from IPython.display import display, HTML display(HTML("<style>.container { width:85% !important; }</style>")) ## Standard libraries import os import math import time import numpy as np import random import copy ## Scikit-learn built-in dataset generator from sklearn.datasets import make blobs ## Progress bar import tqdm ## Imports for plotting import matplotlib.pyplot as plt import matplotlib.animation as animation %matplotlib inline import matplotlib matplotlib.rcParams['lines.linewidth'] = 2.0 plt.style.use('ggplot') ## Useful for creating GIFs import imageio ## PyTorch import torch import torchvision # Function for setting the seed def set seed(seed): random.seed(seed) np.random.seed(seed) torch.manual_seed(seed) if torch.cuda.is_available(): torch.cuda.manual_seed(seed) torch.cuda.manual_seed_all(seed) set_seed(42) # Ensure that all operations are deterministic on GPU (if used) for reproducibility torch.backends.cudnn.determinstic = True torch.backends.cudnn.benchmark = False # device to be used for Parts II-IV is preferably a GPU # try to change the runtime type to GPU if you can in Google Colab device = torch.device("cuda:0") if torch.cuda.is_available() else torch.device("cpu") print("Using device", device) Using device cuda:0 In [4]: # the next lines define the architecture of the model and its functionality in forward path # (e.g how it operates when inputting an image) class ResNet(torch.nn.Module): def __init__(self, n_channels): super().__init__() {'n channels': 16, 'n blocks': 2, 'downsample': False}, {'n_channels': 32, 'n_blocks': 2, 'downsample': True}, {'n channels': 64, 'n blocks': 2, 'downsample': True}, {'n channels': 64, 'n blocks': 2, 'downsample': True}, self. el = torch.nn.ModuleDict() self. el['in conv'] = torch.nn.Conv2d(n_channels, 16, kernel_size=3, padding=3) n channels = 16levels = torch.nn.ModuleList() for level params in levels params: level = torch.nn.ModuleDict() res blocks = torch.nn.ModuleList() ## The first residual block in the level res block = torch.nn.ModuleDict() n channels out = level params['n channels'] if level params['downsample']: res block['shortcut conv'] = torch.nn.Conv2d(n channels, n channels out, kernel size=2, stride= res block['shortcut conv'] = torch.nn.Conv2d(n channels, n channels out, kernel size=1) res_block['conv_1'] = torch.nn.Conv2d(n_channels, n_channels_out, kernel_size=3, padding=1) n channels = n channels out if level params['downsample']: res block['conv 2'] = torch.nn.Conv2d(n channels, n channels, kernel size=4, stride=2, padding= res block['conv 2'] = torch.nn.Conv2d(n channels, n channels, kernel size=3, stride=1, padding= res_blocks.append(res_block) ## The rest of the residual blocks in the level for in range(level params['n blocks'] - 1): res block = torch.nn.ModuleDict() res block['conv 1'] = torch.nn.Conv2d(n channels, n channels, kernel size=3, padding=1) res_block['conv_2'] = torch.nn.Conv2d(n_channels, n_channels, kernel_size=3, padding=1) res blocks.append(res block) level['res blocks'] = res blocks levels.append(level) self. el['levels'] = levels self. el['out fc'] = torch.nn.Linear(n channels, 1, bias=False) for module in self.modules(): if isinstance(module, torch.nn.Conv2d): torch.nn.init.xavier uniform (module.weight, gain=2 ** 0.5) if module.bias is not None: module.bias.data.zero () # functionality when inputting image x to the model: def forward(self, x): x = self._el['in_conv'](x) for level in self. el['levels']: for res_block in level['res_blocks']: shortcut = x x = torch.nn.functional.leaky_relu(x, 0.2) x = res block['conv 1'](x) $x = torch.nn.functional.leaky_relu(x, 0.2)$ x = res block['conv 2'](x)if 'shortcut conv' in res block: shortcut = res block['shortcut conv'] (shortcut) x = x + shortcutx = torch.nn.functional.leaky relu(x, 0.2)x = x.view(x.shape[0], x.shape[1], -1).sum(dim=2)x = self. el['out fc'](x)return x[:, 0] # instantiate the class above for images with 1 channel and load it to the device (CPU/GPU) ebm = ResNet(n_channels=1).to(device) # transfer the model to evaluation mode (as we don't want to train it, just to use it) # load the trained model weights/parameters from the checkpoint file checkpoint_path = 'checkpoint.pt' ebm.load_state_dict(torch.load(checkpoint_path, map_location=device)) Out[5]: <All keys matched successfully> def show_random_imgs(imgs, title, width=4, height=2, figsize=(14,7), all_idx=False): N = imgs.shape[0]if all idx: indices = list(range(0,30))indices = np.random.choice(N, size=N, replace=False) fig, axes = plt.subplots(height, width, figsize=figsize, sharex=True, sharey=True) for i in range(width * height): m = i%width n = i//widthaxes[n,m].imshow(to_np(imgs[indices[i]][0]), cmap='gray') fig.suptitle(title, fontsize=40) plt.show() def to np(x): return x.clone().cpu().detach().numpy() noisy_digits_25 = torch.load('noisy_digits_25_new.pt').to(device).requires_grad_(True) noisy_digits_50 = torch.load('noisy_digits_50_new.pt').to(device).requires_grad_(True) show_random_imgs(imgs=noisy_digits_25, title='Data Imgs with sigma=25/256', width=6, height=5, all_idx=True, Data Imgs with sigma=25/256 show_random_imgs(imgs=noisy_digits_50, title='Data Imgs with sigma=50/256', width=6, height=5, all_idx=True, fi Data Imgs with sigma=50/256 0 0 def perceptual denoising(imgs, K=2000, factored epsilon = 2/256, sigma=50/256): y = torch.clone(imgs).to(device) x = torch.clone(imgs).to(device).requires grad (True) energy = ebm(imgs)grad ebm = -torch.autograd.grad(energy.sum(), imgs)[0] epsilon = (factored epsilon ** 2) / 2 for k in tqdm.tqdm(range(K)): grad = (y - x)/(sigma**2) + grad ebmnoise = torch.randn(imgs.shape).to(device) x = x + epsilon * grad + factored epsilon * noiseenergy = ebm(x)grad ebm = -torch.autograd.grad(energy.sum(), x)[0] return x 1 = []for n in range (30): for i in range(6): for j in range(6): 1.append((noisy digits 25[n][0][27-i][27-j]).item()) print('estimated sigma by bottom left corner of noisy_digits_25: ', str(np.round(np.array(1).std() * 256,1))+', 1 = []for n in range (30): for i in range(6): for j in range(6): 1.append((noisy_digits_50[n][0][27-i][27-j]).item()) print('estimated sigma by bottom left corner of noisy_digits_50: ', str(np.round(np.array(1).std() * 256,1))+' estimated sigma by bottom left corner of noisy digits 25: 24.9/256 estimated sigma by bottom left corner of noisy digits 50: 49.2/256 img_25_de = perceptual_denoising(imgs=noisy_digits_25, K=2000, factored_epsilon=2/256, sigma=(25/256)) 2000/2000 [00:40<00:00, 4 show_random_imgs(imgs=img_25_de, title='Data Imgs with sigma=25/256, Denoised', width=6, height=5, all idx=True Data Imgs with sigma=25/256, Denoised 4829 1525 2007 4 5 8 img_50_de = perceptual_denoising(imgs=noisy_digits_50, K=2000, factored_epsilon=2/256, sigma=(50/256)) 2000/2000 [00:46<00:00, 4 show_random_imgs(imgs=img_50_de, title='Data Imgs with sigma=50/256, Denoised', width=6, height=5, all idx=True Data Imgs with sigma=50/256, Denoised 482 0 In [24]: def mmse(imgs, N=10, K=2000, factored epsilon=2/256, sigma=50/256): res = torch.zeros(imgs.shape).to(device) for n in range(N): res += perceptual_denoising(imgs, K=K, factored_epsilon = factored_epsilon, sigma=sigma) return res / N clean = mmse(imgs=noisy_digits_50, K=2000, N=10, sigma=50/256) 100%| 2000/2000 [00:39<00:00, 5 2000/2000 [00:50<00:00, 3 9.72it/s1 100%| 2000/2000 [00:46<00:00, 4 2.73it/s] 2000/2000 [00:37<00:00, 5 2000/2000 [00:38<00:00, 5 2.45it/s2000/2000 [00:39<00:00, 5 0.87it/s2000/2000 [00:40<00:00, 4 100%| 8.89it/s] 2000/2000 [00:36<00:00, 5 2000/2000 [00:42<00:00, 4 7.50it/s] 100%| 2000/2000 [00:37<00:00, 5 3.35it/s] show random imgs(imgs=clean, title='Data Imgs with sigma=100/256, Denoised', width=6, height=5, figsize=(10,10) Data Imgs with sigma=100/256, Denoised **Discussion:** While the denoising of the $\sigma = \frac{25}{256}$ performed with no significats flaws, the case with $\sigma = \frac{50}{256}$ distorted the digits somewhat. With the usage of the mmse the results was improved and the distortions was mitigated.

