

Neural Bellman-Ford Networks: A General Graph Neural Network Framework for Link Prediction

Zhaocheng Zhu, Zuobai Zhang, Louis-Pascal Xhonneux, Jian Tang

2022/1/4

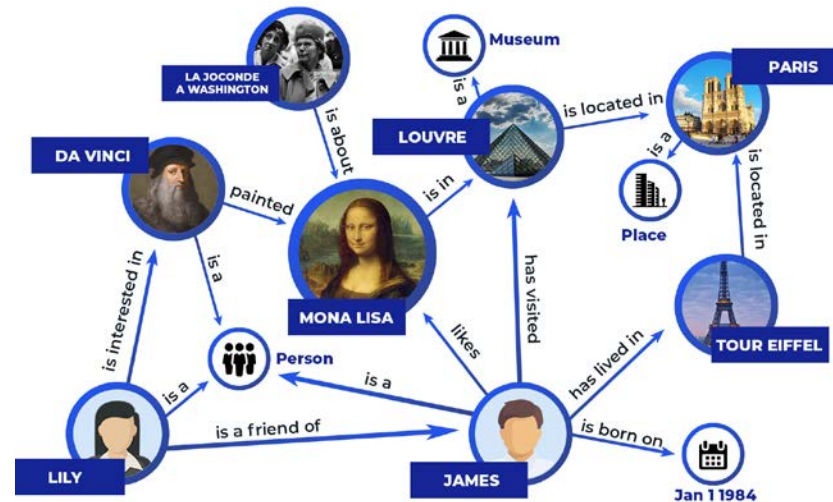


Link Prediction

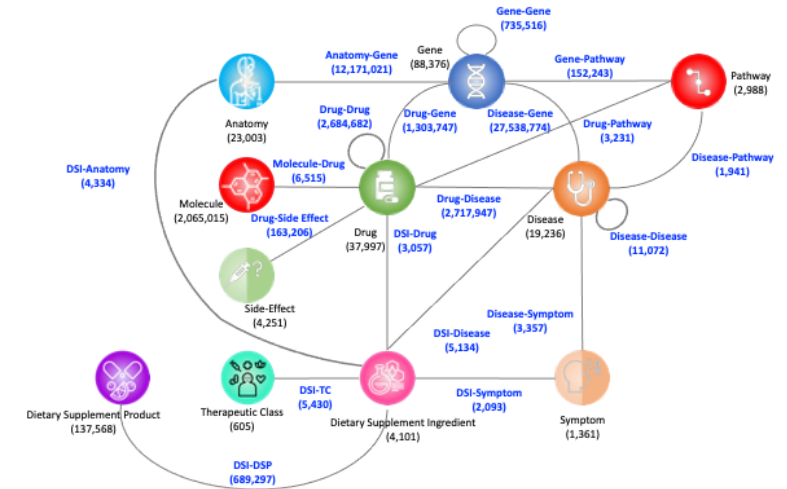
- Predict the interactions between nodes



social networks



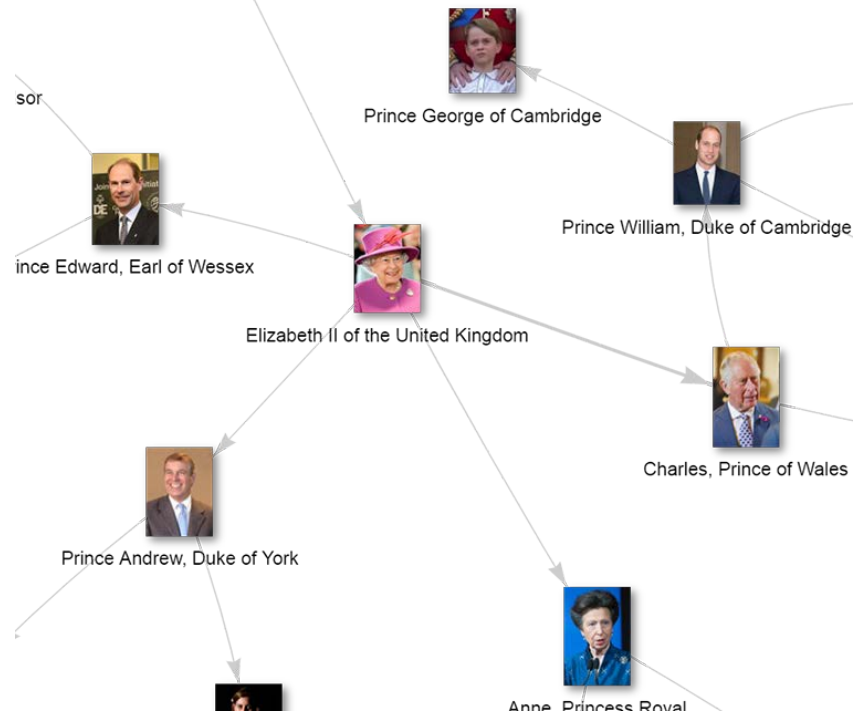
knowledge graph completion



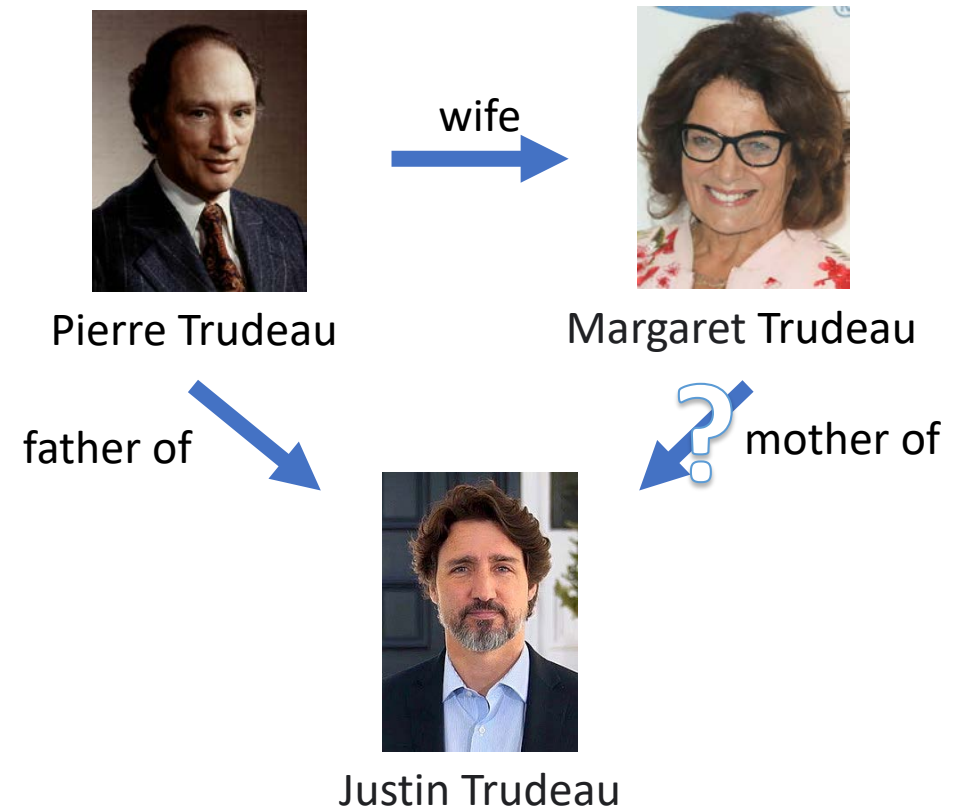
drug repurposing

Challenges

- Inductive setting



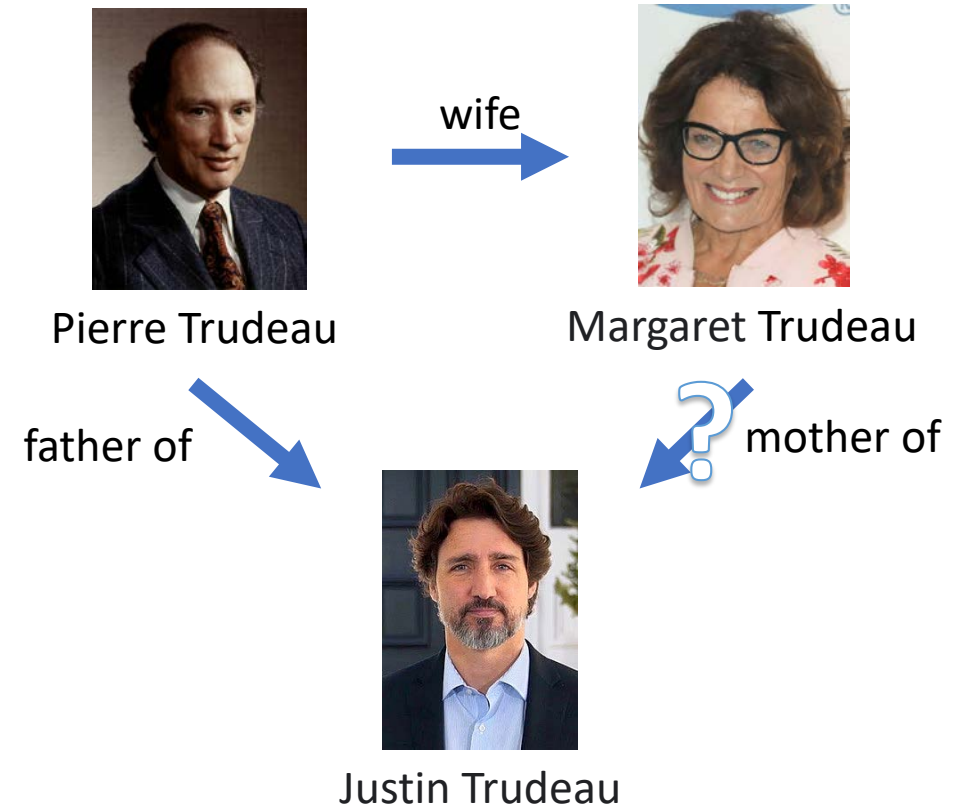
Train



Test (a new graph)

Challenges

- Interpretability
- **Query:** Who is Justin Trudeau's mother?
- **Answer:** Margaret Trudeau
- Why?

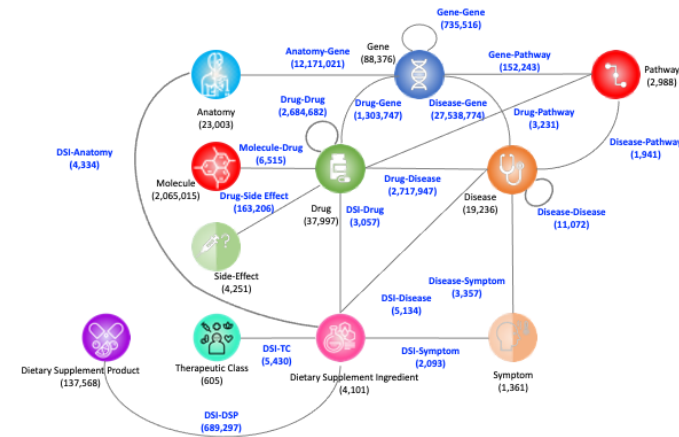


Challenges

- Large scale

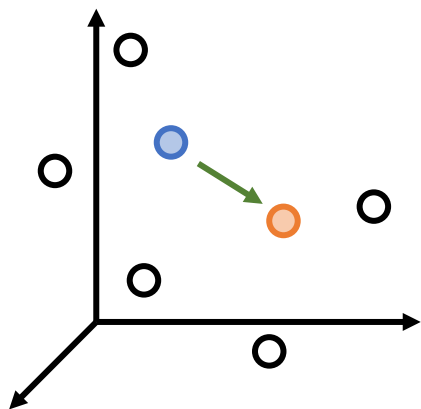
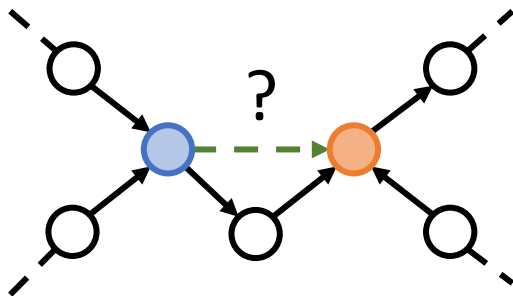


Wikidata
87M entities
504M triplets



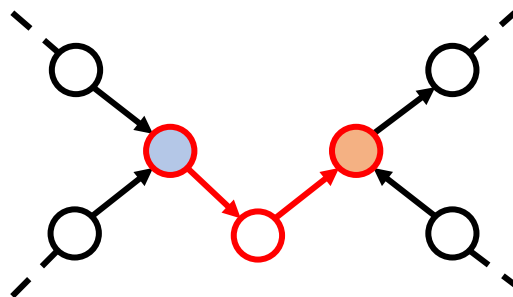
CBKH
2.4M nodes
48M edges

Machine Learning Methods



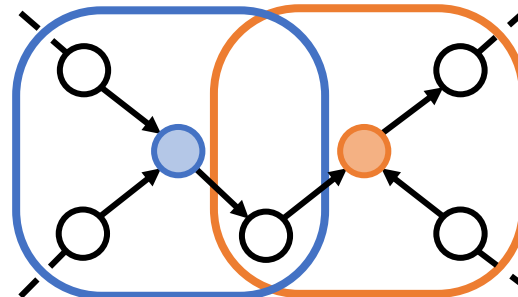
Embeddings

TransE, DistMult,
ComplEx, etc.



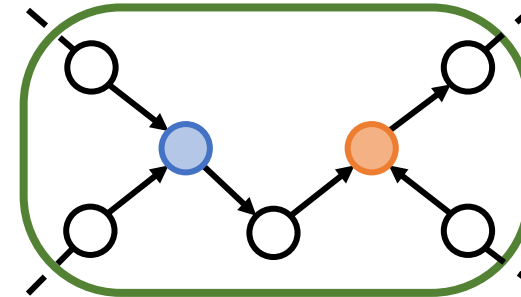
Path-based

PathRanking, PathRNN,
DeepPath, etc.



Node GNN encoders

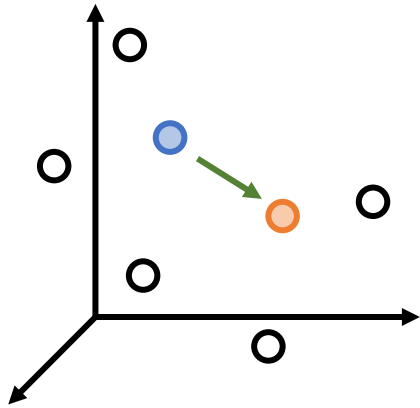
GCN, RGCN,
CompGCN, etc.



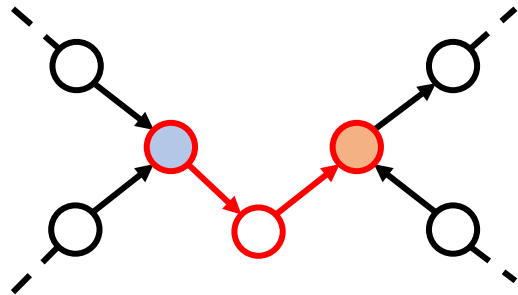
Subgraph GNN encoders

SEAL, GraIL

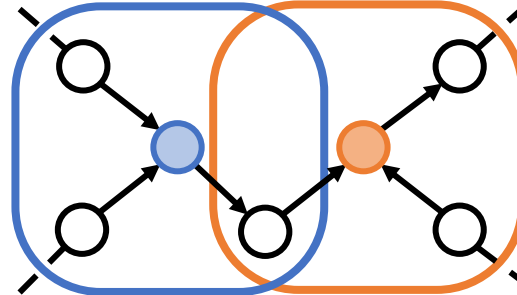
Machine Learning Methods



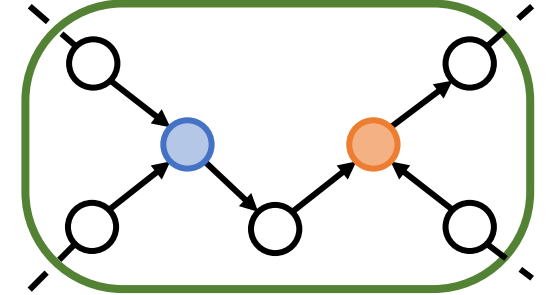
Embeddings



Path-based



Node GNN encoders



Subgraph GNN encoders



strong performance
scalable

interpretability
inductive

good performance
flexibility
scalable
(pseudo) inductive

strong performance
flexibility
inductive



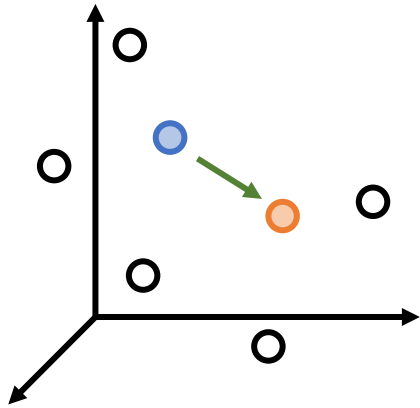
no interpretability
transductive only

weak performance
sometimes not scalable

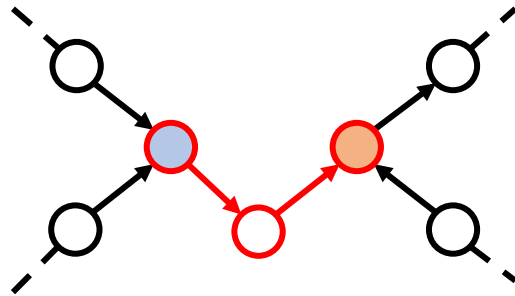
no interpretability

no interpretability
not scalable

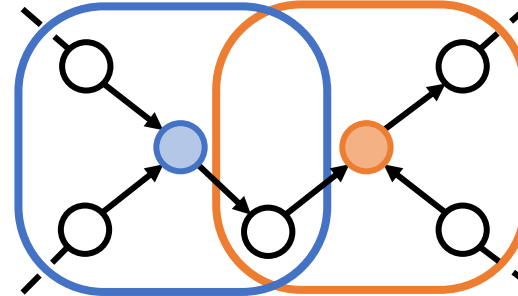
Machine Learning Methods



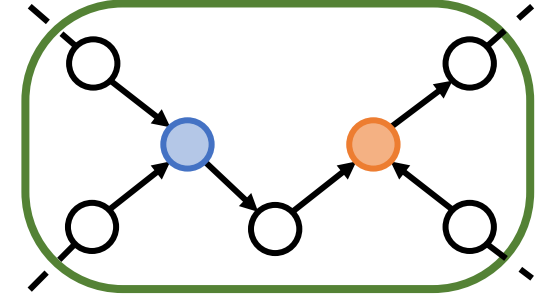
Embeddings



Path-based



Node GNN encoders



Subgraph GNN encoders



strong performance
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Can we achieve the best of all worlds?

Traditional Methods

- Traditional methods
 - Katz index: weighted count of paths between two nodes
 - Personalized PageRank: random walk probability from one to the other
 - Graph distance: the shortest path between two nodes
- Lessons
 - Interpretability via paths
 - Inductive
 - Scalability via dynamic programming

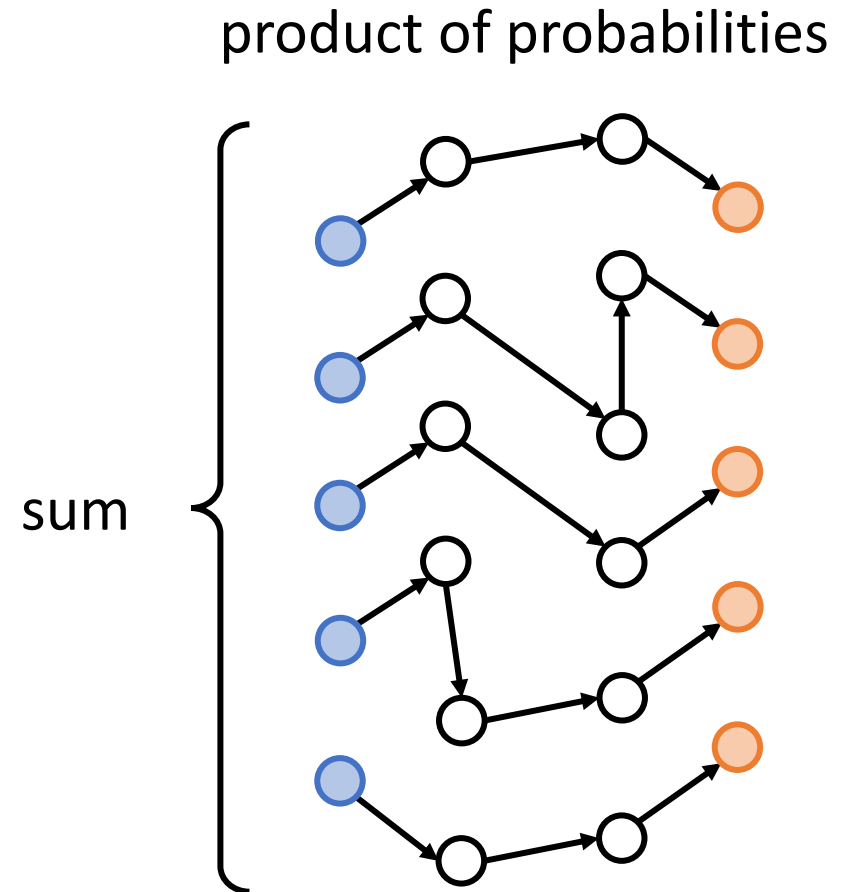
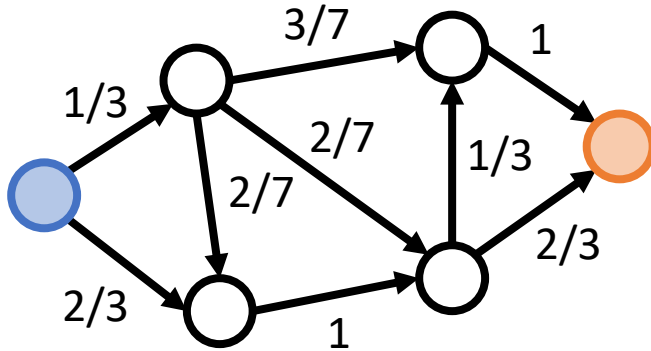
Traditional Methods

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- Lessons
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Can we parameterize them with NNs?

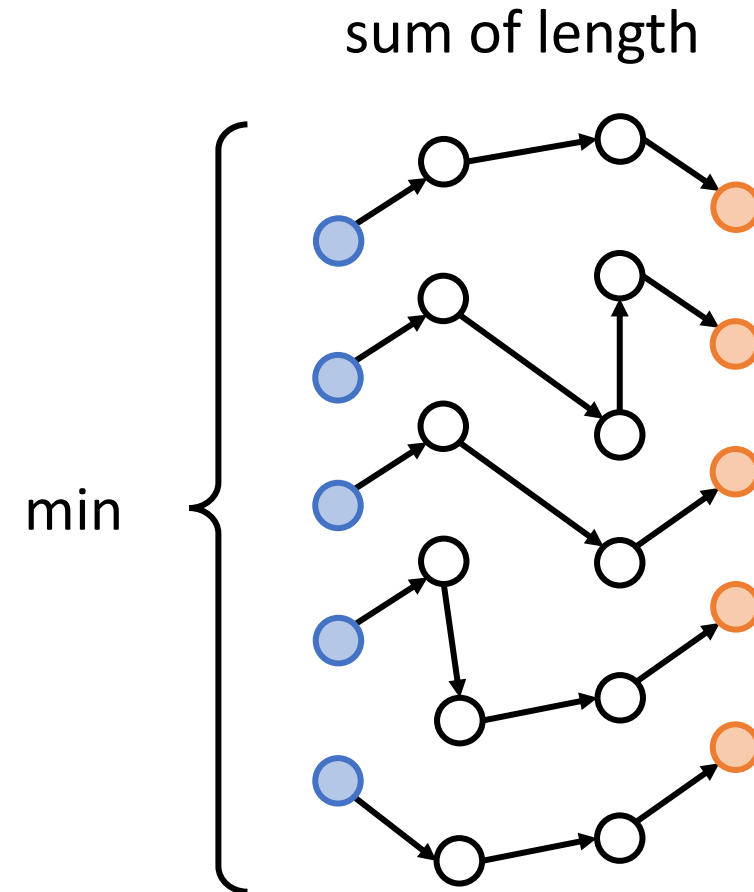
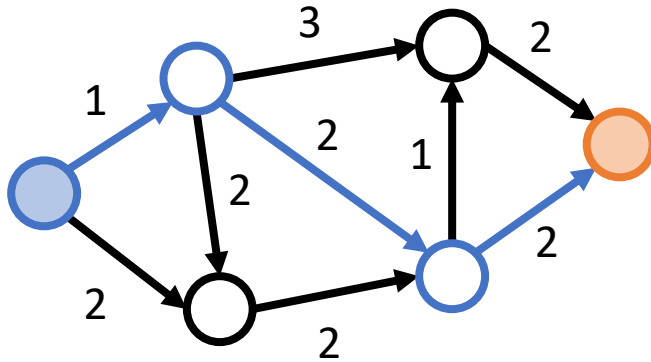
Traditional Methods

- Personalized PageRank

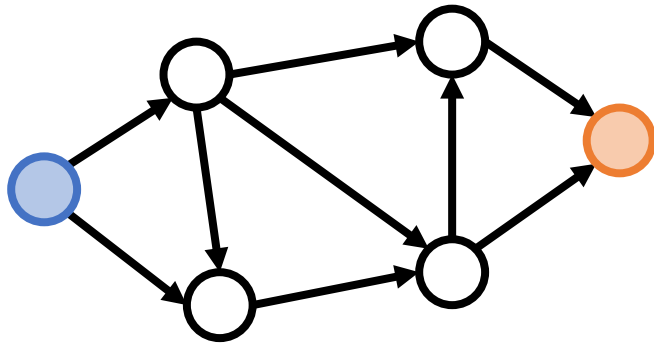


Traditional Methods

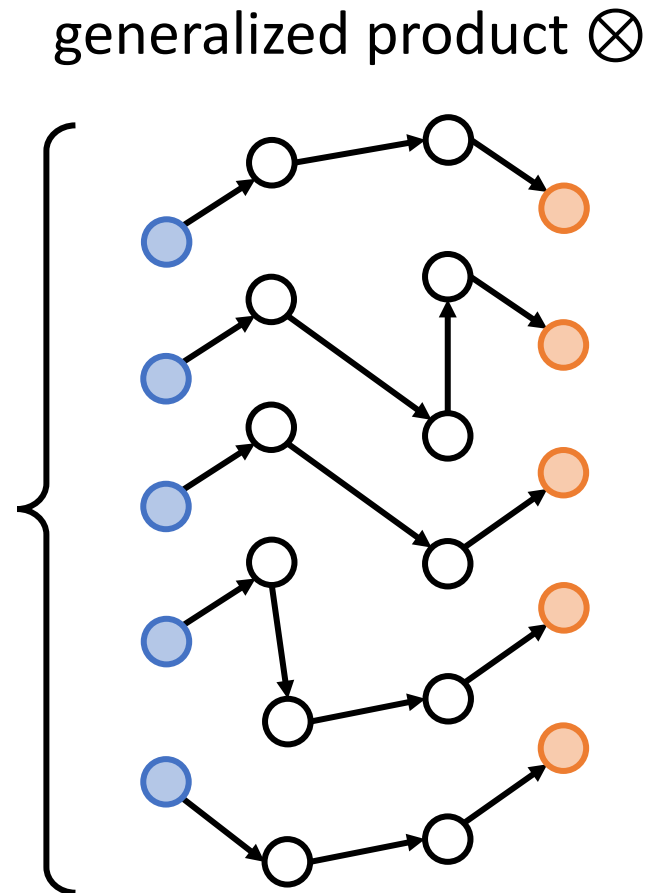
- Graph distance



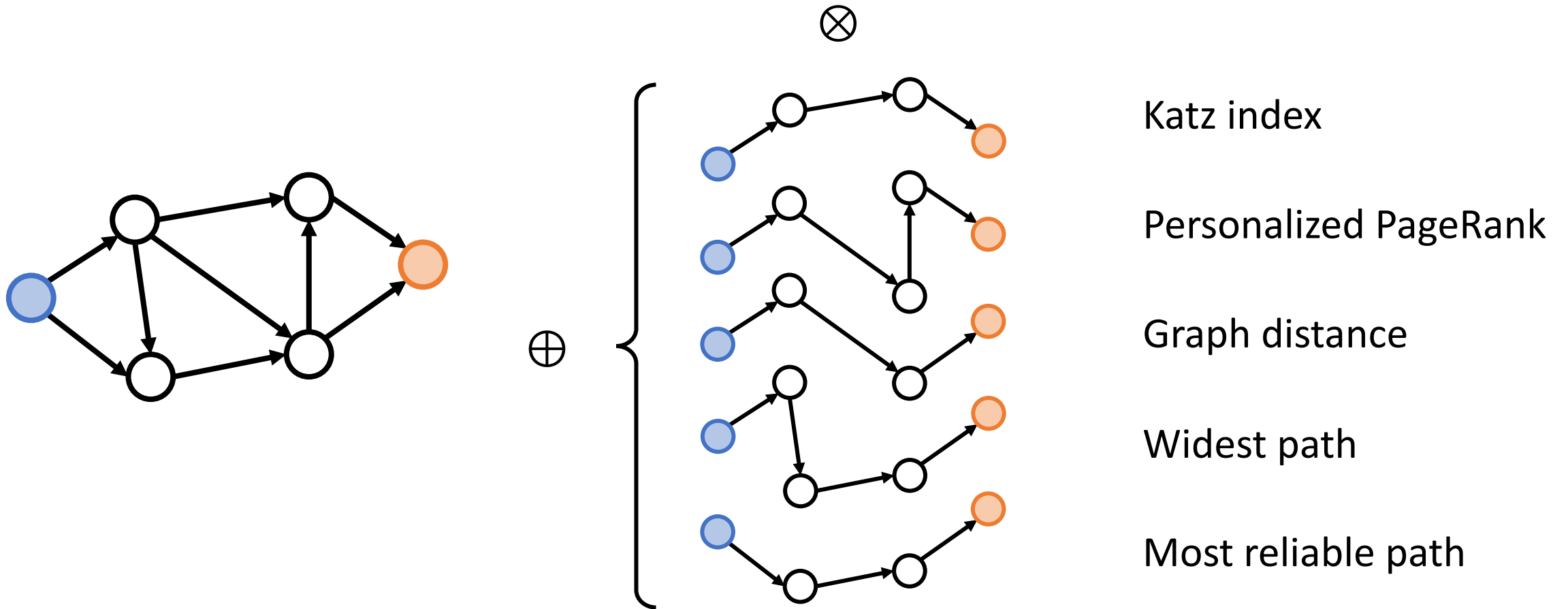
Path Formulation



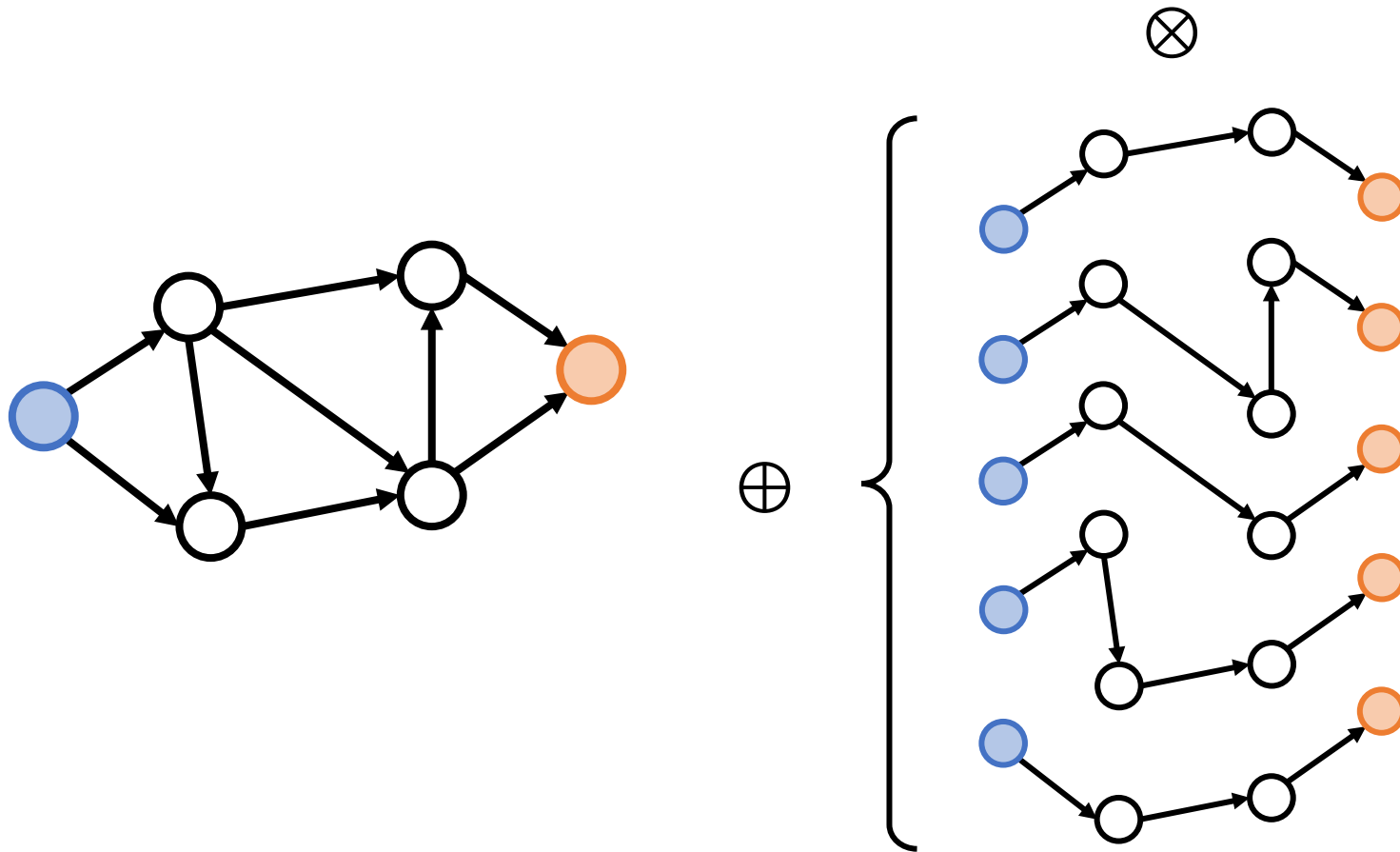
generalized
summation
 \oplus



Path Formulation



Path Formulation



inductive



interpretable



not scalable



handcraft



Make It Better

Path formulation

inductive



interpretable



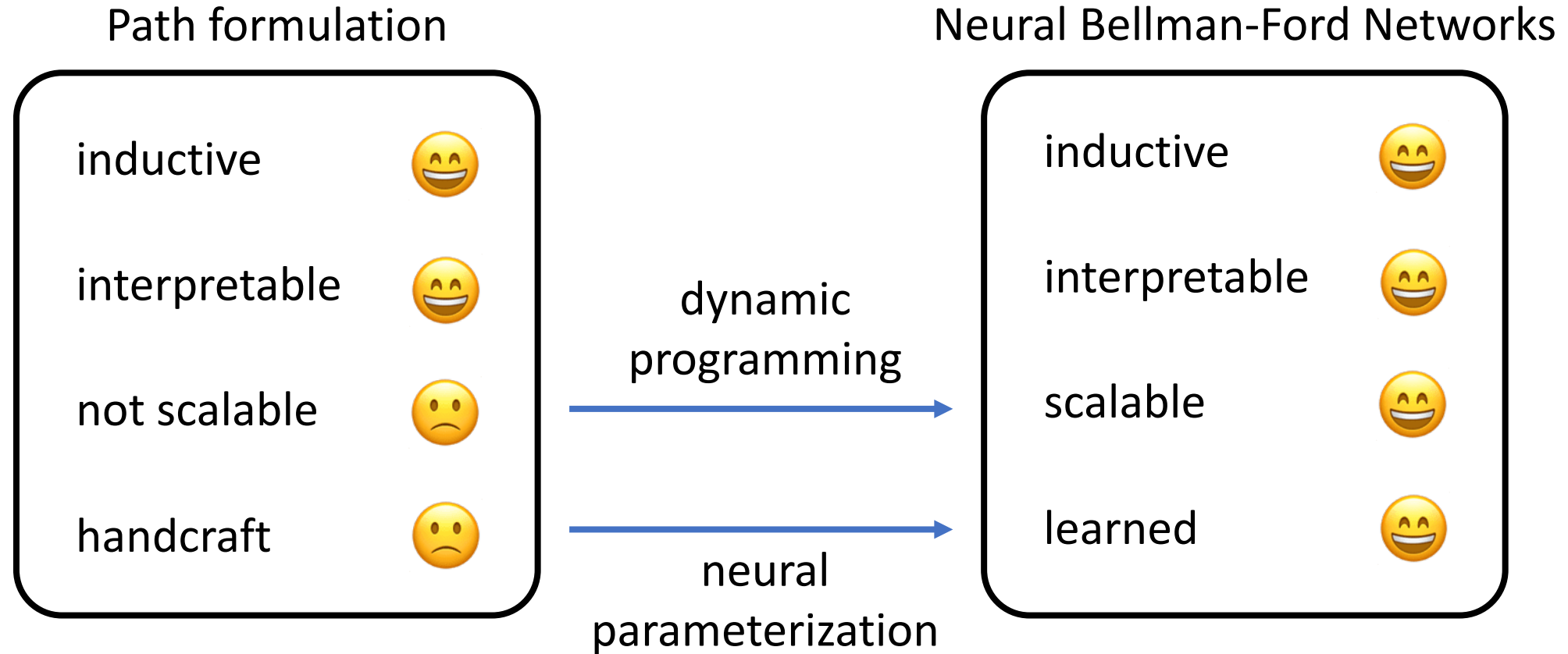
not scalable



handcraft



Make It Better

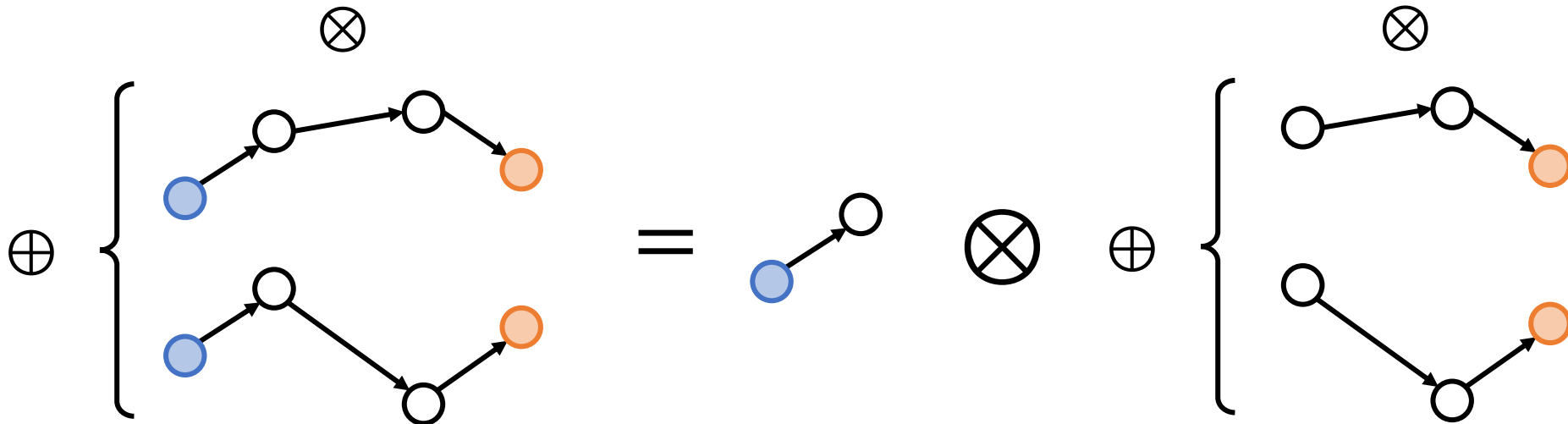


Dynamic Programming

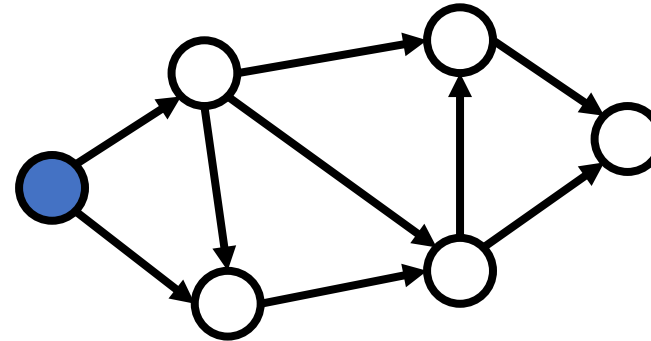
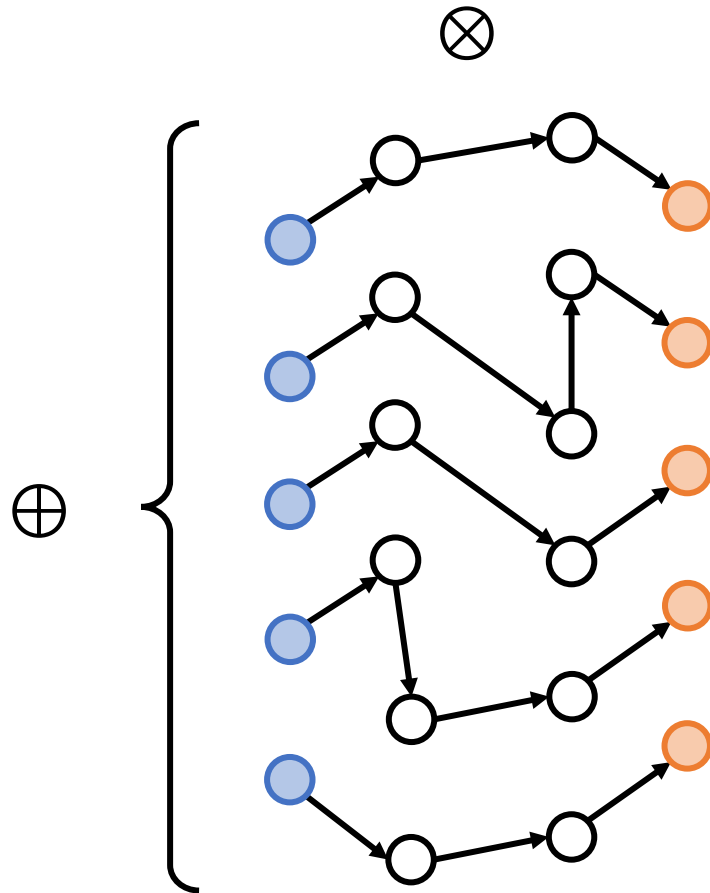
- $ab + ac = a(b + c)$

Dynamic Programming

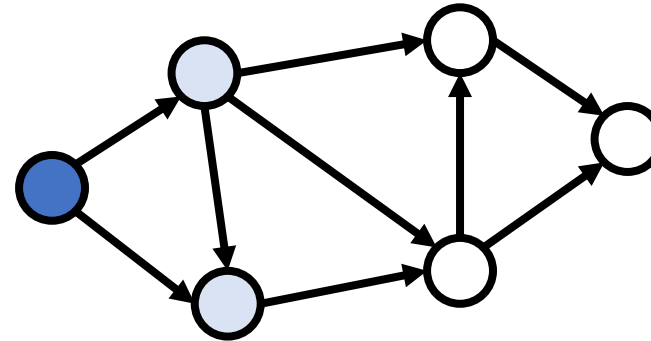
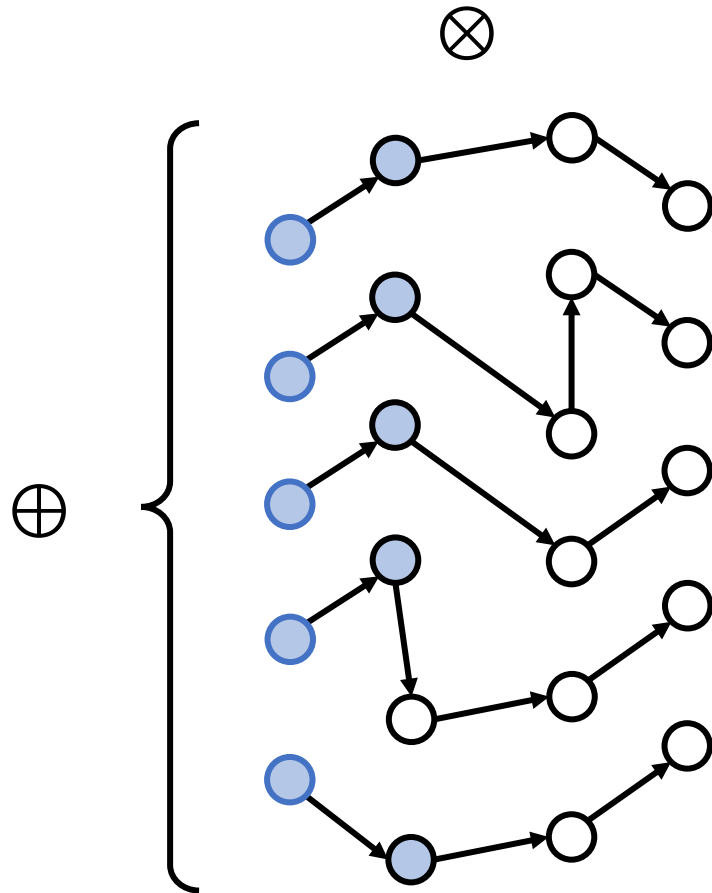
- $ab + ac = a(b + c)$
- $a \otimes b \oplus a \otimes c = a \otimes (b \oplus c)$



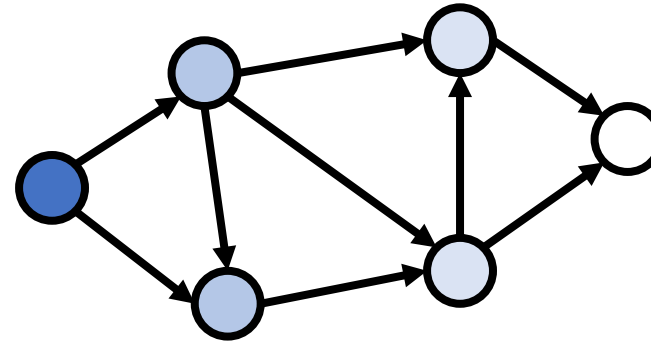
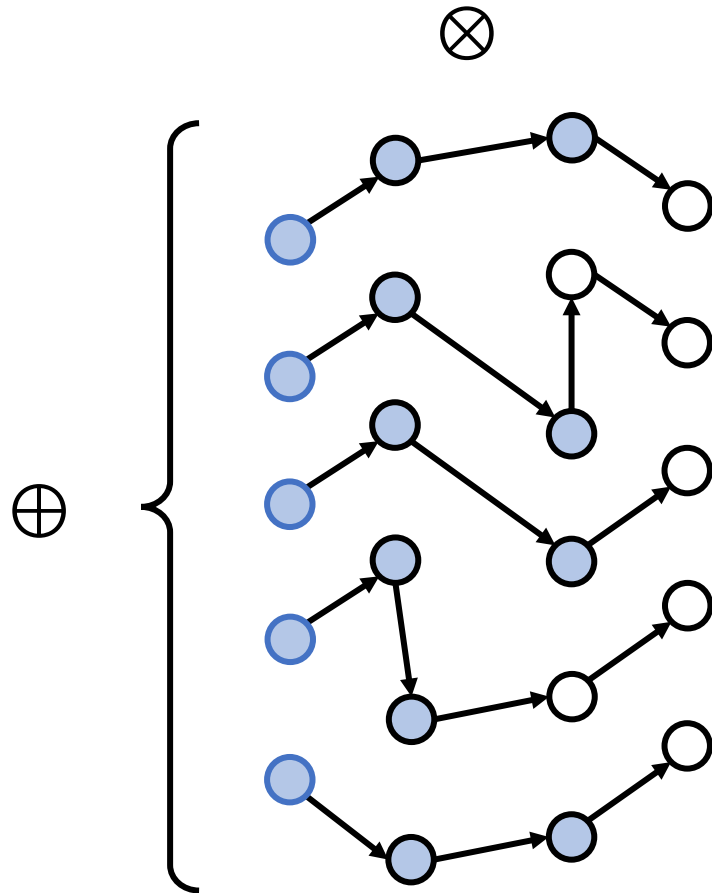
Dynamic Programming



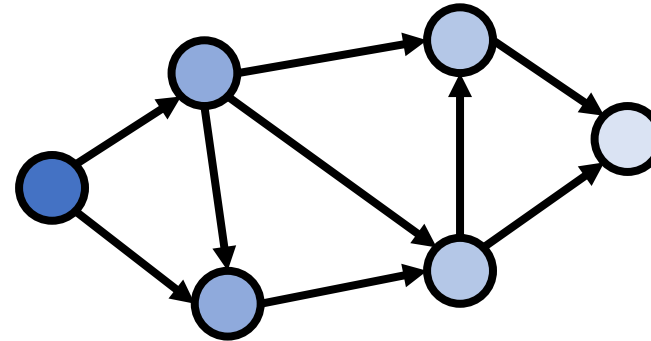
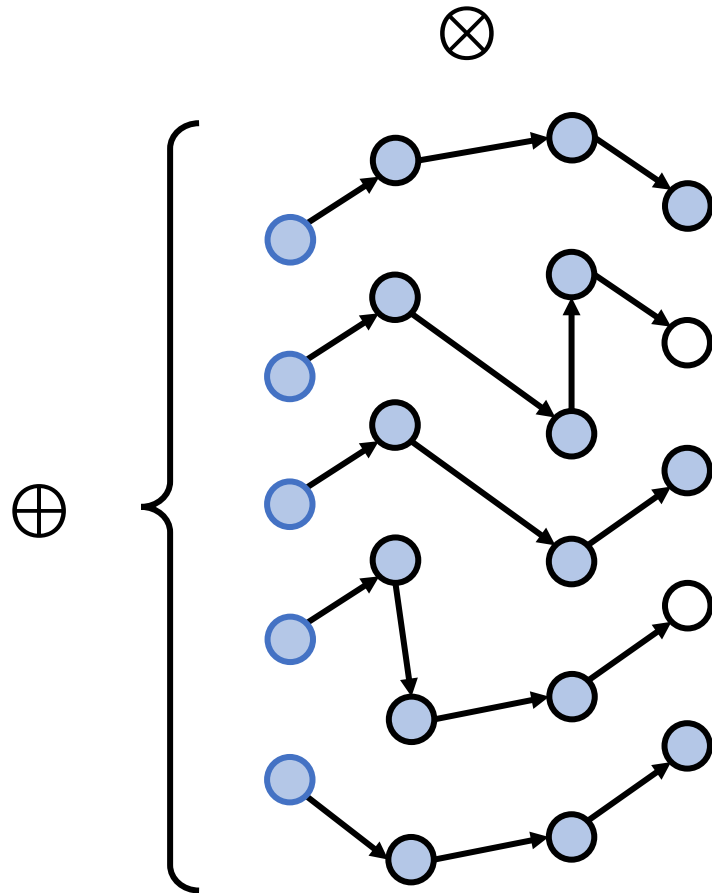
Dynamic Programming



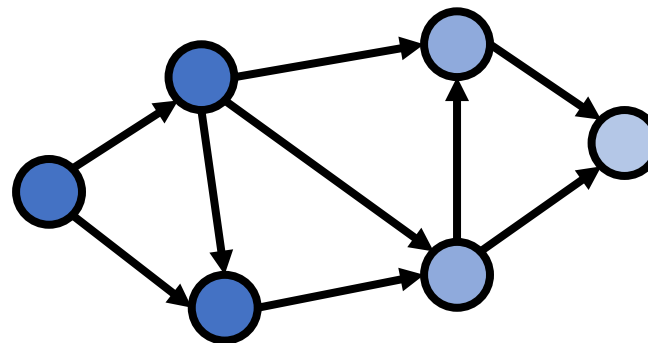
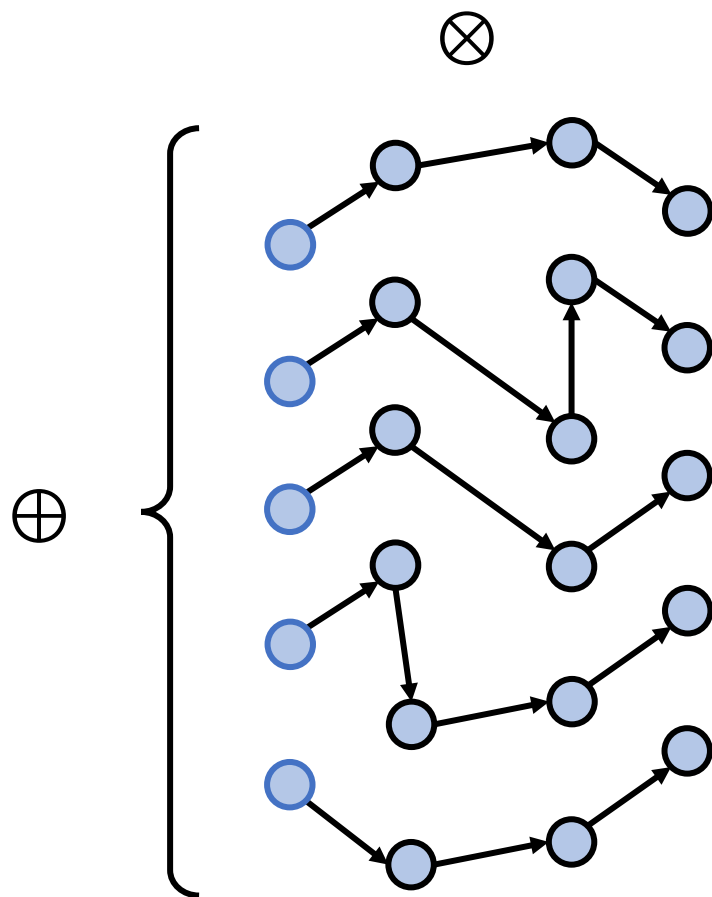
Dynamic Programming



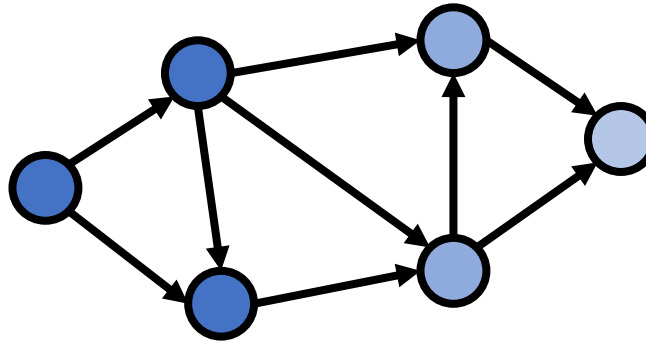
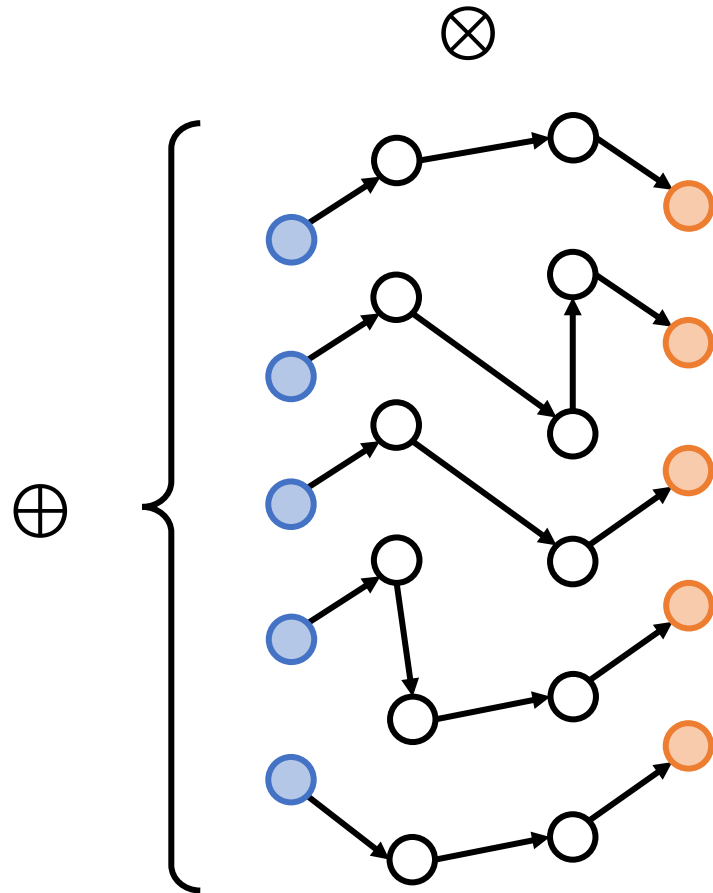
Dynamic Programming



Dynamic Programming



Dynamic Programming



power iteration

Bellman-Ford algorithm

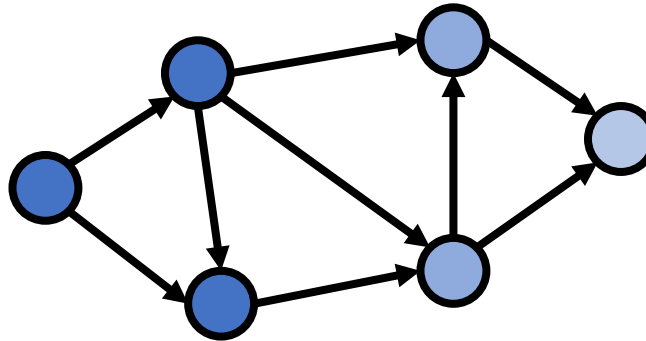
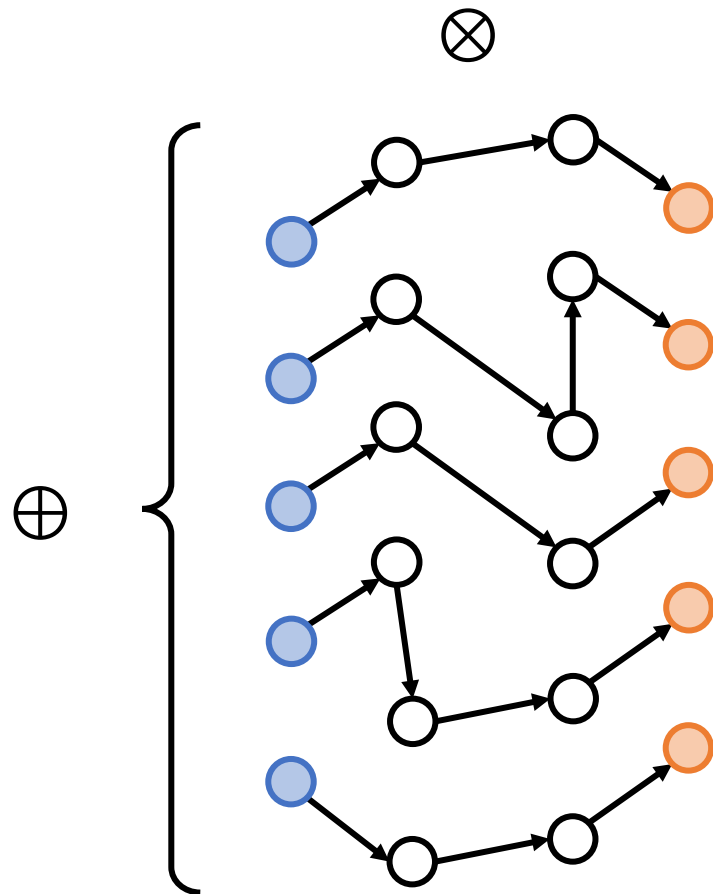
Viterbi algorithm

etc.

scalable



Dynamic Programming



Generalized
Bellman-Ford algorithm

power iteration

Bellman-Ford algorithm

Viterbi algorithm

etc.

scalable



Generalized Bellman-Ford Algorithm

- Path formulation

$$\mathbf{h}_q(u, v) = \bigoplus_{P \in \mathcal{P}_{uv}} \bigotimes_{e \in P} \mathbf{w}_q(e)$$

Generalized Bellman-Ford Algorithm

- Path formulation

$$\mathbf{h}_q(u, v) = \bigoplus_{P \in \mathcal{P}_{uv}} \bigotimes_{e \in P} \mathbf{w}_q(e)$$

- Generalized Bellman-Ford algorithm

$$\mathbf{h}_q^{(0)}(u, v) \leftarrow \begin{cases} \textcircled{1}_q & u = v \\ \textcircled{0}_q & u \neq v \end{cases}$$

boundary condition

Generalized Bellman-Ford Algorithm

- Path formulation

$$\mathbf{h}_q(u, v) = \bigoplus_{P \in \mathcal{P}_{uv}} \bigotimes_{e \in P} \mathbf{w}_q(e)$$

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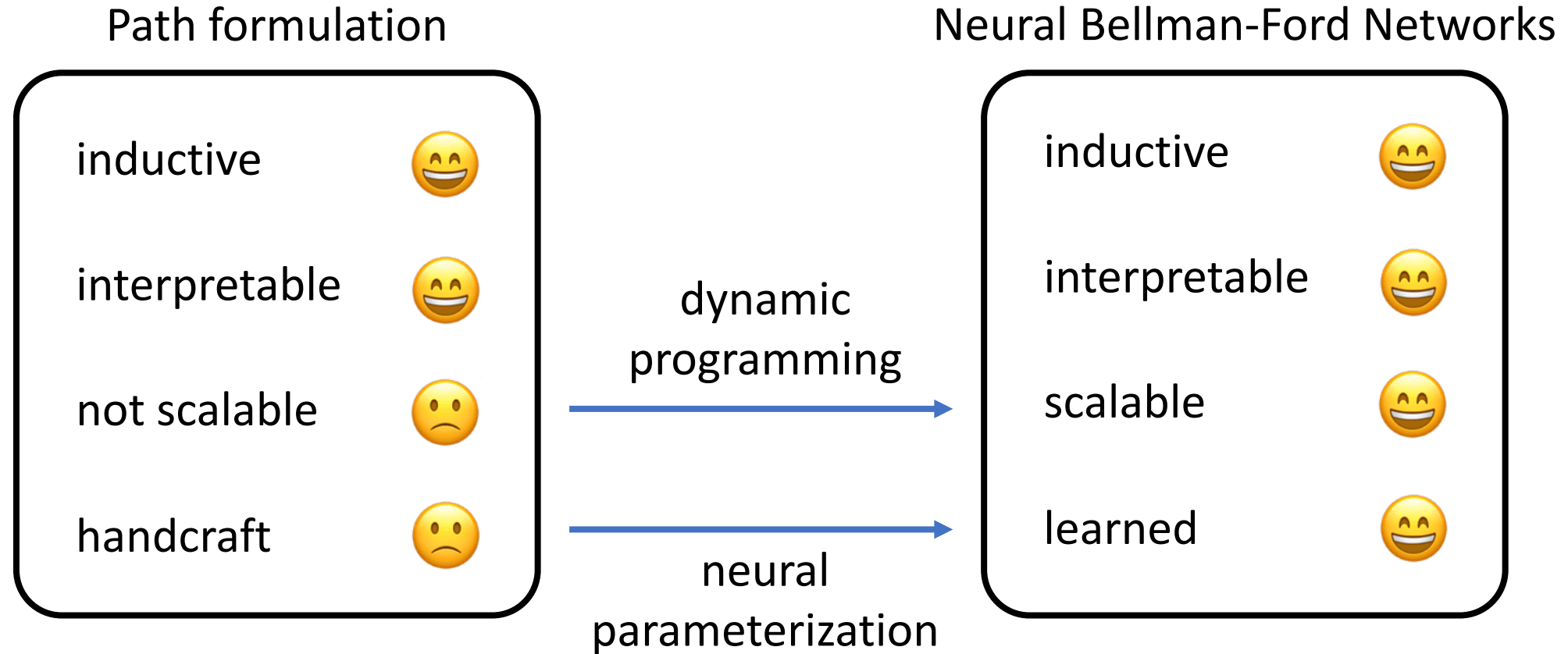
$$\mathbf{h}_q^{(0)}(u, v) \leftarrow \begin{cases} \textcircled{1}_q & u = v \\ \textcircled{0}_q & u \neq v \end{cases}$$

boundary condition

$$\mathbf{h}_q^{(t)}(u, v) \leftarrow \left(\bigoplus_{(x, v) \in \mathcal{E}(v)} \mathbf{h}^{(t-1)}(u, x) \otimes \mathbf{w}(x, r, v) \right) \oplus \mathbf{h}^{(0)}(u, v)$$

Bellman-Ford iteration

Make It Better



Neural Parameterization

- Generalized Bellman-Ford algorithm

$$\mathbf{h}_q^{(0)}(u, v) \leftarrow \mathbf{1}_q(u = v)$$

$$\mathbf{h}_q^{(t)}(u, v) \leftarrow \left(\bigoplus_{(x, v) \in \mathcal{E}(v)} \mathbf{h}_q^{(t-1)}(u, x) \otimes \mathbf{w}_q(x, r, v) \right) \oplus \mathbf{h}_q^{(0)}(u, v)$$

Neural Parameterization

- Generalized Bellman-Ford algorithm

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- Neural parameterization

- Single-source case: abbreviate $\mathbf{h}_q^{(t)}(u, v)$ as $\mathbf{h}_v^{(t)}$

$$\mathbf{h}_v^{(0)} \leftarrow \text{Indicator}(u, v, q)$$

$$\mathbf{h}_v^{(t)} \leftarrow \text{Aggregate} \left(\left\{ \text{Message} \left(\mathbf{h}_x^{(t-1)}, \mathbf{w}_q(x, r, v) \right) \mid (x, r, v) \in \mathcal{E}(v) \right\} \cup \{ \mathbf{h}_v^{(0)} \} \right)$$

Neural Parameterization

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Neural Parameterization

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- **Indicator**: learned embeddings for q
- **Message**: relational operators of KG embeddings (TransE/DistMult/RotatE etc.)
- **Aggregate**: permutation invariant function (sum/mean/max/PNA etc.)

Revisit Path Formulation

- Generalized Bellman-Ford algorithm

$$\mathbf{h}_q^{(0)}(u, v) \leftarrow \begin{cases} \mathbf{q} & u = v \\ 0 & u \neq v \end{cases}$$

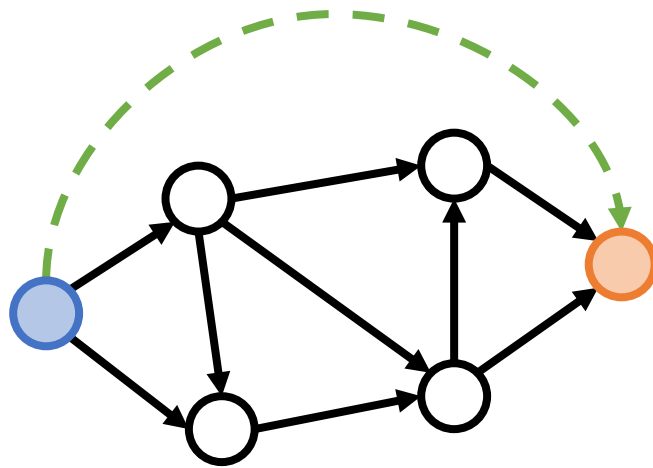
$$\mathbf{h}_q^{(t)}(u, v) \leftarrow \text{Aggregate} \left(\left\{ \text{Message} \left(\mathbf{h}_q^{(t-1)}(u, x), \mathbf{w}_q(x, r, v) \right) \right\} \cup \left\{ \mathbf{h}_v^{(0)} \right\} \right)$$

- Path formulation

$$\mathbf{h}_q(u, v) = \text{Aggregate}_{t=0}^{\infty} \left(\underbrace{\{ \text{Message}(\dots \text{Message}(\mathbf{q}, r_1), \dots r_t) \}}_{t \text{ Message}} \right)$$

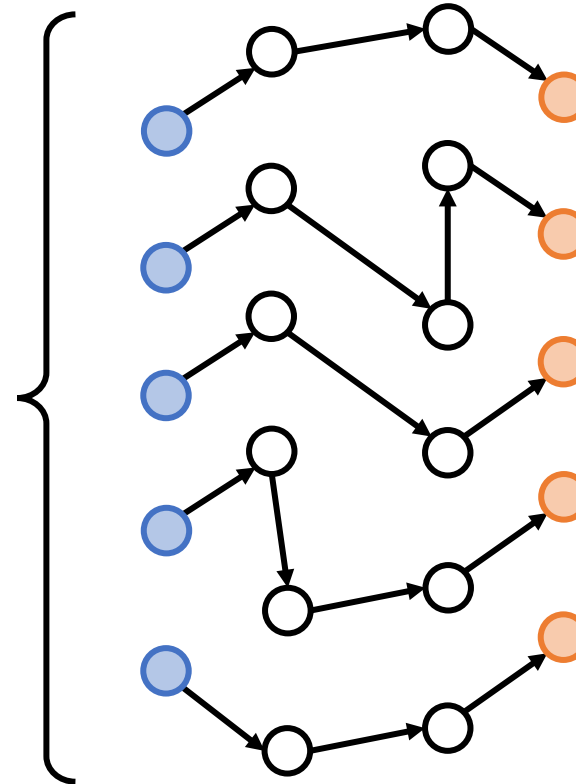
Revisit Path Formulation

- NBFNet

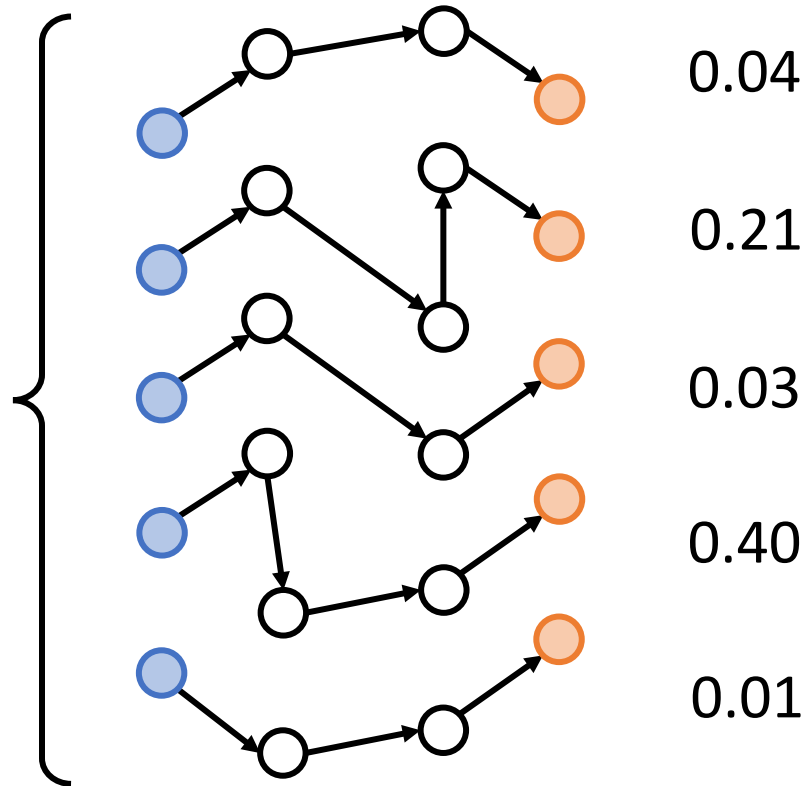
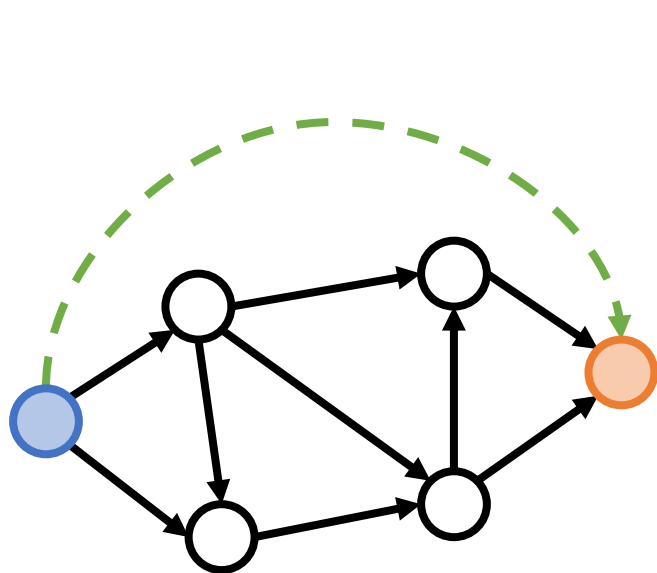


Permutation
invariant
aggregation

Chain of relational operators



Interpretation



path interpretations

Link Prediction

- Apply a MLP over $\mathbf{h}_q^{(t)}(u, v)$
 - $p(v|u, q) = \sigma \left(f \left(\mathbf{h}_q(u, v) \right) \right)$
- Homogeneous variant
 - Use the same relation for every q and r
- Undirected homogeneous variant
 - $p(u, v) = \sigma \left(f \left(\mathbf{h}(u, v) + \mathbf{h}(v, u) \right) \right)$
- Train with standard negative sampling
 - Time complexity is independent of #negative
 - Can use arbitrary large #negative or full softmax

Results

- Knowledge graph completion

Class	Method	FB15k-237					WN18RR				
		MR	MRR	H@1	H@3	H@10	MR	MRR	H@1	H@3	H@10
Path-based	Path Ranking [35]	3521	0.174	0.119	0.186	0.285	22438	0.324	0.276	0.360	0.406
	NeuralLP [69]	-	0.240	-	-	0.362	-	0.435	0.371	0.434	0.566
	DRUM [46]	-	0.343	0.255	0.378	0.516	-	0.486	0.425	0.513	0.586
Embeddings	TransE [6]	357	0.294	-	-	0.465	3384	0.226	-	-	0.501
	DistMult [68]	254	0.241	0.155	0.263	0.419	5110	0.43	0.39	0.44	0.49
	ComplEx [58]	339	0.247	0.158	0.275	0.428	5261	0.44	0.41	0.46	0.51
	RotatE [52]	177	0.338	0.241	0.375	0.553	3340	0.476	0.428	0.492	0.571
	HAKE [76]	-	0.346	0.250	0.381	0.542	-	0.497	0.452	0.516	0.582
	LowFER [1]	-	0.359	0.266	0.396	0.544	-	0.465	0.434	0.479	0.526
GNNs	RGCN [48]	221	0.273	0.182	0.303	0.456	2719	0.402	0.345	0.437	0.494
	GraIL [55]	2053	-	-	-	-	2539	-	-	-	-
	NBFNet	114	0.415	0.321	0.454	0.599	636	0.551	0.497	0.573	0.666

Results

- Homogeneous link prediction

Class	Method	Cora		Citeseer		PubMed	
		AUROC	AP	AUROC	AP	AUROC	AP
Path-based	Katz Index [30]	0.834	0.889	0.768	0.810	0.757	0.856
	Personalized PageRank [42]	0.845	0.899	0.762	0.814	0.763	0.860
	SimRank [28]	0.838	0.888	0.755	0.805	0.743	0.829
Embeddings	DeepWalk [43]	0.831	0.850	0.805	0.836	0.844	0.841
	LINE [53]	0.844	0.876	0.791	0.826	0.849	0.888
	node2vec [17]	0.872	0.879	0.838	0.868	0.891	0.914
GNNs	VGAE [32]	0.914	0.926	0.908	0.920	0.944	0.947
	S-VGAE [12]	0.941	0.941	0.947	0.952	0.960	0.960
	SEAL [73]	0.933	0.942	0.905	0.924	0.978	0.979
	TLC-GNN [67]	0.934	0.931	0.909	0.916	0.970	0.968
	NBFNet	0.956	0.962	0.923	0.936	0.983	0.982

Results

- Inductive relation prediction

Class	Method	FB15k-237				WN18RR			
		v1	v2	v3	v4	v1	v2	v3	v4
Path-based	NeuralLP [16]	0.529	0.589	0.529	0.559	0.744	0.689	0.462	0.671
	DRUM [46]	0.529	0.587	0.529	0.559	0.744	0.689	0.462	0.671
	RuleN [39]	0.498	0.778	0.877	0.856	0.809	0.782	0.534	0.716
GNNs	GraIL [55]	0.642	0.818	0.828	0.893	0.825	0.787	0.584	0.734
	NBFNet	0.834	0.949	0.951	0.960	0.948	0.905	0.893	0.890

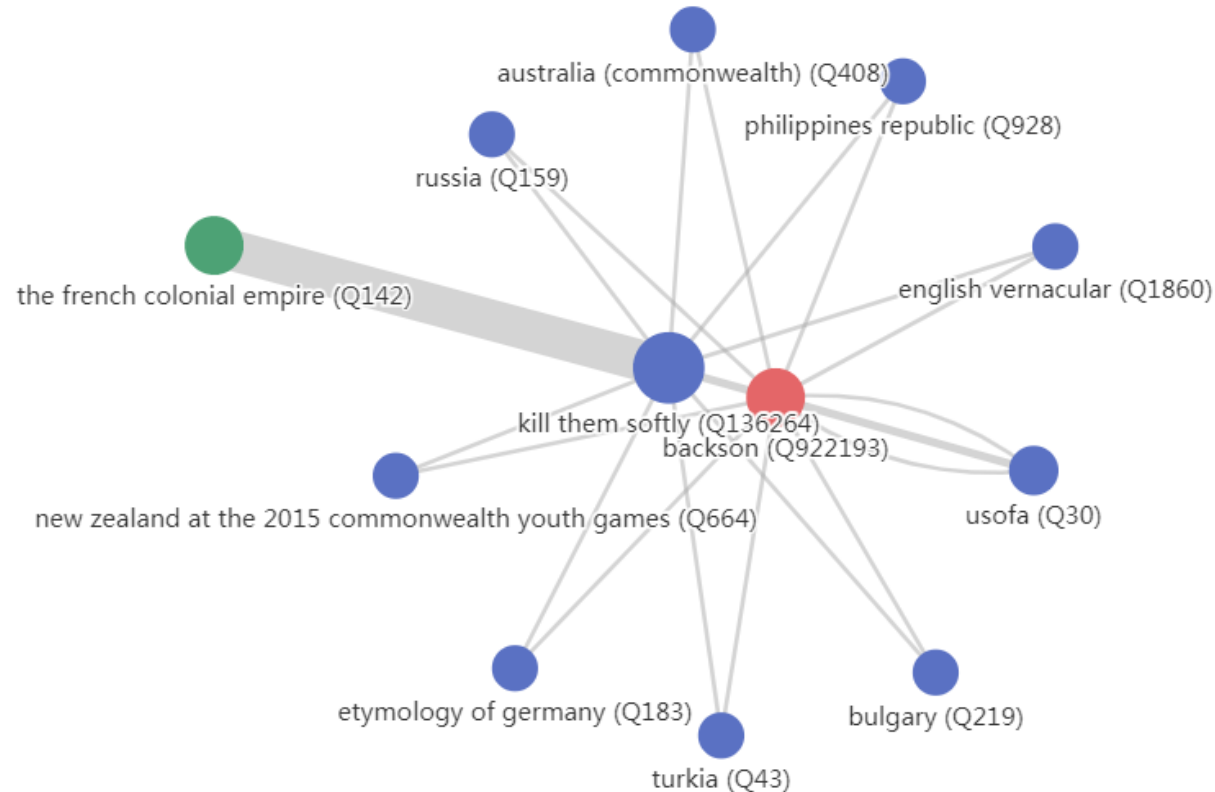
Interpretation

- FB15k-237

Query	$\langle O. Hardy, nationality, U.S. \rangle$
0.243	$\langle O. Hardy, impersonate^{-1}, R. Little \rangle \wedge \langle R. Little, nationality, U.S. \rangle$
0.224	$\langle O. Hardy, ethnicity^{-1}, Scottish American \rangle \wedge \langle Scottish American, distribution, U.S. \rangle$
Query	$\langle Florence, vacationer, D.C. Henrie \rangle$
0.251	$\langle Florence, contain^{-1}, Italy \rangle \wedge \langle Italy, capital, Rome \rangle \wedge \langle Rome, vacationer, D.C. Henrie \rangle$
0.183	$\langle Florence, place live^{-1}, G.F. Handel \rangle \wedge \langle G.F. Handel, place live, Rome \rangle \wedge \langle Rome, vacationer, D.C. Henrie \rangle$
Query	$\langle Pearl Harbor (film), language, Japanese \rangle$
0.211	$\langle Pearl Harbor (film), film actor, C.-H. Tagawa \rangle \wedge \langle C.-H. Tagawa, nationality, Japan \rangle$ $\wedge \langle Japan, country of origin, Yu-Gi-Oh! \rangle \wedge \langle Yu-Gi-Oh!, language, Japanese \rangle$
0.208	$\langle Pearl Harbor (film), film actor, C.-H. Tagawa \rangle \wedge \langle C.-H. Tagawa, nationality, Japan \rangle$ $\wedge \langle Japan, official language, Japanese \rangle$

Interpretation

- $p(\text{France} \mid \text{Winnie the Pooh, release region})$



<https://deepgraphlearning.github.io/project/reasoning>

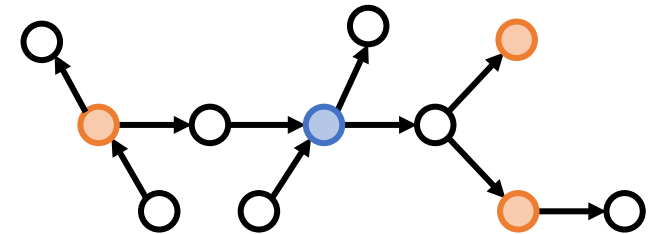
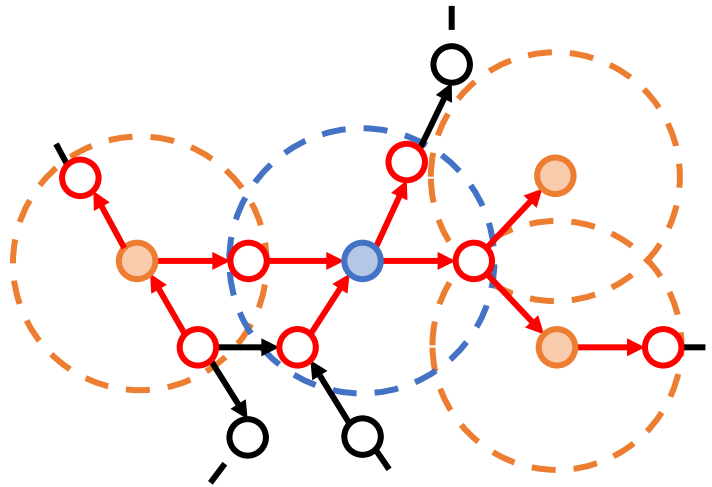
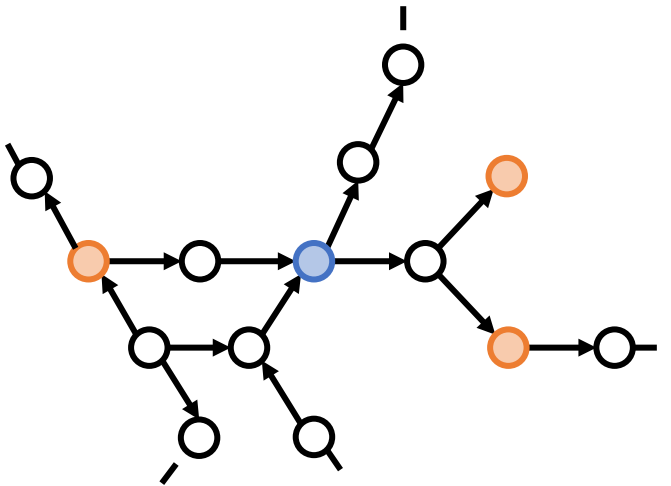


@ KDD Cup 2021

- Setting
 - Rank 1 positive tail entity against 1000 negative tail entities
- Dataset: 90M entity, 1.3K relation, 0.5B triplets
 - 0.5B triplets = 12GB memory
 - Impossible to train such a large graph on GPUs
- How to scale up NBFNet?
 - Sample small graphs like other inductive GNNs

Bi-directional BFS sampling

- Intuition: long paths are not important for prediction
 - Sample nodes and edges that can be reached by BFS
 - Randomly down sample nodes with large neighborhoods
 - Bi-directional BFS to further reduce the size





- Results (MRR)
 - Single model: valid: 0.9237
 - Ensemble of 6 models: valid: 0.9304, test: 0.9178
- Rank 12 out of 39 teams, but ...
 - Stronger than all single models reported by the winner
 - Probably the most parameter efficient

Summary

- Generalize/transfer to unseen graphs with the same semantics
- Interpret predictions via top weighted paths
- Scalable compared to path-based methods and GNNs
- Super parameter efficient compared to popular embedding methods
- Verified on several link prediction tasks and datasets
- Verified in OGB large scale competition (rank 12 out of 39 teams)
- Code at: <https://github.com/DeepGraphLearning/NBFNet>

Thanks for your attention!

- Q & A