

## 4.2.3

$$(1) \ x'(t) = 3, y'(t) = 6t, z'(t) = 6t^2$$

$$\begin{aligned} L &= \int_0^1 \sqrt{(x'(t))^2 + (y'(t))^2 + (z'(t))^2} dt \\ &= \int_0^1 \sqrt{9 + 36t^2 + 36t^4} dt \\ &= 5 \end{aligned}$$

$$(2) \ x'(t) = -e^{-t} \sin t - e^{-t} \cos t, \ y'(t) = e^{-t} \cos t - e^{-t} \sin t, \ z'(t) = -e^{-t}$$

$$\begin{aligned} L &= \int_0^{+\infty} \sqrt{(x'(t))^2 + (y'(t))^2 + (z'(t))^2} dt \\ &= \sqrt{3} \int_0^{+\infty} e^{-t} dt \\ &= \sqrt{3} \end{aligned}$$

注：求该类型的曲线积分线元需要对参数求导，即

$$ds = \sqrt{(x'(t))^2 + (y'(t))^2 + (z'(t))^2} dt$$

有同学没有求导，使用

$$ds = \sqrt{(x(t))^2 + (y(t))^2 + (z(t))^2} dt$$

进行计算，这是错误的。

## 4.2.4.

$$m = \int_{\sqrt{3}}^{\sqrt{15}} \rho(x) \sqrt{1 + (y'(x))^2} dx = \int_{\sqrt{3}}^{\sqrt{15}} x^2 \sqrt{1 + \frac{1}{x^2}} dx = \frac{56}{3}$$

4.2.5. 圆柱面被  $z = 0$  平面截得圆  $L$  的参数方程为

$$x = a \cos \theta, \ y = a \sin \theta, \ z = 0, \ 0 \leq \theta \leq 2\pi$$

截出圆柱面面积为

$$\begin{aligned}
S &= \oint_L \left( a + \frac{x^2}{a} - 0 \right) ds \\
&= \int_0^{2\pi} (a + a \cos^2 \theta) \sqrt{(-a \sin \theta)^2 + (a \cos \theta)^2} d\theta \\
&= 3\pi a^2
\end{aligned}$$

4.2.6. 摆线长度为

$$\begin{aligned}
L &= \int_0^\pi \sqrt{(x'(t))^2 + (y'(t))^2} dt \\
&= \int_0^\pi \sqrt{(a - a \cos t)^2 + (a \sin t)^2} dt \\
&= 2a \int_0^\pi \sin \frac{t}{2} dt \\
&= 4a
\end{aligned}$$

设质心坐标为  $(X_c, Y_c)$ , 记摆线为  $S$ , 则

$$\begin{aligned}
X_c &= \frac{1}{L} \int_S x(t) ds \\
&= \frac{1}{4a} \int_0^\pi a(t - \sin t) \sqrt{a^2(1 - \cos t)^2 + a^2 \sin^2 t} dt \\
&= \frac{a}{2} \int_0^\pi (t - \sin t) \sin \frac{t}{2} dt \\
&= \frac{4}{3}a \\
Y_c &= \frac{1}{L} \int_S y(t) ds \\
&= \frac{1}{4a} \int_0^\pi a(1 - \cos t) \sqrt{a^2(1 - \cos t)^2 + a^2 \sin^2 t} dt \\
&= \frac{a}{2} \int_0^\pi (1 - \cos t) \sin \frac{t}{2} dt \\
&= \frac{4}{3}a
\end{aligned}$$

所以质心坐标为  $(\frac{4}{3}a, \frac{4}{3}a)$

## 4.5.1

(1) 首先写出球面参数方程

$$x = 2R \cos \theta \sin \theta \cos \varphi, \quad y = 2R \cos \theta \sin \theta \sin \varphi, \quad z = 2R \cos^2 \theta$$

$$D_{\theta\varphi} = \{(\theta, \varphi) \mid 0 \leq \theta \leq \frac{\pi}{2}, 0 \leq \varphi \leq 2\pi\}$$

进行该坐标变换对应的 Jacobi 行列式为

$$C = \begin{vmatrix} \frac{\partial x}{\partial \theta} & \frac{\partial x}{\partial \varphi} \\ \frac{\partial y}{\partial \theta} & \frac{\partial y}{\partial \varphi} \end{vmatrix} = \begin{vmatrix} 2R \cos 2\theta \cos \varphi & -R \sin 2\theta \sin \varphi \\ 2R \cos 2\theta \sin \varphi & R \sin 2\theta \cos \varphi \end{vmatrix}$$

$$= 2R^2 \sin 2\theta \cos 2\theta$$

所求积分为

$$\begin{aligned} \iint_{S^+} dx \wedge dy &= + \iint_{D_{\theta\varphi}} C d\theta d\varphi \\ &= \int_0^{\frac{\pi}{2}} 2R^2 \sin 2\theta \cos 2\theta d\theta \int_0^{2\pi} d\varphi \\ &= 0 \end{aligned}$$

(2) 继续采用 (1) 中坐标变换

$$\begin{aligned} \iint_{S^+} z dx \wedge dy &= + \iint_{D_{\theta\varphi}} z(\theta, \varphi) C d\theta d\varphi \\ &= \int_0^{\frac{\pi}{2}} (2R \cos^2 \theta) 2R^2 \sin 2\theta \cos 2\theta d\theta \int_0^{2\pi} d\varphi \\ &= \frac{4}{3} \pi R^3 \end{aligned}$$

(3) 同理

$$\begin{aligned}
\oint_{S^+} z^2 dx \wedge dy &= + \iint_{D_{\theta\varphi}} z(\theta, \varphi)^2 C d\theta d\varphi \\
&= \int_0^{\frac{\pi}{2}} (2R \cos^2 \theta)^2 2R^2 \sin 2\theta \cos 2\theta d\theta \int_0^{2\pi} d\varphi \\
&= \frac{8}{3} \pi R^4
\end{aligned}$$

## 4.5.5

首先写出球面的参数方程

$$\begin{aligned}
x &= \sin \theta \cos \varphi, \quad y = \sin \theta \sin \varphi, \quad z = \cos \theta \\
D_{\theta\varphi} &= \{(\theta, \varphi) | 0 \leq \theta \leq \pi, 0 \leq \varphi \leq 2\pi\}
\end{aligned}$$

进行该坐标变换对应的 Jacobi 行列式为

$$\begin{aligned}
A &= \begin{vmatrix} \frac{\partial y}{\partial \theta} & \frac{\partial y}{\partial \varphi} \\ \frac{\partial z}{\partial \theta} & \frac{\partial z}{\partial \varphi} \end{vmatrix} = \begin{vmatrix} \cos \theta \sin \varphi & \sin \theta \cos \varphi \\ -\sin \theta & 0 \end{vmatrix} = \sin^2 \theta \cos \varphi \\
B &= \begin{vmatrix} \frac{\partial z}{\partial \theta} & \frac{\partial z}{\partial \varphi} \\ \frac{\partial x}{\partial \theta} & \frac{\partial x}{\partial \varphi} \end{vmatrix} = \begin{vmatrix} -\sin \theta & 0 \\ \cos \theta \cos \varphi & -\sin \theta \sin \varphi \end{vmatrix} = \sin^2 \theta \sin \varphi \\
C &= \begin{vmatrix} \frac{\partial x}{\partial \theta} & \frac{\partial x}{\partial \varphi} \\ \frac{\partial y}{\partial \theta} & \frac{\partial y}{\partial \varphi} \end{vmatrix} = \begin{vmatrix} \cos \theta \cos \varphi & -\sin \theta \sin \varphi \\ \cos \theta \sin \varphi & \sin \theta \cos \varphi \end{vmatrix} = \sin \theta \cos \theta
\end{aligned}$$

流量为

$$\begin{aligned}
Q &= \iint_S \mathbf{V} \cdot d\mathbf{S} \\
&= + \iint_{D_{\theta\varphi}} (V_x A + V_y B + V_z C) d\theta d\varphi \\
&= \int_0^{\frac{\pi}{2}} d\theta \int_0^{2\pi} d\varphi (\sin^4 \theta \cos^2 \varphi \sin \varphi + \sin^3 \theta \cos \theta \sin^2 \varphi + \sin^2 \theta \cos^2 \theta \cos \varphi) \\
&= \frac{3\pi}{16}
\end{aligned}$$

注：在计算积分时可以利用被积函数和积分区域的轮换对称性，即  $x \rightarrow y, y \rightarrow z, z \rightarrow x$  积分结果不变。可以验证

$$\iint_{D_{\theta\varphi}} V_x A d\theta d\varphi = \iint_{D_{\theta\varphi}} V_y B d\theta d\varphi = \iint_{D_{\theta\varphi}} V_z C d\theta d\varphi = \frac{\pi}{16}$$

#### 4.5.7

坐标变换对应的 Jacobi 行列式为

$$\begin{aligned} A &= \begin{vmatrix} \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \\ \frac{\partial z}{\partial u} & \frac{\partial z}{\partial v} \end{vmatrix} = \begin{vmatrix} \sin v & u \cos v \\ 0 & a \end{vmatrix} = a \sin v \\ B &= \begin{vmatrix} \frac{\partial z}{\partial u} & \frac{\partial z}{\partial v} \\ \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \end{vmatrix} = \begin{vmatrix} 0 & a \\ \cos v & -u \sin v \end{vmatrix} = -a \cos v \\ C &= \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{vmatrix} = \begin{vmatrix} \cos v & -u \sin v \\ \sin v & u \cos v \end{vmatrix} = u \end{aligned}$$

所以积分变为

$$\begin{aligned} I &= + \iint_{D_{uv}} (u^2 \sin^2 v (a \sin v) + a^2 v^2 (-a \cos v) + u^2 u) du dv \\ &= a \int_0^1 u^2 du \int_0^{2\pi} \sin^3 v dv - a^3 \int_0^1 du \int_0^{2\pi} v^2 \cos v dv \\ &\quad + \int_0^1 u^3 du \int_0^{2\pi} dv \\ &= \frac{\pi}{2} - 4\pi a^3 \end{aligned}$$

注：有同学没有注意到 3 个 Jacobi 行列式需要乘到对应的体元上，计算出积分结果为

$$\begin{aligned} I &= + \iint_{D_{uv}} (u^2 (a \sin v) + u^2 \sin^2 v (-a \cos v) + a^2 v^2 u) du dv \\ &= \frac{4\pi^3}{3} a^2 \end{aligned}$$

是错误的。该题体元的顺序与书上不同，应该写成

$$\iint_{S^+} Z dx \wedge dy + X dy \wedge dz + Y dz \wedge dx = \pm \iint_{D_{uv}} (ZC + XA + YB) du dv$$