

Optimization in Machine Learning

Lecture 11: Lipschitz Continuity and Smoothness, Algorithms for Optimization and their analysis

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Convex Optimization Problem

- Formally, a convex optimization problem is an optimization problem of the form

$$\begin{aligned} & \text{minimize } f(\mathbf{x}) \\ & \text{subject to } \mathbf{x} \in \mathcal{X} \end{aligned}$$

where f is a convex function, \mathcal{X} is a convex set, and \mathbf{x} is the optimization variable.

- if $\mathcal{X} = \text{dom}(f)$, this becomes unconstrained optimization.
- A special case (f is a convex function, g_i are convex functions, and h_i are affine functions, and \mathbf{x} is the vector of optimization variables):

$$\begin{aligned} & \text{minimize } f(\mathbf{x}) \\ & \text{subject to } g_i(\mathbf{x}) \leq 0, i = 1, \dots, m \\ & h_i(\mathbf{x}) = 0, i = 1, \dots, p \end{aligned}$$



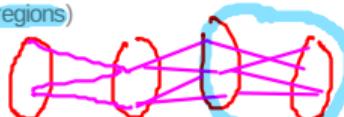
Convex Optimization Problem

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If $\hat{x} \in \text{int}(\mathcal{X})$ then $\partial \mathbf{e}_0 f(\hat{x})$ is sufficient $\underset{\mathbf{x}}{\text{minimize}} \ f(\mathbf{x})$

But the convexity of the set (convexity of the constraint set) is typically not relaxed
subject to $\mathbf{x} \in \mathcal{X}$

Relaxations are typically on the function f (need not be convex everywhere though it might be convex in some regions)



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- A special case (f is a convex function, g_i are convex functions, and h_i are affine functions, and \mathbf{x} is the vector of optimization variables):

Eg: Region could be defined as the region of last layer weights for a deep NN (that with all other layer weights frozen)

$\underset{\mathbf{x}}{\text{minimize}} \ f(\mathbf{x})$

Intersection of convex 0-sublevel sets of g_i 's

subject to $g_i(\mathbf{x}) \leq 0, i = 1, \dots, m$

$h_i(\mathbf{x}) = 0, i = 1, \dots, p$

Either or both of m and p could be 0



Typical convex set. In fact the dual description for convex sets should allow them to be specified as intersections of such inequalities

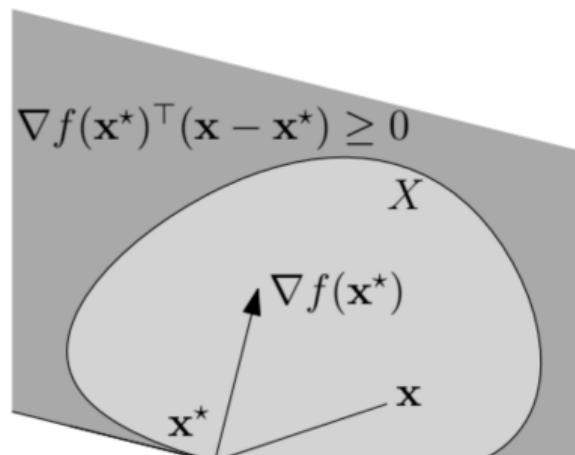


Optimality Condition for Constrained Optimization

- Lemma: Suppose that f is convex and differentiable over an open domain $dmn(f)$. Let $\mathcal{X} \subseteq dom(f)$ be a convex set. A point \mathbf{x}^* is a minimizer of f over \mathcal{X} if and only if

$$\nabla f(\mathbf{x}^*)^\top (\mathbf{x} - \mathbf{x}^*) \geq 0, \forall \mathbf{x} \in \mathcal{X}$$

- Note that the Condition for Unconstrained minimization becomes a special case.
- Nice geometric interpretation: The gradient $\nabla f(\mathbf{x}^*)$ at \mathbf{x}^* is in the same direction as $\mathbf{x} - \mathbf{x}^*$ for any $\mathbf{x} \in dm\mathbf{n}(f)$.

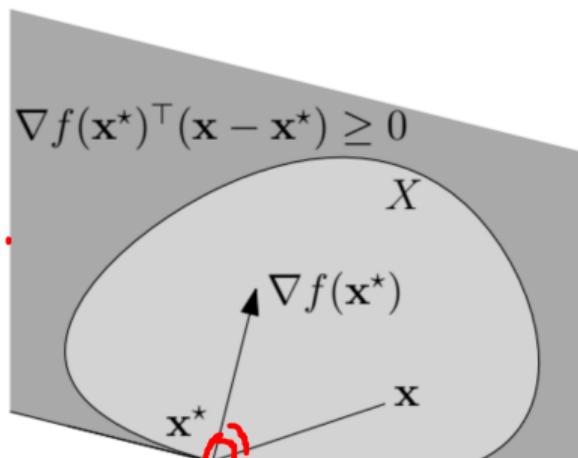
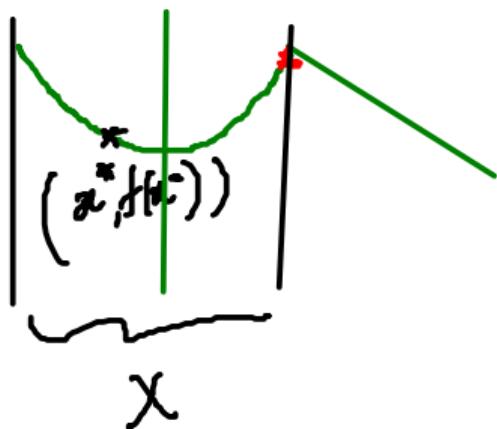


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Case 1: $\mathbf{x}^* \in \text{int}(\mathcal{X})$
 $0 \in \partial f(\mathbf{x}^*)$ or $\nabla f(\mathbf{x}^*) = 0$
is sufficient condition

Case 2: $\mathbf{x}^* \in \text{Bnd}(\mathcal{X})$



Example: Linear and Quadratic Programs

- Linear Program (LP) is a special case of a convex optimization problem:

$$\text{minimize } \mathbf{c}^T \mathbf{x}$$

$$\text{subject to } A\mathbf{x} \leq b$$

- Another special case is Quadratic Programs (QP):

$$\text{minimize } 1/2 \mathbf{x}^T Q \mathbf{x}$$

$$\text{subject to } A\mathbf{x} \leq b$$

- The QP is a convex optimization problem only if



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- The QP is a convex optimization problem only if Q is positive semi-definite,



Outline of next few topics

- Local and Global Minimum [Done]
- Sufficient Subgradient condition for Global Minimum [Done]
- Convexity: Local & Global Minimum [Done]
- Strict Convexity and Unique minimum [Done]
- General Constrained Convex Problem and Optimality Condition [Preliminarily Done]
- Toward Algorithms for Optimization
 - ▶ Lipschitz continuity and (Lipschitz) Smoothness, Strong convexity
 - ★ See lectures 18-19 of my Convex Optimization course
 - ▶ Gradient Descent and Analysis for Lipschitz Continuous, Smooth and Strongly Convex functions
 - ▶ Nesterov's accelerated gradient descent...



Reading on Lipschitz Continuity

- Good Notes on Lipschitz Algebra:
<https://moodle.iitb.ac.in/mod/resource/view.php?id=33825>
- Juha Heinonen, *Lectures on Lipschitz Analysis*,
<http://www.math.jyu.fi/research/reports/rep100.pdf>
- https://ljk.imag.fr/membres/Anatoli.Iouditski/cours/convex/chapitre_3.pdf
- Nice Blog on Lipschitz Continuity:
<https://xingyuzhou.org/blog/notes/Lipschitz-gradient>. The author has a similar blog on Strong Convexity:
<http://xingyuzhou.org/blog/notes/strong-convexity>
- Papers attempting to compute the local Lipschitz constant of various deep networks
 - ▶ <https://arxiv.org/abs/2002.03657>
 - ▶ <https://papers.nips.cc/paper/2020/hash/5227fa9a19dce7ba113f50a405dcaf09-Abstract.html>



Lipschitz Continuity

- A function f is Lipschitz continuous with Lipschitz constant L if

$$|f(x) - f(y)| \leq L\|x - y\|$$



Lipschitz Continuity

- A function f is Lipschitz continuous with Lipschitz constant L if

$$|f(x) - f(y)| \leq L\|x - y\|$$

That is, the function is not changing too soon/fast

Rate of change $\approx \frac{|f(x) - f(y)|}{\|x - y\|} \leq L$

That is, a linearly scaled upper bound on the absolute value of the difference of function values at those points



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- Basically Lipschitz continuity limits how fast a function changes.



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(need not be necessarily differentiable)

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$$y = x + hv$$

IF f is differentiable

$$\left| \lim_{h \rightarrow 0} \frac{f(x+hv) - f(x)}{h} \right| = |D_v f(x)| \leq L$$



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- Lipschitz continuity implies that any $x \in \text{dom}(f)$ the (sub)gradient $h \in \partial f(x)$ satisfies $\|h\| \leq L$.



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IF f is differentiable $\|\nabla^T f(x)v\| = \left\| \lim_{h \rightarrow 0} \frac{f(x+hv) - f(x)}{h} \right\| = \|\nabla f(x)\| \leq L$



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- Calculus of Lipschitz continuity (some properties):

If f_1 is L_1 Lipschitz & f_2 is L_2 Lipschitz

Then $f_1 + f_2$ is $L_1 + L_2$ Lipschitz

$$\left. \begin{array}{l} \Delta^L \text{ Ineq} \\ \|a - b\| \leq \\ \|a - c\| \\ + \|c - b\| \end{array} \right\}$$



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 - ▶ If f_1 is L_1 -Lipschitz continuous and f_2 is L_2 -Lipschitz continuous, then $f_1 + f_2$ is $L_1 + L_2$ Lipschitz continuous



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Product of bounded L_1 & L_2 Lipschitzcts fns (Homework)
 $|f(x)g(x) - f(y)g(y)| \leq \text{Bnd}|f(x) - f(y)|(g(x) - g(y))$

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 - ▶ If f_1 is L_1 -Lipschitz continuous and f_2 is L_2 -Lipschitz continuous, then $f_1 + f_2$ is $L_1 + L_2$ Lipschitz continuous
 - ▶ Product of two Lipschitz continuous and bounded functions is also Lipschitz continuous.



(Lipschitz) Smooth Functions

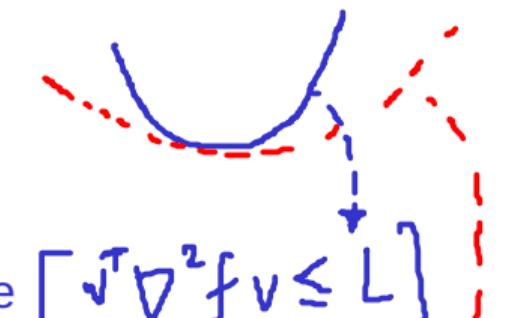
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(Lipschitz) Smooth Functions

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$$\|\nabla f(x) - \nabla f(y)\| \leq L\|x-y\|$$



Roughly - the function has an upper bounded curvature

$$[\sqrt{\nabla^2 f} v \leq L]$$

Recall: Strong convexity is about lower bounded function curvature
(that is, the function cannot be too flat)

$$[L \leq \sqrt{\nabla^2 f} v]$$



(Lipschitz) Smooth Functions

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- Gradient of f being Lipschitz continuous implies

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- This also implies that the Hessian satisfies

$$\nabla^2 f(\mathbf{x}) \preceq LI$$



(Lipschitz) Smooth Functions

Q: Example of function that is both strongly convex and Lipschitz smooth is x^2

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$$\nabla^2 f(\mathbf{x}) \preceq L\mathbf{I}$$

$$\nabla^2 f(\mathbf{x}) \succeq m\mathbf{I}$$

Strong convexity

Quadratic upper bound

?????????????????????

Strong convexity
Quadratic lower bound

$$f(\mathbf{y}) \geq f(\mathbf{x}) + \nabla f(\mathbf{x})(\mathbf{y} - \mathbf{x}) + \frac{m}{2} \|\mathbf{y} - \mathbf{x}\|^2$$

$m \leq L$?



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- Lemma: If a convex function f is smooth (i.e., has Lipschitz continuous gradients) then:

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Strong convexity $\nabla^2 f(\mathbf{x}) \succeq m\mathbb{I}$

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Quadratic upper bound

$$f(\mathbf{y}) \leq f(\mathbf{x}) + \nabla^T f(\mathbf{x})(\mathbf{y} - \mathbf{x}) + \frac{L}{2}\|\mathbf{y} - \mathbf{x}\|^2$$

Strong convexity
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Examples of Smooth Functions

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- Consider $f(x) = x^2$. Note that $\nabla f(x) = 2x$.

$$\nabla^2 f(x) = 2$$

$$1 \leq 2 \leq 3$$

m L

For strong
convexity

For Lipschitz
smoothness



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- Consider $f(x) = x^2$. Note that $\nabla f(x) = 2x$.
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- Is $f(x) = x^4$ Lipschitz smooth? What about $f(x) = x^3/3$? Let us study the latter.
 $\nabla f(x) = x^2$. For, Lipschitz continuity of $\nabla f(x)$, we ask the question: '*Does there exist an L such that $|x^2 - y^2| \leq L|x - y|$?*'



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Ans: Will require constraining the domain

$$|x-y| |x+y| = |x^2 - y^2| \stackrel{?}{\leq} L|x-y|$$

Ans: For any $|x| \leq \alpha$
 $|x+y| \leq 2\alpha = L$



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- Message: Only functions of asymptotically at most quadratic growth can be smooth globally.



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Q: What about this function? Study as homework



Better understanding of Lipschitz continuity and smoothness

- **Consider:** $f'(x) = |x|$

Better understanding of Lipschitz continuity and smoothness

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$$|f(x) - f(y)| \leq L|x-y|$$



Better understanding of Lipschitz continuity and smoothness

- **Consider:** $f'(x) = |x|$
- Since $|f'(x) - f'(y)| = ||x| - |y|| \leq |x - y|$,
 f' is Lipschitz continuous with $L = 1$
(that is f is smooth and f' is L -continuous)

HOWEVER, DOES $f''(x)$ EVEN EXIST EVERYWHERE? THOUGH IT IS DIFFERENTIABLE ALMOST EVERYWHERE!

NOW HOW ABOUT THE LIPSCHITZ CONTINUITY OF $f(x)$ ITSELF?



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Ex: $\|x\|_1$ is also differentiable almost everywhere



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- Is every sub-quadratic function Lipschitz smooth? Consider $f(x) = |x|^{3/2}$ on a closed set X s.t. $0 \in X$. Is this function smooth? Note that the gradient of $f'(x)$ is ∞ at $x = 0$.



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Not globally smooth

Not smooth if 0 is in X

But smooth in a bounded and closed interval
not containing 0

$$f(x) = \frac{3}{2}x^{1/2} \quad f'(x) = \frac{3}{4}x^{-1/2}$$
$$(x > 0)$$



Lipschitz Continuity on closed and bounded functions

$$f: \mathbb{R}^n \rightarrow \mathbb{R}$$

- If f is continuously differentiable almost everywhere, it is also Lipschitz continuous

¹Theorem 1.41 of <https://moodle.iitb.ac.in/mod/resource/view.php?id=33825>



Lipschitz Continuity on closed and bounded functions

- If f is continuously differentiable almost everywhere, it is also Lipschitz continuous
- For functions over a bounded subset of \mathbb{R}^n : f is continuous \supseteq f is differentiable (almost everywhere) $= f$ is Lipschitz continuous¹ \supseteq f is continuously differentiable $= \nabla f$ is continuous \supseteq ∇f is differentiable (almost everywhere) $= f$ is smooth

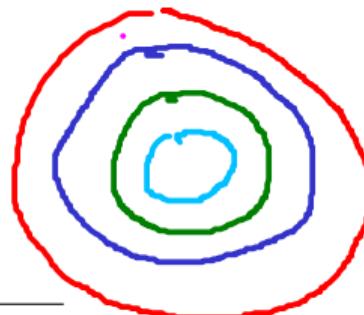
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$\exists \epsilon: \forall$



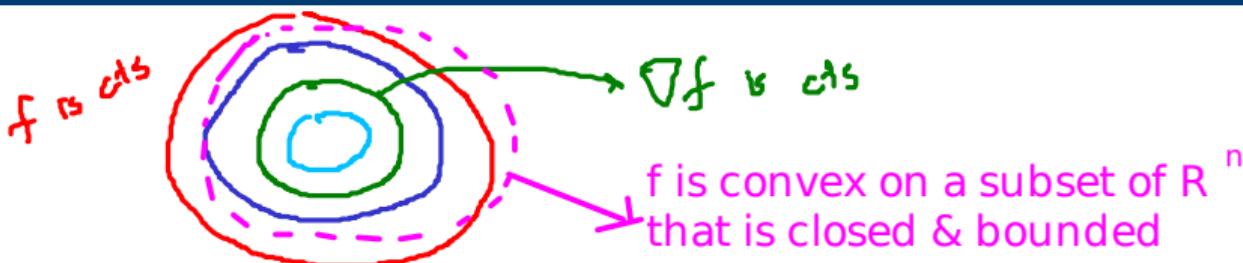
$$\epsilon_1 < \delta \Rightarrow |x - x'| < \delta \Rightarrow |f(x) - f(x')| \leq L|x - x'| = L\delta$$

$$|f(x) - f(x')| \leq L|x - x'|$$

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- Recall that a function is Lipschitz continuous if the norm of the (sub)gradient is bounded!

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- Recall that a function is Lipschitz continuous if the norm of the (sub)gradient is bounded!
- Also it holds that over a closed and bounded subset of \mathbb{R}^n that f is Lipschitz continuous \supseteq f is convex

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More on Strong Convexity, Lipschitz Continuity and Smoothness

- Recall that a function f is strongly convex if there exists a $\mu > 0$ such that $f(x) - \mu/2\|x\|^2$ is convex.



More on Strong Convexity, Lipschitz Continuity and Smoothness

- Recall that a function f is strongly convex if there exists a $\mu > 0$ such that $f(x) - \mu/2\|x\|^2$ is convex.

Recall how we could construct a strongly convex function by adding a regularizer to increase its curvature

Q: Can we construct Lipschitz smooth function from a given function which may not be Lipschitz smooth?
Ans?: Subtract a regularizer to decrease curvature?

$$-g(x) + \frac{L}{2} \|x\|_2^2 ?$$

Does this not require some assumption/property of g ?



More on Strong Convexity, Lipschitz Continuity and Smoothness

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- Is there a similar result for Lipschitz smooth functions?



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Ans: if g is convex we can do such a transformation
See how ubiquitous convexity is!



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- If a Function f is strongly convex and g is convex, the function $f + g$ is strongly convex.



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- In fact there is an interesting duality between the two (more on that later).
- If a Function f is strongly convex and g is convex, the function $f + g$ is strongly convex.
- If a function f_1 is Lipschitz smooth and f_2 is Lipschitz smooth, then $f_1 + f_2$ is also Lipschitz smooth



Properties of ML Loss Functions

- Logistic Loss: $L(\theta) = \sum_{i=1}^n \log(1 + \exp(-y_i \theta^T x_i))$: Lipschitz Smooth (Proof sketch?)



Properties of ML Loss Functions

Proof sketch: Using composition

$$\textcircled{1} \quad f_1(t) = \log(1 + e^t) \quad f_1'(t) = e^t / (1 + e^t) \quad f_1''(t) = \nabla^2 f(t) = \frac{e^t(1 + e^t) - e^t e^t}{(1 + e^t)^2} = \frac{e^t}{(1 + e^t)^2} \leq L \quad \{L = 1/2 \text{ or } 1/4\}$$

- Logistic Loss: $L(\theta) = \sum_{i=1}^n \log(1 + \exp(-y_i \theta^T x_i))$: Lipschitz Smooth (Proof sketch?)

Can be shown to be also Lipschitz Continuous

Using Quotient Rule

$$\frac{d}{dt} \left(\frac{a(t)}{b(t)} \right) = \frac{a'(t)b(t) - b'(t)a(t)}{(b(t))^2}$$

$$\textcircled{2} \quad f_2(\theta) = -y_i \theta^T x_i; \quad \text{The Hessian is indeed upper bounded by an } L = 0$$

$$\sum_i f_1(f_2(\theta))$$

In fact it is also convex



Properties of ML Loss Functions

- Logistic Loss: $L(\theta) = \sum_{i=1}^n \log(1 + \exp(-y_i \theta^T x_i))$: Lipschitz Smooth (Proof sketch?)
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Properties of ML Loss Functions

Consider simpler function $i) \max(0, 1-t) = f(t)$

Case 1: $t_1 < 1 \wedge t_2 \geq 1 \Leftrightarrow t_1 \geq 1 \wedge t_2 < 1 \rightarrow$ Can be done similarly

Case 2: $t_1 \leq 1 \wedge t_2 < 1$

Case 3: $t_1 \geq 1 \wedge t_2 \geq 1$

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Wont expects smoothness
(amounts to differentiability of its gradient almost everywhere)
Case for Hinge Loss and L1 regularization

Case 1: $|f(t_1) - f(t_2)| = |1 - t_1 - 0| = |1 - t_1| \leq |t_2 - t_1| \quad (L=1)$

Case 2: $|f(t_1) - f(t_2)| = |(1-t_1) - (1-t_2)| = |t_2 - t_1| \leq |t_2 - t_1| \quad (L=1)$

Case 3: $|f(t_1) - f(t_2)| = 0 \leq |t_2 - t_1| \quad (L \leq 1)$

Subsequently, we consider a composition of the function $f(\cdot)$ above with a linear function exactly as in the previous case



Properties of ML Loss Functions

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- Multi-class Logistic Regression: $L(\theta_1, \dots, \theta_k) = \sum_{i=1}^n -\theta_{y_i}^T x_i + \log(\sum_{c=1}^k \exp(\theta_c^T x_i))$: Lipschitz Smooth



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Proof Methodology: Generalization of the Logistic Loss case



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- Least Squares: $L(\theta) = \sum_{i=1}^n (\theta^T x_i - y_i)^2$: Lipschitz Smooth and Strongly Convex!



Properties of ML Loss Functions

The first three are also convex

- Logistic Loss: $L(\theta) = \sum_{i=1}^n \log(1 + \exp(-y_i \theta^T x_i))$: Lipschitz Smooth (Proof sketch?)
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$$f(t) = t^2$$

Recap this is both Lipschitz Smooth and Strongly Convex

In a bounded domain, we also expect Least Squares to be Lipschitz continuous



Properties of ML Loss Functions

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- L2 Regularization: Lipschitz Smooth and Strongly Convex!



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- Least Squares: $L(\theta) = \sum_{i=1}^n (\theta^T x_i - y_i)^2$: Lipschitz Smooth and Strongly Convex!
- L2 Regularization: Lipschitz Smooth and Strongly Convex! *same reasoning*

$$\|x\|_2^2 = f(\|x\|_2)$$

where $f(t) = t^2$



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- L2 Regularization: Lipschitz Smooth and Strongly Convex!
- L1 Regularization: Lipschitz Continuous



Properties of ML Loss Functions

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- Least Squares: $L(\theta) = \sum_{i=1}^n (\theta^T x_i - y_i)^2$: Lipschitz Smooth and Strongly Convex!
- L2 Regularization: Lipschitz Smooth and Strongly Convex!
- L1 Regularization: Lipschitz Continuous

Recap: We showed that $|x|_1$ is Lipschitz continuous



Properties of ML Loss Functions **with Regularizers**

- **L1 Regularized** Logistic Loss: Lipschitz Continuous and Convex



Properties of ML Loss Functions with Regularizers

Recap: Sum of Lipschitz continuous functions is Lipschitz continuous

Recap: Sum of convex functions is convex

- L1 Regularized Logistic Loss: Lipschitz Continuous and Convex



Properties of ML Loss Functions **with Regularizers**

- L1 Regularized Logistic Loss: Lipschitz Continuous and Convex
- L2 Regularized Logistic Loss: Lipschitz Smooth and Strongly Convex!



Properties of ML Loss Functions **with Regularizers**

- L1 Regularized Logistic Loss: Lipschitz Continuous and Convex
- L2 Regularized Logistic Loss: Lipschitz Smooth and Strongly Convex!
- L1 Regularized Hinge Loss: Lipschitz Continuous and Convex



Properties of ML Loss Functions **with Regularizers**

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- L2 Regularized Logistic Loss: Lipschitz Smooth and Strongly Convex!
- L1 Regularized Hinge Loss: Lipschitz Continuous and Convex
- L2 Regularized Hinge Loss: Lipschitz Continuous and Strongly Convex (On a Bounded set)



Properties of ML Loss Functions **with Regularizers**

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- L2 Regularized Least Squares (Lasso): Lipschitz Smooth and Strongly Convex!



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- L1 Regularized Least Squares: Lipschitz Continuous and Strongly Convex (On a bounded set)

