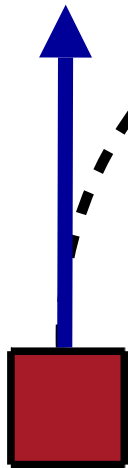
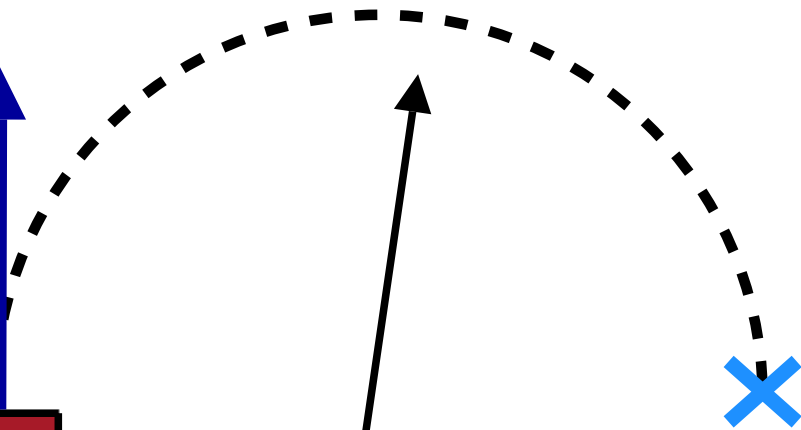


orientacja robota



robot



cel

nieoptymalna
trajektoria