

Assignment #1

① coordinates frames 1 to 6 are in from 0

$${}^0R_1 = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$${}^0R_2 = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1/\sqrt{2} & 1/\sqrt{2} \\ 0 & -1/\sqrt{2} & 1/\sqrt{2} \end{pmatrix}$$

$${}^0R_3 = \begin{pmatrix} 0 & -1/\sqrt{2} & 1/\sqrt{2} \\ 0 & 1/\sqrt{2} & 1/\sqrt{2} \\ -1 & 0 & 0 \end{pmatrix}$$

$${}^0R_4 = \begin{pmatrix} 0 & -1 & 0 \\ 0 & 0 & 1 \\ -1 & 0 & 0 \end{pmatrix}$$

$${}^0R_5 = \begin{pmatrix} 0 & -1 & 0 \\ -1/\sqrt{2} & 0 & 1/\sqrt{2} \\ -1/\sqrt{2} & 0 & -1/\sqrt{2} \end{pmatrix}$$

$${}^0R_6 = \begin{pmatrix} 1/2 & -1/\sqrt{2} & -1/\sqrt{2} \\ -1/2 & -1/\sqrt{2} & 1/\sqrt{2} \\ -1/\sqrt{2} & 0 & -1/\sqrt{2} \end{pmatrix}$$

$${}^1R_2 = {}^1R_1 {}^1R_2$$

$$= {}^0R_1 {}^1R_2$$

$$= \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$${}^2R_3 = {}^2R_2 {}^2R_3 = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1/\sqrt{2} & -1/\sqrt{2} \\ 0 & 1/\sqrt{2} & 1/\sqrt{2} \end{pmatrix}$$

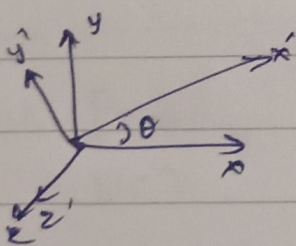
$${}^2R_3 = {}^0R_2 {}^2R_3 = \begin{pmatrix} 0 & -1/\sqrt{2} & 1/\sqrt{2} \\ 1/\sqrt{2} & 1/2 & 1/2 \\ -1/\sqrt{2} & 1/2 & 1/2 \end{pmatrix}$$

$${}^3R_4 = {}^3R_3 {}^3R_4 = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 1/\sqrt{2} & 1/\sqrt{2} \\ 0 & -1/\sqrt{2} & 1/\sqrt{2} \end{pmatrix}$$

$${}^3R_5 = {}^3R_4 {}^3R_5 = \begin{pmatrix} 1/\sqrt{2} & 0 & 1/\sqrt{2} \\ 0 & 1 & 0 \\ -1/\sqrt{2} & 0 & 1/\sqrt{2} \end{pmatrix}$$

$${}^5R_6 = {}^5R_5 {}^5R_6 = \frac{1}{2} \begin{pmatrix} 1+\sqrt{2} & 1 & \sqrt{2}-1 \\ -1 & \sqrt{2} & 1 \\ \sqrt{2}-1 & -1 & 1+\sqrt{2} \end{pmatrix}$$

②



$$x' = x \cos \theta + y \sin \theta$$

$$y' = -x \sin \theta + y \cos \theta$$

$$z' = z$$

$$R_2(\theta) = \begin{pmatrix} \cos \theta & -\sin \theta & 0 \\ \sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

b)

$$y' = \cos \theta y + \sin \theta z$$

$$z' = -\sin \theta y + \cos \theta z$$

$$x' = x$$

$$R_{21}(\theta) = \begin{pmatrix} 1 & 0 & 0 \\ 0 & \cos \theta & -\sin \theta \\ 0 & \sin \theta & \cos \theta \end{pmatrix}$$

$$z' = \cos\theta z + \sin\theta x$$

$$x' = -\sin\theta z + \cos\theta x$$

$$y' = y$$

$$R_z(\theta) = \begin{pmatrix} \cos\theta & 0 & \sin\theta \\ 0 & 1 & 0 \\ -\sin\theta & 0 & \cos\theta \end{pmatrix}$$

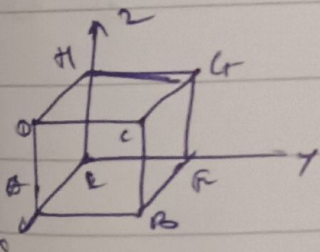
$$2) \quad R_B = R_z(-45^\circ) = \begin{pmatrix} 1 & 0 & 0 \\ 0 & \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ 0 & -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{pmatrix}$$

$$5) \quad R_y(90^\circ) R_B = \begin{pmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ -1 & 0 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ 0 & -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{pmatrix} = \begin{pmatrix} 0 & -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ 0 & \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ -1 & 0 & 0 \end{pmatrix}$$

$$IV) \quad R_x(-45^\circ) R_B = \begin{pmatrix} 1 & 0 & 0 \\ 0 & \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ 0 & -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{pmatrix} \begin{pmatrix} 0 & -1 & 0 \\ 0 & 0 & 1 \\ -1 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 0 & -1 & 0 \\ -\frac{1}{\sqrt{2}} & 0 & \frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} & 0 & -\frac{1}{\sqrt{2}} \end{pmatrix}$$

$$II) \quad R_z(45^\circ) R_B = \begin{pmatrix} \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} & 0 \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 0 & -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ 0 & \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ -1 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 0 & -1 & 0 \\ 0 & 0 & 1 \\ -1 & 0 & 0 \end{pmatrix}$$

$$VI) \quad R_y(45^\circ) R_B = \begin{pmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} & 0 \\ \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 0 & -1 & 0 \\ -\frac{1}{\sqrt{2}} & 0 & \frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} & 0 & -\frac{1}{\sqrt{2}} \end{pmatrix} = \begin{pmatrix} \frac{1}{2} & -\frac{1}{\sqrt{2}} & \frac{1}{2} \\ -\frac{1}{2} & -\frac{1}{\sqrt{2}} & \frac{1}{2} \\ -\frac{1}{\sqrt{2}} & 0 & -\frac{1}{\sqrt{2}} \end{pmatrix}$$



final axes:—

$$\hat{EP} = -\cos 45^\circ \hat{i} + \sin 45^\circ \hat{j} = \frac{1}{\sqrt{2}} (-\hat{i} + \hat{j})$$

$$\hat{EH} = \frac{1}{\sqrt{2}} (-\hat{i} - \hat{j})$$

$$\hat{EA} = \hat{k}$$

initial axes:—

$$\hat{EA} = \hat{i}, \quad \hat{EP} = \hat{j}, \quad \hat{EH} = \hat{k}$$

$$R = \begin{pmatrix} 0 & -\frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \\ 0 & \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \\ 1 & 0 & 0 \end{pmatrix}$$

$$a) \quad R, \text{ then Translated by } [1, 1, 1]^T \quad T = \begin{pmatrix} R & \begin{matrix} 1 \\ 1 \\ 1 \end{matrix} \\ 0 & 1 \end{pmatrix}$$

$$T = \begin{pmatrix} \frac{1}{2} & -\frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} & 1 \\ -\frac{1}{2} & -\frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} & 1 \\ -\frac{1}{\sqrt{2}} & 0 & -\frac{1}{\sqrt{2}} & 1 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

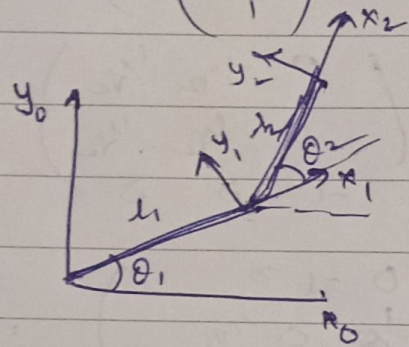
b) Translatⁿ by $[1\ 1\ 1]^T$ then R

$$R_v = \begin{pmatrix} \frac{1}{2} & -\frac{1}{\sqrt{2}} & -\frac{1}{2} \\ -\frac{1}{2} & -\frac{1}{\sqrt{2}} & \frac{1}{2} \\ -\frac{1}{\sqrt{2}} & 0 & -\frac{1}{\sqrt{2}} \end{pmatrix} \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} = \begin{pmatrix} -\frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} \end{pmatrix} = \begin{matrix} A_P \\ A_B \end{matrix}$$

$$T = \begin{pmatrix} \frac{1}{2} & \frac{1}{\sqrt{2}} & -\frac{1}{2} & 1 & \frac{1}{\sqrt{2}} \\ \frac{1}{2} & \frac{1}{\sqrt{2}} & \frac{1}{2} & 1 & \frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} & 0 & \frac{1}{\sqrt{2}} & 1 & \frac{1}{\sqrt{2}} \\ 0 & 0 & 0 & 1 & 1 \end{pmatrix}$$

$$R_{PQ} \begin{pmatrix} A_P \\ -1 \\ 1 \end{pmatrix} = T \begin{pmatrix} 2 \\ 1 \\ 0 \\ 1 \end{pmatrix} = A_P = \begin{pmatrix} 2 - \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} + 1 \end{pmatrix}$$

5) a)



$${}^0_1T = \begin{pmatrix} {}^0R_1 & {}^0P_{OB} \\ 0 & 1 \end{pmatrix}$$

$${}^0_1R = R_z(\theta_1) = \begin{pmatrix} c\theta_1 & -s\theta_1 & 0 \\ s\theta_1 & c\theta_1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$${}^0_1T = \begin{pmatrix} c\theta_1 & -s\theta_1 & 0 & l_1 c\theta_1 \\ s\theta_1 & c\theta_1 & 0 & l_1 s\theta_1 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

$${}^1_2T = \begin{pmatrix} {}^1R_2 & {}^1P_{12} \\ 0 & 1 \end{pmatrix} ; {}^1_2R = R_z(\theta_2) = \begin{pmatrix} c\theta_2 & -s\theta_2 & 0 \\ s\theta_2 & c\theta_2 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$${}^1_2T = \begin{pmatrix} c\theta_2 & -s\theta_2 & 0 & l_2 c\theta_2 \\ s\theta_2 & c\theta_2 & 0 & l_2 s\theta_2 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

$$b) {}^0_2T = {}^0_1T {}^1_2T = \begin{pmatrix} {}^0R_1 & {}^0P_{O1} \\ 0 & 1 \end{pmatrix} \begin{pmatrix} {}^1R_2 & {}^1P_{12} \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} {}^0R_1 {}^1R_2 & {}^0R_1 {}^1P_{12} \\ 0 & 1 \end{pmatrix}$$

$${}^0_2R = R_z(\theta_1 + \theta_2) = \begin{pmatrix} c(\theta_1 + \theta_2) & -s(\theta_1 + \theta_2) & 0 \\ s(\theta_1 + \theta_2) & c(\theta_1 + \theta_2) & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$${}^0_1P_{12} + {}^0P_{01} = \begin{pmatrix} c\theta_1 & -s\theta_1 & 0 \\ s\theta_1 & c\theta_1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} d_2 c\theta_2 \\ d_2 s\theta_2 \\ 0 \end{pmatrix} + \begin{pmatrix} d_1 c\theta_1 \\ d_1 s\theta_1 \\ 0 \end{pmatrix}$$

$$= \begin{pmatrix} d_2 c(\theta_1+\theta_2) + d_1 c\theta_1 \\ d_2 s(\theta_1+\theta_2) + d_1 s\theta_1 \\ 0 \end{pmatrix}$$

$${}^2T_0 = \begin{bmatrix} c(\theta_1+\theta_2) & -s(\theta_1+\theta_2) & 0 & d_2 c(\theta_1+\theta_2) + d_1 c\theta_1 \\ s(\theta_1+\theta_2) & c(\theta_1+\theta_2) & 0 & d_2 s(\theta_1+\theta_2) + d_1 s\theta_1 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

II)

$${}^0T_1 = \begin{pmatrix} {}^0R_1 & {}^0P_{01} \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & d \\ 0 & -1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

$${}^1T_2 = \begin{pmatrix} {}^1R_2 & {}^1P_{12} \\ 0 & 1 \end{pmatrix} = \begin{bmatrix} s\theta & c\theta & 0 & 0 \\ 0 & 0 & -1 & 0 \\ -c\theta & s\theta & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$${}^2T_3 = \begin{pmatrix} {}^2R_3 & {}^2P_{23} \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} 0 & -1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

$$b) {}^0T_3 = {}^0T_1 {}^1T_2 {}^2T_3$$

$$= \begin{pmatrix} {}^0R_3 & {}^0P_{03} \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} c\theta & -s\theta & 0 & d + c\theta d \\ s\theta & c\theta & 0 & d + s\theta d \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

$${}^0P_{03} = d \hat{y}_0 + d \hat{x}_0 + L [\cos\theta \hat{x}_0 + \sin\theta \hat{y}_0]$$

$$= (1 + L \cos\theta) \hat{x}_0 + (d + L \sin\theta) \hat{y}_0$$

$$c) \quad \vec{w}_{PE} = (-25, 100, 13)^T$$

$$\vec{O} \times \vec{E} = (-12, 9, 0)^T = \vec{w}_{RE} = \left(-\frac{4}{5}, \frac{3}{5}, 0\right)^T$$

$$\vec{O} \times \vec{E} = (9, 12, 20)^T = \vec{w}_{YE} = \left(\frac{9}{25}, \frac{12}{25}, \frac{20}{25}\right)^T$$

$$\vec{O} \times \vec{E} = (24, 32, -30)^T = \vec{w}_{ZE} = \left(\frac{12}{25}, \frac{16}{25}, -\frac{3}{5}\right)^T$$

$$\vec{w}_E = \begin{pmatrix} -4/5 & 9/25 & 12/25 \\ 3/5 & 12/25 & 16/25 \\ 0 & 9/5 & -3/5 \end{pmatrix}$$

$$\vec{w}_E^T = \left(\begin{array}{c|c} \vec{w}_E & \vec{w}_{PE} \\ \hline 0 & 1 \end{array} \right) = \left(\begin{array}{c|c} - & - \\ \hline 0 & 1 \end{array} \right)$$

$$\vec{B}_E^T = \begin{pmatrix} -4/5 & 9/25 & 12/25 & 68 \\ 3/5 & 12/25 & 16/25 & 174 \\ 0 & -4/5 & -3/5 & -60 \\ 0 & 0 & 0 & 1 \end{pmatrix} = \left(\begin{array}{c|c} \vec{B}_E & \vec{B}_{PE} \\ \hline 0 & 1 \end{array} \right)$$

$$\vec{w}_B^T = \left(\begin{array}{c|c} \vec{w}_E^T & \vec{B}_E^T \\ \hline \vec{E}^T & \vec{B}^T \end{array} \right) = \left(\begin{array}{cccc} 1 & 0 & 0 & 143 \\ 0 & 1 & 0 & 274 \\ 0 & 0 & 1 & -5 \\ 0 & 0 & 0 & 1 \end{array} \right)$$

$$a) \quad \vec{F}_1 \rightarrow \vec{OP} = (1, -1, 1)^T$$

$$\vec{F}_2 \rightarrow \vec{SP} = (-1, 0, 0)^T$$

$$\vec{F}_1 \rightarrow \vec{SP} = \vec{F}_1 \vec{OP} + \frac{1}{2} \vec{F}_2 \vec{SP}$$

$$= \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix} + \frac{1}{2} \begin{pmatrix} 1 & 1-\sqrt{3} & 1+\sqrt{3} \\ 1+\sqrt{3} & 1 & 1-\sqrt{3} \\ 1-\sqrt{3} & 1+\sqrt{3} & 1 \end{pmatrix} \begin{pmatrix} 1 \\ \sqrt{3} \\ 2+1 \end{pmatrix}$$

$$= \begin{pmatrix} 2/3 \\ -4/3 - \frac{1}{\sqrt{3}} \\ \frac{2}{3} + \frac{1}{\sqrt{3}} \end{pmatrix}$$

$$b) \quad \vec{F}_1 [x + y + z] = 1$$

$$\begin{bmatrix} 2 & 1 & 1 \\ 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$\begin{bmatrix} 2 & 1 & 1 \\ 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$${}^2P_1 = \frac{1}{3} \begin{bmatrix} 1 & 1+\sqrt{3} & 1-\sqrt{3} \\ 1-\sqrt{3} & 1 & 1+\sqrt{3} \\ 1+\sqrt{3} & 1-\sqrt{3} & 1 \end{bmatrix}$$

$${}^1P_{12} = \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix}; \quad {}^2P_{21} = -\frac{1}{3} {}^1P_{12}$$

$$= \frac{1}{3} \begin{bmatrix} 1 & 1+\sqrt{3} & 1-\sqrt{3} \\ 1-\sqrt{3} & 1 & 1+\sqrt{3} \\ 1+\sqrt{3} & 1-\sqrt{3} & 1 \end{bmatrix} \begin{bmatrix} -1 \\ 1 \\ -1 \end{bmatrix}$$

$$= \frac{1}{3} \begin{bmatrix} -1+2\sqrt{3} \\ -1 \\ -2\sqrt{3}-1 \end{bmatrix}$$

$$\begin{bmatrix} \frac{1}{3} \\ \frac{2}{3} \\ 1 \end{bmatrix} = \frac{1}{3} \begin{bmatrix} {}^2P_1 & {}^1P_{12} \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

$$= \frac{1}{3} \begin{bmatrix} 2+2\sqrt{3} \\ 2 \\ 2-2\sqrt{3} \end{bmatrix}$$

eqⁿ in F_2

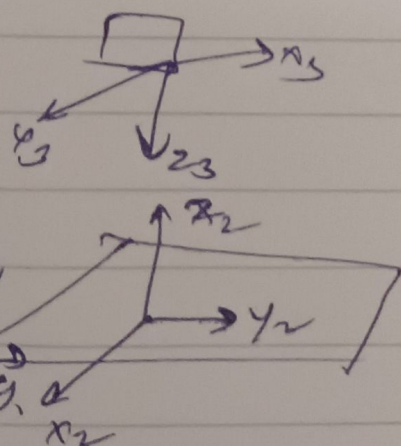
$${}^2[x \ y \ z]^T \cdot \frac{2}{3} \begin{bmatrix} 2+2\sqrt{3} \\ 2 \\ 2-2\sqrt{3} \end{bmatrix} = 1$$

$$\frac{2}{3} [(1+\sqrt{3})x + y + (1-\sqrt{3})z] = 1$$

$$\text{a) } {}^0T_1 = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

$$\text{b) } {}^0T_2 = \begin{pmatrix} 1 & 0 & 0 & -0.5 \\ 0 & 1 & 0 & 1.5 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

$$\text{c) } {}^0T_3 = \begin{pmatrix} 0 & 1 & 0 & -0.5 \\ 1 & 0 & 0 & 1.5 \\ 0 & 0 & 1 & 3 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$



$$\text{d) } R(45^\circ) \text{ } T \rightarrow [0.5, 0, 0]$$

$$T = \begin{bmatrix} 1 & 0 & 0 & 0.5 \\ 0 & \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} & 0 \\ 0 & \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$${}^0T_1 = {}^0T_2 {}^2T_1 = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} & 1.5 \\ 0 & \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} & 3 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$