 x 224



- vImage is used for image operations
- https://developer.apple.com/documentation/accelerate/vimage

```
let inputWidth = 224
let inputHeight = 224
let scaledSize = CGSize(width: inputWidth, height: inputHeight)
```

let thumbnailPixelBuffer = pixelBuffer.centerThumbnail(ofSize: scaledSize)

```
let inputChannels = 3

let rgbData = rgbDataFromBuffer(
    thumbnailPixelBuffer,
    byteCount: inputWidth * inputHeight * inputChannels
)
```

```
private func rgbDataFromBuffer(_ buffer: CVPixelBuffer,byteCount: Int) ->
Data? {
    let mutableRawPointer = CVPixelBufferGetBaseAddress(buffer)
    let count = CVPixelBufferGetDataSize(buffer)
    let bufferData = Data(bytesNoCopy: mutableRawPointer, count: count,
deallocator: .none)
    var rgbBytes = [UInt8](repeating: 0, count: byteCount)
```

```
for component in bufferData.enumerated() {
    let offset = component.offset
    let isAlphaComponent = (offset % alphaComponent.baseOffset) ==
                                       alphaComponent.moduloRemainder
    guard !isAlphaComponent else { continue }
    rgbBytes[index] = Float(component.element) / 255.0
    index += 1
```

return rgbBytes.withUnsafeBufferPointer(Data.init)

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## Initialize the Interpreter

Model is loaded in the interpreter at this stage

#### Preparing the Image Input

Input image pixel buffer is converted to the format recognized by the model

### Perform Inference

Pass input to the Interpreter and Invoke the Interpreter

# Obtain and Map Results

```
// Copy the RGB data to the input Tensor.
try interpreter.copy(rgbData, toInputAt: 0)
// Run inference by invoking the Interpreter.
try interpreter.invoke()
// Get the output Tensor to process the inference results.
outputTensor = try interpreter.output(at: 0)
```

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1 - 2 - 3 -

# Initialize the Interpreter

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#### Preparing the Image Input

Input image pixel buffer is converted to the format recognized by the model

## Perform Inference

Pass input to the Interpreter and Invoke the Interpreter

# Obtain and Map Results

4

```
let results = [Float32](unsafeData: outputTensor.data) ?? []
```

```
private var labels: [String] = ["Cat", "Dog"]
let topNInferences = getTopN(results: results)
private func getTopN(results: [Float]) -> [Inference] {
   let zippedResults = zip(labels.indices, results)
   // Sort the zipped results by confidence value in descending order.
   let sortedResults = zippedResults.sorted { $0.1 > $1.1 }
   return sortedResults.map
            { result in Inference(confidence: result.1, label: labels[result.0]) }
```

```
private var labels: [String] = ["Cat", "Dog"]
let topNInferences = getTopN(results: results)
private func getTopN(results: [Float]) -> [Inference] {
   let zippedResults = zip(labels.indices, results)
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   return sortedResults.map
            { result in Inference(confidence: result.1, label: labels[result.0]) }
```

#### Calling Inference from UI

- ViewController uses a UICollectionView to display images
- Initializes ModelDataHandler
- Hands over Inference to ModelDatahandler

#### Initializing the ModelDataHandler

```
var result: Result?
func collectionView(_ collectionView: UICollectionView,
                    didSelectItemAt indexPath: IndexPath) {
    let image = UIImage(named: imageNames[indexPath.item])
    let pixelBuffer = pixelBuffer(from: image)
    result = modelDataHandler?.runModel(onFrame: pixelBuffer)
```

```
var result: Result?
func collectionView(_ collectionView: UICollectionView,
                    didSelectItemAt indexPath: IndexPath) {
    let image = UIImage(named: imageNames[indexPath.item])
    let pixelBuffer = pixelBuffer(from: image)
    result = modelDataHandler?.runModel(onFrame: pixelBuffer)
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var result: Result?
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                    didSelectItemAt indexPath: IndexPath) {
    let image = UIImage(named: imageNames[indexPath.item])
    let pixelBuffer = pixelBuffer(from: image)
    result = modelDataHandler?.runModel(onFrame: pixelBuffer)
```

```
var result: Result?
func collectionView(_ collectionView: UICollectionView,
                    didSelectItemAt indexPath: IndexPath) {
    let image = UIImage(named: imageNames[indexPath.item])
    let pixelBuffer = pixelBuffer(from: image)
    result = modelDataHandler?.runModel(onFrame: pixelBuffer)
```



#### Please click on the images to perform inference

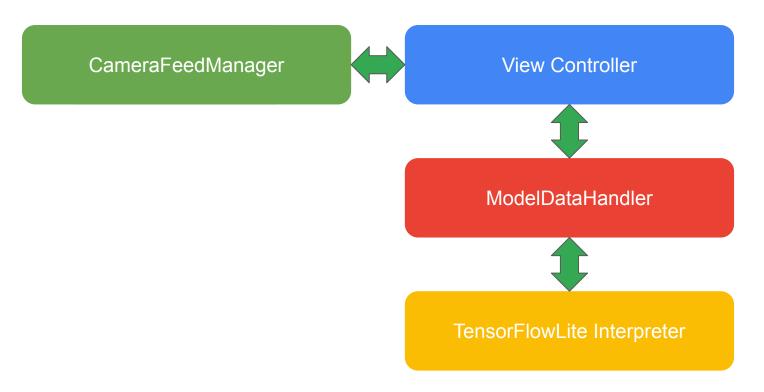








### **App Architecture**



#### Image Classification Model Details

- Quantized MobileNet SSD trained on COCO dataset
- Trained on ImageNet 1000 classes.
- More details on the model can be found in the link below https://www.tensorflow.org/lite/models/image\_classification/overview
- Labels file is used to list 1000 classes and map to output confidences
- You can download the .tflite file and .txt file from the following link.

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## Initialize the Interpreter

Model is loaded in the interpreter at this stage

#### Preparing the Image Input

Input image pixel buffer is converted to the format recognized by the model

### Perform Inference

Pass input to the Interpreter and Invoke the Interpreter

## Obtain and Map Results

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### Initialize the Interpreter

Model is loaded in the interpreter at this stage

#### Preparing the Image Input

Input image pixel buffer is converted to the format recognized by the model

### Perform Inference

Pass input to the Interpreter and Invoke the Interpreter

## Obtain and Map Results

```
let modelPath = Bundle.main.path(forResource: modelFilename,
                                 ofType: modelFileInfo.extension)
// Specify the options for the `Interpreter`.
var options = InterpreterOptions()
options.threadCount = threadCount
interpreter = try Interpreter(modelPath: modelPath, options: options)
// Load the classes listed in the labels file.
loadLabels(fileInfo: labelsFileInfo)
```

```
do {
    // Allocate memory for the model's input `Tensor`s.
    try interpreter.allocateTensors()
}
catch let error {
}
```

1 - 2 - 3 -

## Initialize the Interpreter

Model is loaded in the interpreter at this stage

#### Preparing the Image Input

Input image pixel buffer is converted to the format recognized by the model

### Perform Inference

Pass input to the Interpreter and Invoke the Interpreter

## Obtain and Map Results

#### CameraFeedManager

- Initialized by ViewController
- Communicates with ViewController using delegates.
- Handles all camera initialization and functionality
- Uses AVFoundation to initialize and obtain frames from the back camera.
- Link to camera handling using AVFoundation
- https://developer.apple.com/documentation/avfoundation/cam
   eras and media capture/avcam building a camera app

```
private lazy var cameraCapture = CameraFeedManager(previewView: previewView)
override func viewWillAppear(_ animated: Bool) {
    cameraCapture.checkCameraConfigurationAndStartSession()
override func viewDidLoad() {
    cameraCapture.delegate = self
```

```
private lazy var cameraCapture = CameraFeedManager(previewView: previewView)
override func viewWillAppear(_ animated: Bool) {
    cameraCapture.checkCameraConfigurationAndStartSession()
override func viewDidLoad() {
    cameraCapture.delegate = self
```

```
private lazy var cameraCapture = CameraFeedManager(previewView: previewView)
override func viewWillAppear(_ animated: Bool) {
    cameraCapture.checkCameraConfigurationAndStartSession()
override func viewDidLoad() {
    cameraCapture.delegate = self
```

```
private lazy var cameraCapture = CameraFeedManager(previewView: previewView)

override func viewWillAppear(_ animated: Bool) {
    cameraCapture.checkCameraConfigurationAndStartSession()
}
```

```
override func viewDidLoad() {
     ...
     cameraCapture.delegate = self
}
```

```
extension CameraFeedManager: AVCaptureVideoDataOutputSampleBufferDelegate() {
   func captureOutput(_ output: AVCaptureOutput,
                        didOutput sampleBuffer: CMSampleBuffer
                        from connection: AVCaptureConnection){
        let pixelBuffer: CVPixelBuffer? = CMSampleBufferGetImageBuffer(sampleBuffer)
       quard let imagePixelBuffer = pixelBuffer else{
            return
       delegate?.didOutput(pixelBuffer: imagePixelBuffer)
```

#### **Preparing the Input**

- Expects pixel buffer of size 224 x 224 x 3
- Our CVPixelBuffer is of type BGRA\_32
- Has to be converted to Pixel buffer with only R, G, B channels.
- Pixel Buffer has to be converted to Data

### Scaling and Cropping the CVPixelBuffer

- Crop the biggest square and scale down to 224 x 224
- vImage is used for image operations
- https://developer.apple.com/documentation/accelerate/vimage

### **Handling Quantized Model Inputs**

```
isModelQuantized: inputTensor.dataType == .uInt8

if isModelQuantized { return Data(bytes: rgbBytes) }

return Data(copyingBufferOf: rgbBytes.map { Float($0) / 255.0 })
```

1 - 2 - 3 -

## Initialize the Interpreter

Model is loaded in the interpreter at this stage

#### Preparing the Image Input

Input image pixel buffer is converted to the format recognized by the model

### Perform Inference

Pass input to the Interpreter and Invoke the Interpreter

## Obtain and Map Results

#### Invoking the Interpreter

```
// Copy the RGB data to the input `Tensor`.
try interpreter.copy(rgbData, toInputAt: 0)

// Run inference by invoking the `Interpreter`.
try interpreter.invoke()

// Get the output `Tensor` to process the inference results.
outputTensor = try interpreter.output(at: 0)
```

1 - 2 -

Preparing the Image Input

Input image pixel buffer is converted to the format recognized by the model

Perform Inference

3

Pass input to the Interpreter and Invoke the Interpreter

Obtain and Map Results

4

Map our resulting confidence values to labels

### Initialize the Interpreter

Model is loaded in the interpreter at this stage

```
let results: [Float]
switch(outputTensor.dataType) {

    case .uInt8:
        let quantization = outputTensor.quantizationParameters
        let quantizedResults = [UInt8](outputTensor.data)
        results = quantizedResults.map {
            quantization.scale * Float(Int($0) - quantization.zeroPoint)
        }

    case .float32:
        results = [Float32](unsafeData: outputTensor.data) ?? []
```

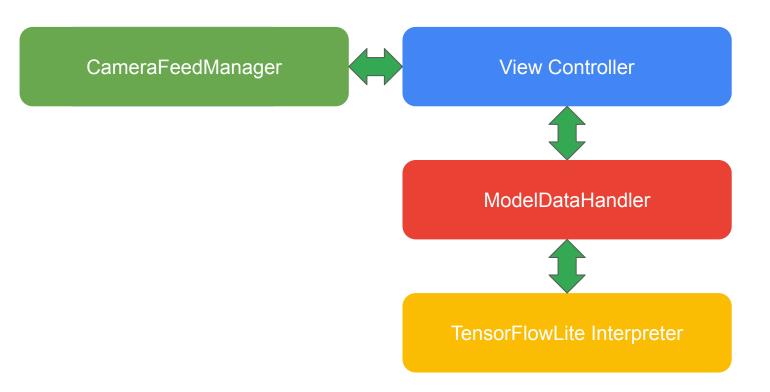
```
let topNInferences = getTopN(results: results)
private func getTopN(results: [Float]) -> [Inference] {
   let zippedResults = zip(labels.indices, results)
   // Sort the zipped results by confidence value in descending order.
   let sortedResults = zippedResults.sorted { $0.1 > $1.1 }.prefix(resultCount)
   return sortedResults.map { result in Inference(confidence: result.1,
                                                  label: labels[result.0]) }
```

```
DispatchQueue.main.async {

    //Formatting each result into an array of strings
    let resultStrings = finalInferences.map({ (inference) in
        return String(format: "%s %.2f",inference.label, inference.confidence)
    })

    //Preparing them for display
    self.resultLabel.text = resultStrings.joined(separator: "\n")
```

#### **App Architecture**



### **Object Detection Model Details**

MobileNet SSD trained on COCO dataset

https://github.com/tensorflow/models/tree/master/research/object\_detection

COCO dataset has 90 classes

Labels file is used to list COCO classes and map to output confidences

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## Initialize the Interpreter

Model is loaded in the interpreter at this stage

#### Preparing the Image Input

Input image pixel buffer is converted to the format recognized by the model

### Perform Inference

Pass input to the Interpreter and Invoke the Interpreter

## Obtain and Map Results

### Initializing the Interpreter

```
let modelPath = Bundle.main.path(forResource: modelFilename, ofType: modelFileInfo.extension)

// Specify the options for the `Interpreter`.

var options = InterpreterOptions()

options.threadCount = threadCount

interpreter = try Interpreter(modelPath: modelPath, options: options)

// Load the classes listed in the labels file.
loadLabels(fileInfo: labelsFileInfo)
```

1 - 2 - 3 -

## Initialize the Interpreter

Model is loaded in the interpreter at this stage

#### Preparing the Image Input

Input image pixel buffer is converted to the format recognized by the model

### Perform Inference

Pass input to the Interpreter and Invoke the Interpreter

## Obtain and Map Results

### **Preparing the Input**

- Expects pixel buffer of size 300 x 300 x 3
- Our CVPixelBuffer is of type BGRA\_32
- Has to be converted to Pixel buffer with only R, G, B channels.
- Pixel Buffer has to be converted to Data
- vImage is used for image operations
- https://developer.apple.com/documentation/accelerate/vimage

1 - 2 - 3 -

### Initialize the Interpreter

Model is loaded in the interpreter at this stage

#### Preparing the Image Input

Input image pixel buffer is converted to the format recognized by the model

### Perform Inference

Pass input to the Interpreter and Invoke the Interpreter

## Obtain and Map Results

#### **Invoking the Interpreter**

```
// Copy the RGB data to the input Tensor.
try interpreter.copy(rgbData, toInputAt: 0)

// Run inference by invoking the Interpreter.
try interpreter.invoke()
```

1 - 2 - 3 - 4

## Initialize the Interpreter

Model is loaded in the interpreter at this stage

#### Preparing the Image Input

Input image pixel buffer is converted to the format recognized by the model

### Perform Inference

Pass input to the Interpreter and Invoke the Interpreter

## Obtain and Map Results

### **Output Tensors**

0	Bounding Boxes
1	Classes
2	Scores
3	Number of Results

#### **Getting the Output Tensors**

```
outputBoundingBox = try interpreter.output(at: 0)
outputClasses = try interpreter.output(at: 1)
outputScores = try interpreter.output(at: 2)
outputCount = try interpreter.output(at: 3)
```

```
// Format the results
let resultArray = formatResults(
  boundingBox: [Float](unsafeData: outputBoundingBox.data) ?? [],
  outputClasses: [Float](unsafeData: outputClasses.data) ?? [],
  outputScores: [Float](unsafeData: outputScores.data) ?? [],
  outputCount: Int(([Float](unsafeData: outputCount.data) ?? [0])[0]),
  width: CGFloat(imageWidth),
  height: CGFloat(imageHeight)
return resultArray
```

```
func formatResults( boundingBox: [Float],
                    outputClasses: [Float],
                    outputScores: [Float],
                    outputCount: Int,
                    width: CGFloat, height: CGFloat) -> [Inference]{
var resultsArray: [Inference] = []
    for i in 0..<outputCount {</pre>
        //Obtain formatted results from the tensors
```

```
let score = outputScores[i]
// Filters results with confidence < threshold.
guard score >= threshold else {
    continue
// Gets the output class names for detected classes from labels list.
let outputClassIndex = Int(outputClasses[i])
let outputClass = labels[outputClassIndex + 1]
```

```
var rect: CGRect = CGRect.zero
// Translates the detected bounding box to CGRect.
rect.origin.y = CGFloat(boundingBox[4*i])
rect.origin.x = CGFloat(boundingBox[4*i+1])
rect.size.height = CGFloat(boundingBox[4*i+2]) - rect.origin.y
rect.size.width = CGFloat(boundingBox[4*i+3]) - rect.origin.x
// The detected corners are for model dimensions. So we scale the rect with respect to the
// actual image dimensions.
let newRect = rect.applying(CGAffineTransform(scaleX: width, y: height))
```

```
func runModel(onPixelBuffer pixelBuffer: CVPixelBuffer) {
  //Run the live camera pixelBuffer through tensorFlow to get the result
  let inferences = self.modelDataHandler?.runModel(onFrame: pixelBuffer)
  let width = CVPixelBufferGetWidth(pixelBuffer)
  let height = CVPixelBufferGetHeight(pixelBuffer)
  DispatchQueue.main.async {
  // Draws the bounding boxes and displays class names and confidence scores.
  self.drawAfterPerformingCalculations(
     onInferences: inferences,
     withImageSize: CGSize(width: CGFloat(width), height: CGFloat(height)))
```

```
func runModel(onPixelBuffer pixelBuffer: CVPixelBuffer) {
  //Run the live camera pixelBuffer through tensorFlow to get the result
  let inferences = self.modelDataHandler?.runModel(onFrame: pixelBuffer)
  let width = CVPixelBufferGetWidth(pixelBuffer)
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