```
function [y] = utriangle(U,y,n)
for j=n:-1:2
    y(j)=y(j)/U(j,j);
    y(1:j-1)=y(1:j-1)-y(j)*U(1:j-1,j);
end
y(1)=y(1)/U(1,1);
end
function [v,b] = house(x)
n = length(x);
t = norm(x, "inf");
x = x./t;
c = x(2:n)'*x(2:n);
v=zeros(1,n);
v(2:n) = x(2:n);
if c == 0
    b=0;
else
    a = sqrt((x(1))^2 + c);
    if x(1) <= 0
        v(1)=x(1)-a;
    else
        v(1) = -c/(x(1)+a);
    end
    b=2*v(1)*v(1)/(c+(v(1))^2);
    v=v/v(1);
end
end
function [A,d] = QR(A)
[m,n]=size(A);
d=zeros(1,n);
for j=1:n
    if j<m</pre>
        v=zeros(1,m-j+1);
        b=0;
        [v,b]=house(A(j:m,j));
        v=v';
        A(j:m,j:n) = (eye(m-j+1)-b*v*v')*A(j:m,j:n);
        d(j)=b;
        A(j+1:m,j)=v(2:m-j+1);
    end
end
end
```

```
function [Q] = culculateQ(A)
[m,n]=size(A);
d=zeros(1,n);
Q=eye(m);
[A,d]=QR(A);
for k=1:n
    H1=zeros(m-k+1);
    v=zeros(1,m-k+1);
    v(1)=1;
    v(2:m-k+1)=A(k+1:m,k);
    v=v';
    H1 = eye(m-k+1) - d(k) *v*v';
    H=eye(m);
    H(k:m,k:m)=H1;
    Q=Q*H;
end
end
function [R] = culculateR(A)
[m,n]=size(A);
d=zeros(1,n);
[A,d]=QR(A);
R=zeros(n);
for j=1:n
    for i=1:j
        R(i,j)=A(i,j);
    end
end
end
a1=[4.9176 5.0208 4.5429 4.5573 5.0597 3.891 5.898 5.6039 15.4202
 14.4598 5.8282 5.3003 6.2712 5.9592...
    5.05 5.6039 8.2464 6.6969 7.7841 9.0384 5.9894 7.5422 8.7951
 6.0931 8.3607 8.14 9.1416 12];
a2=[ones(1,8) 2.5 2.5 ones(1,6) 1.5 1.5 1.5 1 1 1.5 1.5 1.5 1.5 1 1.5
 1.51;
a3=[3.472 3.531 2.275 4.05 4.455 4.455 5.85 9.52 9.8 12.8 6.435 4.9883
 5.52 6.666 5 9.52 5.15 6.092 7.102...
    7.8 5.52 4 9.89 6.7265 9.15 8 7.3262 5]';
a4=[0.998 1.5 1.175 1.232 1.121 0.988 1.24 1.501 3.42 3 1.225 1.552
 0.975 1.121 1.02 1.501 1.664 1.488...
    1.376 1.5 1.256 1.69 1.82 1.652 1.777 1.504 1.831 1.2]';
a5=[1 2 1 1 1 1 1 0 2 2 2 1 1 2 0 0 2 1.5 1 1.5 2 1 2 1 2 2 1.5 2]';
a6=[7 7 6 6 6 6 7 6 10 9 6 6 5 6 5 6 8 7 6 7 6 6 8 6 8 7 8 6]';
a7=[4 4 3 3 3 3 3 3 5 5 3 3 2 3 2 3 4 3 3 3 3 4 3 4 3 4 3]';
a8=[42 62 40 54 42 56 51 32 42 14 32 30 30 32 46 32 50 22 17 23 40 22
 50 44 48 3 31 30];
a9=[3 1 2 4 3 2 2 1 2 4 1 1 1 2 4 1 4 1 2 3 4 1 1 4 1 1 4 3]';
```

2

```
al0=[ones(1,11) 2 2 1 1 1 1 1 1 3 1 1 1 1 1 3 1 1]';
all=[0 0 0 0 0 0 1 0 1 1 0 0 0 0 1 0 1 0 0 1 0 1 0 1 0 1];
A=[ones(28,1) a1 a2 a3 a4 a5 a6 a7 a8 a9 a10 a11];
b=[25.9 29.5 27.9 25.9 29.9 29.9 30.9 28.9 84.9 82.9 35.9 31.5 31
 30.9...
    30 28.9 36.9 41.9 40.5 43.9 37.5 37.9 44.5 37.9 38.9 36.9 45.8
 41]';
[m,n]=size(A);
Q=culculateQ(A);
Q1=zeros(m,n);
Q1=Q(1:m,1:n);
c1=Q1'*b;
R=zeros(n);
R=culculateR(A);
x=utriangle(R,c1,n)
x =
    2.0775
    0.7189
    9.6802
    0.1535
   13.6796
    1.9868
   -0.9582
   -0.4840
   -0.0736
    1.0187
    1.4435
    2.9028
```

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