



Behavior Recognition via Sparse Spatio-Temporal Features

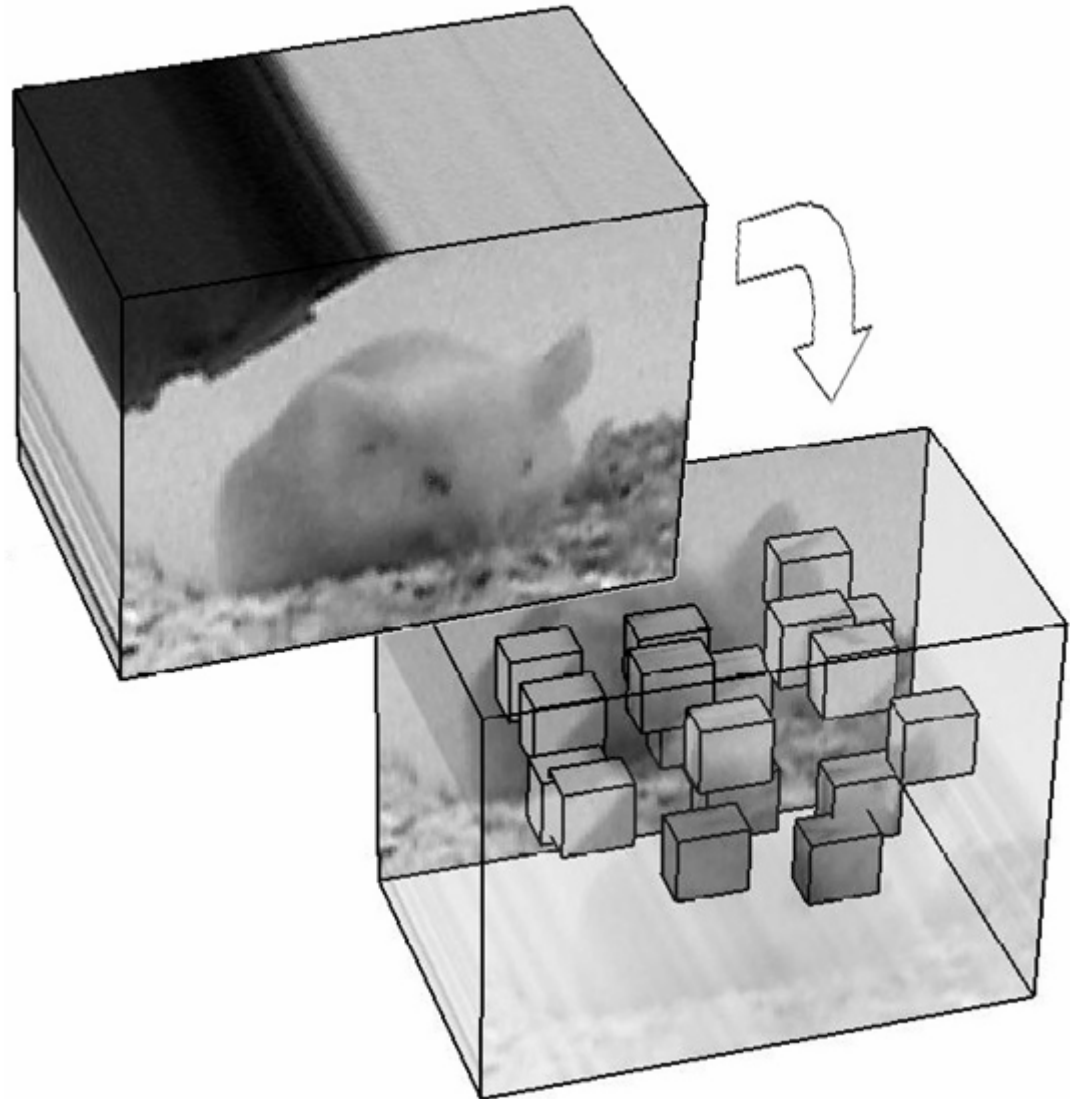
Piotr Dollár
Garrison Cottrell

Vincent Rabaud
Serge Belongie

Antón R. Escobedo
cse 252c

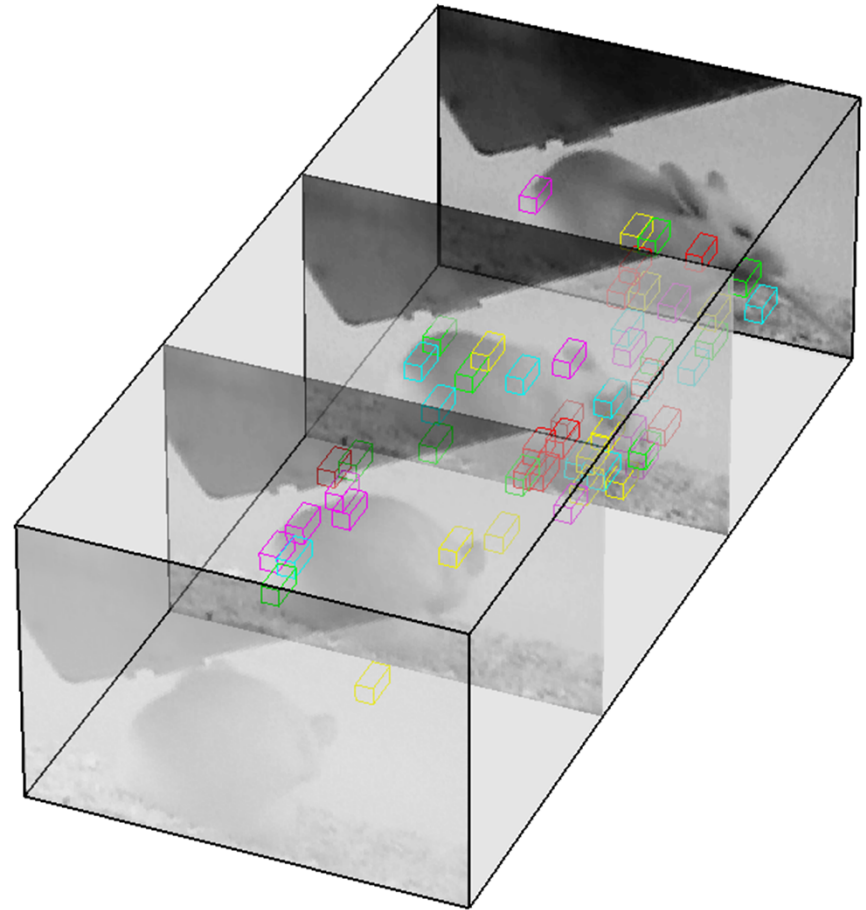
Outline

- I. Introduction
- II. Related Work
- III. Algorithm
- IV. Experiments
- V. Current Work



[Part I: Introduction]

- Motivation:
 - Sparse feature points extended to the spatio-temporal case



[Part I: Introduction]

- Motivation:
 - Behavior detection from video sequences
 - Behavior recognition faces similar issues to those seen in object recognition.
 - Posture, appearance, size, image clutter, variations in the environment such as illumination.
 - Imprecise nature of feature detectors.

[Part I: Introduction]

- Inspiration: Sparsely detected features in object recognition.
 - Fergus et al. “Object Class Recognition by Unsupervised Scale-Invariant Learning”
 - Agarwal et al. “Learning to Detect Objects in Images via a Sparse, Part-Based Representation”
 - Leibe, Schiele “Scale invariant Object Categorization Using a Scale-Adaptive Mean-Shift Search”

[Part I: Introduction]

Advantages of Sparse Features

- Robustness
- Very good results

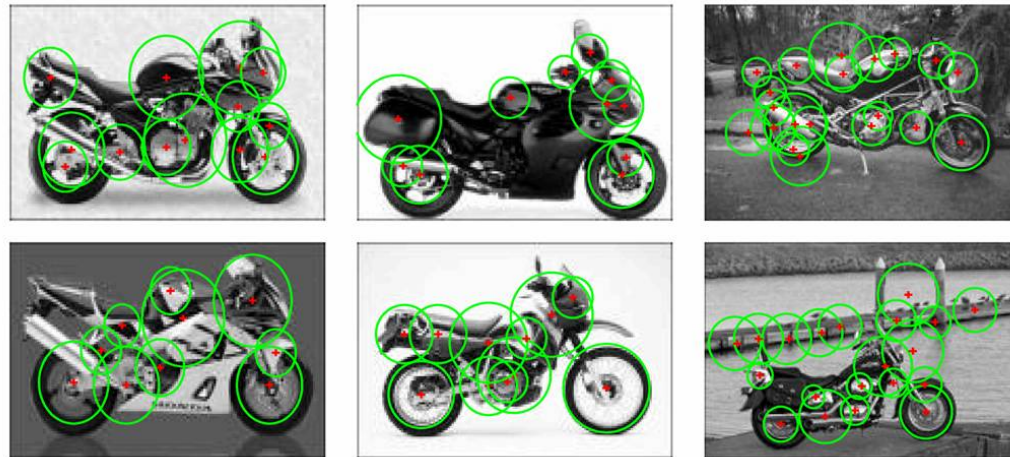


example from: <http://www.robots.ox.ac.uk/~fergus/research/index.html>

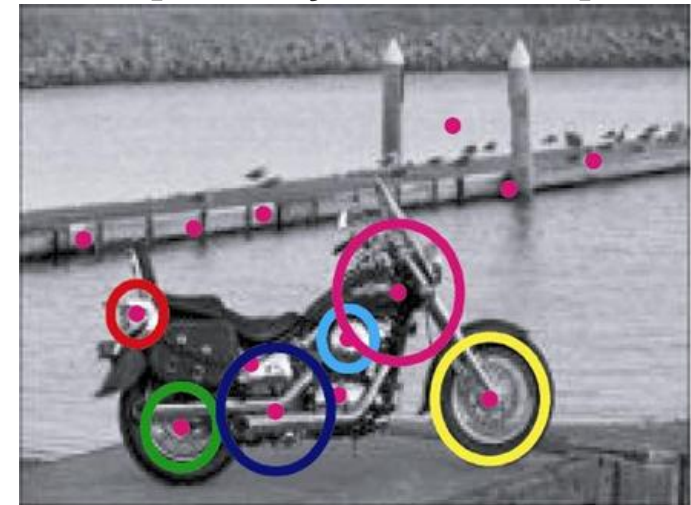
object recognition

example from: <http://www.robots.ox.ac.uk/~fergus/research/index.html>

[training data & features]



[motorcycle detected]

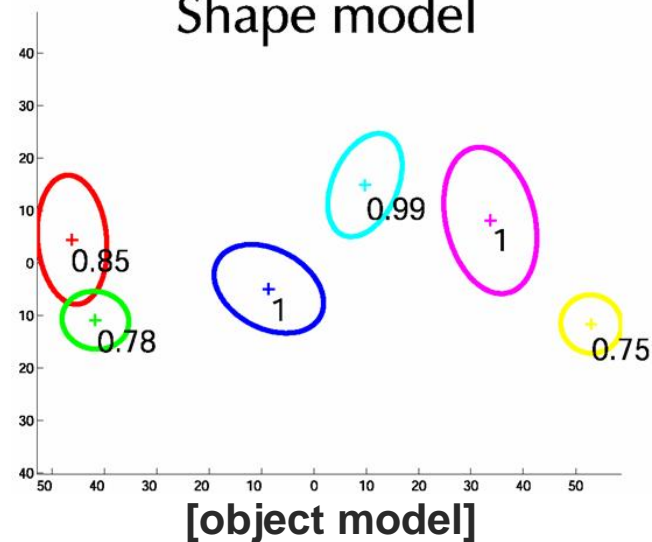


train



[parts]

Shape model



classify

[Spatial-Temporal Features]

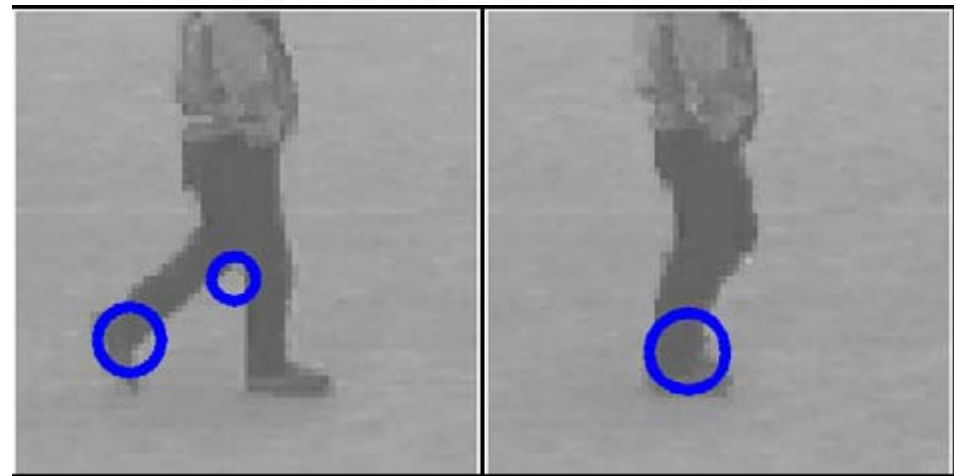
- Short, local video sequence that can be used to describe a behavior.
- Behavior recognition based on features detected and compared with a rich set of features.
- 3rd dimension
 - Temporal, not spatial

[Part I: Introduction]

- Will Show:
 - Direct 3D counterparts to feature detectors are inadequate.
 - Development and testing of descriptors used in this paper.
 - A dictionary of descriptors is all that is needed to recognize behavior.
 - Proven on human behavior, facial expressions and mouse behavior dataset

[Part II: Related Work]

- Articulated models
- Efros et al.
 - 30 pixel man
- Schuldt et al.
 - Spatio-Temporal features



Images from:

http://www.eecs.berkeley.edu/Research/Projects/CS/vision/human/efros-iccv03_slides/efrosbmm_iccv03.ppt

<ftp://ftp.nada.kth.se/CVAP/users/laptev/icpr04actions.pdf>

[Part III: Proposed Algorithm]

- Feature Detection
- Cuboids
- Cuboid Prototypes
- Behavior Descriptors

[Feature Detection (spatial domain)]

- Corner Detectors
- Laplacian of Gaussian (SIFT)
- Extensions to Spatio-Temporal Case
 - Stacks of images denoted by: $I(x,y,t)$
 - Detected features also have temporal extent.

[Feature Detection]

- Harris in 3D
 - Spatio-Temporal corners:
 - Regions where the local gradient vectors point in orthogonal directions for x, y and t .
 - Why this doesn't work
- Develop an Alternative detector
 - Err on the side of too many features
 - Why this works

[Feature Detection]

■ Response Function

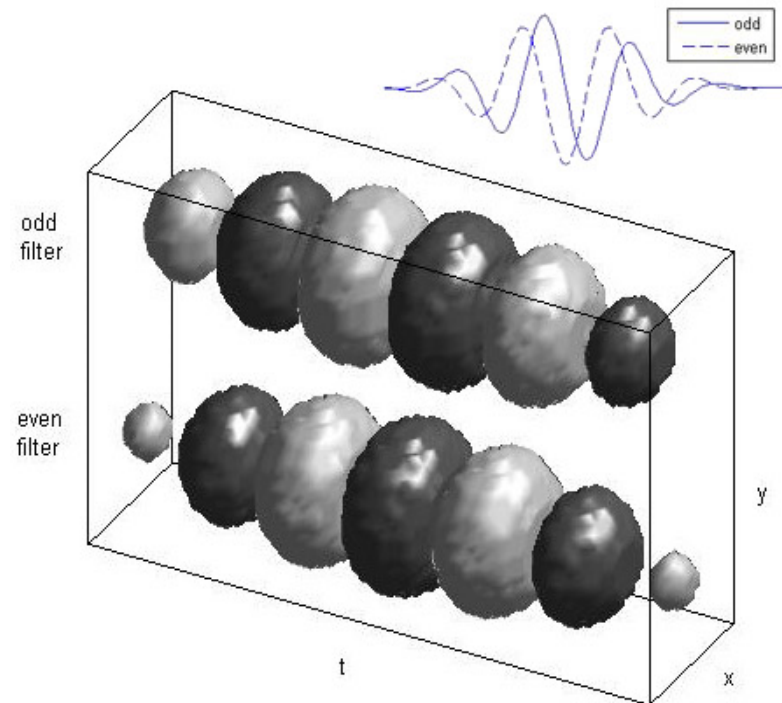
$$R = (I * g * h_{ev})^2 + (I * g * h_{od})^2$$

- Spatial Filter:
Gaussian

- Temporal Filter:
Gabor

$$h_{ev}(t; \tau, \omega) = -\cos(2\pi t\omega)e^{-t^2/\tau^2}$$

$$h_{od}(t; \tau, \omega) = -\sin(2\pi t\omega)e^{-t^2/\tau^2}$$

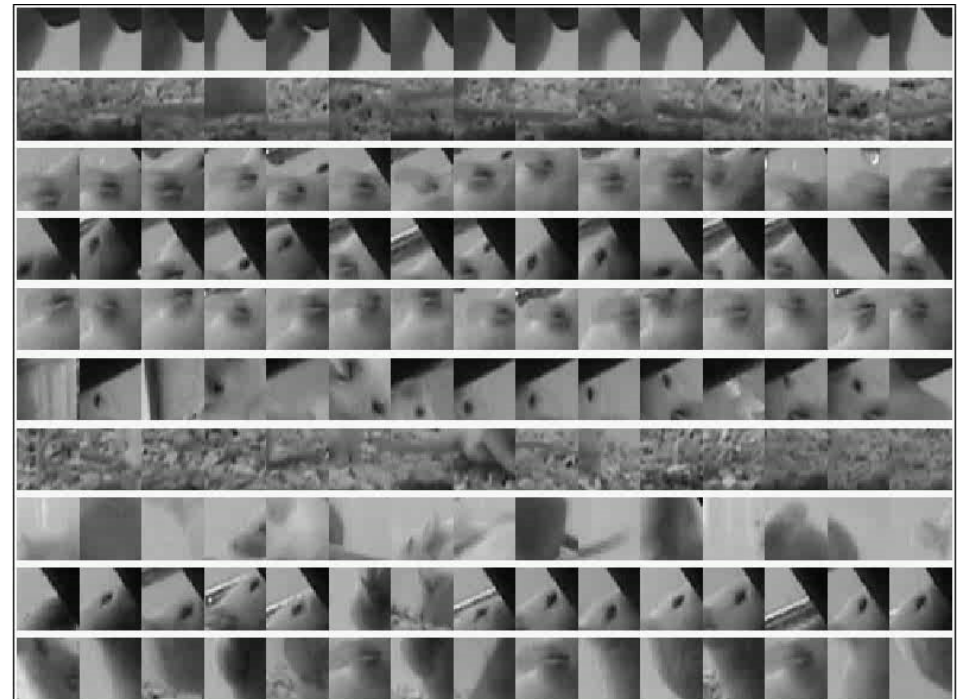


[Feature Detection]

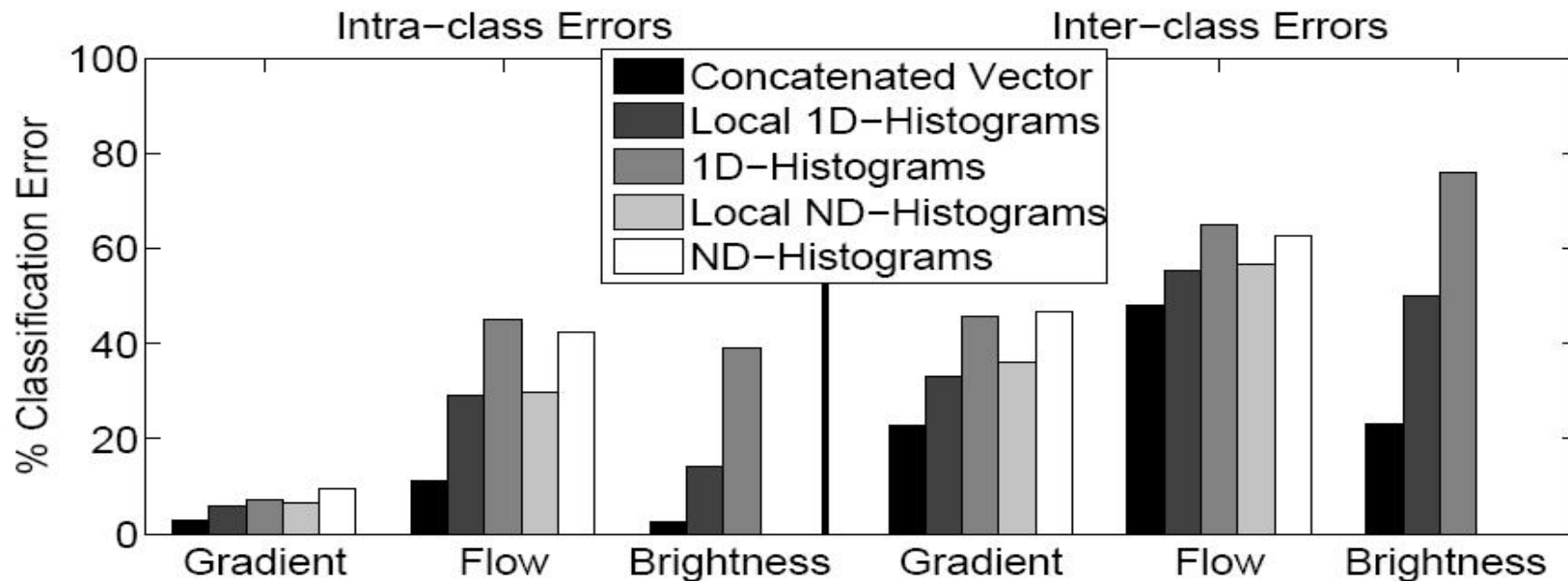
- What this implies:
 - Any region with spatially distinguishing characteristics undergoing a complex motion will induce a strong response.
 - Pure translation will not induce a response.

[Cuboids]

- Extracted at each interest point
 - ~6x scale at which detected
- Descriptor: Feature Vector
 - Transformations Applied
 - Normalize Pixel Values
 - Brightness Gradient
 - Optical Flow
 - Feature Vector from local histograms



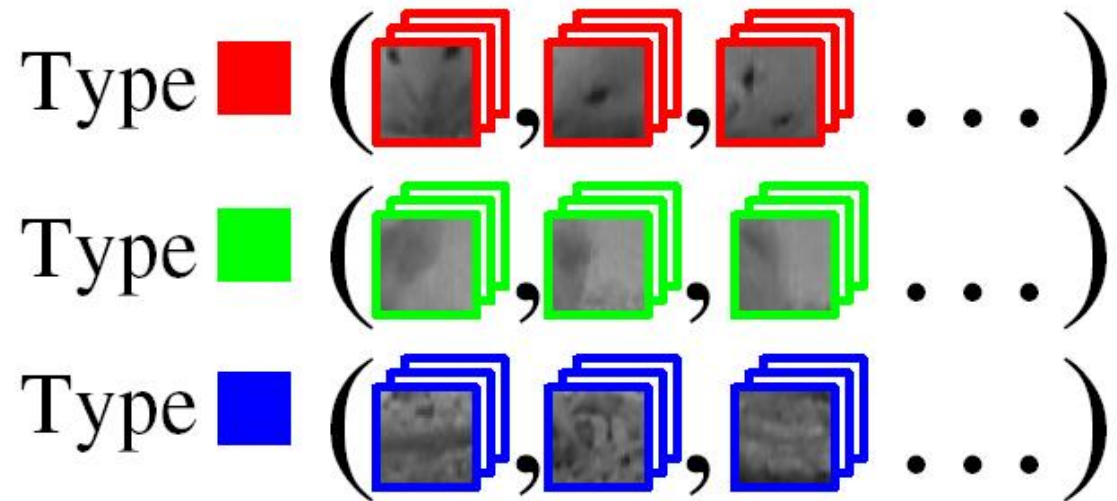
Cuboid Descriptor



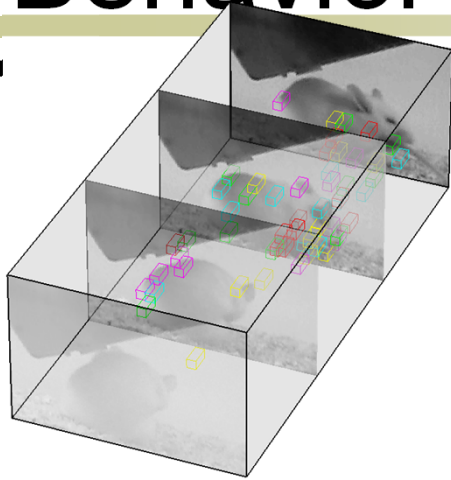
- Flattened Gradient vector gave best results
- Generalization of PCA-SIFT descriptor

[Cuboid Prototypes]

- Unlimited cuboids are possible, but only a limited number of types exist.
- Use k-means algorithm to cluster extracted cuboids together by type.



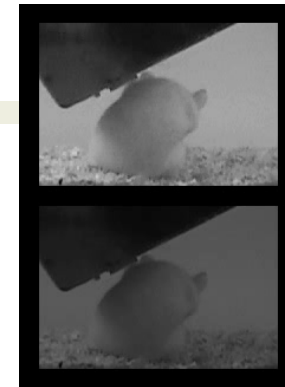
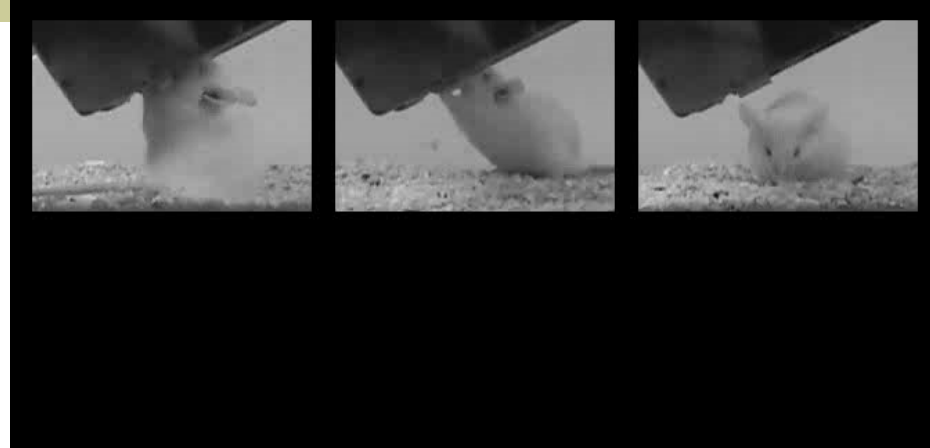
Behavior Descriptor



- Assumption is that cuboid types present capture all information about behavior.
- Behavior descriptor: histogram of cuboid types
 - Simple.
 - Distance measured using chi-squared distance.
 - Can easily be used in classification framework.
 - Discards spatial layout and temporal order of cuboids.

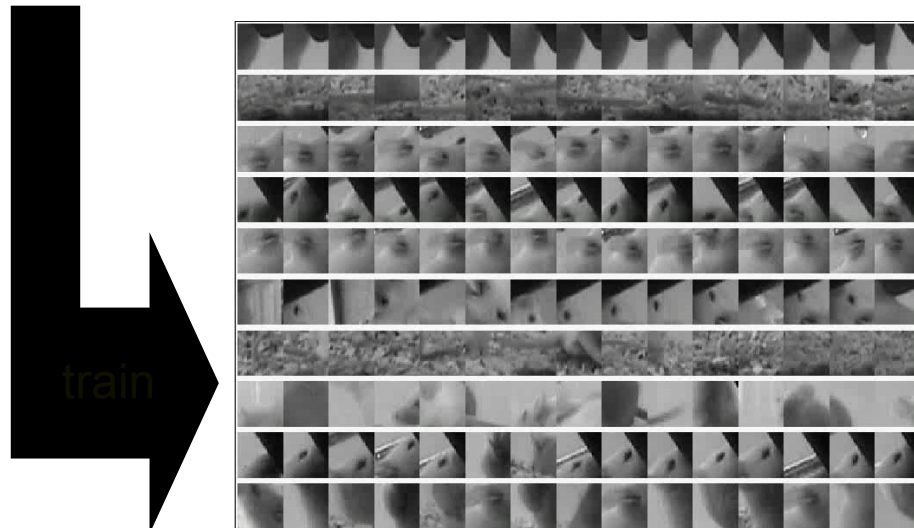
sppatio-temporal features

[training data & features]

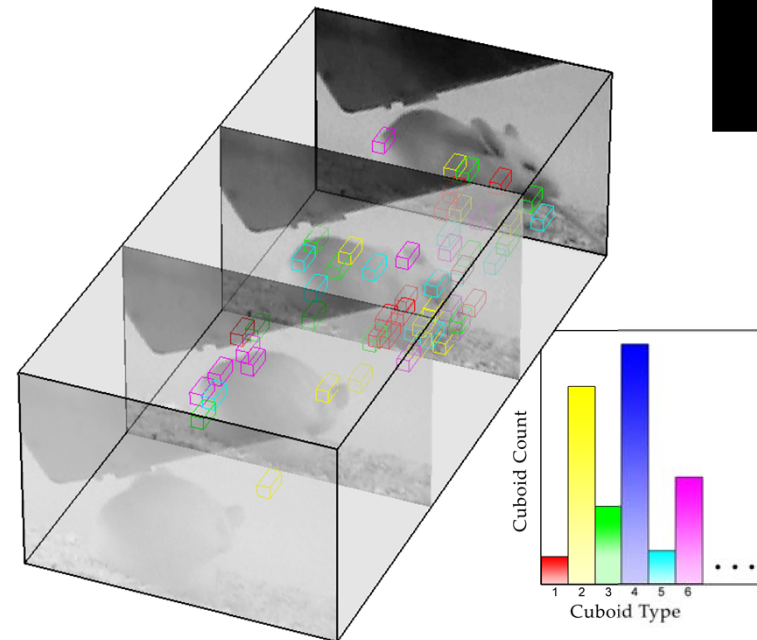


[grooming detected]

classify



[cuboid prototypes]



[behavior model]

[domain 1: human activity]

training examples:

boxing



clapping



test example:

boxing



[domain 2: facial expressions]

training examples:

disgust



happiness



test example:

disgust



[domain 3: mouse behavior]

training examples:

eating



exploring



test example:

eating



[near vs. medium field]

Efros et al. 2003

near field



medium field



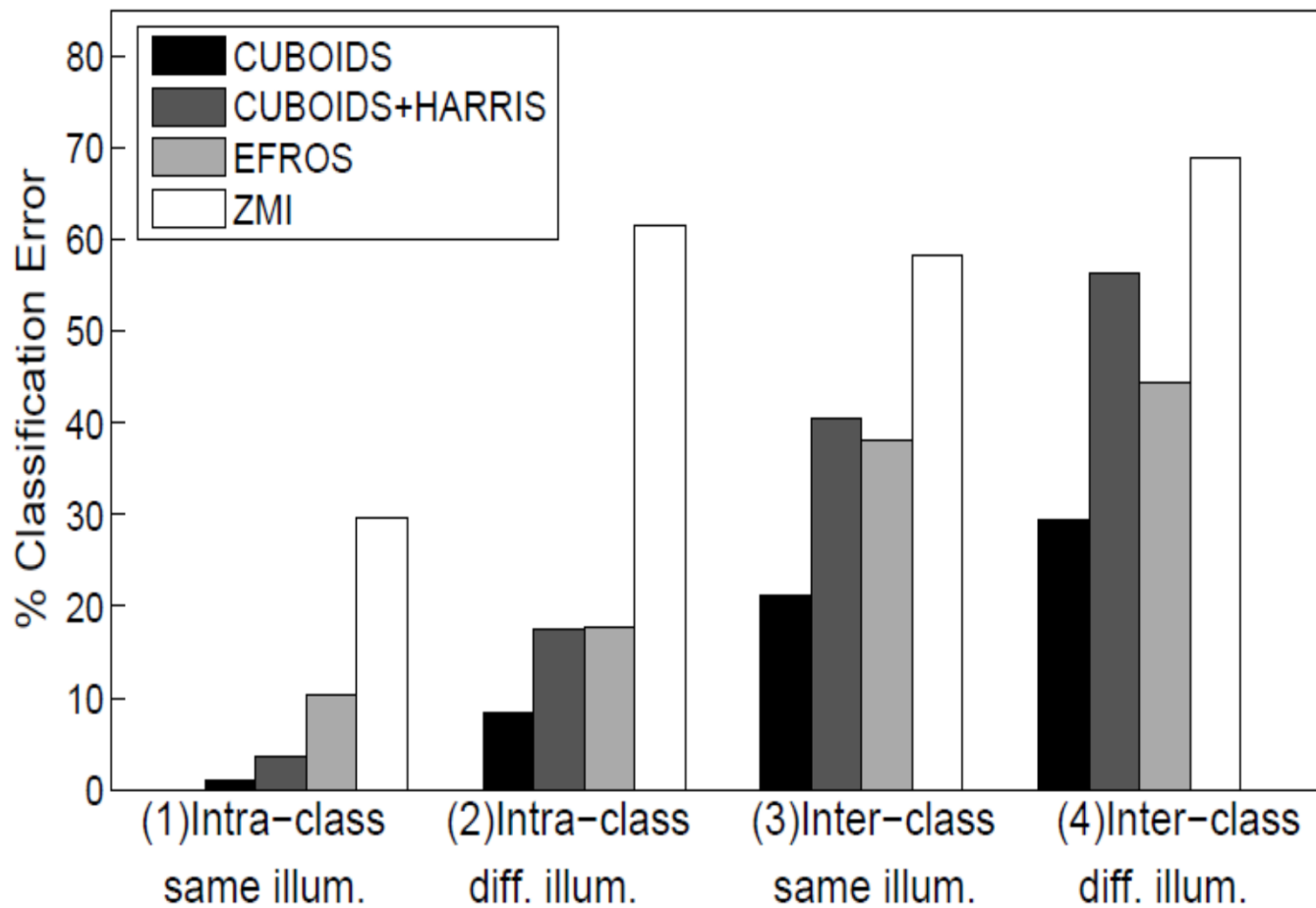
far field



[performance evaluation]

- compared 4 methods:
 - **CUBOIDS** – our approach
 - **CUBOIDS+HARRIS** – our approach using Laptev's 3D corner detector
 - **ZMI** – Zelnik-Manor & Irani 2001
 - Statistical measure of gross activity using histograms of spatio-temporal gradients gives activity descriptor
 - **EFROS** – Efros et al. 2003
 - Normalized cross correlation of optical flow gives distance measure between activities
- analysis in terms of **relative** performance
- not all algorithms are always applied
 - format of data, computational complexity

facial expressions I



[facial expressions II]

Train on Sub 1 / Test on Sub 2

anger	.29	.13	.47	.11	.00	.00
disgust	.02	.94	.04	.00	.00	.00
fear	.00	.00	.90	.00	.06	.04
joy	.00	.00	.00	1.0	.00	.00
sadness	.00	.01	.11	.00	.88	.00
surprise	.00	.00	.00	.00	.00	1.0
	anger	disgust	fear	joy	sadness	surprise

Train on Sub 2 / Test on Sub 1

anger	.61	.32	.00	.07	.00	.00
disgust	.06	.94	.00	.00	.00	.00
fear	.17	.13	.64	.04	.00	.03
joy	.07	.00	.00	.93	.00	.00
sadness	.00	.00	.00	.00	1.0	.00
surprise	.00	.00	.00	.00	.00	1.0
	anger	disgust	fear	joy	sadness	surprise

confusion matrices, row normalized

mouse behavior full database results

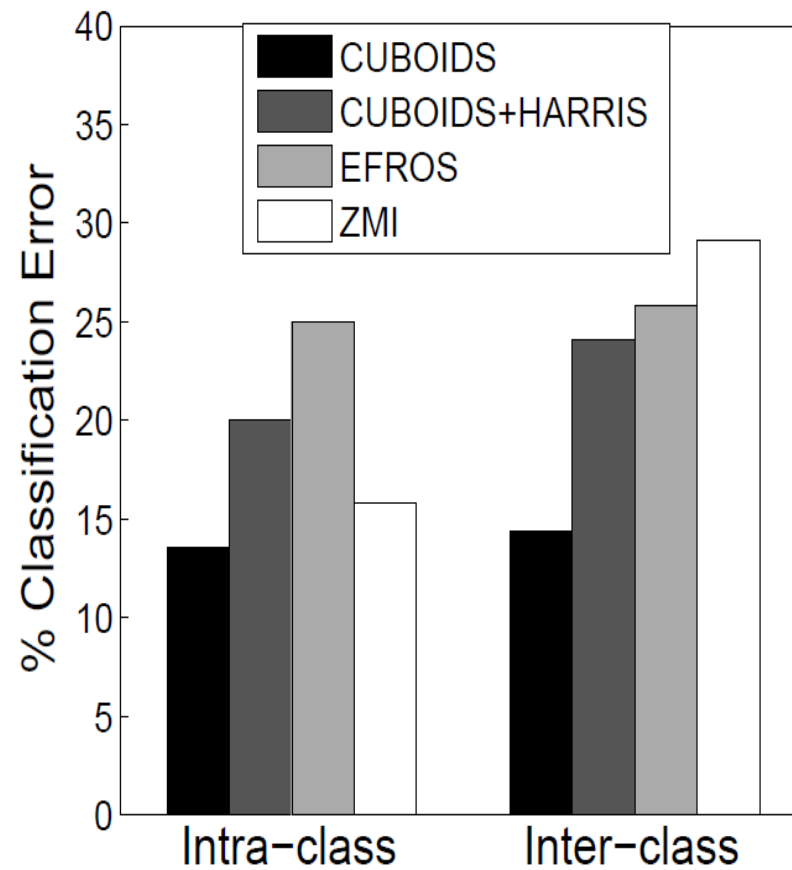
1-NN

drink	.65	.00	.24	.06	.06
eat	.00	.89	.09	.02	.00
explore	.02	.04	.86	.07	.02
groom	.05	.00	.64	.32	.00
sleep	.02	.00	.09	.02	.87
	drink	eat	explore	groom	sleep

LDA

drink	.76	.06	.00	.00	.18
eat	.01	.88	.07	.02	.01
explore	.04	.02	.74	.14	.05
groom	.09	.00	.34	.55	.02
sleep	.02	.00	.09	.00	.89
	drink	eat	explore	groom	sleep

[mouse behavior pilot study]

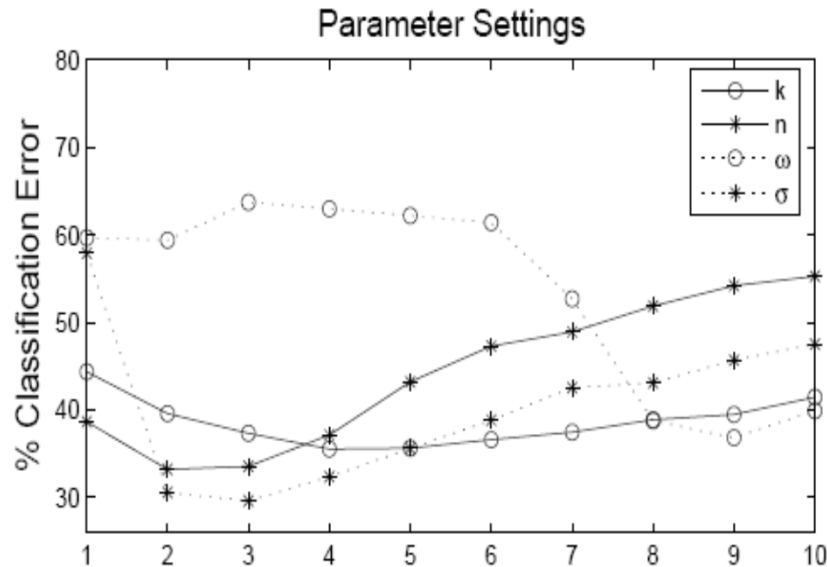


[human activity]

	1-NN					
walking	.89	.10	.00	.00	.01	.02
jogging	.25	.63	.12	.00	.00	.00
running	.05	.23	.73	.00	.00	.00
boxing	.00	.00	.00	.80	.15	.05
handclapping	.00	.00	.00	.09	.82	.09
handwaving	.00	.00	.00	.06	.10	.84
	walking	jogging	running	boxing	handclapping	handwaving

	SVM					
walking	.90	.04	.05	.01	.01	.00
jogging	.20	.57	.24	.00	.00	.00
running	.03	.13	.85	.00	.00	.00
boxing	.00	.00	.00	.93	.06	.01
handclapping	.00	.00	.01	.22	.77	.01
handwaving	.03	.00	.01	.07	.04	.85
	walking	jogging	running	boxing	handclapping	handwaving

[parameter settings]



- k , $50 < k < 500$, number of clusters
- n , $10 \leq n \leq 200$, number of cuboids per clip
- ω , $0 < \omega < 1$ overlap allowed between cuboids
- σ , $2 < \sigma < 9$, spatial scale of the detector
- Base settings used were approximately:
 - $k = 250$, $n = 30$, $\omega = .9$, and $\sigma = 2$

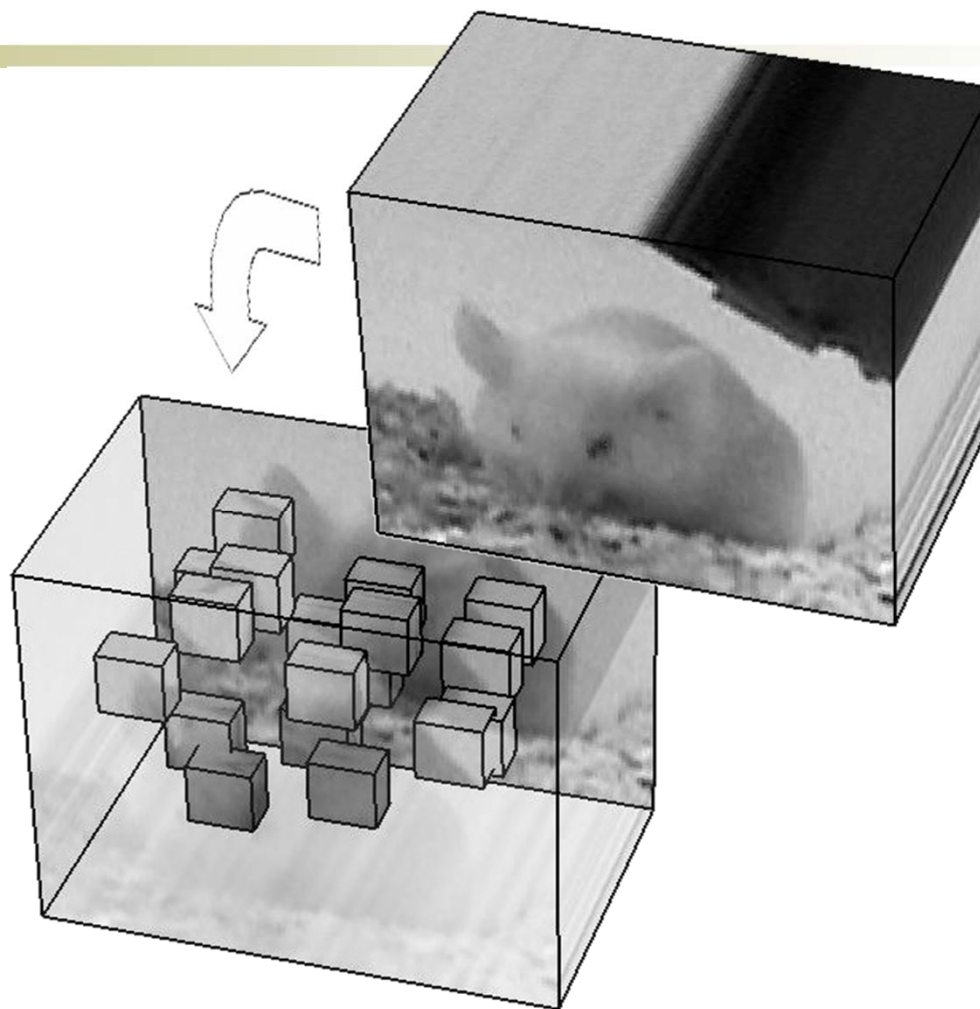
[summary of results]

- achieved good performance in all domains [typically 10-20% error]
- achieved best performance of algorithms tested in all domains
- comparison to domain specific algorithms necessary

[Current Work]

- Niebles et al.
 - “Unsupervised Learning of Human Action Categories Using Spatial-Temporal Words”
BMVC, 2006
 - Recognizes multiple activities in a single video sequence
 - Using the same interest point detector, cluster cuboids into a set of video codewords, then use pLSA graphical model to determine probability distributions.
 - 81.50% accuracy vs 81.17% for Dollár et al.
 - However, learning is unsupervised for Niebles et al.

[Questions?]



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