Hopefully by now, we know about *Gradient Descent*

- Solving for weights/parameters
- That minimize a loss function
- By updating weights/parameters in the *negative* direction of the gradients with respect to the parameters/weights

In code, it looks like this

- from <u>Keras docs (https://colab.research.google.com/github/keras-team/keras-io/blob/master/guides/ipynb/customizing_what_happens_in_fit.ipynb#scrollTo=9z4</u>
- one step of Gradient Descent (inputs are a mini-batch of examples)

```
with tf.GradientTape() as tape:
    y_pred = self(x, training=True) # Forward pass
    # Compute the loss value
    # (the loss function is configured in `compile()`)
    loss = self.compiled_loss(y, y_pred, regularization_losses=self.losses)

# Compute gradients
trainable_vars = self.trainable_variables
gradients = tape.gradient(loss, trainable_vars)

# Update weights
self.optimizer.apply_gradients(zip(gradients, trainable_vars))
```

Key points

- Define a loss \mathcal{L}
 - the loss is dependent on the weights ("trainable variables") of the model
- Compute the loss within the scope of tf.GradientTape()
 - Enables TensorFlow to compute gradients of any variable accessed in the scope
 - Loss calculated via self.compiled_loss in this case
 - but any calculation that you would chose to define
- Obtain the gradients of the loss with respect to the trainable variables
- Updates the trainable variables
 - self.optimizer.apply_gradients(zip(gradients, trainable_vars)) in this case
 - General case weight += learning_rate * gradient
 - Subtract the gradient: we are descending (reducing loss)

Gradient Ascent is nearly identical

- Except that we update weights/parameters in the *positive* direction of the gradients
- So as to maximize a function ("utility")
 - we will continue, in code, to use "loss" for the function/variable name

```
In code, it looks like this:
with tf.GradientTape() as tape:
    tape.watch(vars)
    loss = compute_loss(vars)

# Compute gradients.
gradients = tape.gradient(loss, vars)

vars += learning_rate * gradients
```

- vars is a list of variables
- loss is dependent on vars
- we add the gradient: we are ascending (increasing loss: better to call it "utility")

Uses of Gradient Ascent

We will show some interesting things you can do using Gradient Ascent

Suppose

- \mathcal{L} defines some property of the model.
- vars are the model's inputs

Then Gradient Ascent solves for the values of an input that maximize the property

Property to maximize: value of a single "logit" of the Classifier head

Suppose our Neural Network $\mathbb C$ terminates in a Classifier head, over classes $\{c_1,\ldots c_k\}$.

The Classifier Head is a Dense layer with k units ("logits"), one per class.

Define the property to be maximized

• The value of logit corresponding to c_i

Gradient Ascent will find the input value to $\mathbb C$ that will be classified with highest probability as being from class c_i .

This is the "paradigmatic" input of class c_j .

Property to maximize: summary of values of one feature map

Recall that a feature map is

- a Tensor (with shape equal to the spatial dimensions)
- ullet corresponding to the value of a single feature at some layer l
 - over each spatial location

Since this feature is not a singleton, imagine we reduced it to a single value

• e.g., maximum value

Define the property to be maximized as the value of this summary of a single feature map. Gradient Ascent will find the input that "maximally activates" the feature map. • The pattern in the input that this feature map is responsible for identifying • May help us in understanding the role of each feature map

Visualizing what convnets learn, via Gradient Ascent

Let's illustrate Gradient Ascent to visualize what one feature map within a Convolutional Layer of an Image Classifier is "looking for"

<u>Visualizing what convnets learn (https://colab.research.google.com/github/kerasteam/keras-</u>

<u>io/blob/master/examples/vision/ipynb/visualizing what convnets learn.ipynb#)</u>

A blog post from a [previous version] of the code shows the patterns of multiple feature maps at multiple layers.

```
In [2]: print("Done")
```

Done