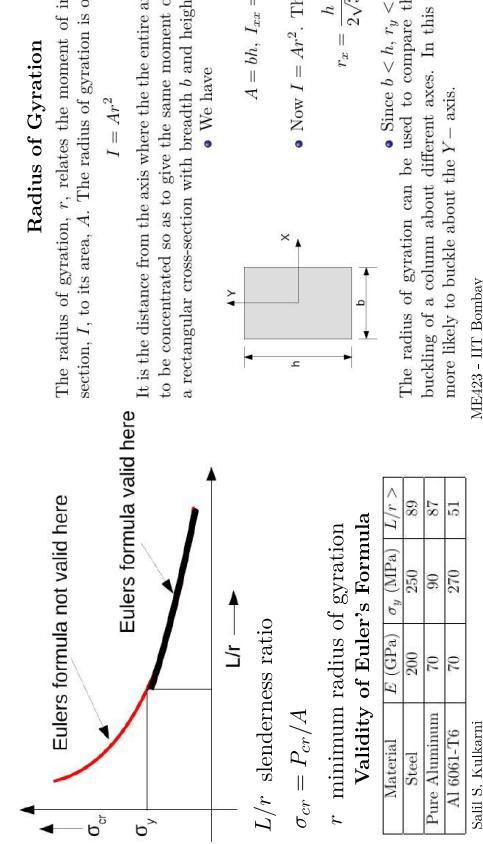


Column Buckling

Beam Bending and Deflection



Sajid S. Kulkarni

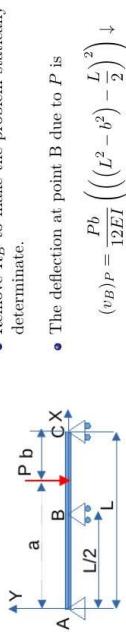
ME423 - IIT Bombay

56

53

Statically Indeterminate Problem

- Remove R_B to make the problem statically determinate.



- The deflection at point B due to P is

$$(v_B)_P = \frac{Pb}{12EI} \left(\left(L^2 - b^2 \right) - \frac{L}{2} \right)$$

- Now consider the beam with only R_B acting.

- The deflection at B due to R_B is

$$(v_B)_{R_B} = \frac{R_B L^3}{48EI}$$

- The net deflection at B is zero due to the support. Hence

$$\frac{Pb}{12EI} \left(\left(L^2 - b^2 \right) - \frac{L}{2} \right)^2 = \frac{R_B L^3}{48EI}$$

- Solve for R_B

ME423 - IIT Bombay

53

Problem

A tensile specimen with a 12 mm initial diameter and 50 mm gauge length reaches maximum load at 90 kN and fractures at 70 kN. The minimum diameter at fracture is 10 mm. Determine the engineering stress at the maximum load (UTS), the engineering stress at the fracture load and the true stress at the fracture load.

Given data:			
$d_0 := 12 \text{ mm}$	$L_0 := 50 \text{ mm}$	$P_m := 90 \text{ kN}$	$d_f := 10 \text{ mm}$
$\sigma_u := 7.9577 \cdot 10^8 \text{ Pa}$	$\sigma_u = 7.9577 \cdot 10^8 \text{ Pa}$	$\text{Ultimate tensile stress}$	$\text{Engineering fracture stress}$
$\sigma_f := \frac{P_f}{\frac{\pi}{4} \cdot d_0^2}$	$\sigma_f = 6.1894 \cdot 10^8 \text{ Pa}$		
$\sigma_{UTS} := \frac{P_f}{\frac{\pi}{4} \cdot d_f^2}$	$\sigma_{UTS} = 8.9127 \cdot 10^8 \text{ Pa}$	$\text{True fracture stress}$	

ME423 - IIT Bombay

4

Column Buckling

The critical column buckling load, P_{cr} , is estimated using Euler's formula

$$P_{cr} = c\pi^2 \frac{EI}{L^2} \quad \text{or} \quad P_{cr} = \pi^2 \frac{(kL)^2}{EI}$$

where the constants c (and k) depend on the boundary conditions ($k = 1/\sqrt{c}$).

	Boundary conditions	c	k
1.	P-P	1.00	1.00
2.	P-C	2.05	0.70
3.	C-F	0.25	2.00
4.	C-C	4.00	0.50

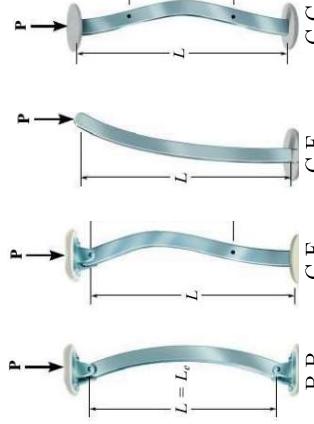
P-Pinned, C-Clamped, F-Free

Assumptions:

- Column is perfectly straight before loading.
- It is made up homogeneous material.
- The material behaves as a linear elastic material.
- The load is applied through the centroid of the cross section and the column bends in a single plane.

ME423 - IIT Bombay

55



C-C

C-F

C-F

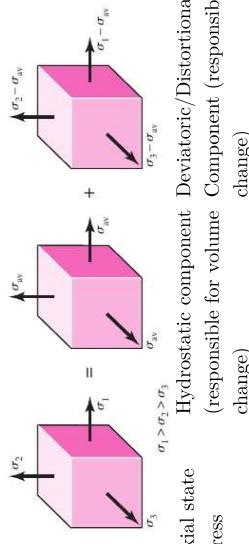
C-F

C-C

Distortion Energy Theory or von Mises-Hencky Theory

Applicable to Ductile Materials

Yielding occurs when the distortion strain energy per unit volume at a point in a part reaches or exceeds the distortion strain energy per unit volume at yield in the same material when it is subjected to uniaxial tension.



Triaxial state of stress
Hydrostatic component (responsible for volume change)
Deviatoric/Distortional Component (responsible for shape change)

Shigley's Mechanical Engineering Design
Saiji S. Kulkarni

ME423 - IIT Bombay

10

8

Maximum Shear Stress Theory or Tresca Yield Criterion

Applicable to Ductile Materials

Yielding occurs when the maximum shear stress at a point in the part reaches the shear stress that causes the same material to yield when it is subjected to uniaxial tension.

$$\tau_{max} \geq \tau_y$$

- If $\sigma_1 \geq \sigma_2 \geq \sigma_3$ are the principal stresses, then the maximum shear stress is given by
- $$\tau_{max} = \frac{|\sigma_1 - \sigma_3|}{2}$$
- For the case of uniaxial tension at yielding $\sigma_1 = \sigma_y, \sigma_2 = 0, \sigma_3 = 0$. Therefore shear stress at yielding is
- $$\tau_y = \frac{\sigma_y}{2}$$
- Therefore yielding occurs when
- $$|\sigma_1 - \sigma_3| \geq \sigma_y$$
- For design purposes one introduces a factor of safety N and uses the following equation
- $$|\sigma_1 - \sigma_3| = \frac{\sigma_y}{N}$$

Saiji S. Kulkarni

ME423 - IIT Bombay

8

Distortion Energy Theory or von Mises-Hencky Theory

The distortional strain energy density per unit volume for a general state of stress is

$$U_d = \frac{1}{6G} \left[\frac{(\sigma_1 - \sigma_2)^2 + (\sigma_2 - \sigma_3)^2 + (\sigma_3 - \sigma_1)^2}{2} \right]$$

- For the case of uniaxial tension at yielding $\sigma_1 = \sigma_y, \sigma_2 = 0, \sigma_3 = 0$

$$U_d^{uniaxial} = \frac{1}{6G} \sigma_y^2$$

Yielding occurs when

$$U_d \geq U_d^{uniaxial}$$

$$\left[\frac{(\sigma_1 - \sigma_2)^2 + (\sigma_2 - \sigma_3)^2 + (\sigma_3 - \sigma_1)^2}{2} \right]^{1/2} \geq \sigma_y$$

- von Mises or equivalent stress is defined as

$$\sigma_{vm} = \sigma_{eq} = \left[\frac{(\sigma_1 - \sigma_2)^2 + (\sigma_2 - \sigma_3)^2 + (\sigma_3 - \sigma_1)^2}{2} \right]^{1/2}$$

Yielding occurs when

$$\sigma_{vm} \geq \sigma_y$$

$$\sigma_{vm} = \frac{\sigma_y}{\sqrt{N}}$$

- For design purposes one introduces a factor of safety N and uses the following equation

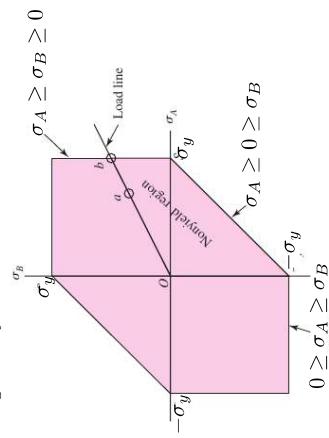
Shigley's Mechanical Engineering Design
Saiji S. Kulkarni

ME423 - IIT Bombay

11

Maximum Shear Stress Theory for Plane Stress Problems

- Let σ_A and σ_B represent the two in-plane principal stresses and let $\sigma_C = 0$ (out of plane stress component).
- Then the yield locus is given by



Factor of safety available at point a against yielding
 $n = \frac{l(Ob)}{l(Oa)}$

Distortion Energy Theory or von Mises-Hencky Theory

- The distortional strain energy density per unit volume for a general state of stress is

$$U_d = \frac{1}{6G} \left[\frac{(\sigma_1 - \sigma_2)^2 + (\sigma_2 - \sigma_3)^2 + (\sigma_3 - \sigma_1)^2}{2} \right]$$

- For the case of uniaxial tension at yielding $\sigma_1 = \sigma_y, \sigma_2 = 0, \sigma_3 = 0$

$$U_d^{uniaxial} = \frac{1}{6G} \sigma_y^2$$

Yielding occurs when

$$U_d \geq U_d^{uniaxial}$$

$$\left[\frac{(\sigma_1 - \sigma_2)^2 + (\sigma_2 - \sigma_3)^2 + (\sigma_3 - \sigma_1)^2}{2} \right]^{1/2} \geq \sigma_y$$

- von Mises or equivalent stress is defined as

$$\sigma_{vm} = \sigma_{eq} = \left[\frac{(\sigma_1 - \sigma_2)^2 + (\sigma_2 - \sigma_3)^2 + (\sigma_3 - \sigma_1)^2}{2} \right]^{1/2}$$

Yielding occurs when

$$\sigma_{vm} \geq \sigma_y$$

$$\sigma_{vm} = \frac{\sigma_y}{\sqrt{N}}$$

- For design purposes one introduces a factor of safety N and uses the following equation

Shigley's Mechanical Engineering Design
Saiji S. Kulkarni

ME423 - IIT Bombay

9

Comparison of Failure Theories for Ductile Materials

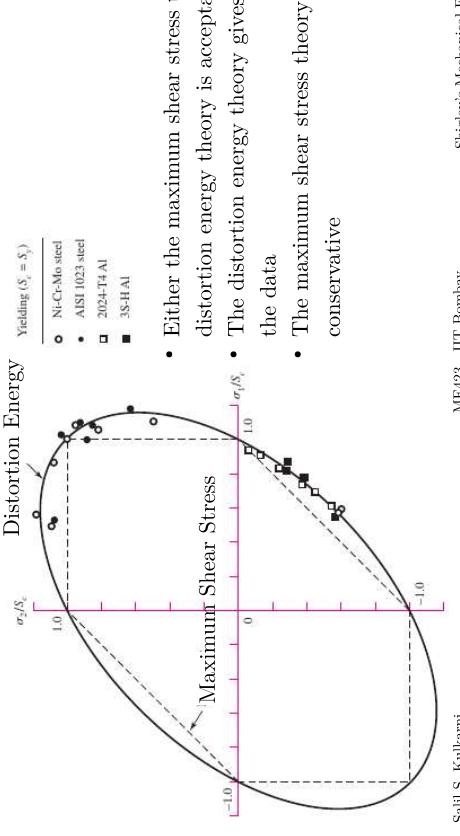
Distortion Energy Theory or von Mises-Hencky Theory

- The distortion energy theory is also called:
 - The shear-energy theory
 - The octahedral-shear-stress theory
- The von Mises stress terms of the components of the stress tensor referred to a Cartesian coordinate system is given by

$$\sigma_{vm} = \frac{1}{\sqrt{2}} [(\sigma_{xx} - \sigma_{yy})^2 + (\sigma_{yy} - \sigma_{zz})^2 + (\sigma_{zz} - \sigma_{xx})^2 + 6(\sigma_{xy}^2 + \sigma_{yz}^2 + \sigma_{zx}^2)]^{1/2}$$
- The von Mises stress terms of the components of the stress tensor referred to a Cartesian coordinate system is given by

$$\sigma_{vm} = (\sigma_{xx}^2 - \sigma_{xy}\sigma_{yy} + \sigma_{yy}^2 + 3\sigma_{xy}^2)^{1/2}$$
- The von Mises stress terms of the components of the stress tensor referred to a Cartesian coordinate system is given by

$$\sigma_{vm} = (\sigma_{xx}^2 - \sigma_{xy}\sigma_{yy} + \sigma_{yy}^2 + 3\sigma_{xy}^2)^{1/2}$$
- Either the maximum shear stress theory or the distortion energy theory is acceptable
- The distortion energy theory gives better fit to the data
- The maximum shear stress theory is more conservative



12

Problem – Ductile Material

A stationary shaft, 50 mm in diameter and made of AISI 1060 hot-rolled steel, is subjected to a maximum bending moment of 3000 Nm and a maximum torque of 2000 Nm. Find the factor of safety corresponding to failure based on the distortion energy theory. The yield stress is 372 MPa.

$$\begin{aligned} d &:= 50 \text{ mm} & M &:= 3000 \text{ N} \cdot \text{m} & T &:= 2000 \text{ N} \cdot \text{m} & \sigma_y &:= 372 \text{ MPa} \\ \sigma_{xx} &:= \frac{M \cdot \frac{d}{2}}{\frac{\pi}{32} \cdot d^4} & \sigma_{xy} &:= 2 \cdot 4446 \cdot 10^{-8} \text{ Pa} \\ \sigma_{yy} &:= 0 \text{ Pa} & \sigma_{xy} &:= 8 \cdot 1487 \cdot 10^{-7} \text{ Pa} \end{aligned}$$

$$\begin{aligned} \sigma_{vm} &:= \left[\sigma_{xx}^2 + \sigma_{yy}^2 - \sigma_{xx} \cdot \sigma_{yy} + 3 \cdot \sigma_{xy}^2 \right]^{\frac{1}{2}} & \sigma_{vm} &= 2 \cdot 8228 \cdot 10^{-8} \text{ Pa} \\ FOS &:= \frac{\sigma_y}{\sigma_{vm}} & FOS &= 1.3178 \end{aligned}$$

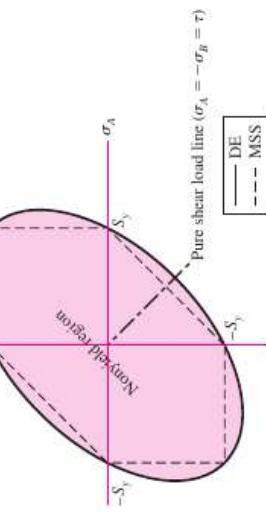
ME423 - IIT Bombay

Shigley's Mechanical Engineering Design

Sajid S. Kulkarni

Distortion Energy Theory for Plane Stress Problems

- Let σ_A and σ_B represent the two in-plane principal stresses and let $\sigma_C = 0$ (out of plane stress component).
- Then the yield locus is given by $\sigma_A^2 + \sigma_B^2 - \sigma_A \sigma_B = \sigma_y^2$
- MSS – Maximum shear stress theory
- DE – Distortion Energy Theory



ME423 - IIT Bombay

Shigley's Mechanical Engineering Design

Sajid S. Kulkarni

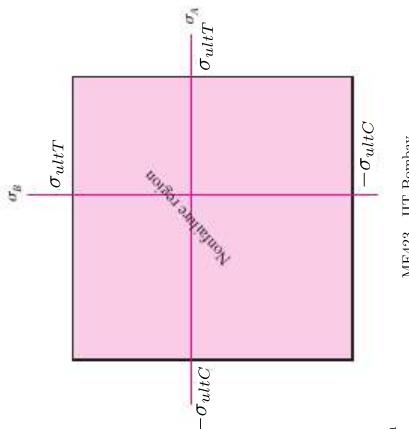
13

15

Maximum Normal Stress Theory for Plane Stress Problems

- Let σ_A and σ_B represent the two in-plane principal stresses and let $\sigma_C = 0$ (out of plane stress component). Let $\sigma_A \geq \sigma_B$

- Then the yield locus is



Shigley's Mechanical Engineering Design

Problem – Ductile Material

The cantilevered tube shown in Figure 1 is to be made of 2014 Aluminum alloy treated to obtain a specified minimum yield strength of 276 MPa. We wish to select a stock-size tube from Table given below using a design factor $n_d = 4$. The bending is $F = 1.75$ kN, the axial tension is $P = 9.0$ kN, and the torsion $T = 72$ Nm. What is the realized factor of safety? Use both

Size, mm	<i>m</i>	<i>A</i>	<i>I</i>	<i>k</i>	<i>Z</i>	<i>J</i>
12 × 2	0.490	0.628	0.082	0.361	0.136	0.163
16 × 2	0.687	0.879	0.220	0.500	0.275	0.440
16 × 3	0.956	1.225	0.273	0.472	0.341	0.545
20 × 4	1.569	2.010	0.684	0.583	0.684	1.367
25 × 4	2.060	2.638	1.508	0.756	1.206	3.015
25 × 5	2.452	3.140	1.669	0.729	1.336	3.338
30 × 4	2.550	3.266	2.827	0.930	1.885	5.632
30 × 5	3.065	3.925	3.192	0.901	2.128	6.381
42 × 4	3.727	4.773	8.717	1.351	4.151	17.430
42 × 5	4.536	5.809	10.130	1.320	4.863	20.255
50 × 4	4.512	5.774	15.409	1.632	6.164	30.810
50 × 5	5.517	7.065	18.118	1.601	7.247	36.226

Shallow Mechanical Engineering Design [6]

Choice of Failure Theory

- For isotropic material that fail by yielding, use the distortion energy theory
 - For isotropic material that fail by yielding, use maximum shear stress is more conservative than the distortion energy theory
 - For isotropic material that fail by brittle fracture, use the maximum normal stress theory.
 - For materials that fail by brittle fracture but whose compressive ultimate compressive strength is significantly different from the tensile ultimate strength, use the modified Mohr's theory (not covered in class)

Maximum Normal Stress Theory

卷之三

Applicable to Brittle Materials (primarily applied to isotropic material)
Failure occurs whenever one of the three principal stresses at a point in a part reaches or exceeds the strength of the material either in tension or compression.

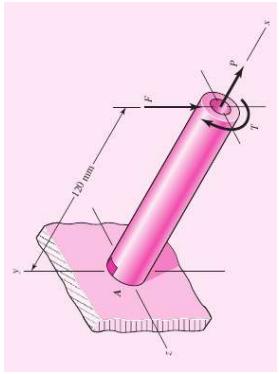
- Let $\sigma_1 \geq \sigma_2 \geq \sigma_3$ be the principal stresses at a point
 - The material fails whenever

$$\sigma_1 \geq \sigma_{ultT}, \sigma_3 \leq -\sigma_{ultC}$$

Here σ_{ultT} and σ_{ultC} are the ultimate strength in tension and compression, respectively
 - For design purposes one introduces a factor of safety N and uses the following equation
$$\sigma_1 = \frac{\sigma_{ultT}}{N}, \text{ or } \sigma_3 = \frac{-\sigma_{ultC}}{N}$$

$$\sigma_1 \geq \sigma_{ultT}, \quad \sigma_3 \leq -\sigma_{ultC}$$

Ultimate strength in tension and compression



w_a	unit weight of aluminum tubing, lb/ft
w_s	unit weight of steel tubing, lb/ft
m	unit mass, kg/m
A	area, in. ² (cm ²)
I	second moment of area, in. ⁴ (cm ⁴)
J	second polar moment of area, in. ⁴ (cm ⁴)
k	radius of gyration, in. (cm)
Z	section modulus, in. ³ (cm ³)
d, t	size (OD) and thickness, in. (mm)

Stress Life Approach – Endurance Limits and Fatigue Strengths of Common Metals

Steels	$\sigma'_e \approx \begin{cases} 0.5\sigma_{ult} & \sigma_{ult} < 1400 \text{ MPa} \\ 700 \text{ MPa} & \sigma_{ult} \geq 1400 \text{ MPa} \end{cases}$	σ'_e, σ'_f are the endurance limit or fatigue strength obtained in lab conditions using polished specimens using bending fatigue tests
Cast Iron	$\sigma'_e \approx \begin{cases} 0.4\sigma_{ult} & \sigma_{ult} < 400 \text{ MPa} \\ 160 \text{ MPa} & \sigma_{ult} \geq 400 \text{ MPa} \end{cases}$	
Aluminium	$\sigma'_{f@5e8} \approx \begin{cases} 0.4\sigma_{ult} & \sigma_{ult} < 330 \text{ MPa} \\ 130 \text{ MPa} & \sigma_{ult} \geq 300 \text{ MPa} \end{cases}$	These are only estimates and are to be used only if the S-N data is unavailable and must be used with caution
Copper	$\sigma'_{f@5e8} \approx \begin{cases} 0.4\sigma_{ult} & \sigma_{ult} < 280 \text{ MPa} \\ 100 \text{ MPa} & \sigma_{ult} \geq 280 \text{ MPa} \end{cases}$	

Salil S. Kulkarni

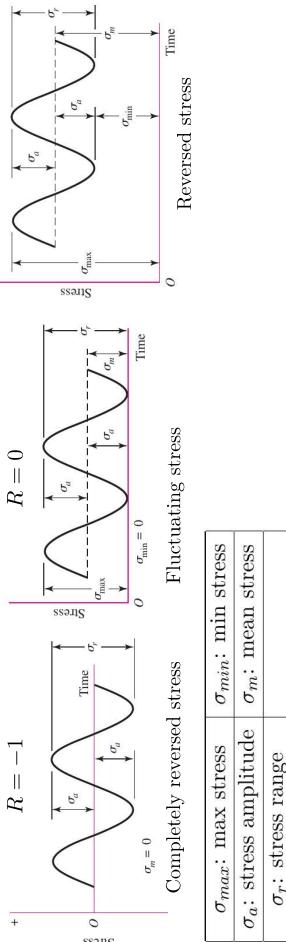
ME423 - IIT Bombay

30

Salil S. Kulkarni

25

Representative Types of Loading and Terminology



$$\sigma_a = \frac{\sigma_{max} + \sigma_{min}}{2}$$

$$\sigma_r = \frac{|\sigma_{max} - \sigma_{min}|}{2}$$

$$A = \frac{\sigma_a}{\sigma_m} = \frac{1-R}{1+R}$$

$$\text{Amplitude ratio}$$

σ_{max} : max stress

σ_a : stress amplitude

σ_r : stress range

σ_m : min stress

σ_m : mean stress

$R = \frac{\sigma_{min}}{\sigma_{max}}$

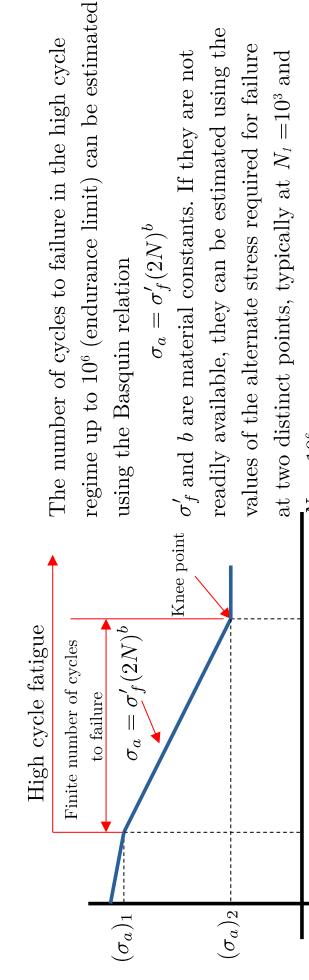
Stress ratio

ME423 - IIT Bombay

31

28

Estimating Cycles to Failure in the High Cycle Regime



$(\sigma_a)_2$ is the endurance limit
 $(\sigma_a)_1$ is the stress amplitude that the specimen fails at $N = 10^3$
 $(\sigma_a)_1 \approx f\sigma_{ult}$ if no data is available (See next slide for f)

Salil S. Kulkarni

ME423 - IIT Bombay

31

Fatigue Life Methods

Attempt to predict the life in number of cycles to failure, N , for a specific level of loading.

- Stress life method** – used for high cycle fatigue ($N \geq 10^3$)
 - Based on stress levels only, assumes stresses are within elastic limit
 - Easiest to implement for a wide range of design applications
 - Has ample supporting data (experimental results)
 - Works best when the load amplitudes are predictable and consistent over the life of the part
 - Is the least accurate approach, especially for low-cycle applications.
 - Involves detailed analysis of the plastic deformation at localized regions.
 - Gives a good picture of the crack initiation stage
 - In applying this method, several idealizations must be made and hence uncertainties exist in the results. Hence not very widely used.
- Strain life method** – used for low cycle fatigue ($N \leq 10^3$)
 - Provides a more accurate approach than stress life methods.
 - Based on strain levels only, assumes strains are within elastic limit
 - More difficult to implement than stress life methods.
 - Requires knowledge of material properties and loading conditions.
 - Can predict fatigue life for both tension and compression cyclic loading.
- Linear elastic fracture mechanics method**
 - Assumes a crack is already present and detected.
 - It is employed to predict crack growth with respect to stress intensity.
 - Used in conjunction with computer codes and a periodic inspection program.

Salil S. Kulkarni

ME423 - IIT Bombay

28

Endurance Limit Modifying Factors

$$\text{Surface Factor } k_a = a\sigma_{ult}^b$$

Surface Finish	S_{av} , ksi	Factor a	S_{av} , MPa	Exponent b
Ground	1.34	1.58	-0.085	
Machined or cold-drawn	2.70	4.51	-0.265	
Hot-rolled	14.4	57.7	-0.718	
As-forged	39.9	272.	-0.995	

Size Factor k_b

For bending and torsion

$$k_b = \begin{cases} 1.24d^{-0.107} & 2.79 \leq d \leq 51 \text{ mm} \\ 1.51d^{-0.157} & 51 \leq d \leq 254 \text{ mm} \end{cases}$$

For non rotating round bar in bending or noncircular

c/s see Shigley

For axial loading $k_b = 1$

Salil S. Kulkarni
ME423 - IIT Bombay

33

$$\text{Load Factor } k_c = \begin{cases} 1 & \text{bending} \\ 0.85 & \text{axial} \\ 0.59 & \text{torsion} \end{cases}$$

Temperature Factor k_d

Temperature, °C

If σ'_e is known,

UTS for HR 1050 steel

$\sigma_{ult} = 620 \text{ MPa}$

Endurance strength

$\sigma_2 = 0.5 \cdot \sigma_{ult} = 310 \text{ MPa}$

N = 10⁶

Stress amplitude corresponding to 1000 cycles

$N1 := 10^3$

To find:

$\sigma_1 := f \cdot \sigma_{ult} = 533.2 \text{ MPa}$

$f = 0.86$

$\sigma_1 = 445.0212 \text{ MPa}$

$N2 := 10^6$

$\sigma_2 = 445.0212 \text{ MPa}$

Number of cycles to failure at stress amplitude $\sigma_2 = 380 \text{ MPa}$

$Np := \frac{1}{f} \cdot \left(\frac{\sigma_2}{\sigma_1} \right)^{\frac{1}{N1}} = 74772.5822$

approximately 74700 cycles

Number of cycles to failure at stress amplitude $\sigma_2 = 380 \text{ MPa}$

$Np := 74772.5822$

n/day

And use $k_d = 1$

35

33

Problem – No Endurance limit Correction & Zero Mean Stress

Given a 1050 HR (hot rolled) steel, estimate

- (a) the rotating-beam endurance limit at 10⁶ cycles.
- (b) the fatigue strength of a polished rotating-beam specimen corresponding to 10⁴ cycles to failure
- (c) the expected life of a polished rotating-beam specimen under a completely reversed stress of 380 MPa.

$b := \frac{\log \left(\frac{\sigma_1}{\sigma_2} \right)}{\log \left(\frac{N1}{N2} \right)} = -0.0785$

$sF := \frac{s^2}{(2 \cdot N2)^B} = 968.3945 \text{ MPa}$

Answers

Fatigue strength at $N = 100000$

$sN := sF \cdot (2 \cdot N)^B = 445.0212 \text{ MPa}$

Number of cycles to failure at stress amplitude $\sigma_2 = 380 \text{ MPa}$

$Np := \frac{1}{f} \cdot \left(\frac{\sigma_2}{\sigma_1} \right)^{\frac{1}{N1}} = 74772.5822$

approximately 74700 cycles

Endurance Limit Modifying Factors

Reliability Factor k_e

Reliability, %	Transformation Variate z_e	Reliability Factor k_e
50	0	1.000
90	1.288	0.897
95	1.645	0.868
99	2.326	0.814
99.9	3.091	0.753
99.99	3.719	0.702
99.999	4.265	0.659
	4.733	0.620

$\sigma_e = k_a k_b k_c k_d k_e k_f \sigma'$

σ_e = endurance limit of the machine part at the critical location
 k_a = surface condition modification factor (highly polished sample has a higher endurance limit as compared to an unpolished sample)

k_b = size modification factor (smaller sample has larger endurance limit as compared to a larger sample)

k_c = load modification factor (parts subjected to bending have higher endurance as compared to parts subjected to axial loads and torsion)

k_d = temperature modification factor (endurance limit for steel decreases for temperatures $> 300^\circ \text{C}$)

k_e = reliability factor (higher reliability requirements leads to a lower value of k_e)

k_f = miscellaneous-effects modification factor (accounts for reduction in endurance limit due to all other factors – residual stress, corrosion, cyclic frequency)

$\sigma'_e = \text{rotary-beam test specimen endurance limit}$
 Salil S. Kulkarni
 $\text{ME423 - IIT Bombay}$

34

Endurance Limit Modifying Factors

Reliability Factor k_e

Reliability, %	Transformation Variate z_e	Reliability Factor k_e
50	0	1.000
90	1.288	0.897
95	1.645	0.868
99	2.326	0.814
99.9	3.091	0.753
99.99	3.719	0.702
99.999	4.265	0.659
	4.733	0.620

Miscellaneous-Effects Factor k_f

Factors including residual stress, corrosion, cyclic frequency, electrolytic plating, metal spraying, fretting corrosion

34

Salil S. Kulkarni
ME423 - IIT Bombay

Problem – Zero Mean Stress & Endurance Limit Correction

Problem: Find the fatigue strength at $N = 10000$	
$f := 0.86$	
Number of cycles to fail at $sp := 380 \text{ MPa}$	
$b := \frac{\log \left[\frac{s}{s_{2C}} \right]}{\log \left[\frac{N_1}{N_2} \right]} = -0.1604$	$s_f := \frac{s_{2C}}{(2 \cdot N_2)^b} = 1804.9931 \text{ MPa}$
Answers	
Fatigue strength at $N = 10000$	
$s_N := s_f \cdot (2 \cdot N)^b = 368.5185 \text{ MPa}$	
Number of cycles to fail at $sp = 380 \text{ MPa}$	
$N_p := \frac{1}{2} \cdot \left(\frac{s_p}{s_f} \right) = 8259.3729$	Approximately 8200 cycles
No size effect for axial loading	
$k_c = 0.85$ Load factor	
$k_d = 1$ Temperature effect	
$k_e = 0.814$ Reliability factor	
$k_f = 1$ Miscellaneous factor	
$s_{2C} := k_a \cdot k_b \cdot k_c \cdot k_d \cdot k_e \cdot k_f \cdot s_2 = 176.0345 \text{ MPa}$	
$s_1 := f \cdot s_{2C} = 533.2 \text{ MPa}$	$N_1 := 10^3$
Salil S. Kulkarni	
ME423 - IIT Bombay	
40	

37

Stress Concentration and Notch Sensitivity

- Have looked at the theoretical or geometrical stress concentration factors (K_t , K_s) earlier
- It depends on the geometry and loading
- Not all materials are equally sensitive to the presence of geometrically discontinuous
- For materials which are not fully sensitive to the presence of geometric discontinuous, a reduced value of K_t (K_f) are used.
- This reduced factor is referred to as fatigue stress concentration factor K_f or K_{fs}
- Notch sensitivity factor is defined as

$$q = \frac{K_f - 1}{K_t - 1} \quad \text{or} \quad q_{shear} = \frac{K_{fs} - 1}{K_s - 1}$$

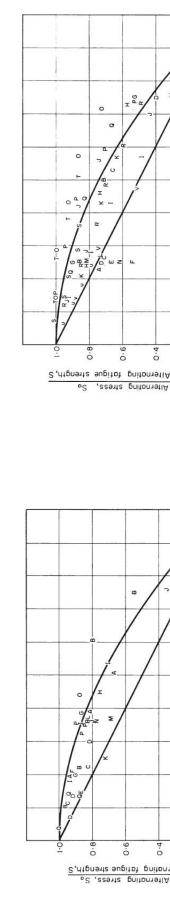
- $q = 0$ indicates that the material is insensitive to a notch while $q = 1$ indicates that the material is fully sensitive to the notch

Salil S. Kulkarni

ME423 - IIT Bombay

40

Effect of Tensile Mean Stress on the Fatigue Life

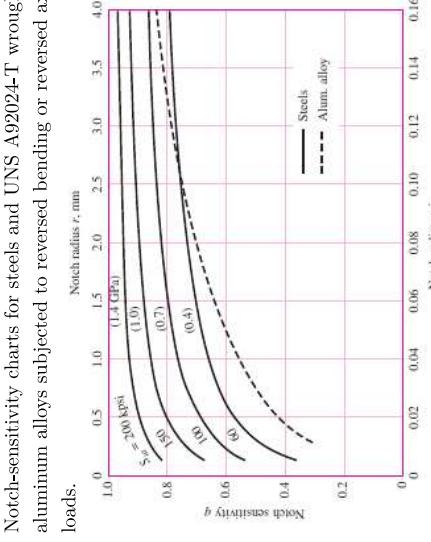


Effects of Mean Stress on Fatigue Strength of Steels based on 10^7 to 10^8 Cycles

- A parabola called the Gerber line, can be fitted to the data with reasonable accuracy.
- A straight line connecting the fatigue strength with the ultimate strength, called the modified Goodman line, is a reasonable fit to the lower envelope of the data.

Stress Concentration and Notch Sensitivity

Notch-sensitivity charts for steels and UNS A92024-T wrought aluminum alloys subjected to reversed bending or reversed axial loads.



The fatigue stress-concentration factor is then used as a multiplier of the nominal stress. We will use to modify both the mean stress component and the alternating stress component

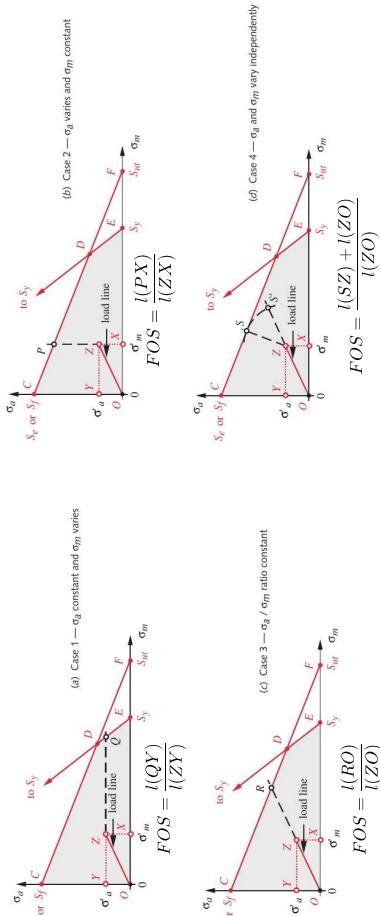
- For a given material, geometric discontinuity and loading determine K_t and q . Using the equation for the notch sensitivity find K_f i.e.
- $K_f = 1 + q(K_t - 1)$

38

Factor of Safety (FoS) in the Presence of Mean Stress using augmented modified Goodman diagram

Effect of Mean Stress on the Fatigue Life

augmented modified Goodman diagram



ton, Machine Design, An Integrated Approach
S. Kulkarni

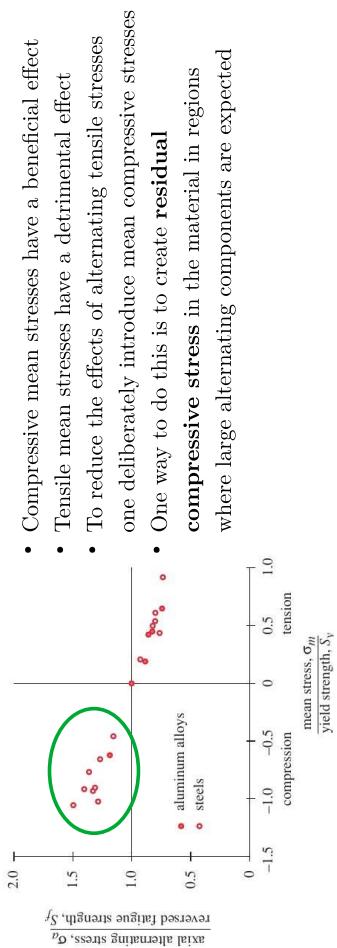
ME423 = 111 Boundary

Norton, Machine Design, An Integrated Approach
Sølil S Kullarni

MF423 IIT Bombay

MELZI = 11 BOUDAY

- Compressive mean stresses have a beneficial effect
 - Tensile mean stresses have a detrimental effect
 - To reduce the effects of alternating tensile stresses one deliberately introduce mean compressive stresses
 - One way to do this is to create **residual compressive stress** in the material in regions where large alternating components are expected

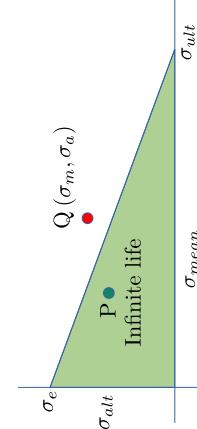


ME-492 ITT Bombar
S. Kullar

ML-423 - III. Domday

- С.А. Михайлов
МЛ-423 - III.1. Downey

Finite Life in Proseance of Mean Stress

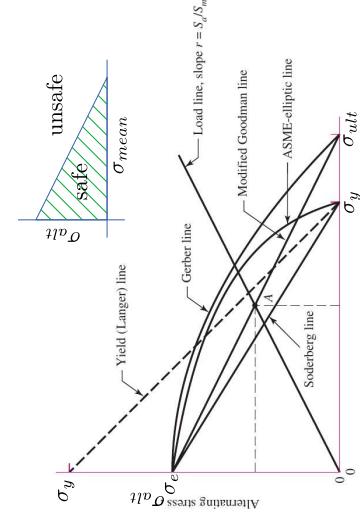


- At point P, the part has infinite life
 - At point Q, the part will fail before 10^6 cycles (finite life)
 - Want to estimate the number of cycles when it fails
 - Data is generally available for completely reversed loading
 - Procedure: Find the equivalent complete reversed stress amplitude σ'_a and then use the Basquin equation to estimate the number of cycles to failure
$$\sigma'_a = \sigma'_f (2N_f)^b$$

ME423 - IIT Bombay

II is one factor or source that can replace sand and soil and is occupying
 Sail S. Kulkarni
 ME423 - IIT Bombay

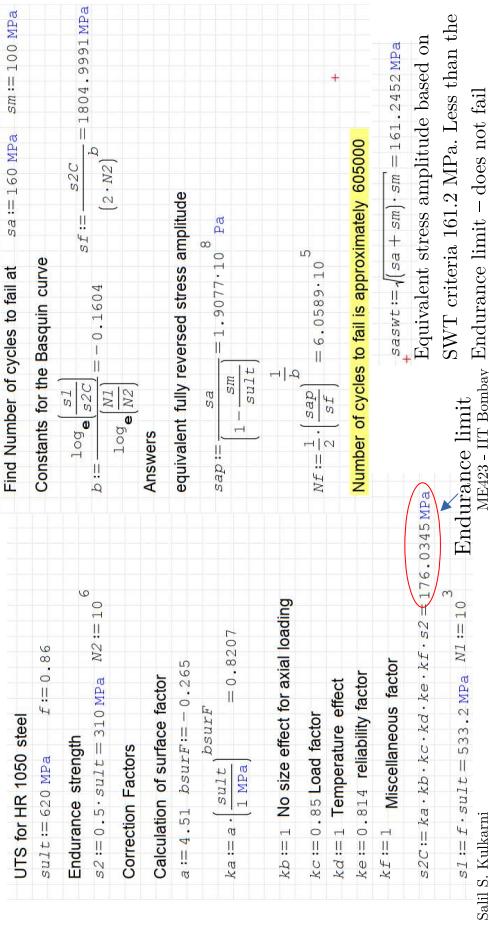
Estimative Criteria in Progeny of Mean Stress



σ_e is the modified/corrected endurance limit
 $\sigma_e = \sqrt{\sigma_{max}\sigma_a} = \sqrt{(\sigma_m + \sigma_a)\sigma_a}$

If N is the factor of safety then replace σ_m and σ_a with $N\sigma_m$ and $N\sigma_a$, respectively
 S. Kulkarni
 ME423 - IIT Bombay

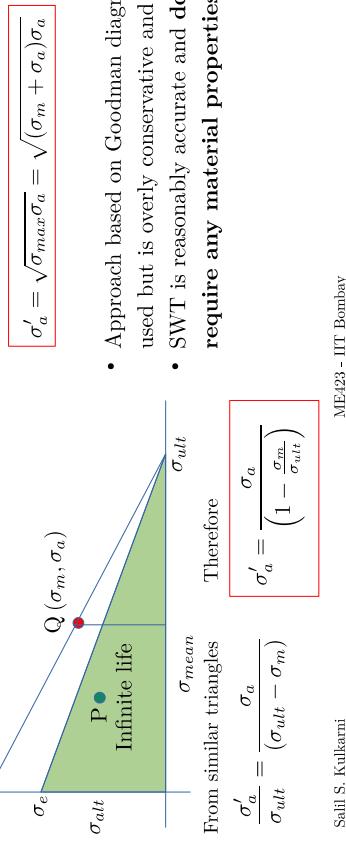
Problem – Endurance Limit Correction & Non Zero Mean Stress



Finite Life in Presence of Mean Stress

Multiple approaches available to estimate the equivalent fully reversed stress amplitude, σ'_a corresponding to (σ_m, σ_a)

Approach based on Goodman Diagram (SWT) criterion



Combination of Loading Modes (Multiaxial Loading)

In general loading can be classified as

- Completely reversing simple loads (zero mean, but only one mode of loading)
- Fluctuating simple loads (nonzero mean, but only one mode of loading)
- Combinations of loading modes (axial, torsion, bending, e.g. rotating shaft subject to a static bending moment and carrying a torque)

Complications:

- The loading components can be at same/different frequencies, same/different phases
- As a result, in general, the direction of principal stresses change with time and damage accumulates in different planes

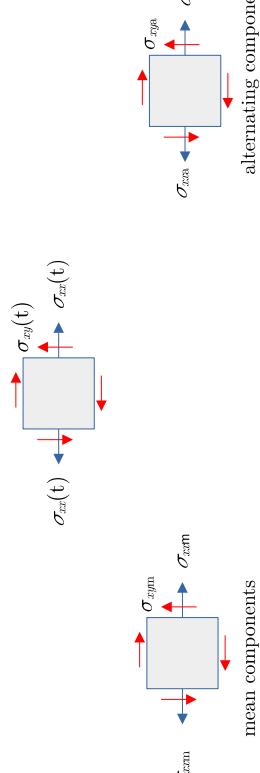
Classification of combined (multiaxial) loading:

- Simple multiaxial loading
loading where direction of principal stresses do not change with time
- Complex multiaxial
loading where direction of principal stresses change with time

Combination of Loading Modes (Multiaxial Loading)

Approach:

- To analyse static failures we used the idea of von Mises stress to combine various stress components to come up with a single number characterizing the state of stress at a point.
- Here too we will use the von Mises stress to find the equivalent alternating component and the equivalent mean components

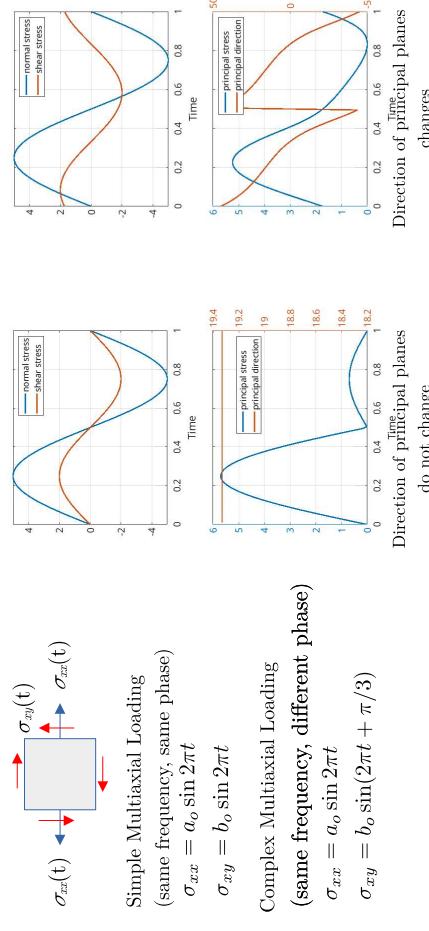


Salil S. Kulkarni

51

Combination of Loading Modes (Multiaxial Loading)

Complex Multiaxial Loading



53

ME423 - IIT Bombay

51

Combination of Loading Modes (Multiaxial Loading)

Biaxial state of stress

$$\sigma_{vma} = (\sigma_{xxa}^2 - \sigma_{xxa}\sigma_{yya} + \sigma_{yya}^2 + 3\sigma_{xya} + 3\sigma_{yza})^{1/2}$$

Equivalent alternating stress

$$\sigma_{vmm} = (\sigma_{xym}^2 - \sigma_{xym}\sigma_{yym} + \sigma_{yym}^2 + 3\sigma_{xym})^{1/2}$$

Equivalent mean stress

Here

$$\sigma_{xxa} = \frac{(\sigma_{xx})_{max} - (\sigma_{xx})_{min}}{2}, \quad \sigma_{xym} = \frac{(\sigma_{xx})_{max} + (\sigma_{xx})_{min}}{2}$$

$$\sigma_{yym} = \frac{(\sigma_{yy})_{max} - (\sigma_{yy})_{min}}{2}, \quad \sigma_{yza} = \frac{(\sigma_{yy})_{max} + (\sigma_{yy})_{min}}{2}$$

Triaxial state of stress

$$\sigma_{vma} = \frac{1}{\sqrt{2}} [(\sigma_{xxa} - \sigma_{yya})^2 + (\sigma_{yya} - \sigma_{zza})^2 + (\sigma_{zza} - \sigma_{xza})^2 + 6(\sigma_{xza}^2 + \sigma_{yza}^2 + \sigma_{zza}^2)]^{1/2}$$

$$\sigma_{vmm} = \frac{1}{\sqrt{2}} [(\sigma_{xym} - \sigma_{yym})^2 + (\sigma_{yym} - \sigma_{zym})^2 + (\sigma_{zym} - \sigma_{xym})^2 + 6(\sigma_{xym}^2 + \sigma_{yym}^2 + \sigma_{zym}^2)]^{1/2}$$

Salil S. Kulkarni

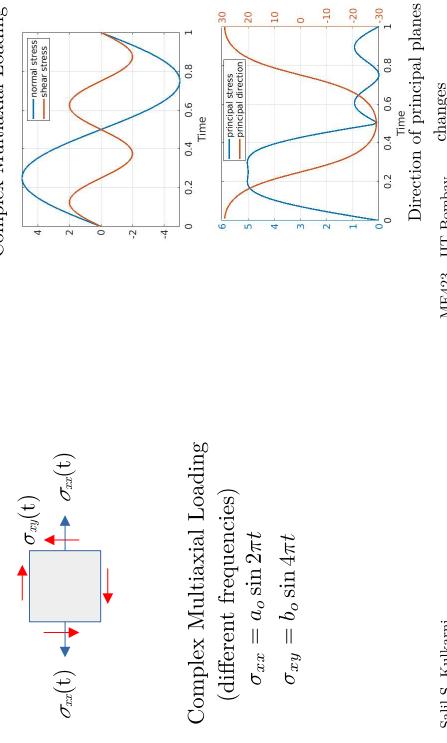
ME423 - IIT Bombay

54

52

Combination of Loading Modes (Multiaxial Loading)

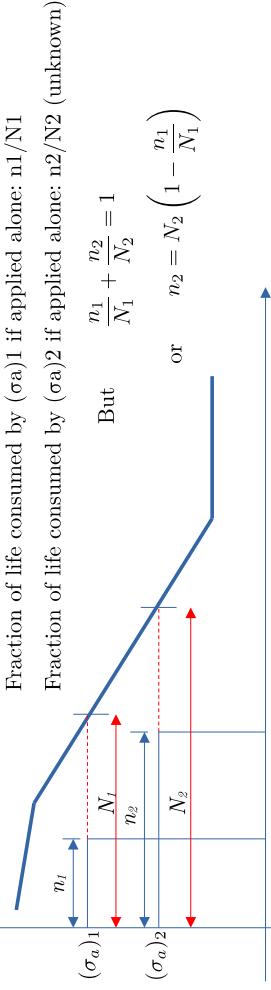
Complex Multiaxial Loading



52

Cumulative Damage – Palmgren – Miner Theory

A machine part is subject to n_1 (given) fully reversed stress cycles with amplitude $(\sigma_a)_1$ (given). It is then subject to n_2 (not known) fully reversed stress cycles of amplitude $(\sigma_a)_2$ (given) before it eventually fails. Find n_2 . Assume $(\sigma_a)_1 > \sigma_e$, $(\sigma_a)_1 > \sigma_e$. Assume that the equation of the Basquin curve is known.



Salil S. Kulkarni

ME423 - IIT Bombay

57

Steps for Multiaxial Loading

- Theoretical/geometric stress concentration factors and notch sensitivity will be different for different loadings. Calculate the corresponding fatigue stress concentration factors
- Generate two stress elements—one for the alternating stresses and one for the mean stresses.
- Apply the appropriate fatigue stress concentration factors to each of the stresses; that is, apply $(K_f)_{bending}$ for the bending stresses, $(K_f)_{torsion}$ for the torsional stresses, and $(K_f)_{axial}$ for the axial stresses.
- Calculate an equivalent von Mises stress for each of these two stress elements, σ_n' and σ_m'
- Select a fatigue failure criterion.
- For the endurance limit, σ_e , the only correction factors that are affected by multiple load types are the size factor k_b and the load factor k_e .
- Find k_b , calculate it for each load and select the lowest one.
- The only load factor to be applied is corresponding to the axial load if it happens to be the dominant mode of loading. The load factor corresponding to the torsion load should not
- be applied as the that mode of loading is already considered while calculating the von Mises

Salil S. Kulkarni

ME423 - IIT Bombay

55

Cumulative Damage – Palmgren–Miner Theory

In general, if fully reversed stress cycles with amplitude $(\sigma_a)_1, (\sigma_a)_2, \dots, (\sigma_a)_k$ act for n_1, n_2, \dots, n_k cycles with $\sum_{i=1}^k n_i = n_{total}$, n_{total} total number of cycles to failure

then

$$\sum_{i=1}^k \frac{n_i}{N_i} = 1$$

$$\sum_{i=1}^k \frac{\alpha_i}{N_i} = \frac{1}{n_{total}}, \quad \sum_{i=1}^k \alpha_i = 1, \quad \alpha_i = \frac{n_i}{n_{total}}$$

$\alpha_1, \alpha_2, \dots, \alpha_k$ are the fraction of the total life spent at $(\sigma_a)_1, (\sigma_a)_2, \dots, (\sigma_a)_k$

Limitations of the Miner Rule:

Does not take into account the sequence in which the stress cycles are applied

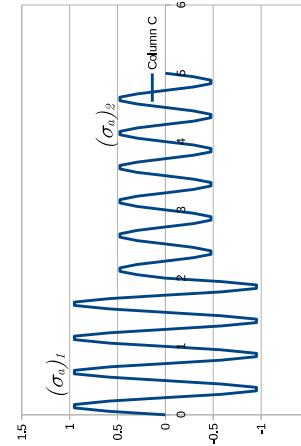
Salil S. Kulkarni

ME423 - IIT Bombay

58

Cumulative Damage

A machine part is subject to n_1 (given) fully reversed stress cycles with amplitude $(\sigma_a)_1$ (given). It is then subject to n_2 (not known) fully reversed stress cycles of amplitude $(\sigma_a)_2$ (given) before it eventually fails. Find n_2 . Assume $(\sigma_a)_1 > \sigma_e$, $(\sigma_a)_1 > \sigma_e$. Assume that the equation of the Basquin curve is known.



ME423 - IIT Bombay

Salil S. Kulkarni

56

Design Factors to be used for Ductile Materials

1.25 to 2.0	Design of structures under static load for which there is a high level of confidence in all design data
2.0 to 2.5	Design of machine elements under dynamic loading with average confidence in all design data
2.5 to 4.0	Design of static structures or machine element under dynamic loading with uncertainty about loads, material properties, environment
4.0 and higher	Design of static structures or machine element under dynamic loading with uncertainty about some combinations of loads, material properties, environment

Saint Venant's Principle

Saint Venant's principle states that the displacement, strain and stress distributions caused by statically equivalent force distributions in parts of the body which are sufficiently far from the loading parts are approximately the same.

59

Design Factors to be used for Brittle Materials

3.0 to 4.0	Design of structures under static load for which there is a high level of confidence in all design data
4.0 to 8.0	Design of static structures or machine element under dynamic loading with uncertainty about loads, material properties, environment

Design Factor and Factor of Safety

A solid circular rod undergoes a bending moment $M = 100 \text{ Nm}$. Assuming that the yield strength of the material is 170 MPa and a **design factor of 2.5**, determine the minimum diameter of the rod. From the available sizes, choose an appropriate sized rod and determine the **factor of safety**.

Given: $M = 100 \text{ Nm}$, $\sigma_y = 170 \text{ MPa}$, $n_d = 2.5$
 To find: diameter of the circular rod and the factor of safety

maximum bending stress is given by

$$v_{max} = \frac{I}{\pi d^3} = \frac{\pi d^4}{64} = \frac{\pi d^3}{16}$$

component is to be designed for

The minimum diameter, d_{min} , required to withstand σ_{max} is obtained by solving

$$\sigma_y = \sigma_{max}$$

$$\text{FOS} = \frac{\sigma_y}{32M/(\pi d_s^3)}$$

卷之三

卷之三

6

Curved Beams

- To obtain R , the location of the neutral axis, we use the condition that the normal force acting on the crosssection is zero.

$$\int_A \sigma_{yy} dA = 0$$

$$\text{or } - \int_A E k \frac{(R-r)}{r} dA = 0$$

$$\text{or } R \int_A \frac{dA}{r} - \int_A dA = 0$$

$$\text{or } R = \frac{A}{\int_A \frac{dA}{r}}$$

• We have $A = b(r_2 - r_1)$. Also $\int_A \frac{dA}{r} = \int_{r_1}^{r_2} \frac{b dr}{r} = b \ln \frac{r_2}{r_1}$

• Therefore

$$R = \frac{r_2 - r_1}{\ln \frac{r_2}{r_1}}$$

MED202 Brønning (ITB)

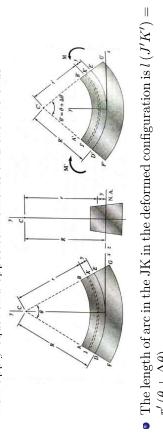
January 2022 Semester

74

Curved Beams

- The length of arc JK in the undeformed beam is $l(JK) = r\theta$.

- Now apply equal and opposite moments and the two ends.



• The length of arc in the JK in the deformed configuration is $l(J'K') = \frac{r}{r'}(\theta + \Delta\theta)$

- The strain $\epsilon_{\theta\theta}$ in the circumferential direction are given by

$$\epsilon_{\theta\theta} = \frac{l(J'K') - l(JK)}{l(JK)}$$

$$= \frac{r'(\theta + \Delta\theta) - r\theta}{r\theta}$$

$$= \frac{r'(\theta + \Delta\theta) - r\theta}{r\theta}$$

$$= \frac{(R' - R)(\theta + \Delta\theta) - (R - r)\theta}{r\theta}$$

MED202 Brønning (ITB)

January 2022 Semester

72

Curved Beams

The relation between the internal resisting moment and the developed stress is obtained as follows:

- We have

$$\epsilon_{\theta\theta} = -k \frac{(R-r)}{r}, \quad k = \Delta\theta/\theta$$

- The strain does not vary linearly with distance from the neutral axis.

- For a linear elastic material (assuming all the other stress components are negligible) we get

$$\sigma_{\theta\theta} = E \epsilon_{\theta\theta} = -E k \frac{(R-r)}{r}$$

- The stress does not vary linearly with distance from the neutral axis.

(A)

$\therefore M = E k A (\bar{r} - R)$

(B)

• We also have

$$\sigma_{\theta\theta} = -E k \frac{(R-r)}{r}$$

Still S. Kallurai

January 2022 Semester

75

MED202 Brønning (ITB)

January 2022 Semester

72

Curved Beams

- We have

$$\epsilon_{\theta\theta} = -k \frac{(R-r)}{r}, \quad k = \Delta\theta/\theta$$

- The strain does not vary linearly with distance from the neutral axis.

- For a linear elastic material (assuming all the other stress components are negligible) we get

$$\sigma_{\theta\theta} = E \epsilon_{\theta\theta} = -E k \frac{(R-r)}{r}$$

- The stress does not vary linearly with distance from the neutral axis.

(A)

$\therefore M = E k A (\bar{r} - R)$

(B)

Still S. Kallurai

January 2022 Semester

75

MED202 Brønning (ITB)

January 2022 Semester

72

Selection of Materials in Mechanical Design

Factors to Consider While Selecting a Material

- Nature of loading on the component
- Expected stress state at the critical locations
- Allowable deformations at the critical locations
- Interfaces with other components of the product
- Environment in which the component is expected to operate.
- Physical size and weight of the component
- Aesthetics expected of the component/product
- Cost target of the component/product
- Availability of anticipated manufacturing processes

Primary Reference

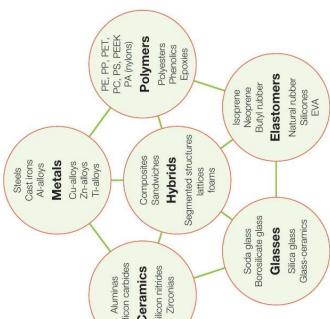
Ashby, Material Selection in Mechanical Design

Sailil S. Kulkarni

2

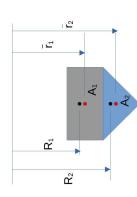
<http://www.matweb.com>

Material Families



Curved Beams

Find R of the c/s made of two areas A_1 and A_2 shown below



• Also,

$$R_1 = \frac{A_1}{\int_{A_1} r dA}, \quad R_2 = \frac{A_2}{\int_{A_2} r dA}$$

• Therefore

$$\int_A \frac{dA}{r} = \frac{A_1}{R_1} + \frac{A_2}{R_2}$$

• Hence

$$R = \frac{A_1 + A_2}{\frac{A_1}{R_1} + \frac{A_2}{R_2}}$$

• In general for a c/s made up of n areas, $A_i, i = 1, 2, \dots, n$

$$R = \frac{\sum_{i=1}^n A_i}{\sum_{i=1}^n \left(\frac{A_i}{R_i}\right)}$$

Now

$$\int_A \frac{dA}{r} = \int_{A_1} \frac{dA}{r} + \int_{A_2} \frac{dA}{r}$$

ME423-Bending (17TB) Still S. Kulkarni

January 2022 Semester 81

Design Limiting Material Properties

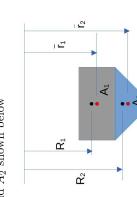
Class	Property	Symbol and units
General	ρ	(kg/m ³ or lb/in ³)
Mechanical	Density	
	Modulus (Young's)	E , G, K
	Shear modulus	(GPa)
	Yield strength	σ_y
	Ultimate strength	σ_u
	Fatigue strength	σ_f
	Fibre strength	σ_c
Hardness	H	(Vickers)
Biologics	E	(10 ¹⁰ Pa)
	Fracture surface limit	K_{Ic}
	Toughness	(10 ¹⁰ Pa m ^{0.5})
Lec. coefficients	α	(10 ⁻⁶ m/K)
(or capacity)	η	(-)
Melting point	T_m	(C or K)
Glass temperature	T_g	(C or K)
Platinum service	T_{max}	(C or K)
Temperature coefficient	T_{co}	(C or K)
Thermal conductivity	λ	(W/mK)
Specific heat	C_p	(J/kgK)
Thermal expansion coefficient	α	(K ⁻¹)
Thermal shock resistance	ΔT_c	(C or K)
Electrical resistivity	ρ	(Ω m or µΩ cm)
Dielectric constant	ϵ_0	(C ² /N·Vm)
Dielectric loss factor	V	(-)
Power factor	P	(-)
Optical transparency	Yes/No	
Translucent, opaque		
Reflective index	n	(-)
Energy to extract	E	(J/kg)
CO ₂ to extract		(kg/kg)
Environmental resistance	Very low, low, average, high, very high	
Water resistance	K_w	(m/s ⁻¹)

ME423-Bending (17TB) Still S. Kulkarni

January 2022 Semester 81

Curved Beams

Find \bar{r} of the c/s made of two areas A_1 and A_2 shown below



• Also,

$$\bar{r}_1 = \frac{\int_{A_1} r dA}{A_1}, \quad \bar{r}_2 = \frac{\int_{A_2} r dA}{A_2}$$

• Therefore

$$\bar{r} = \frac{\bar{r}_1 A_1 + \bar{r}_2 A_2}{A_1 + A_2}$$

• In general for a c/s made up of n areas, $A_i, i = 1, 2, \dots, n$

$$\bar{r} = \frac{\sum_{i=1}^n \bar{r}_i A_i}{\sum_{i=1}^n A_i}$$

• We have

$$\bar{r} = \frac{\int_A r dA}{A}$$

Now

$$\int_A r dA = \int_{A_1} r dA + \int_{A_2} r dA$$

ME423-Bending (17TB) Still S. Kulkarni

January 2022 Semester 81

Important Thermal Properties of Engineering Materials

- Coefficient of Thermal Expansion (K^{-1}) – The thermal strain per degree of temperature change is measured by the coefficient of thermal expansion

- Thermal Conductivity (W/m.K) – indicates the ability to conduct/transfer heat at steady state

• Thermal Diffusivity (m^2/s) . It is given by $\alpha = \lambda/\rho C_p$. The distance x the heat diffuses in time t is given by $x \approx \sqrt{2\alpha t}$

• Heat capacity or Specific heat (units J/kg.K) It is the energy required to heat 1 kg of a material by 1 K. The measurement is usually done at constant pressure for solids

Salil S. Kulkarni

ME423 - IIT Bombay

4

- Ductility: It is the ability to undergo inelastic deformation before failure. It is measured in terms of elongation (tensile strain at failure)
- Elastic Modulus (GPa) – measure of stiffness

- Resilience: The ability of a material to absorb energy per unit volume without permanent deformation is called its resilience U_R (also called modulus of resilience) and is equal to the area under the stress-strain curve up to the elastic limit
- Toughness: The ability of a material to absorb energy per unit volume without fracture is called its toughness U_T (also called modulus of toughness) and is equal to the area under the stress-strain curve up to the fracture point

- Fracture toughness($M Pa\sqrt{m}$) It is a material property that defines its ability of a material to resist crack growth and is denoted by K_{Ic}

6

Important Mechanical Properties of Engineering Materials

- Ductility – the ability to undergo inelastic deformation before failure. It is measured in terms of elongation (tensile strain at failure)

- Elastic Modulus (GPa) – measure of stiffness

- Resilience: The ability of a material to absorb energy per unit volume without permanent deformation is called its resilience U_R (also called modulus of resilience) and is equal to the area under the stress-strain curve up to the elastic limit
- Toughness: The ability of a material to absorb energy per unit volume without fracture is called its toughness U_T (also called modulus of toughness) and is equal to the area under the stress-strain curve up to the fracture point

- Fracture toughness($M Pa\sqrt{m}$) It is a material property that defines its ability of a material to resist crack growth and is denoted by K_{Ic}

4

AISI/SAE Designation of Steel Alloys

Type	AISI/SAE Series	Principal Alloying Elements
Carbon Steels		Carbon
Plain	10xx	Carbon plus Sulphur (resulfurized)
Free-cutting	11xx	
Alloy Steels		
Manganese	13xx	1.75% Manganese
Nickel	15xx	1.00 to 1.65% Manganese
Nickel	23xx	3.50% Nickel
Nickel-Chrome	25xx	5.00% Nickel
Molybdenum	31xx	1.25% Nickel and 0.65 or 0.80% Chromium
Nickel-Chrome-Moly	33xx	3.50% Nickel and 1.5% Chromium
Nickel-Chrome-Moly	40xx	0.25% Molybdenum
Chrome-Moly	41xx	0.35% Chromium and 0.20% Molybdenum
Nickel-Chrome-Moly	43xx	0.32% Nickel, 0.50 or 0.80% Chromium, and 0.25% Molybdenum
Nickel-Moly	47xx	1.5% Nickel, 0.45% Chromium, and 0.20 or 0.35% Molybdenum
Chrome	46xx	0.82 or 1.82% Nickel and 0.25% Molybdenum
Chrome	48xx	3.50% Nickel and 0.25% Molybdenum
Chrome	50xx	0.27 to 0.65% Chromium
Chrome-Vanadium	51xx	0.80 to 1.05% Chromium
Chrome-Vanadium	52xx	1.45% Chromium
Chrome-Vanadium	61xx	0.60 to 0.95% Chromium and 0.10 to 0.15% Vanadium minimum carbon present. e.g. 1040 – plain carbon steel with 0.40 % carbon (0.37% - 0.43%

Salil S. Kulkarni
ME423 - IIT Bombay

13

Important Mechanical Properties of Engineering Materials

- Hardness – the resistance of a material to penetration by a pointed tool (Rockwell hardness, Brinell hardness). For steel: $\sigma_{ult} = 3.40H_B$ (MPa)
- Machinability – related to the ease with which the material can be machined to a good surface finish with a reasonable tool life
- Creep – progressive elongation experienced by materials when subjected to high stress (less than yield strength) at high temperatures. ($T > 0.3$ Tm)

AISI – American Iron and Steel Institute

SAE – Society of Automotive Engineers

Last two digits indicate the % of carbon present.
e.g. 1040 – plain carbon steel
with 0.40 % carbon (0.37% - 0.43%

Salil S. Kulkarni
ME423 - IIT Bombay

5

Example

Mass $m = \rho A L$
 Stiffness $S = \frac{4EA^2}{L^3}$

To minimize the mass we therefore need
 to maximize the material index $\frac{E^{1/2}}{\rho}$

$$\begin{aligned} S &\geq S^* \quad \text{constraint} \\ \frac{4EA^2}{L^3} &\geq S^* \\ \frac{4Em^2}{L^5\rho^2} &\geq S^* \quad \text{Substitute for the area } A \\ \text{or } m &\geq \left(\frac{1}{2}\sqrt{S^*}\right)\left(L^{5/2}\right)\left(\frac{\rho}{E^{1/2}}\right) \end{aligned}$$

Functional Geometric Material
 parameters parameters properties

$m \geq f_1(F)f_2(G)f_3(M)$ separable form

Salil S. Kulkarni

ME423 - IIT Bombay

20

18

Material Index

- Material index: group of material properties which govern some aspect of performance of the component
- The material is selected by maximizing/minimizing the material index

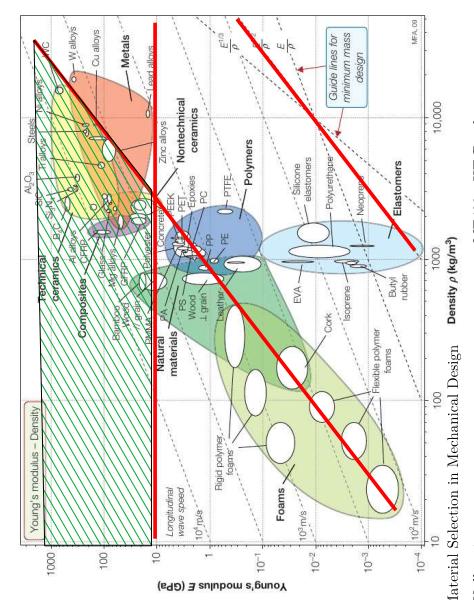
Function, objective, and constraints					
Material	$\rho (\text{kg/m}^3)$	$E(\text{GPa})$	$\sigma_y(\text{MPa})$	$E^{1/2}/\rho$	Index
1020 Steel	7850	205	320	58	$\frac{E}{\rho}$
6061 Al	2700	70	120	98	$\frac{E^{1/2}}{\rho}$
Ti-6Al-4V	4400	115	950	77	$\frac{\rho}{\sigma_y}$
GFRP	1750	28	300	96	$\frac{\rho}{\sigma_y^2}$
					$\frac{E^{1/2}}{C_m\rho}$
					$\frac{E^{1/2}}{C_e\rho}$
					$\frac{\sigma_y^2}{C_p\rho}$
					$\frac{1}{\lambda C_p\rho}$
					$\frac{C_p\rho}{\rho_e}$

Ashby, Material Selection in Mechanical Design, Young's modulus, σ_y = yield stress, C_m = thermal conductivity, C_e = electrical resistivity, C_p = specific heat.

Salil S. Kulkarni

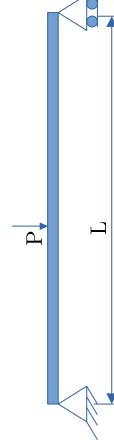
18

Material Property Chart



Example

Choose a material for a simply supported light stiff beam with a square c/s. The stiffness of the beam should be at least S^*



Function: The beam supports a load P
 Constraint: stiffness should be at least S^*
 Objective: minimize the mass of the beam
 Free variable: material and c/s area A

Material	$\rho (\text{kg/m}^3)$	$E(\text{GPa})$	$\sigma_y(\text{MPa})$
1020 Steel	7850	205	320
6061 Al	2700	70	120
Ti-6Al-4V	4400	115	950
GFRP	1750	28	300

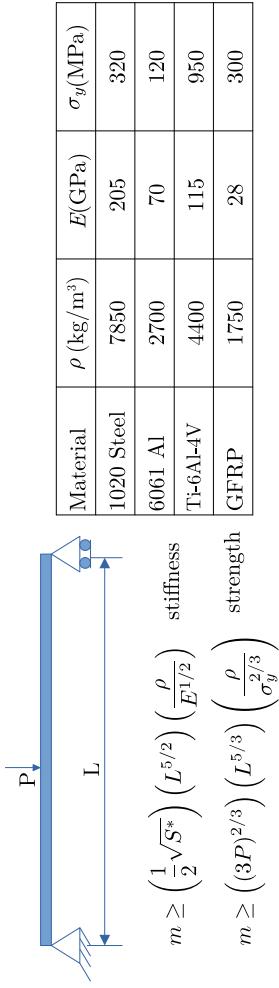
Ashby, Material Selection in Mechanical Design
 Salil S. Kulkarni
 ME423 - IIT Bombay

21

Salil S. Kulkarni
 ME423 - IIT Bombay
 19

Example – Single Objective Multiple Constraints

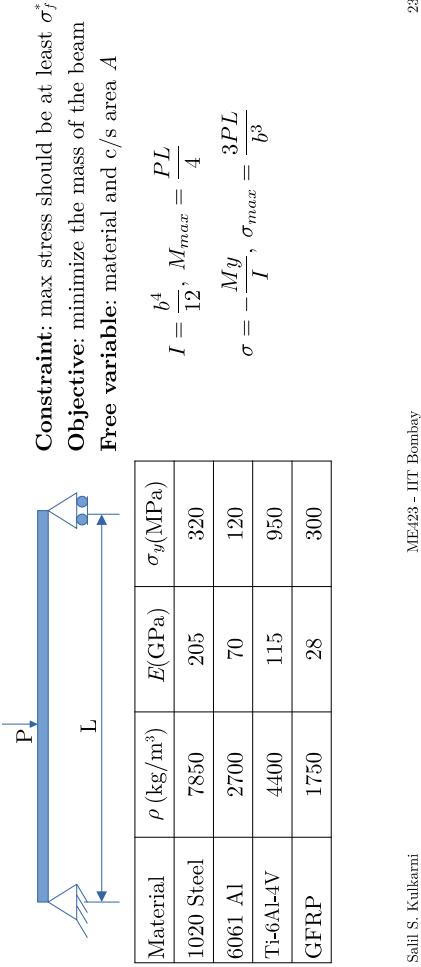
Choose a material for a simply supported light beam with a square c/s with max stress being less than the failure strength and stiffness being at least S^* . Here L = 1m, P = 100 kN, $S^* = 3 \times 10^7$ N/m



Salil S. Kulkarni

ME423 - IIT Bombay

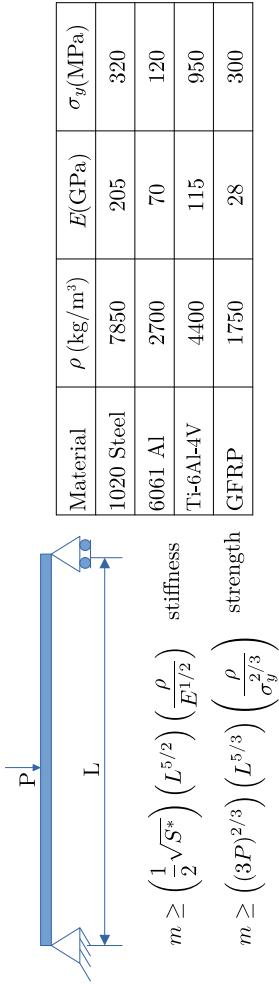
27



23

Example – Single Objective Single Constraint

Choose a material for a simply supported light beam with a square c/s with max stress being less than the failure strength



27

ME423 - IIT Bombay

23

Example – Single Objective Multiple Constraints

Example – Single Objective Single Constraint

Material	ρ (kg/m ³)	E(GPa)	σ_y (MPa)	E (GPa)	σ_y (MPa)	$\sigma_y^{2/3}/\rho$
1020 Steel	7850	205	320	205	320	60
6061 Al	2700	70	120	70	120	90
Ti-6Al-4V	4400	115	950	115	950	219
GFRP	1750	28	300	28	300	256

$$\min(\max(m1, m2)) = 29$$

Example of a min-max problem

$$\text{or } m \geq \left(\frac{3P}{\rho L}\right)^{2/3} \left(L^{5/3}\right) \left(\frac{\rho}{\sigma_y^{2/3}}\right)$$

To minimize the mass we therefore need to maximize the material index $\frac{\sigma_y^{2/3}}{\rho}$

Salil S. Kulkarni

28

ME423 - IIT Bombay

$$\frac{3PL}{b^3} \leq \sigma_y \text{ Substitute for } b \text{ in terms of mass } m$$

$$\left(\frac{m}{\rho L}\right)^{3/2} \leq \sigma_y \text{ terms of mass } m$$

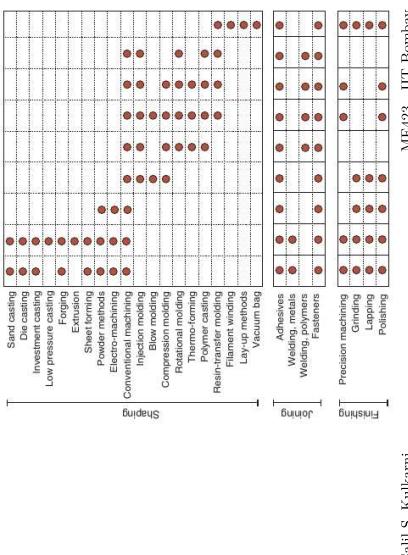
24

ME423 - IIT Bombay

The Process–Material Matrix

Multi-Objective Problems

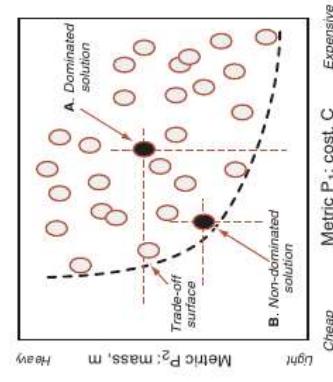
Problem: Identify a material which minimizes both mass (performance metric P1) and cost (performance metric P2) while also meeting a set of constraints



31

Ashby, Material Selection in Mechanical Design
Salil S. Kulkarni

ME423 - IIT Bombay



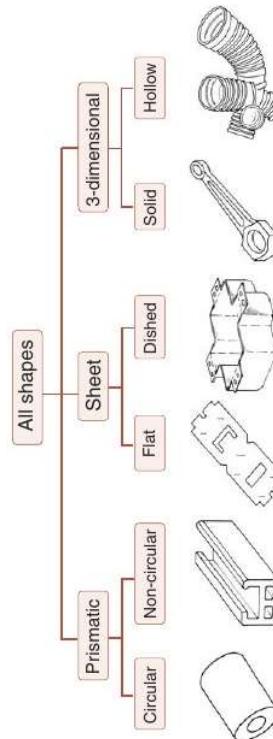
29

Ashby, Material Selection in Mechanical Design
Salil S. Kulkarni

ME423 - IIT Bombay

- Each bubble represents a material – does not violate any constraints
- The materials that minimize P1 do not minimize P2 and vice versa
- Materials such as that at A, are far from optimal — all the materials in the box attached have lower values of both P1 and P2 – Dominated Solutions
- Materials like those at B have the characteristic that no other materials exists with lower values of both P1 and P2. Non-dominated solutions.
- The line or surface on which the non-dominated solutions lie is called the optimal trade-off surface or Pareto surface
- Different methods exists for solving such projections

Types of Shapes

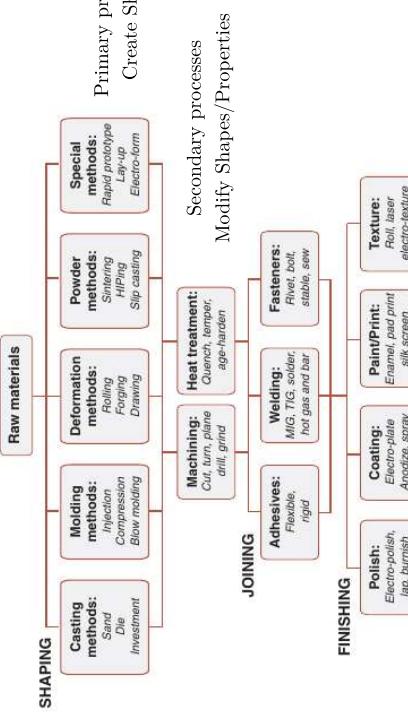


Ashby, Material Selection in Mechanical Design
Salil S. Kulkarni

32

ME423 - IIT Bombay

Types of Processes



Ashby, Material Selection in Mechanical Design
ME423 - IIT Bombay

30

Shaft Design Considerations – Static Strength

- The maximum shear stress is then given by

$$\tau_{max} = \frac{\sigma_A - \sigma_B}{2} = \left[\left(\frac{\sigma_{xx}}{2} \right)^2 + \tau_{xy}^2 \right]^{1/2}$$

- The equivalent or the von Mises stress is then given by

$$\sigma_{eq} = (\sigma_A^2 + \sigma_B^2 - \sigma_A \sigma_B)^{1/2} = (\sigma_{xx}^2 + 3\tau_{xy}^2)^{1/2}$$

- Substituting the expression for the stress components:

$$\tau_{max} = \frac{2}{\pi d^3} \sqrt{(Fd + 8M)^2 + (8T)^2}$$

- If N is the factor of safety and σ_y is the yield strength of the material in tension, then the diameter d is chosen such that

$$\frac{\sigma_y}{2N} = \frac{2}{\pi d^3} \sqrt{(Fd + 8M)^2 + (8T)^2}$$

If $F = 0$, it is easier to solve these equations for d

(Distortion Energy criterion)

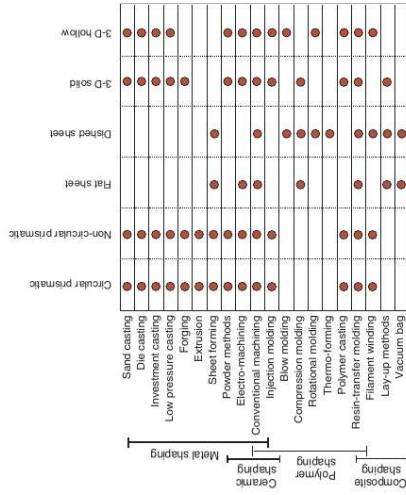
8

Sali S. Kulkarni

ME423 - IIT Bombay

Sali S. Kulkarni

Ashby, Material Selection in Mechanical Design 33



ME423 - IIT Bombay

Ashby, Material Selection in Mechanical Design 33

The Process–Shape Matrix

Shaft Design Considerations – Fatigue Strength

For a point on the surface of a circular solid shaft of diameter d located at a critical location with fluctuating bending moment (mean component M_m , alternating component M_a) and fluctuating torque (mean component T_m , alternating component T_a) [axial loading is ignored]

$$\begin{aligned} \sigma_m &= K_f \frac{32M_m}{\pi d^3}, & \sigma_a &= K_f \frac{32M_a}{\pi d^3} & K_f \text{ and } K_s \text{ are the fatigue stress} \\ \tau_m &= K_f s \frac{16T_m}{\pi d^3}, & \tau_a &= K_f s \frac{16T_a}{\pi d^3} & \text{concentration factors at the} \\ &&&& \text{critical location} \end{aligned}$$

$$\begin{aligned} \sigma_{eqm} &= (\sigma_m^2 + 3\tau_m^2)^{1/2} & \sigma_{eqa} &= (\sigma_a^2 + 3\tau_a^2)^{1/2} \\ \text{or} \quad \sigma_{eqm} &= \left[\left(K_f \frac{32M_m}{\pi d^3} \right)^2 + 3 \left(K_f s \frac{16T_m}{\pi d^3} \right)^2 \right]^{1/2} & \sigma_{eqa} &= \left[\left(K_f \frac{32M_a}{\pi d^3} \right)^2 + 3 \left(K_f s \frac{16T_a}{\pi d^3} \right)^2 \right]^{1/2} \end{aligned}$$

- The mean and alternating von Mises (equivalent) stresses are given by

$$\sigma_{eqm} = (\sigma_m^2 + 3\tau_m^2)^{1/2} \quad \sigma_{eqa} = (\sigma_a^2 + 3\tau_a^2)^{1/2}$$

$$\sigma_A, \sigma_B = \frac{\sigma_{eq}}{2} \pm \left[\left(\frac{\sigma_{xx}}{2} \right)^2 + \tau_{xy}^2 \right]^{1/2}$$

ME423 - IIT Bombay

9

Ashby, Material Selection in Mechanical Design 33

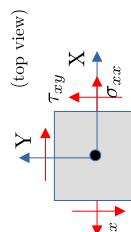
Shaft Design Considerations – Static Strength

• Though a shaft is under dynamic loading (fatigue), a static analysis gives a preliminary estimate of the dimensions of the required dimensions.

- For a point on the surface of a circular solid shaft of diameter d located at a critical location with constant bending moment M , constant torque T and constant axial force F (xx-axis along the axis, y - horizontal)

$$\begin{aligned} \sigma_{xx} &= \frac{32M}{\pi d^3} + \frac{4F}{\pi d^2} & \text{(the second component can be either} \\ &&& \text{positive or negative (tension/compression)}) \\ \tau_{xy} &= \frac{16T}{\pi d^3} & \text{(stress concentration effects are neglected} \\ &&& \text{for ductile material}) \end{aligned}$$

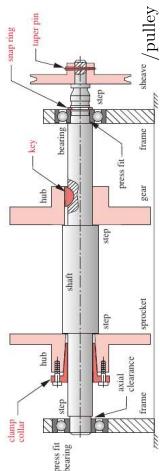
- Since the point is assumed to be on an unloaded surface, it is in the state of plane stress.



Shaft Design Considerations – Fatigue Strength

- Estimates of the Stress Concentration Factors

The design of the shaft is greatly influenced by the presence of geometric features such as shoulders, holes, keyways which lead to stress concentration.



Stress concentration factors depend on the dimensions of the shaft which is not available. Hence estimates of these factors are needed and are given by

	Bending	Torsional	Axial
Shoulder fillet – sharp ($r/d = 0.02$)	2.7	2.2	3.0
Shoulder fillet – well rounded ($r/d = 0.1$)	1.7	1.5	1.9
End-mill keyseat ($r/d = 0.02$)	2.14	3.0	—
Sled runner keyseat	1.7	—	—
Retaining ring groove	3.0	5.0	—

Sali S. Kulkarni

12

10

Shaft Design Considerations – Fatigue Strength

- If N is the factor of safety (given), the Goodman criterion can be written as

$$\frac{\sigma_{eqa}}{\sigma_e} + \frac{\sigma_{eqm}}{\sigma_{ult}} = \frac{1}{N}$$

- Substituting the expressions for σ_{eqa} and σ_{eqm} obtained earlier one gets an equation for d .

- On solving the equation, we get the estimate of the minimum diameter which needs to be used.

- One can also use the other fatigue criterion – Gerber, etc

ME423 - IIT Bombay

10

What is a Countershaft

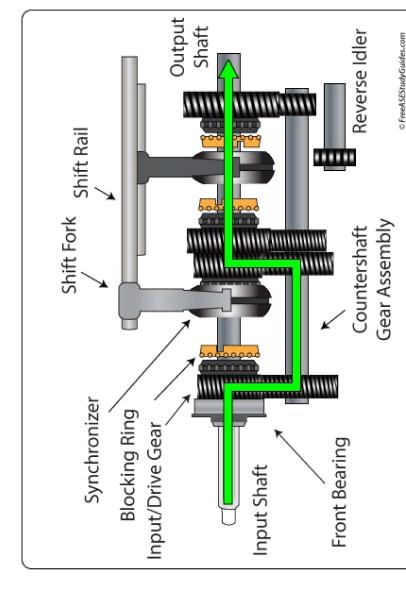
Shaft Design Considerations – Fatigue Strength

- In addition one also needs to check for static failure in the first cycle itself – for the estimated d , we calculate the maximum equivalent (von Mises) stress

$$\sigma_{eqmax} = ((\sigma_m + \sigma_a)^2 + 3(\tau_m + \tau_a)^2)^{1/2}$$

and compare it with $\frac{\sigma_y}{N}$

- Another class of problems consists of given d , estimate the factor safety, N . This is typically easier to solve.



<https://www.freestudyguides.com/manual-transmission-countershafts.html>
Sali S. Kulkarni

13

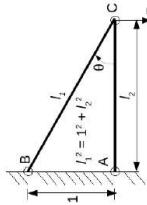
ME423 - IIT Bombay

11

ME423 - IIT Bombay

Problem – Dummy Load Method

Find the deflection of the point of application of point in the horizontal direction. The material is linear elastic with Young's modulus E .



- We are asked to find the displacement in a direction where there is no applied force.
- Assume a dummy load, Q , acts in the direction in which the displacement is required.
- Castigliano's Second Theorem gives us the displacement in the direction of the load.
- In this problem there is no applied force in the horizontal direction.
- Castigliano's Second Theorem gives us the displacement in the direction of the load.
- Express the strain energy of the system in terms of the applied loads and the dummy load Q .
- Find the displacement in the direction of the dummy load using Castigliano's Second Theorem.
- Set $Q = 0$ in the expression of δ_Q . This gives the answer to the original problem.

Sailil S. Kulkarni

27

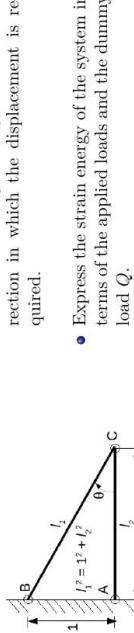
Sailil S. Kulkarni

Problem

Main Idea of the Dummy Load Method

We are asked to find the displacement in a direction where there is no applied force.

The material is linear elastic with Young's modulus E .



- We are asked to find the displacement in a direction where there is no applied force.
- Assume a dummy load, Q , acts in the direction in which the displacement is required.
- Castigliano's Second Theorem gives us the displacement in the direction of the load.
- Express the strain energy of the system in terms of the applied loads and the dummy load Q .
- Find the displacement in the direction of the dummy load using Castigliano's Second Theorem.
- Set $Q = 0$ in the expression of δ_Q . This gives the answer to the original problem.

Sailil S. Kulkarni

27

Sailil S. Kulkarni

25

- The strain energy in the two member truss is given by

$$U = \sum_{i=1}^2 \frac{P_i^2 l_i}{2EA_i}$$

$$= \frac{F_{AC}^2 l_2}{2EA_2} + \frac{F_{BC}^2 l_1}{2EA_1}$$

$$U(P) = \frac{1}{2} \frac{P^2 l_2^3}{A_2 E} + \frac{1}{2} \frac{P^2 l_1^3}{A_1 E}$$

- Let δ denote the vertical displacement of point C. From Castigliano's Second theorem

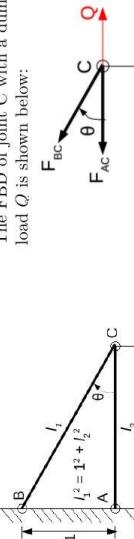
$$\delta = \frac{\partial U}{\partial P}$$

$$\delta = \frac{P l_2^3}{A_2 E} + \frac{P l_1^3}{A_1 E}$$

- Let δ denote the vertical displacement of point C. From Castigliano's Second theorem
- Therefore
- This is a statically determinate problem.

Problem

The FBD of joint C with a dummy load Q is shown below:



Force balance in the horizontal direction and the vertical direction gives:

$$F_{BC} = \frac{P}{\sin \theta}$$

$$F_{AC} = Q - P \cot \theta$$

$$U = \frac{F_{AC}^2 l_2}{2EA_2} + \frac{F_{BC}^2 l_1}{2EA_1} \text{ or } U(P, Q) = \frac{(Q - P l_2)^2 l_2}{2EA_2} + \frac{P^2 l_1^3}{2A_1 E}$$

From Castigliano's Second Theorem

$$\tilde{\delta}_Q = \frac{\partial U}{\partial Q} = \frac{(Q - P l_2) l_2}{E A_2}$$

The horizontal displacement, δ_Q in the original problem is then given by

$$\delta_Q = (\tilde{\delta}_Q)_{Q=0} = -\frac{P l_2^2}{E A_2}$$

ME423 - IIT Bombay

Sailil S. Kulkarni

28

- The strain energy in the member is given by
- Let δ denote the vertical displacement of point C. From Castigliano's Second theorem
- Therefore

$$U = \frac{P^2 a^3}{6EI} + \frac{P^2 L^3}{6EI} + \frac{P^2 L a^2}{2GJ}$$

- Let δ denote the vertical displacement of point C. From Castigliano's Second theorem
- Therefore

$$\delta = \frac{P a^3}{3EI} + \frac{PL^3}{3EI} + \frac{PL a^2}{GJ}$$

26

Sailil S. Kulkarni

Shaft Deflection using Castigliano's Second Theorem

Using Castigliano's Second Theorem, the vertical displacement at the point of application of F_1 is

$$\delta_1 = \frac{\partial U}{\partial F_1} = \int_o^a \frac{M_1}{EI_1} \frac{\partial M_1}{\partial F_1} dx + \int_a^b \frac{M_2}{EI_2} \frac{\partial M_2}{\partial F_1} dx + \int_b^L \frac{M_3}{EI_3} \frac{\partial M_3}{\partial F_1} dx$$

Similarly, the vertical displacement at the point of application of F_2 is

$$\delta_2 = \frac{\partial U}{\partial F_2} = \int_o^a \frac{M_1}{EI_1} \frac{\partial M_1}{\partial F_2} dx + \int_a^b \frac{M_2}{EI_2} \frac{\partial M_2}{\partial F_2} dx + \int_b^L \frac{M_3}{EI_3} \frac{\partial M_3}{\partial F_2} dx$$

Substituting the problem parameters, we get $\delta_1 = 0.092$ mm. and $\delta_2 = -0.033$ mm

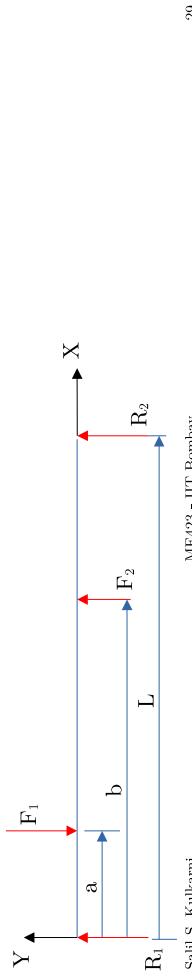
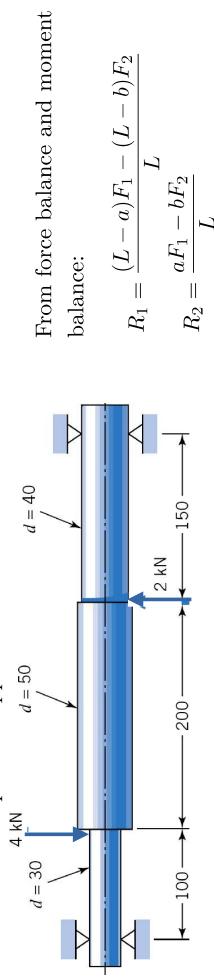
In case we take the the transverse shear into account
In the direction opposite to F_2

$$U(F_1, F_2) = \int_o^a \frac{M_1^2}{2EI_1} dx + \int_a^b \frac{M_2^2}{2EI_2} dx + \int_b^L \frac{M_3^2}{2EI_3} dx \\ + \int_o^a \frac{f_s V_1^2}{2GA_1} dx + \int_a^b \frac{f_s V_2^2}{2GA_2} dx + \int_b^L \frac{f_s V_3^2}{2GA_3} dx$$

f_s is the correction factor
 $f_s = 1.11$ for circular c/s

31

ME423 - IIT Bombay



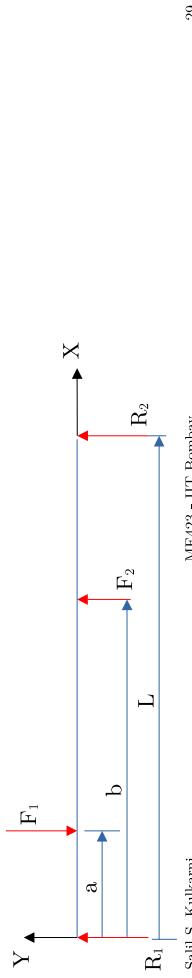
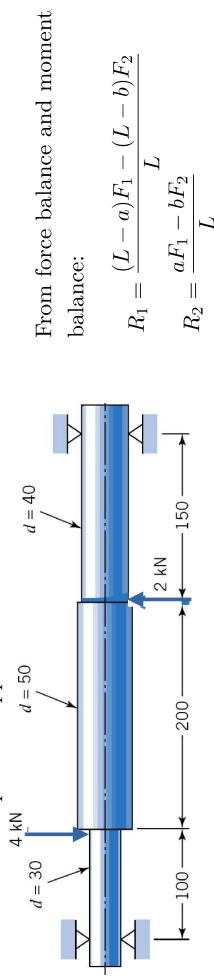
29

Salil S. Kulkarni

ME423 - IIT Bombay

Shaft Deflection using Castigliano's Second Theorem

The shaft shown in the figure is made up of low carbon steel with $E = 207$ GPa. Find the deflection at the point of application of the 4 kN and 2 kN forces



29

Salil S. Kulkarni

ME423 - IIT Bombay

Lateral Vibrations

The natural frequency for an elastic system on mass m and stiffness k can be estimated using

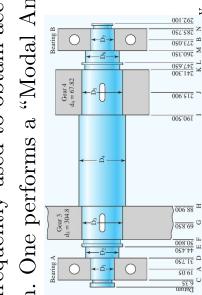
$$\omega_n = \sqrt{\frac{k}{m}}$$

The influence of various parameters which includes shaft diameter D , length L , material with Young's modulus E and density ρ is expressed as

$$\omega_n \propto \frac{D}{L^2} \sqrt{\frac{E}{\rho}}$$

An external periodic force is necessary for these vibrations to occur.

Finite Element Method is frequently used to obtain accurate estimates of the natural frequencies of the vibration. One performs a "Modal Analysis".



Salil S. Kulkarni

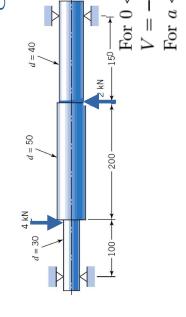
33

Shaft Deflection using Castigliano's Second Theorem

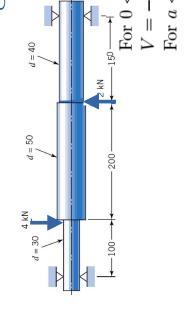
$$R_1 = \frac{(L-a)F_1 - (L-b)F_2}{L}$$

$$R_2 = \frac{aF_1 - bF_2}{L}$$

From force balance and moment balance:



From force balance and moment balance:



29

Let

$$M_1 = R_1 x$$

$$M_2 = R_1 x - F_1(x-a)$$

$$M_3 = R_1 x - F_1(x-a) + F_2(x-b)$$

The total strain energy (neglecting shear deformation) is given by

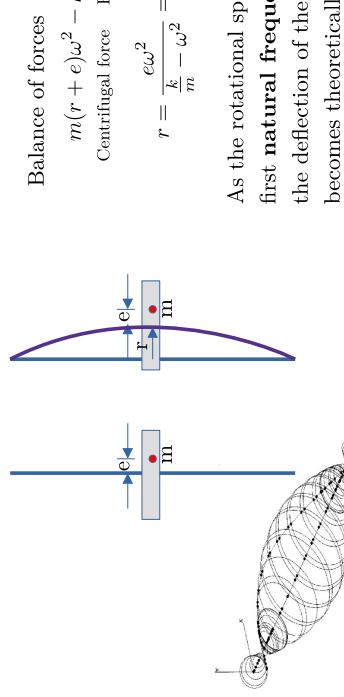
$$U(F_1, F_2) = \int_o^a \frac{M_1^2}{2EI_1} dx + \int_a^b \frac{M_2^2}{2EI_2} dx + \int_b^L \frac{M_3^2}{2EI_3} dx$$

ME423 - IIT Bombay

30

Whirling of Shafts

Shaft whirl is a self-excited phenomenon caused due to an unbalanced rotating mass.



$$\text{Balance of forces}$$

$$m(r + e)\omega^2 - kr = 0$$

$$\text{Centrifugal force} \quad \text{Elastic restoring force}$$

$$r = \frac{e\omega^2}{k} = \frac{e(\omega/\omega_n)^2}{1 - (\frac{\omega}{\omega_n})^2}$$

As the rotational speed approaches the first natural frequency of lateral vibration,

the deflection of the shaft increases and becomes theoretically infinite when they coincide.

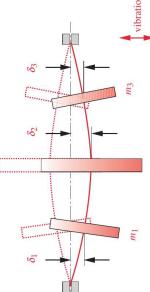
Critical Speeds: The shaft rotation speed or the spin speed which coincide with one of the natural frequencies of the shaft are referred to as the critical speeds.

ME423 - IIT Bombay

36

Sailil S. Kulkarni

Lateral Vibrations



Rayleigh's Method:

The lowest natural frequency of the shaft corresponding to lateral vibrations can be estimated using the Rayleigh Method as follows

$$\omega_1^2 = \frac{g \sum_{i=1}^N m_i \delta_i}{\sum_{i=1}^N m_i \delta_i^2}$$

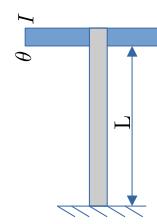
Here $\delta_1, \delta_2, \dots, \delta_N$ are the static deflections of the shaft due to masses m_1, m_2, \dots, m_N mounted on the shaft. It is assumed that the mass of the shaft is negligible as compared to the other mass. The deflections $\delta_1, \delta_2, \dots, \delta_N$ are always taken to be positive. The Rayleigh method always overestimates the lowest natural frequency $(\omega_1)_{\text{Rayleigh}} \geq (\omega_1)_{\text{actual}}$

34

ME423 - IIT Bombay

Torsional Vibrations

Single Degree of Freedom System

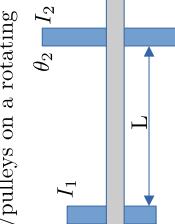


$$I\ddot{\theta} = -k_t\theta, \quad k_t = \frac{GJ}{L} \quad \text{Torsional stiffness}$$

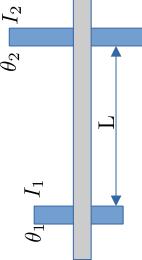
$$\omega_n = \sqrt{\frac{k_t}{I}} = \sqrt{\frac{GJ}{IL}}$$

$$I\ddot{\theta}_1 = k_t(\theta_2 - \theta_1), \quad k_t = \frac{GJ}{L}$$

$$I\ddot{\theta}_2 = -k_t(\theta_2 - \theta_1)$$



Two Degree of Freedom System
Two gears/pulleys on a rotating shaft



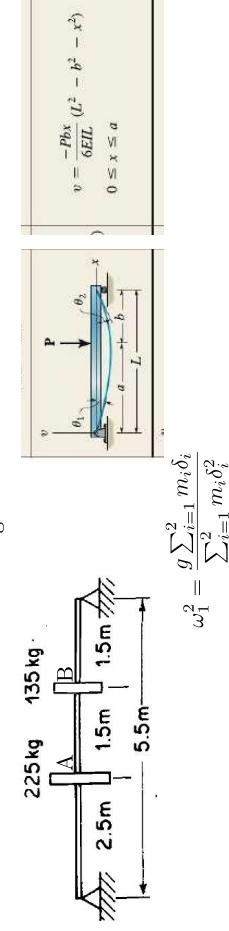
Rigid body mode $\dot{\theta}_1^2 = 0, \omega_1^2 = k_1^2 \frac{I_1 + I_2}{I_1 I_2}$
Natural frequency

ME423 - IIT Bombay

Sailil S. Kulkarni
38
Sailil S. Kulkarni
35
Salil S. Kulkarni
34
Salil S. Kulkarni
33
Salil S. Kulkarni
32
Salil S. Kulkarni
31
Salil S. Kulkarni
30
Salil S. Kulkarni
29
Salil S. Kulkarni
28
Salil S. Kulkarni
27
Salil S. Kulkarni
26
Salil S. Kulkarni
25
Salil S. Kulkarni
24
Salil S. Kulkarni
23
Salil S. Kulkarni
22
Salil S. Kulkarni
21
Salil S. Kulkarni
20
Salil S. Kulkarni
19
Salil S. Kulkarni
18
Salil S. Kulkarni
17
Salil S. Kulkarni
16
Salil S. Kulkarni
15
Salil S. Kulkarni
14
Salil S. Kulkarni
13
Salil S. Kulkarni
12
Salil S. Kulkarni
11
Salil S. Kulkarni
10
Salil S. Kulkarni
9
Salil S. Kulkarni
8
Salil S. Kulkarni
7
Salil S. Kulkarni
6
Salil S. Kulkarni
5
Salil S. Kulkarni
4
Salil S. Kulkarni
3
Salil S. Kulkarni
2
Salil S. Kulkarni
1
Salil S. Kulkarni
0

Lateral Vibrations

Estimate the lowest natural frequency of the shaft in lateral vibration of the system shown below. The mass of the shaft can be neglected.



$$\omega_1^2 = \frac{g \sum_{i=1}^2 m_i \delta_i}{\sum_{i=1}^2 m_i \delta_i^2}$$

$$\delta_A = \delta_{AA} + \delta_{BA} = \frac{10798.0}{EI} \text{ m}$$

$$\delta_B = \delta_{AB} + \delta_{BB} = \frac{8344.9}{EI} \text{ m}$$

$$\omega_1 = \frac{0.0312}{\sqrt{EI}} \text{ rad/s}$$

ME423 - IIT Bombay
Sailil S. Kulkarni
38
Sailil S. Kulkarni
37
Sailil S. Kulkarni
36
Sailil S. Kulkarni
35
Sailil S. Kulkarni
34
Sailil S. Kulkarni
33
Sailil S. Kulkarni
32
Sailil S. Kulkarni
31
Sailil S. Kulkarni
30
Sailil S. Kulkarni
29
Sailil S. Kulkarni
28
Sailil S. Kulkarni
27
Sailil S. Kulkarni
26
Sailil S. Kulkarni
25
Sailil S. Kulkarni
24
Sailil S. Kulkarni
23
Sailil S. Kulkarni
22
Sailil S. Kulkarni
21
Sailil S. Kulkarni
20
Sailil S. Kulkarni
19
Sailil S. Kulkarni
18
Sailil S. Kulkarni
17
Sailil S. Kulkarni
16
Sailil S. Kulkarni
15
Sailil S. Kulkarni
14
Sailil S. Kulkarni
13
Sailil S. Kulkarni
12
Sailil S. Kulkarni
11
Sailil S. Kulkarni
10
Sailil S. Kulkarni
9
Sailil S. Kulkarni
8
Sailil S. Kulkarni
7
Sailil S. Kulkarni
6
Sailil S. Kulkarni
5
Sailil S. Kulkarni
4
Sailil S. Kulkarni
3
Sailil S. Kulkarni
2
Sailil S. Kulkarni
1
Sailil S. Kulkarni
0

Need to solve an eigenvalue problem to obtain the natural frequencies

Shaft Design Considerations – Shaft Layout

Axial Layout of Components (primary aim is reduce deflections)

- Shafts should be kept short to minimize bending moments and deflections
- It is best to support load-carrying components between bearings in order to minimize deflections.
- The length of the cantilever part of the shaft should be kept short to minimize the deflection.
- Only two bearings should be used in most cases for ease of alignment.
- Load-bearing components should be placed near the bearings to minimize the bending moment at the locations that will likely have stress concentrations and to minimize the deflection at the load-carrying components.
- The components must be accurately located on the shaft to line up with other mating components, and provision must be made to securely hold the components in position.
- The primary means of locating the components is to position them against a shoulder of the shaft. A shoulder also provides a solid support to minimize deflection and vibration of the component.

39

ME423 - IIT Bombay

Saili S. Kulkarni

3

$$X_A = 5 \text{ cm}^2, X_B = 3 \text{ cm}^2, X_C = 1 \text{ cm}^2$$

$$L = 10 \text{ cm}$$

$$\delta_A = \delta_B = \delta_C = \delta$$

$\sigma_A = \sigma_B = \sigma_C = 100 \text{ MPa}$
$\sigma_{yc} = 400 \text{ MPa}$
$\sigma_{ya} = 50 \text{ MPa}$
$\sigma_{yb} = 100 \text{ MPa}$

For the yield limit,

σ must cross the yield values for the respective tie rods,

$$\frac{\sigma_A}{5} = \frac{F_A}{5} = \frac{\sigma_B}{3} = \frac{F_B}{3} = \frac{\sigma_C}{1} = \frac{F_C}{1}$$

where $F_A + F_B + F_C = F$

Case 1 No rod yielded.

$$\frac{\sigma_A}{L} = \frac{\delta_A}{\delta}, \frac{\sigma_B}{L} = \frac{\delta_B}{\delta}, \frac{\sigma_C}{L} = \frac{\delta_C}{\delta} = \frac{\delta}{L}$$

$$\frac{\sigma_A}{L} = \frac{\sigma_B}{L} = \frac{\sigma_C}{L}$$

Since $\sigma_A < \sigma_B < \sigma_C$, σ_A is reached first.

$$\sigma_A = \sigma_B = \sigma_C = 50 \text{ MPa} = E \cdot \frac{\delta}{L}$$

$$\delta_A = \frac{F_A \times 10^6 \times 10}{5 \times 10^4} = 0.005 \text{ cm.}$$

$$\sigma_A = \frac{F_A}{5 \times 10^4} = 50 \text{ MPa.}$$

General Principles for Shaft Design

1. Keep shafts as short as possible, with bearings close to the applied loads. This reduces deflections and bending moments and increases critical speeds.
2. Place necessary stress raisers away from highly stressed shaft regions if possible. If not possible, use generous radii and good surface finishes. Consider local surface-strengthening processes (as shot peening or cold rolling).
3. Use inexpensive steels for deflection-critical shafts, as all steels have essentially the same elastic modulus.
4. When weight is critical, consider hollow shafts. For example, propeller shafts on rear-wheel-drive cars are made of tubing in order to obtain the low-weight-stiffness ratio needed to keep critical speeds above the operating range.

ME423 - IIT Bombay

Saili S. Kulkarni

case 2 Date _____ Page _____

$$\frac{F_A}{5} = 50 \times 10^3$$

$$F_A = 250 \times 10^3$$

$$F_A = 2.5 \text{ kN}$$

$$\therefore \sigma_A = \sigma_B = \sigma_C$$

$$F_A = 5F_C \rightarrow F_C = 5 \text{ kN}$$

$$F_B = 3F_C \rightarrow F_B = 15 \text{ kN}$$

$$F_M = F_A + F_B + F_C = 45 \text{ kN}$$

Case 2 A has yielded.

$$F = F_B + F_C + F_A$$

$$\sigma_B = \frac{F_B}{3} \quad \sigma_C = F_C \quad \sigma_A = 50 \text{ MPa} = F_A \frac{5}{5}$$

$$\delta = \delta_B = \delta_C = \frac{\sigma_B}{E} = \frac{\sigma_C}{E} = \frac{F_A}{5E}$$

For yielding, σ_B is reached next.

$$100 \times 10^6 = \sigma_B = E \times \frac{\delta}{L}$$

$$\sigma_B = \frac{100 \times 10^6 \times 10}{700 \times 100 \times 10^3} = 0.01 \text{ cm}$$

$$\sigma_B = \frac{F_B}{3 \times 10^4} \rightarrow 100 \text{ MPa.}$$

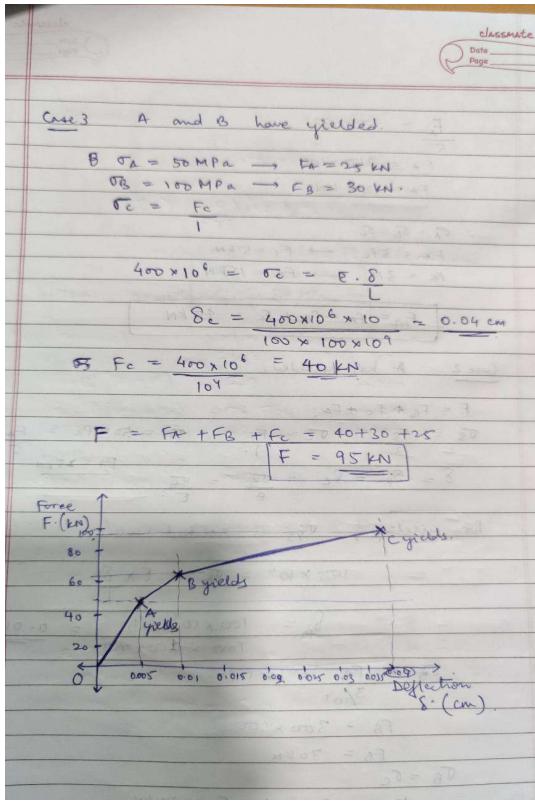
$$F_B = 300 \times 10^3$$

$$F_B = 30 \text{ kN}$$

$$\sigma_B = \sigma_C$$

$$F_B = 3F_C \rightarrow F_C = 10 \text{ kN.}$$

$$F = F_B + F_C = 40 \text{ kN} + 30 \text{ kN} = 65 \text{ kN}$$



Given

$$\begin{aligned} l &= 750; \\ t &= 6; \\ d_o &= 250; \\ d_i &= 250 - 12; \\ W &= 45000; \\ p &= 3.5; \\ r &= 125; \\ T &= W \cdot r; \\ M &= W \cdot r; \\ I_b &= \frac{\pi}{64} (d_o^4 - d_i^4) \\ J_t &= \frac{\pi}{32} (d_o^4 - d_i^4) \\ &10901676 \pi \\ &21803352 \pi \end{aligned}$$

Polar moment of Inertia

$$\begin{aligned} J_t &= \frac{\pi}{32} (d_o^4 - d_i^4) \\ &21803352 \pi \end{aligned}$$

Second Area moment of Inertia

$$\begin{aligned} I_b &= \frac{\pi}{64} (d_o^4 - d_i^4) \\ &N[10901676 \pi] \\ &3.42486 \times 10^7 \end{aligned}$$

Two most critical points are A and B. Let the axis be zz and hoop be θθ

At A there will be bending stress and axial stress due to pressure

$$\begin{aligned} \sigma_{zzb} &= \frac{M r}{I_b} \\ \sigma_{zpz} &= \frac{p r}{2 t} \\ \sigma_{\theta\theta} &= \frac{p r}{t} \\ \tau_{z\theta} &= \frac{T r}{J_t} \\ &351562500 \\ &908473 \pi \\ &36.4583 \\ &72.9167 \\ &29296875 \\ &908473 \pi \end{aligned}$$

Printed by Wolfram Mathematica Student Edition

2 | Exam_ques1.nb

Exam_ques1.nb | 3

$$N[\frac{351562500}{908473 \pi}]$$

123.18

$$N[\frac{29296875}{908473 \pi}]$$

10.265

$$\sigma_{zz} = \sigma_{zzb} + \sigma_{zpz}$$

159.638

$$\begin{aligned} \sigma_1 &= \frac{\sigma_{zz} + \sigma_{\theta\theta}}{2} + \sqrt{\left(\frac{\sigma_{zz} - \sigma_{\theta\theta}}{2}\right)^2 + \tau_{z\theta}^2} \\ \sigma_2 &= \frac{\sigma_{zz} + \sigma_{\theta\theta}}{2} - \sqrt{\left(\frac{\sigma_{zz} - \sigma_{\theta\theta}}{2}\right)^2 + \tau_{z\theta}^2} \end{aligned}$$

$\sigma_3 = 0$

160.837

71.7182

0

$$\sigma_{vmb} = \frac{1}{\sqrt{2}} \left(\sqrt{(\sigma_1 - \sigma_2)^2 + (\sigma_2 - \sigma_3)^2 + (\sigma_3 - \sigma_1)^2} \right)$$

139.56

Clear["Global`*"]

At B,

$$\sigma_{zzb} = 0$$

$$\sigma_{zpz} = \frac{p r}{2 t}$$

$$\sigma_{zpz} = \frac{p r}{2 t}$$

$$\sigma_{\theta\theta} = \frac{p r}{t}$$

$$\tau_{z\theta} = \frac{T r}{J_t}$$

0

36.4583

72.9167

29296875

908473 π

$$\sigma_{zz} = \sigma_{zzb} + \sigma_{zpz}$$

$$\sigma_1 = \frac{\sigma_{zz} + \sigma_{\theta\theta}}{2} + \sqrt{\left(\frac{\sigma_{zz} - \sigma_{\theta\theta}}{2}\right)^2 + \tau_{z\theta}^2}$$

$$\sigma_2 = \frac{\sigma_{zz} + \sigma_{\theta\theta}}{2} - \sqrt{\left(\frac{\sigma_{zz} - \sigma_{\theta\theta}}{2}\right)^2 + \tau_{z\theta}^2}$$

$\sigma_3 = 0$

75.6081

33.7669

0

$$\sigma_{vmb} = \frac{1}{\sqrt{2}} \left(\sqrt{(\sigma_1 - \sigma_2)^2 + (\sigma_2 - \sigma_3)^2 + (\sigma_3 - \sigma_1)^2} \right)$$

65.602907971277

At C in the bottom,

$$\sigma_{zzb} = - \frac{M r}{I_b}$$

$$\sigma_{zpz} = \frac{p r}{2 t}$$

$$\sigma_{\theta\theta} = \frac{p r}{t}$$

$$\tau_{z\theta} = \frac{T r}{J_t}$$

$$- \frac{351562500}{908473 \pi}$$

36.4583

72.9167

29296875

908473 π

$$N[-\frac{351562500}{908473 \pi}]$$

-123.18

$$\sigma_{zz} = \sigma_{zzb} + \sigma_{zpz}$$

-86.7218

$$\sigma_1 = \frac{\sigma_{zz} + \sigma_{\theta\theta}}{2} + \sqrt{\left(\frac{\sigma_{zz} - \sigma_{\theta\theta}}{2}\right)^2 + \tau z \theta^2}$$

$$\sigma_2 = \frac{\sigma_{zz} + \sigma_{\theta\theta}}{2} - \sqrt{\left(\frac{\sigma_{zz} - \sigma_{\theta\theta}}{2}\right)^2 + \tau z \theta^2}$$

$$\sigma_3 = 0$$

$$73.574$$

$$-87.3791$$

$$0$$

$$\sigma_{vmb} = \frac{1}{\sqrt{2}} \left(\sqrt{(\sigma_1 - \sigma_2)^2 + (\sigma_2 - \sigma_3)^2 + (\sigma_3 - \sigma_1)^2} \right)$$

$$139.56$$

Most critical location is A The vonMises is 139.56 and the Tresca gives 160 MPa

If the hydrostatic tests 1.5 p and load is 1.25 W

$$l = 750;$$

$$t = 6;$$

$$d_o = 250;$$

$$d_i = 250 - 12;$$

$$W = 45000;$$

$$p = 1.5 - 3.5;$$

$$r = 125;$$

$$T = 1.25 W;$$

$$M = 1.25 W l;$$

$$Ib = \frac{\pi}{64} (d_o^4 - d_i^4)$$

$$Jt = \frac{\pi}{32} (d_o^4 - d_i^4)$$

$$10901.676 \pi$$

$$21803.352 \pi$$

$$\sigma_{zzb} = \frac{M r}{Ib}$$

$$\sigma_{zpp} = \frac{p r}{2 t}$$

$$\sigma_{\theta\theta} = \frac{p r}{t}$$

$$\tau z \theta = \frac{T r}{3 t}$$

$$153.975$$

$$54.6875$$

$$109.375$$

$$12.8313$$

Printed by Wolfram Mathematica Student Edition

$$\sigma_{zz} = \sigma_{zzb} + \sigma_{zpp}$$

$$208.663$$

$$\sigma_1 = \frac{\sigma_{zz} + \sigma_{\theta\theta}}{2} + \sqrt{\left(\frac{\sigma_{zz} - \sigma_{\theta\theta}}{2}\right)^2 + \tau z \theta^2}$$

$$\sigma_2 = \frac{\sigma_{zz} + \sigma_{\theta\theta}}{2} - \sqrt{\left(\frac{\sigma_{zz} - \sigma_{\theta\theta}}{2}\right)^2 + \tau z \theta^2}$$

$$\sigma_3 = 0$$

$$210.294$$

$$107.744$$

$$0$$

$$\sigma_{vma} = \frac{1}{\sqrt{2}} \left(\sqrt{(\sigma_1 - \sigma_2)^2 + (\sigma_2 - \sigma_3)^2 + (\sigma_3 - \sigma_1)^2} \right)$$

$$182.139$$

The factor of safety is $182.13 / 139.56 = 1.30$

$$\text{In[1]:= } \sigma = \frac{4 F x}{\pi \left(\frac{a x}{2 l} + \frac{a}{2} \right)^3}$$

$$\text{Out[1]:= } \frac{4 F x}{\pi \left(\frac{a}{2} + \frac{a x}{2 l} \right)^3}$$

$$\text{In[2]:= } D[\sigma, x]$$

$$\text{Out[2]:= } -\frac{6 a F x}{l \pi \left(\frac{a}{2} + \frac{a x}{2 l} \right)^4} + \frac{4 F}{\pi \left(\frac{a}{2} + \frac{a x}{2 l} \right)^3}$$

$$\text{In[3]:= } \text{Solve}[D[\sigma, x] = 0, x]$$

$$\text{Out[3]:= } \left\{ \left\{ x \rightarrow \frac{l}{2} \right\} \right\}$$

Printed by Wolfram Mathematica Student Edition