





Executive Summary



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Introduction



Goal:

- · Apply data science methods to solve a real-world problem.
- · Analysis of successful and failed SpaceX rocket landings.

What was done:

- · Collection, processing, and analysis of data.
- · Building machine learning models for forecasting.

Data Collection & Data Wrangling Methodology

Data sources:

- SpaceX API
- Web scraping for additional data

[21]:	Flight No.	Launch site	Payload	Payload mass	Orbit	Customer	Launch outcome	Version Booster	Booster landing	Date	Time
	0 1	CCAFS	Dragon Spacecraft Qualification Unit	0	LEO	SpaceX	Success\n	F9 v1.07B0003.18	Failure	4 June 2010	18:45
	1 2	CCAFS	Dragon	0	LEO	NASA	Success	F9 v1.07B0004.18	Failure	8 December 2010	15:43
:	2 3	CCAFS	Dragon	525 kg	LEO	NASA	Success	F9 v1.07B0005.18		22 May 2012	
:	3 4	CCAFS	SpaceX CRS-1	4,700 kg	LEO	NASA	Success\n	F9 v1.07B0006.18	No attempt	8 October 2012	00:35
	4 5	CCAFS	SpaceX CRS-2	4,877 kg	LEO	NASA	Success\n	F9 v1.07B0007.18	No attempt\n	1 March 2013	15:10

In [27]:	<pre>data_falcon9.loc[:,'FlightNumber'] = list(range(1, data_falcon9.shape[0]+1)) data_falcon9</pre>
	_

27]:		FlightNumber	Date	BoosterVersion	PayloadMass	Orbit	LaunchSite	Outcome	Flights	GridFins	Reused
	4	1	2010-06-04	Falcon 9	NaN	LEO	CCSFS SLC 40	None None	1	False	False
	5	2	2012-05-22	Falcon 9	525.0	LEO	CCSFS SLC 40	None None	1	False	False
	6	3	2013-03-01	Falcon 9	677.0	ISS	CCSFS SLC 40	None None	1	False	False
	7	4	2013-09-29	Falcon 9	500.0	PO	VAFB SLC 4E	False Ocean	1	False	False
	8	5	2013-12-03	Falcon 9	3170.0	GTO	CCSFS SLC 40	None None	1	False	False
	89	86	2020-09-03	Falcon 9	15600.0	VLEO	KSC LC 39A	True ASDS	2	True	True
	90	87	2020-10-06	Falcon 9	15600.0	VLEO	KSC LC 39A	True ASDS	3	True	True
	91	88	2020-10-18	Falcon 9	15600.0	VLEO	KSC LC 39A	True ASDS	6	True	True
	92	89	2020-10-24	Falcon 9	15600.0	VLEO	CCSFS SLC 40	True ASDS	3	True	True
	93	90	2020-11-05	Falcon 9	3681.0	MEO	CCSFS SLC 40	True ASDS	1	True	False

90 rows × 17 columns





Data wrangling:

- · Data cleaning, gap filling
- Variable transformation for further analysis

[13]:	df.	.head(5)									
t[13]:		FlightNumber	Date	BoosterVersion	PayloadMass	Orbit	LaunchSite	Outcome	Flights	GridFins	Reused
	0	1	2010-06-04	Falcon 9	6104.959412	LEO	CCAFS SLC 40	None None	1	False	False
	1	2	2012-05-22	Falcon 9	525.000000	LEO	CCAFS SLC 40	None None	1	False	False
	2	3	2013-03-01	Falcon 9	677.000000	ISS	CCAFS SLC 40	None None	1	False	False
	3	4	2013-09-29	Falcon 9	500.000000	РО	VAFB SLC 4E	False Ocean	1	False	False
	4	5	2013-12-03	Falcon 9	3170.000000	GTO	CCAFS SLC 40	None None	1	False	False

Name: count, dtype: int64

```
In [8]:
         # landing_outcomes = values on Outcome column
         landing_outcomes = df['Outcome'].value_counts()
         landing_outcomes
Out[8]:
        Outcome
                        41
         True ASDS
         None None
                        19
         True RTLS
         False ASDS
         True Ocean
         False Ocean
         None ASDS
         False RTLS
         Name: count, dtype: int64
```





EDA & Interactive Visual Analytics Methodology

EDA & Visualization Methods

Exploratory Data Analysis

First, let's read the SpaceX dataset into a Pandas dataframe and print its summary

```
from js import fetch
import io

URL = "https://cf-courses-data.s3.us.cloud-object-storage.appdomain.cloud/IBM-DS0321EN-SkillsNetwork/datasets
resp = await fetch(URL)
dataset_part_2_csv = io.BytesIO((await resp.arrayBuffer()).to_py())
df=pd.read_csv(dataset_part_2_csv)
df.head(5)
```

t[3]:		FlightNumber	Date	BoosterVersion	PayloadMass	Orbit	LaunchSite	Outcome	Flights	GridFins	Reused	
	0	1	2010-06-04	Falcon 9	6104.959412	LEO	CCAFS SLC 40	None None	1	False	False	
	1	2	2012-05-22	Falcon 9	525.000000	LEO	CCAFS SLC 40	None None	1	False	False	
	2	3	2013-03-01	Falcon 9	677.000000	ISS	CCAFS SLC 40	None None	1	False	False	
	3	4	2013-09-29	Falcon 9	500.000000	РО	VAFB SLC 4E	False Ocean	1	False	False	
	4	5	2013-12-03	Falcon 9	3170.000000	GTO	CCAFS SLC 40	None None	1	False	False	





Interactive analysis tools (Folium, Dash)

'SpaceX Launch Records Dashboard',

style={'textAlign': 'center', 'color': '#077533', 'font-size': 40}

```
# Initial the map
                                                                            site_map = folium.Map(location=nasa_coordinate, zoom_start=5)
                                                                            # For each launch site, add a Circle object based on its coordinate (Lat, Long) values. In addition, add La
                                                                            for i in range (len(launch sites df.index)):
                                                                                coordinate = [launch_sites_df["Lat"][i], launch_sites_df["Long"][i]]
        import pandas as pd
                                                                                circle = folium.Circle(coordinate, radius=100, color='#0aa153', fill=True).add_child(folium.Popup(launc
       import dash
                                                                                marker = folium.map.Marker(
        from dash import dcc, html
                                                                                    coordinate,
                                                                                    icon=DivIcon(
        from dash.dependencies import Input, Output
                                                                                        icon size=(20, 20),
        import plotly.express as px
                                                                                        icon anchor=(0, 0),
                                                                                        html='<div style="font-size: 12; color:#620aa1;"><b>%s</b></div>' % launch sites df["Launch Sit
        spacex_df = pd.read_csv("spacex_launch_dash.csv")
                                                                                site map.add child(circle)
        max_payload = spacex_df['Payload Mass (kg)'].max()
                                                                                site map.add child(marker)
        min_payload = spacex_df['Payload Mass (kg)'].min()
                                                                            site map
10
11
        app = dash.Dash( name )
12
        app.layout = html.Div(children=[
13
14
            html.H1(
```



),

15 16

17



Predictive Analysis Methodology

Used machine learning algorithms (KNN, decision tree, logistic regression, support vector machine)

```
parameters = {'criterion': ['gini', 'entropy'],
      'splitter': ['best', 'random'],
      'max depth': [2*n for n in range(1,10)],
      'max_features': ['sqrt', 'log2', None],
      'min_samples_leaf': [1, 2, 4],
      'min samples_split': [2, 5, 10]}
 tree = DecisionTreeClassifier()
 tree cv = GridSearchCV(tree, parameters, cv=10)
 tree cv.fit(X train, Y train)
GridSearchCV(cv=10, estimator=DecisionTreeClassifier(),
              param_grid={'criterion': ['gini', 'entropy'],
                            'max_depth': [2, 4, 6, 8, 10, 12, 14, 16, 18],
                           'max_features': ['sqrt', 'log2', None],
                           'min_samples_leaf': [1, 2, 4],
                           'min samples_split': [2, 5, 10],
                           'splitter': ['best', 'random']})
```



Evaluated the accuracy of the models

```
In [14]:
    print("tuned hpyerparameters :(best parameters) ",logreg_cv.best_params_)
    print("accuracy :",logreg_cv.best_score_)

tuned hpyerparameters :(best parameters) {'C': 0.01, 'penalty': '12', 'solver': 'lbfgs'}
accuracy : 0.8464285714285713
```

```
In [21]: print("tuned hpyerparameters :(best parameters) ",svm_cv.best_params_)
    print("accuracy :",svm_cv.best_score_)

tuned hpyerparameters :(best parameters) {'C': 1.0, 'gamma': 0.03162277660168379, 'kernel': 'sigmoid'}
    accuracy : 0.8482142857142856
```

```
print("tuned hpyerparameters :(best parameters) ",tree_cv.best_params_)
print("accuracy :",tree_cv.best_score_)

tuned hpyerparameters :(best parameters) {'criterion': 'entropy', 'max_depth': 16, 'max_features': 'sqrt', 'min_samples_leaf': 4, 'min_samples_split': 2, 'splitter': 'random'}
accuracy : 0.875
```

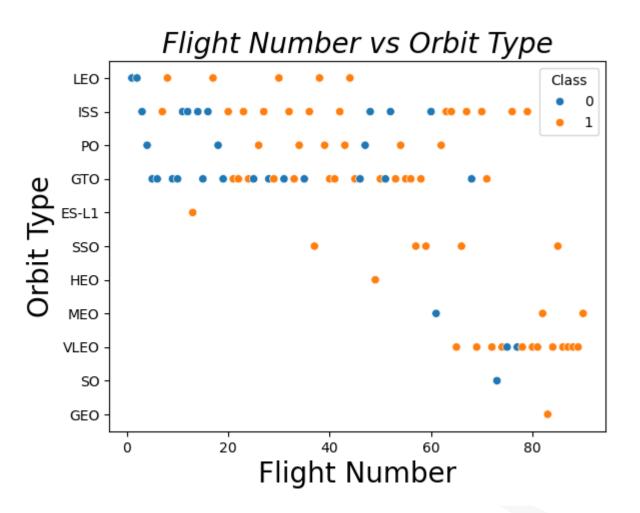
```
In [34]:
    print("tuned hpyerparameters :(best parameters) ",knn_cv.best_params_)
    print("accuracy :",knn_cv.best_score_)

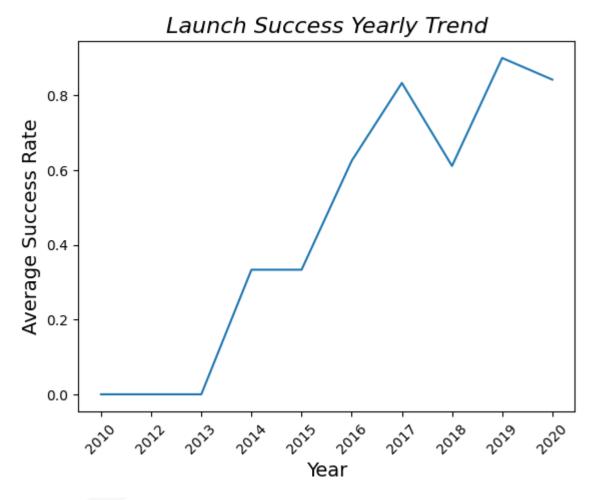
tuned hpyerparameters :(best parameters) {'algorithm': 'auto', 'n_neighbors': 10, 'p': 1}
    accuracy : 0.8482142857142858
```



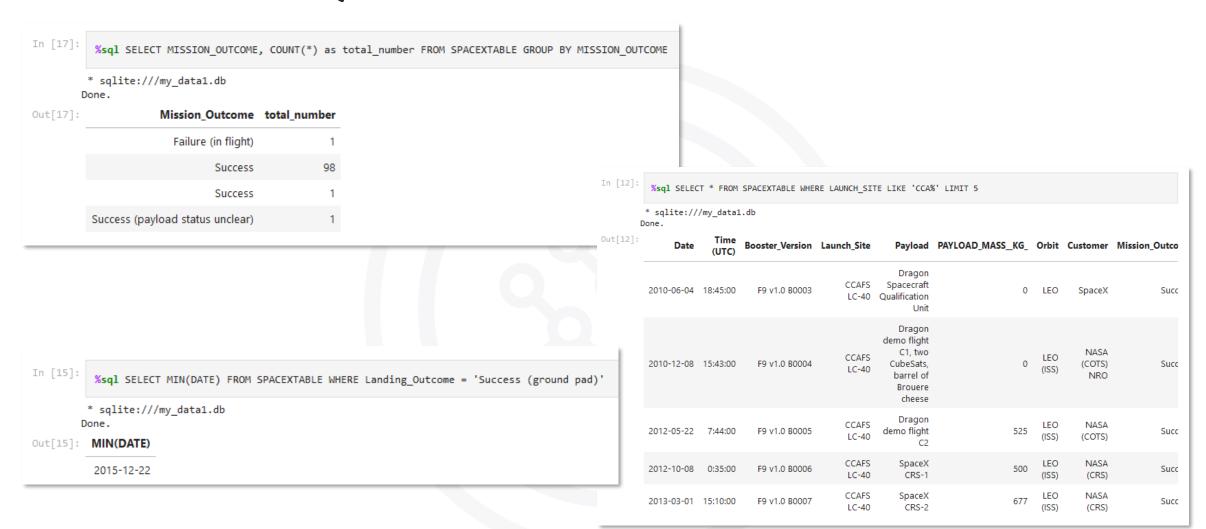


EDA with Visualization Results





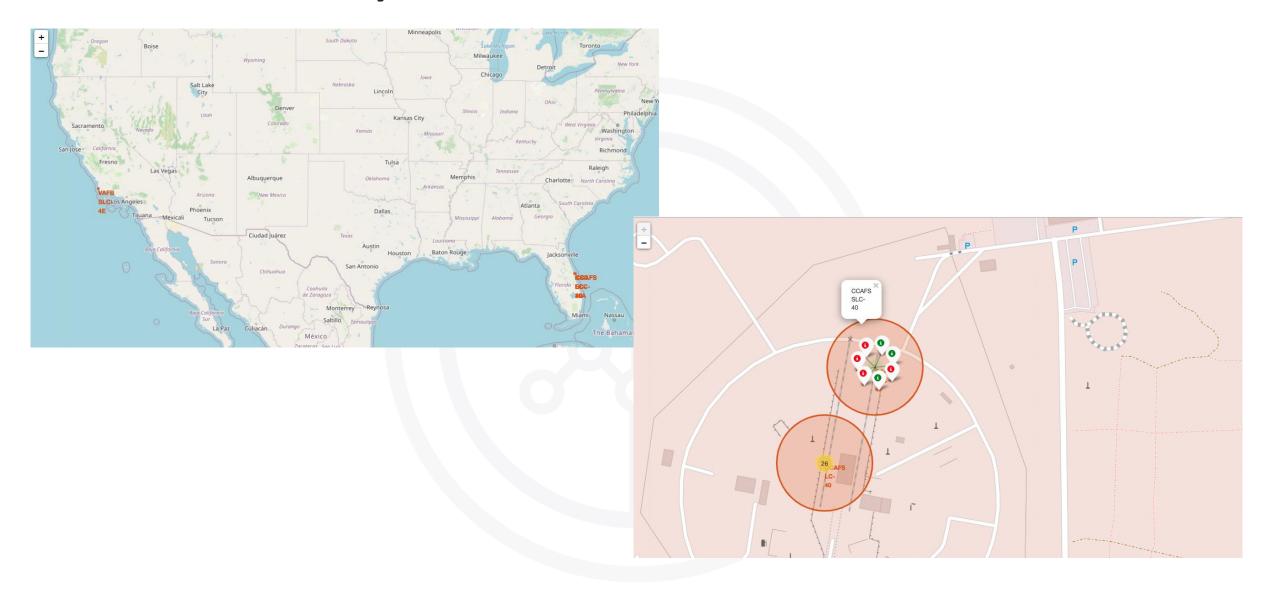
EDA with SQL Results







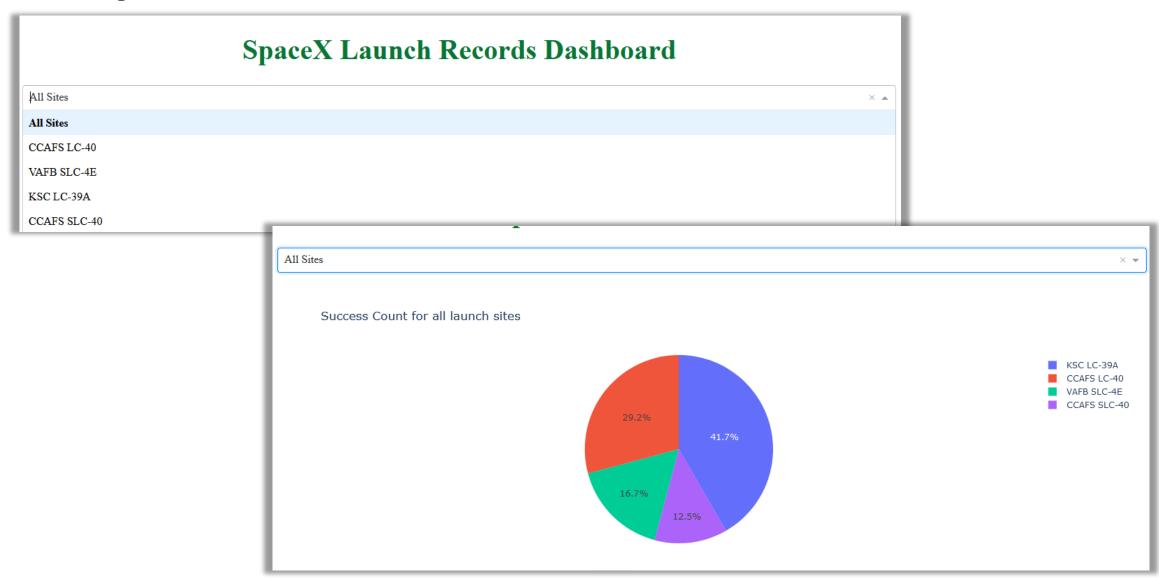
Interactive Map with Folium Results







Plotly Dash Dashboard Results





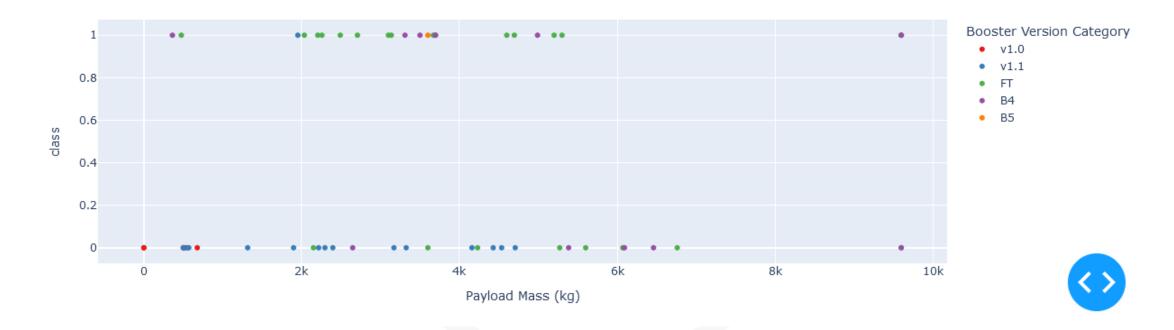


Plotly Dash Dashboard Results

Payload range (Kg):



Success count on Payload mass for site ALL (Payload range: 0-10000 kg)







Predictive Analysis

Model	Accuracy
Logistic Regression	0.846
Decision Tree	0.875
SVM	0.848
KNN	0.848

The results of the model comparison showed that the Decision Tree algorithm demonstrated the best accuracy in predicting successful SpaceX rocket landings with an accuracy of 87.5%. The Logistic Regression, SVM and KNN algorithms have similar results, around 84.6-84.8%, which indicates their reliability, but slightly lower accuracy compared to decision trees.

Decision Tree was found to be the most effective model for prediction, with an accuracy of 87.5%. This algorithm works well due to its ability to handle categorical variables and detect important patterns in the data.



Conclusion



Key insights from the analysis:

The collected and analyzed data allowed us to identify key factors influencing the success of SpaceX rocket landings.

Deep analysis was performed using visualizations, SQL, and interactive tools, which helped better understand launch dynamics.

The best forecasting method turned out to be Decision Tree, which achieved 87.5% accuracy, confirming its effectiveness in similar tasks.

Interactive dashboards and maps significantly simplify the visualization of results for a non-technical audience.

- Meaning for SpaceX:

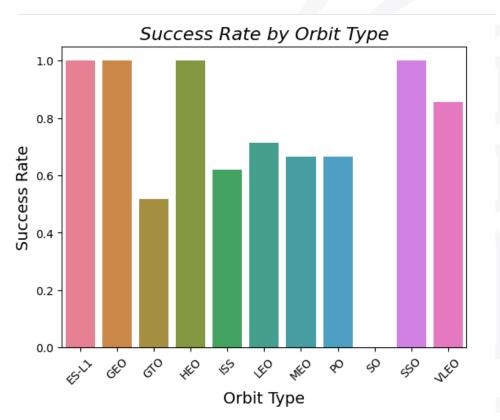
The results can help SpaceX improve launch planning and reduce the risk of unsuccessful landings.

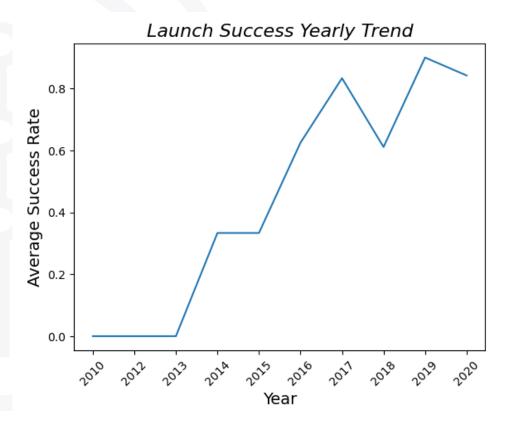
Identifying critical success factors will allow us to optimize mission preparation processes and test new technologies.

Forecasting and analysis provide a basis for automating decision-making and developing more sustainable engineering solutions.

Creativity & Insights

I decided to add color to some of the graphs and changed the font and angle a bit for better readability. This approach improved the overall look of the graphs and emphasized the attention to detail that is important for presenting complex information.







Thank you for your attention!



