Name: Eslam Mohamed Abbas Abbas Hammad

Section: 2

Department: CS ID:1000263795

Name: Hanin Baher Elsaid Ali Hamza

Section: 2

Department: CS ID:1000263927

## (a) Algorithms for Kruskal's Algorithm

To find the Minimum Spanning Tree (MST) using Kruskal's Algorithm, we require the following algorithms:

Kruskal's Algorithm: Finds the MST by repeatedly adding the smallest edge to the tree while ensuring no cycles are formed.

Union-Find (Disjoint Set): Ensures cycle detection and efficient merging of sets.

## Algorithm 1: Kruskal's Algorithm

\_\_\_\_\_

Kruskal(G)

Input: A graph G with vertices V and edges E (each edge has weight w).

Output: A Minimum Spanning Tree (MST).

- 1. Initialize MST as an empty set.
- 2. Sort all edges in non-decreasing order of their weights.
- 3. Create a disjoint-set for each vertex in G.
- 4. for each edge (u, v) in the sorted edge list:
- 5. if Find(u)  $\neq$  Find(v):
- 6. Add (u, v) to MST.
- 7. Union(u, v).
- 8. Return MST.

### Algorithm 2: Union-Find (Disjoint Set)

\_\_\_\_\_

The union-find data structure is used for cycle detection and managing connected components. Find with Path Compression

Find(x)

Input: An element x.

Output: The representative of the set containing x.

- 1. if parent[x]  $\neq$  x:
- parent[x] = Find(parent[x]) # Path compression

## 3. Return parent[x].

Union by Rank

Union(x, y)

Input: Two elements x and y.

Output: Combines the sets containing x and y.

- 1. rootX = Find(x).
- 2. rootY = Find(y).
- 3. if rootX  $\neq$  rootY:
- if rank[rootX] > rank[rootY]:
- parent[rootY] = rootX.
- else if rank[rootX] < rank[rootY]:</li>
- 7. parent[rootX] = rootY.
- 8. else:
- 9. parent[rootY] = rootX.
- 10. rank[rootX] += 1.

#### (b) Analysis of Kruskal's Algorithm

# 1. Time Complexity

Sorting edges: O(ElogE)O(ElogE), where EE is the number of edges.

Union-Find operations: Each union and find operation runs in  $O(\alpha(V))O(\alpha(V))$ , where  $\alpha\alpha$  is the inverse Ackermann function (very small, effectively constant). For EE edges, this contributes  $O(E\alpha(V))O(E\alpha(V))$ .

Overall complexity:

 $O(ElogE+E\alpha(V))=O(ElogE)O(ElogE+E\alpha(V))=O(ElogE)$ 

Since E≥V-1E≥V-1 for a connected graph, the complexity can also be written as O(ElogV)O(ElogV).

#### 2. Space Complexity

Space for storing edges: O(E)O(E).

Space for disjoint-set data structure (parent and rank arrays): O(V)O(V).

Total space complexity: O(V+E)O(V+E).

# 3. Properties

Greedy: Kruskal's algorithm works by greedily adding edges of the smallest weight while avoiding cycles.

Suitable for sparse graphs: EE is much smaller than V2V2. Output for Example

For the input graph with edges:

(0,1,10),(0,2,6),(0,3,5),(1,3,15),(2,3,4)(0,1,10),(0,2,6),(0,3,5),(1,3,15),(2,3,4)

```
The output is:
Edges in MST: [(2, 3, 4), (0, 3, 5), (0, 1, 10)]
Total weight of MST: 19
```

\_\_\_\_\_

## (c) Code Of MST using Kruskal's Algorithm

```
class DisjointSet:
     def init (self, n):
     self.parent = list(range(n))
     self.rank = [0] * n
     def find(self, x):
      """Find with path compression."""
     if self.parent[x] != x:
            self.parent[x] = self.find(self.parent[x]) # Path compression
     return self.parent[x]
     def union(self, x, y):
      """Union by rank."""
     rootX = self.find(x)
     rootY = self.find(y)
     if rootX != rootY:
            if self.rank[rootX] > self.rank[rootY]:
                  self.parent[rootY] = rootX
            elif self.rank[rootX] < self.rank[rootY]:</pre>
                  self.parent[rootX] = rootY
            else:
                  self.parent[rootY] = rootX
                  self.rank[rootX] += 1
def kruskal(edges, n):
      """Finds the MST using Kruskal's algorithm."""
     # Sort edges by weight
     edges.sort(key=lambda edge: edge[2])
     ds = DisjointSet(n)
     mst = []
     mst_weight = 0
     for u, v, w in edges:
     # If u and v belong to different sets, add the edge to MST
```