

Review

- •偏导数的定义与几何意义
- ●n元函数可微的定义与判别

 $f 则 x_0$ 可微 \Leftrightarrow 3常数 $a_1, a_2, \dots, a_n \in \mathbb{R}, s.t.$

$$\lim_{x \to x_0} \frac{f(x) - f(x_0) - a_1 \Delta x_1 - a_2 \Delta x_2 - \dots - a_n \Delta x_n}{\|x - x_0\|} = 0.$$

•梯度 $grad f(x_0)$ 的定义与意义





•方向导数的定义与几何意义

$$g(t) = f(x_0 + \frac{v}{\|v\|}t) = f(x_0^{(1)} + \frac{v_1}{\|v\|}t, \dots, x_0^{(n)} + \frac{v_n}{\|v\|}t)$$

$$\frac{\partial f(x_0)}{\partial v} = \lim_{t \to 0^+} \frac{g(t) - g(0)}{t} = g'_+(0)$$

$$\frac{\partial f(x_0)}{\partial v} = \operatorname{grad} f(x_0) \cdot \frac{v}{\|v\|}$$



- 多元函数连续、可微、偏导数存在、 偏导函数连续之间的关系
- • f''_{xy} , f''_{yx} 都在 (x_0, y_0) 连续 $\Rightarrow f''_{xy}(x_0, y_0) = f''_{yx}(x_0, y_0)$
- • f''_{xy} , f''_{yx} 也记为 $f''_{12} = f''_{21}$

S 5

§ 5. 向量值函数的微分

1. 线性映射

Def. 称向量值函数 $f: \mathbb{R}^n \to \mathbb{R}^m$ 为线性的, 若对任意 α, β $\in \mathbb{R}, x, y \in \mathbb{R}^n$, 都有 $f(\alpha x + \beta y) = \alpha f(x) + \beta f(y)$.

Thm. $\mathbb{R}^n \to \mathbb{R}^m$ 的线性映射与 M_{mn} 中矩阵——对应.

Proof. 1) 若存在 $A \in M_{mn}$, s.t. f(x) = Ax, 则 方线性映射.

2)设 $f: \mathbb{R}^n \to \mathbb{R}^m$ 为线性映射. 记 e_1, e_2, \dots, e_n 为 \mathbb{R}^n 中自然基, 则 $f(e_i) \in \mathbb{R}^m$, $i = 1, 2, \dots n$.令A = $(f(e_1), f(e_2), \dots, f(e_n))$, 则A $\in M_{mn}$.对任意 $x = (x_1, x_2, \dots, x_n)^T \in \mathbb{R}^n$,有

$$f(x) = f(x_1e_1 + x_2e_2 + \dots + x_ne_n)$$

$$= x_1f(e_1) + x_2f(e_2) + \dots + x_nf(e_n)$$

$$= (f(e_1), f(e_2), \dots, f(e_n))(x_1, x_2, \dots, x_n)^{\mathrm{T}} = Ax.\square$$

Thm. $A \in M_{mn}$,则存在 $C \ge 0$, s.t.

$$\|\mathbf{A}x\|_{m} \leq \mathbf{C} \|x\|_{n}, \forall x \in \mathbb{R}^{n}.$$

使得此不等式成立的最小的C记为||A||.

Proof.
$$y = \|Ax\|_m$$
 连续, $C = \max\{\|Ax\|_m : x \in \mathbb{R}^n, \|x\|_n = 1\}$ 存在,

$$\|\mathbf{A}x\|_{m} = \|\mathbf{A}\left(\|x\|_{n} \frac{x}{\|x\|_{n}}\right)\|_{m} = \|\mathbf{A}\frac{x}{\|x\|_{n}}\|_{m} \|x\|_{n} \le \mathbf{C}\|x\|_{n}, \forall x \in \mathbb{R}^{n}.\square$$



2.向量值函数的微分

Def. 设
$$f: \Omega(\subset \mathbb{R}^n) \to \mathbb{R}^m, x_0 \in \Omega.$$
 若存在 $m \times n$ 矩阵A, s.t.
$$\Delta f(x_0) = f(x_0 + \Delta x) - f(x_0) = A\Delta x + \alpha,$$

其中,
$$\alpha = \alpha(\Delta x) = (\alpha_1(\Delta x), \dots, \alpha_m(\Delta x))^T$$
,且当 $\Delta x \to 0$ 时,

$$\alpha = o(\Delta x), \exists \beta \qquad \lim_{\Delta x \to 0} \frac{\|\alpha\|_m}{\|\Delta x\|_m} = 0,$$

则称f在点 x_0 可微,称 $A\Delta x$ 为f在点 x_0 的微分,记为

$$df(x_0) = A\Delta x = Adx,$$

称A为f在 x_0 的Jacobi矩阵,记作A= $J(f)|_{x_0}=J_f(x_0)$.



Thm. $f = (f_1, f_2, \dots, f_m)^{\mathrm{T}} : \Omega(\subset \mathbb{R}^n) \to \mathbb{R}^m \times x_0$ 可微 $\Leftrightarrow n$ 元函数 $f_i : \Omega(\subset \mathbb{R}^n) \to \mathbb{R} \times x_0$ 可微, $i = 1, 2, \dots, m$.

Proof.(必要性) 设f在点x₀可微,则

$$\Delta f(x_0) = f(x_0 + \Delta x) - f(x_0) = A\Delta x + \alpha, \lim_{\Delta x \to 0} \frac{\|\alpha\|_m}{\|\Delta x\|_n} = 0,$$

比较第i个分量 $(1 \le i \le m)$,得

$$f_i(x_0 + \Delta x) - f_i(x_0) = \sum_{j=1}^n a_{ij} \Delta x_j + \alpha_i(\Delta x), \lim_{\Delta x \to 0} \frac{\alpha_i(\Delta x)}{\|\Delta x\|_n} = 0,$$

即 f_i 在 x_0 可微, $i=1,2,\cdots,m$.

(充分性) 设 f_i 在 x_0 可微, $i=1,2,\dots,m$,则

$$\begin{pmatrix} \Delta f_1(x_0) \\ \Delta f_2(x_0) \\ \vdots \\ \Delta f_m(x_0) \end{pmatrix} = \begin{pmatrix} \frac{\partial f_1}{\partial x_1} & \frac{\partial f_1}{\partial x_2} & \cdots & \frac{\partial f_1}{\partial x_n} \\ \frac{\partial f_2}{\partial x_1} & \frac{\partial f_2}{\partial x_2} & \cdots & \frac{\partial f_2}{\partial x_n} \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ \frac{\partial f_m}{\partial x_1} & \frac{\partial f_m}{\partial x_2} & \cdots & \frac{\partial f_m}{\partial x_n} \end{pmatrix}_{x_0} \begin{pmatrix} \Delta x_1 \\ \Delta x_2 \\ \vdots \\ \Delta x_n \end{pmatrix} + \begin{pmatrix} \alpha_1(\Delta x) \\ \alpha_2(\Delta x) \\ \vdots \\ \alpha_n(\Delta x) \end{pmatrix},$$

且 $\alpha_i(\Delta x) = o(\|\Delta x\|_n), \Delta x \to 0$ 时, $1 \le i \le m$. 故f 在 x_0 可微.

Remark: $f = (f_1, f_2, \dots, f_m)^{\mathrm{T}} : \Omega(\subset \mathbb{R}^n) \to \mathbb{R}^m$ 在 x_0 可微,

则f在x₀的Jacobi矩阵为

$$Jf(x_0) = \begin{pmatrix} \frac{\partial f_1}{\partial x_1} & \frac{\partial f_1}{\partial x_2} & \cdots & \frac{\partial f_1}{\partial x_n} \\ \frac{\partial f_2}{\partial x_1} & \frac{\partial f_2}{\partial x_2} & \cdots & \frac{\partial f_2}{\partial x_n} \\ \vdots & \vdots & \vdots & \vdots \\ \frac{\partial f_m}{\partial x_1} & \frac{\partial f_m}{\partial x_2} & \cdots & \frac{\partial f_m}{\partial x_n} \end{pmatrix}_{x_0} \triangleq \frac{\partial (f_1, f_2, \dots, f_m)}{\partial (x_1, x_2, \dots, x_n)} \Big|_{x_0}.$$

3.复合映射的微分

Thm.
$$u = g(x): \Omega \subset \mathbb{R}^n \to \mathbb{R}^m, y = f(u): g(\Omega) \subset \mathbb{R}^m \to \mathbb{R}^k,$$
 $x_0 \in \Omega, u_0 = g(x_0), \overline{a}g(x)$ 在 x_0 可微, $f(u)$ 在 u_0 可微, 则复合映

射 $y = (f \circ g)(x) = f(g(x))$ 在 x_0 可微, 且
$$J(f \circ g)|_{x_0} = J(f)|_{u_0} \cdot J(g)|_{x_0},$$
即 $\frac{\partial(y_1, y_2, \dots, y_k)}{\partial(x_1, x_2, \dots, x_n)}|_{x_0} = \frac{\partial(y_1, y_2, \dots, y_k)}{\partial(u_1, u_2, \dots, u_m)}|_{u_0} \cdot \frac{\partial(u_1, u_2, \dots, u_m)}{\partial(x_1, x_2, \dots, x_n)}|_{x_0}.$

Proof.
$$i \exists A = \frac{\partial (y_1, y_2, \dots, y_k)}{\partial (u_1, u_2, \dots, u_m)} \Big|_{u_0}$$
, $B = \frac{\partial (u_1, u_2, \dots, u_m)}{\partial (x_1, x_2, \dots, x_n)} \Big|_{x_0}$.

$$u = g(x)$$
在 x_0 可微, $y = f(u)$ 在 u_0 可微,则
$$\Delta u = g(x_0 + \Delta x) - g(x_0) = B\Delta x + o(\Delta x),$$

$$\Delta y = f(u_0 + \Delta u) - f(u_0) = A\Delta u + o(\Delta u),$$
于是
$$\Delta (f \circ g)(x_0) = f(g(x_0 + \Delta x)) - f(g(x_0))$$

$$= f(u_0 + \Delta u) - f(u_0) = A\Delta u + o(\Delta u)$$

$$= A(B\Delta x + o(\Delta x)) + o(\Delta u) = AB\Delta x + Ao(\Delta x) + o(\Delta u),$$
往证: $\Delta o(\Delta x) + o(\Delta u) = o(\Delta x)$

往证: $Ao(\Delta x) + o(\Delta u) = o(\Delta x)$.

$$\frac{\|Ao(\Delta x)\|}{\|\Delta x\|} \le \frac{\|A\|\|o(\Delta x)\|}{\|\Delta x\|} \to 0, \quad \exists \Delta x \to 0 \text{ B}.$$

$$\frac{\|\Delta u\|}{\|\Delta x\|} = \frac{\|B\Delta x + o(\Delta x)\|}{\|\Delta x\|} \le \frac{\|B\Delta x\|}{\|\Delta x\|} + \frac{\|o(\Delta x)\|}{\|\Delta x\|}$$

$$\le \|B\| + \frac{\|o(\Delta x)\|}{\|\Delta x\|} \to \|B\|, \quad \exists \Delta x \to 0 \text{ B}.$$

$$\frac{\|o(\Delta u)\|}{\|\Delta x\|} = \frac{\|o(\Delta u)\|}{\|\Delta u\|} \cdot \frac{\|\Delta u\|}{\|\Delta x\|} \to 0, \quad \exists \Delta x \to 0 \text{ B}.$$

$$\frac{\|Ao(\Delta x) + o(\Delta u)\|}{\|\Delta x\|} \le \frac{\|Ao(\Delta x)\|}{\|\Delta x\|} + \frac{\|o(\Delta u)\|}{\|\Delta x\|} \to 0, \quad \exists \Delta x \to 0 \text{ B}.$$



Remark. k = 1时, $y = f(u_1, u_2, \dots, u_m)$, $u_i = g_i(x_1, x_2, \dots, x_n)$, $1 \le i \le m$, 则 $y = y(x_1, x_2, \dots, x_n)$ 的偏导数满足链式法则 $\frac{\partial y}{\partial x_i} = \frac{\partial y}{\partial u_1} \frac{\partial u_1}{\partial x_i} + \frac{\partial y}{\partial u_2} \frac{\partial u_2}{\partial x_i} + \dots + \frac{\partial y}{\partial u_m} \frac{\partial u_m}{\partial x_i}$, $i = 1, 2, \dots, n$.

例. 球坐标变换 $\begin{cases} x = r \sin \varphi \cos \theta, \\ y = r \sin \varphi \sin \theta, \\ z = r \cos \varphi, \end{cases}$

是 $\Omega = \{(r, \varphi, \theta) | 0 \le r < \infty, 0 \le \varphi \le \pi, 0 \le \theta < 2\pi\}$ 到 \mathbb{R}^3 的连续可微映射.

$$\frac{\partial(x, y, z)}{\partial(r, \varphi, \theta)} = \begin{pmatrix} \sin\varphi\cos\theta & r\cos\varphi\cos\theta & -r\sin\varphi\sin\theta \\ \sin\varphi\sin\theta & r\cos\varphi\sin\theta & r\sin\varphi\cos\theta \\ \cos\varphi & -r\sin\varphi & 0 \end{pmatrix}$$

$$\frac{D(x, y, z)}{D(r, \varphi, \theta)} \triangleq \det \frac{\partial(x, y, z)}{\partial(r, \varphi, \theta)} = r^2 \sin \varphi. \square$$

$$y_1 = u_1 u_2 - u_1 u_3,$$

$$y_2 = u_1 u_3 - u_2^2,$$

$$\left. \frac{\partial \left(y_1, y_2 \right)}{\partial \left(x_1, x_2 \right)} \right|_{(1,0)}.$$

$$u_1 = x_1 \cos x_2 + (x_1 + x_2)^2$$

$$u_2 = x_1 \sin x_2 + x_1 x_2$$

$$u_3 = x_1^2 - x_1 x_2 + x_2^2$$

解:
$$(x_1, x_2) = (1,0)$$
时, $(u_1, u_2, u_3) = (2,0,1)$,

$$\frac{\partial \left(y_1, y_2\right)}{\partial (x_1, x_2)} \bigg|_{(1,0)} = \frac{\partial \left(y_1, y_2\right)}{\partial \left(u_1, u_2, u_3\right)} \bigg|_{(2,0,1)} \cdot \frac{\partial \left(u_1, u_2, u_3\right)}{\partial (x_1, x_2)}$$

$$\left. \cdot \frac{\partial \left(u_1, u_2, u_3 \right)}{\partial (x_1, x_2)} \right|_{(1,0)}$$



$$= \begin{pmatrix} u_2 - u_3 & u_1 & -u_1 \\ u_3 & -2u_2 & u_1 \end{pmatrix}_{(2,0,1)}$$

$$\begin{pmatrix}
\cos x_2 + 2(x_1 + x_2) & -x_1 \sin x_2 + 2(x_1 + x_2) \\
\sin x_2 + x_2 & x_1 \cos x_2 + x_1 \\
2x_1 - x_2 & -x_1 + 2x_2
\end{pmatrix}_{(1,0)}$$

$$= \begin{pmatrix} -1 & 2 & -2 \\ 1 & 0 & 2 \end{pmatrix} \times \begin{pmatrix} 3 & 2 \\ 0 & 2 \\ 2 & -1 \end{pmatrix} = \begin{pmatrix} -7 & 4 \\ 7 & 0 \end{pmatrix}. \square$$

例. $z = 2yf(\frac{x^2}{y},3y), f$ 二阶连续可微. 求 z''_{xy} .

解:f二阶连续可微,则 $z''_{xy}=z''_{yx}$.后者求解相对容易. 设 $u = x^2/y, v = 3y, z = 2yf(u, v)$.则 $z'_{x} = 2y \left\lceil f'_{u} \cdot (2x/y) + f'_{v} \cdot 0 \right\rceil = 4xf'_{u}$ $z''_{xy} = z''_{yx} = \frac{\partial}{\partial v} (4xf'_u) = 4x \left| f''_{uu} \cdot \frac{-x^2}{v^2} + f''_{vu} \cdot 3 \right|$ $= -\frac{4x^3}{v^2} f''_{uu} + 12x f''_{vu}.\Box$

例 u(x,y)二阶连续可微,且 $u''_{xx}-u''_{yy}=0.$ 令 $\xi=x-y$, $\eta=x+y$.试证: $u''_{\xi\eta}=0$.

$$\begin{aligned}
\mathbf{m} &: \ x = (\xi + \eta)/2, \ y = (\eta - \xi)/2, \\
u'_{\eta} &= u'_{x}x'_{\eta} + u'_{y}y'_{\eta} = (u'_{x} + u'_{y})/2 \\
u''_{\xi\eta} &= \frac{1}{2} \frac{\partial}{\partial \xi} \left(u'_{x} + u'_{y} \right) \\
&= \left(u''_{xx}x'_{\xi} + u''_{yx}y'_{\xi} + u''_{xy}x'_{\xi} + u''_{yy}y'_{\xi} \right)/2 \\
&= \left(u''_{xx} - u''_{yx} + u''_{xy} - u''_{yy} \right)/4 = \left(u''_{xx} - u''_{yy} \right)/4 = 0. \square
\end{aligned}$$



例 f(x, y)可微 $f(x, x^2) = 1$, $f'_x(x, x^2) = x$, 求 $f'_y(x, x^2)$, $(x \neq 0)$.

分析:
$$f'_{\mathcal{X}}(x,x^2) = \frac{\partial f}{\partial x}\Big|_{(x,y)=(x,x^2)}$$
.

解:将 $f(x,x^2)$ =1两边同时对x求导,有

$$f'_{x}(x, x^{2}) \cdot 1 + f'_{y}(x, x^{2}) \cdot 2x = 0,$$
$$x + 2xf'_{y}(x, x^{2}) = 0,$$

故
$$f'_y(x, x^2) = -\frac{1}{2}, \forall x \neq 0.$$

例.
$$y = (1/x)^{-(1/x)}$$
, 求 $y'(x)$.

解:
$$\Rightarrow u = 1/x, v = -1/x, y = u(x)^{v(x)}$$
.

$$\frac{dy}{dx} = \frac{\partial y}{\partial u} \cdot \frac{du}{dx} + \frac{\partial y}{\partial v} \cdot \frac{dv}{dx}$$

$$= vu^{v-1}(-1/x^2) + u^v(\ln u)(1/x^2)$$

$$=u^{\nu+2}(1+\ln u)$$

$$= (1/x)^{2-\frac{1}{x}} (1-\ln x).\Box$$



作业: 习题1.5 No. 4,5,7,9.

