EPITECH. TECHNOLOGY

B-CPE-200 : Lem-in

Projects

B-CPE-200 - Projects

B-CPE-200 : 20/02/23 - 04/06/23 **: 9 crédits**

Dante

Maze generation and resolution

1 – 2p
3 weeks

Lemin

Pathfinding and optimization algorithm

3 – 4p
4 weeks

Corewar

Simulation of combat in memory via a virtual machine

3 – 4p
5 weeks

Each project assesses these skills:

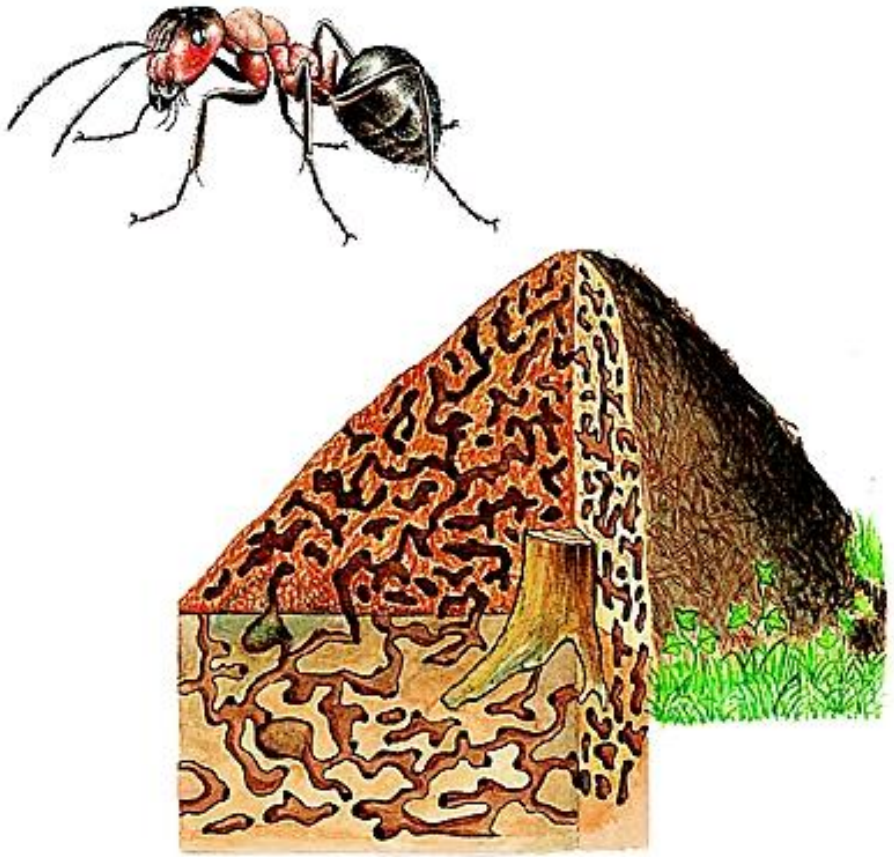
Algorithm	**Data structure**	**Parsing**	**Optimization**	**Robustness**

Lem-in

B-CPE-200 – Lem-in

Lem-in

The goal of Lem-in is to work on pathfinding algorithms. The goal is not necessarily to manage the distance but rather the simultaneous occupation of the rooms.



B-CPE-200 – Pathfinding

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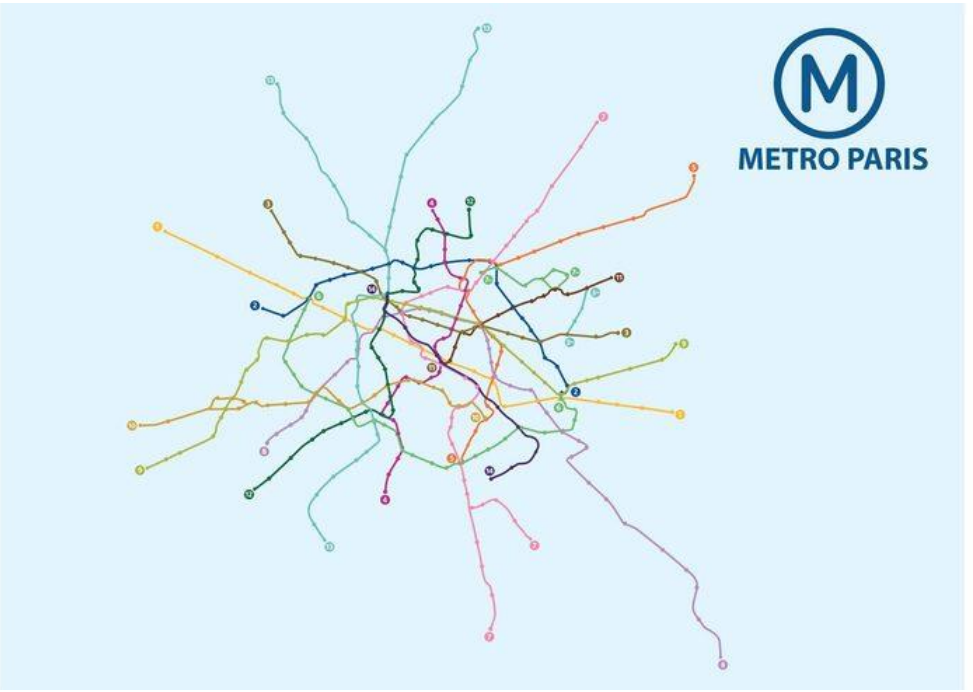
Why ?

- Usefull for many projects (who said moves in video games ?)
- Pathfinding is everywhere (google maps, waze, subway network)



B-CPE-200 – Graphs

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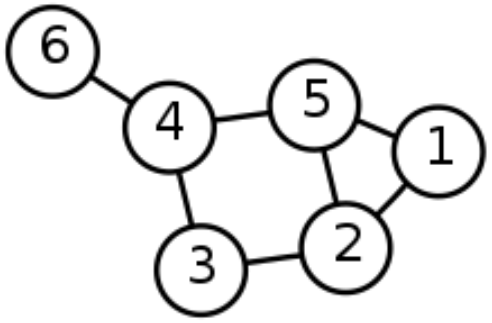
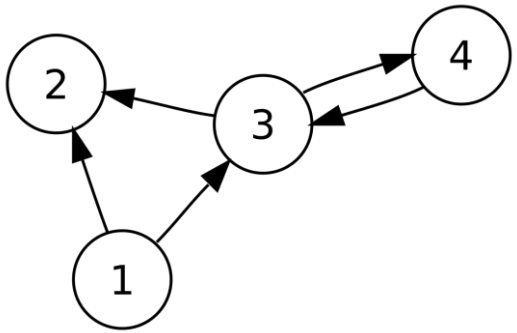
How to

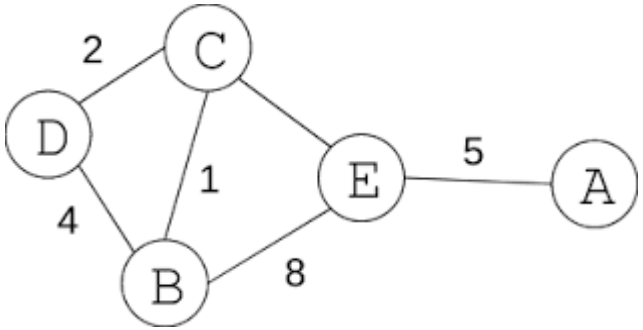
The solution of this kind of problem is feasible by applying graph theory



Graph



Oriented Graph



Weighted graph

B-CPE-200 – Graphs

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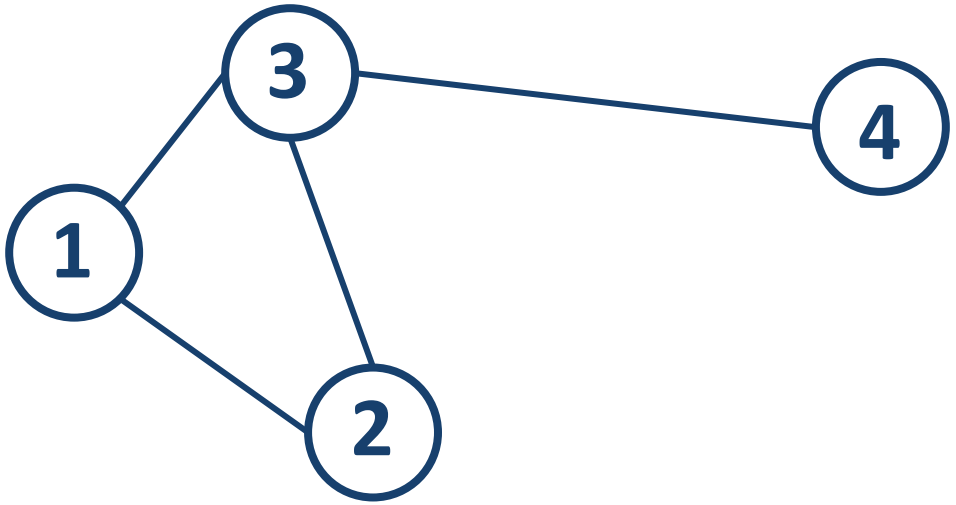
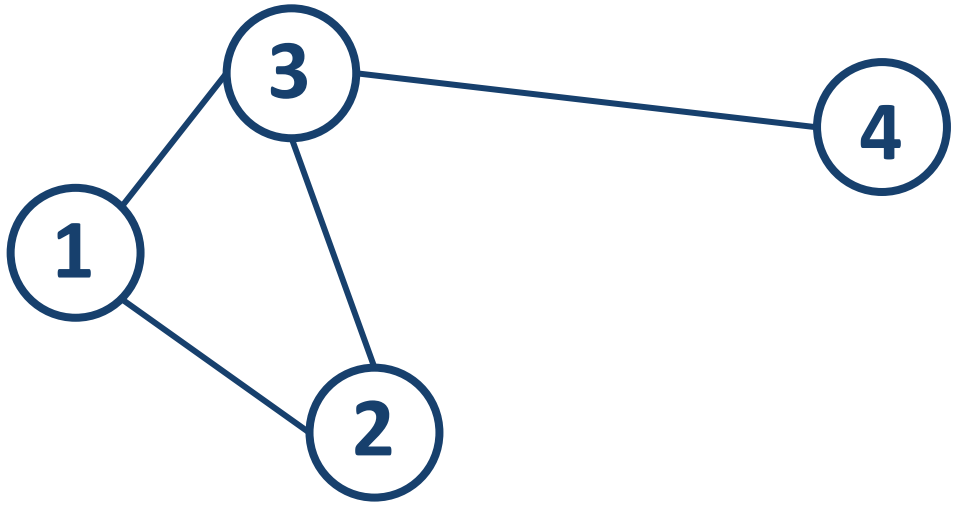


There are 2 ways to represent our graph in C :

- Linked lists
- Adjacency matrix

B-CPE-200 – Linked lists



B-CPE-200 – Linked lists

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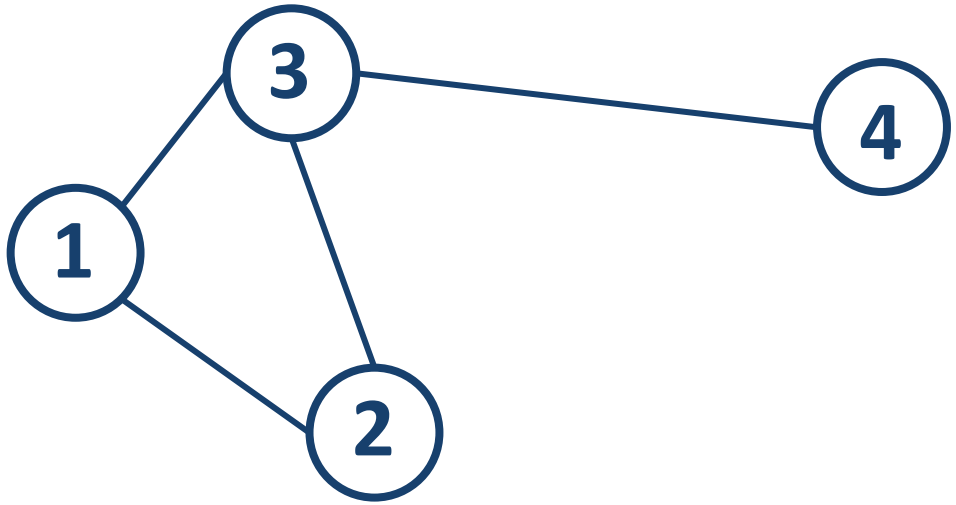
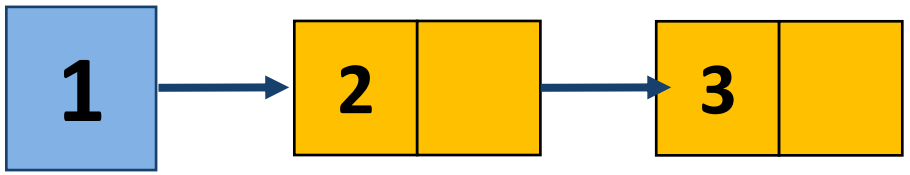
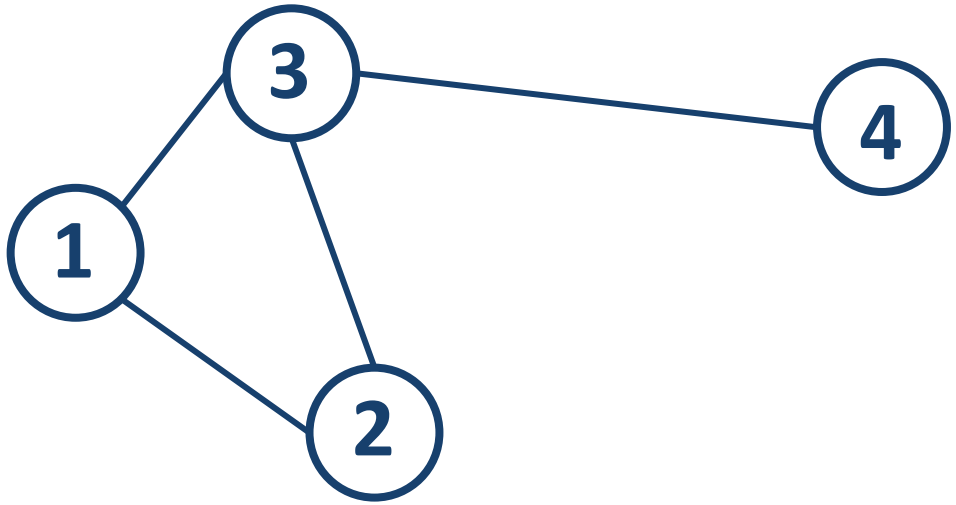
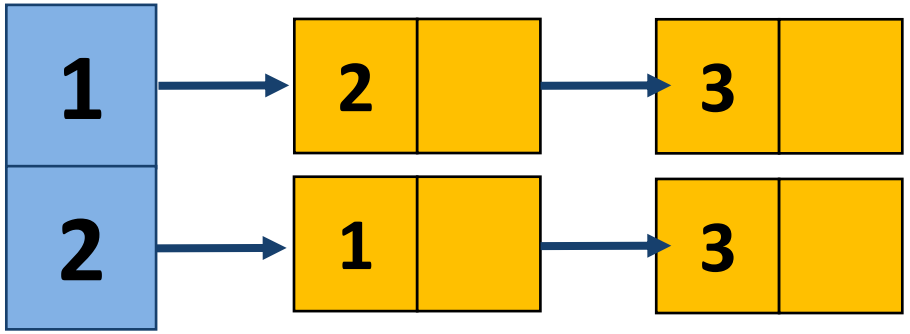




B-CPE-200 – Linked lists





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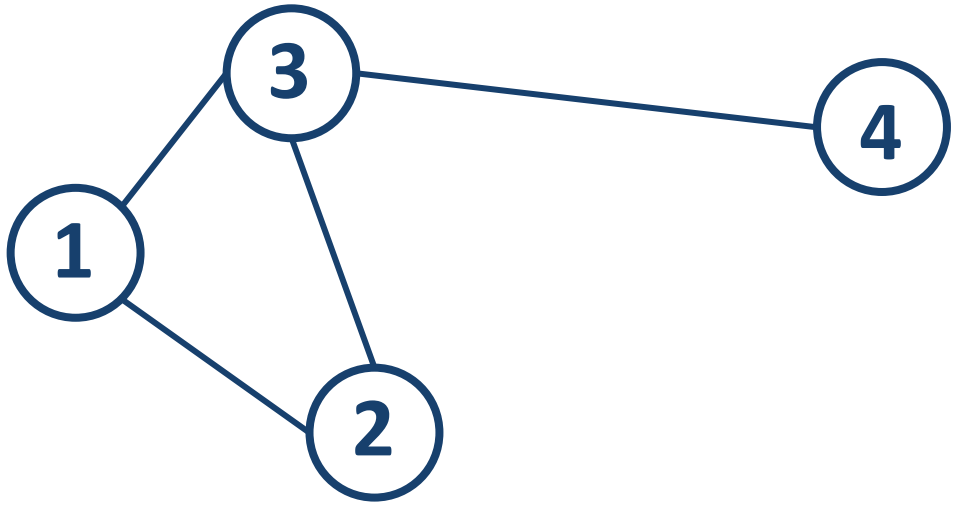
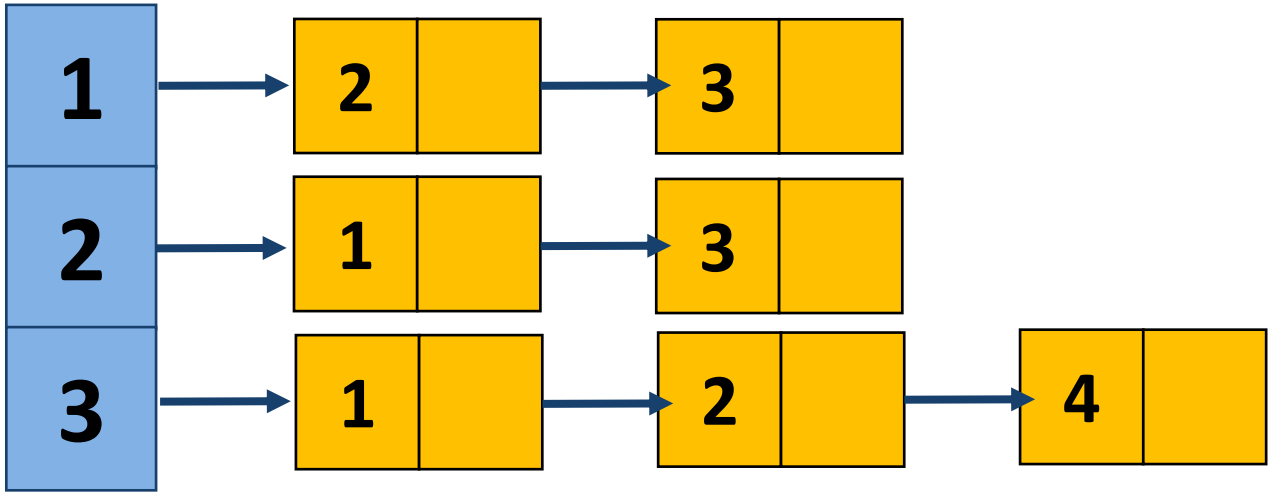
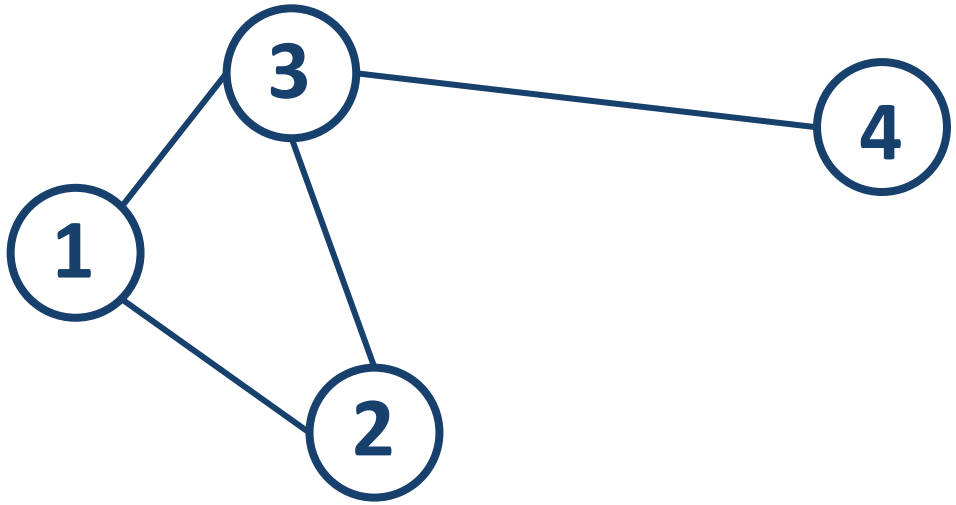
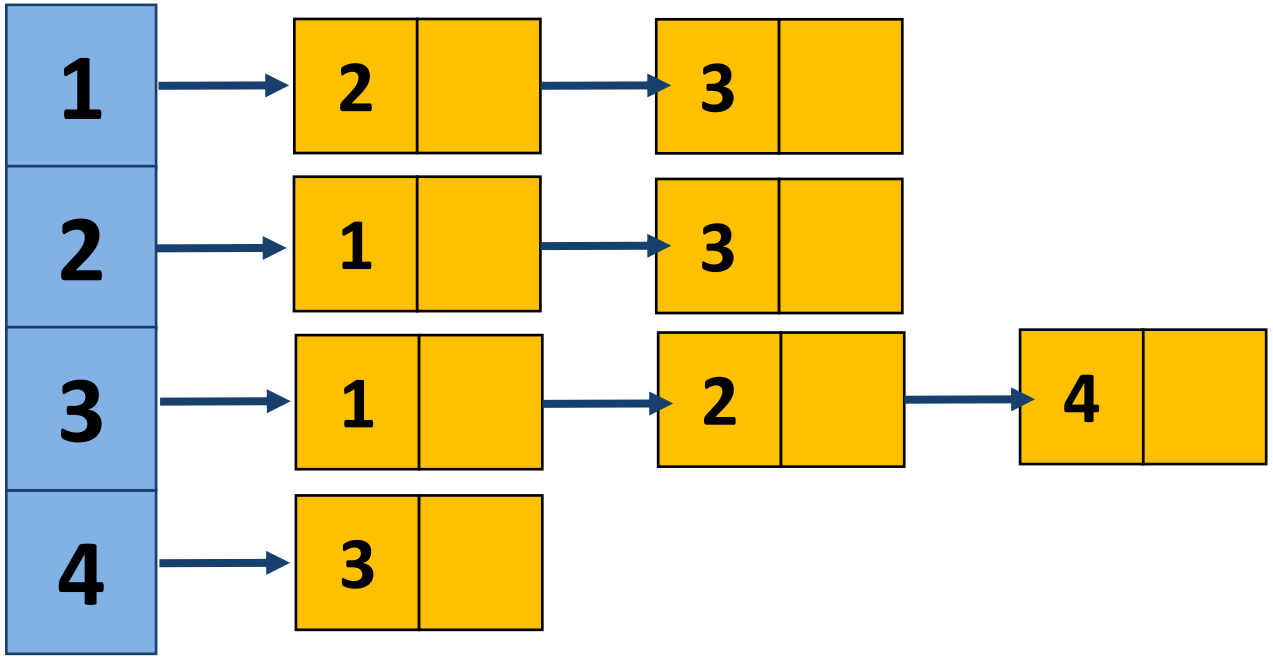




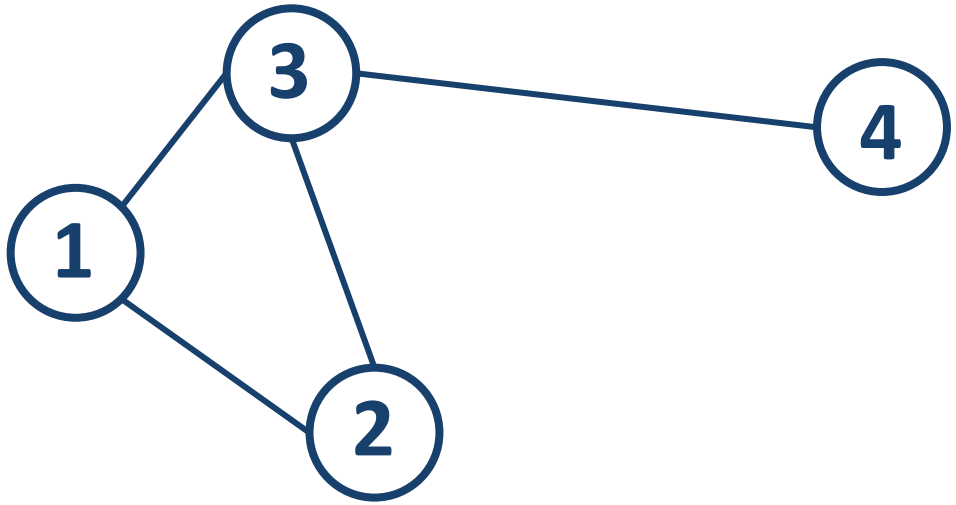
B-CPE-200 – Linked lists





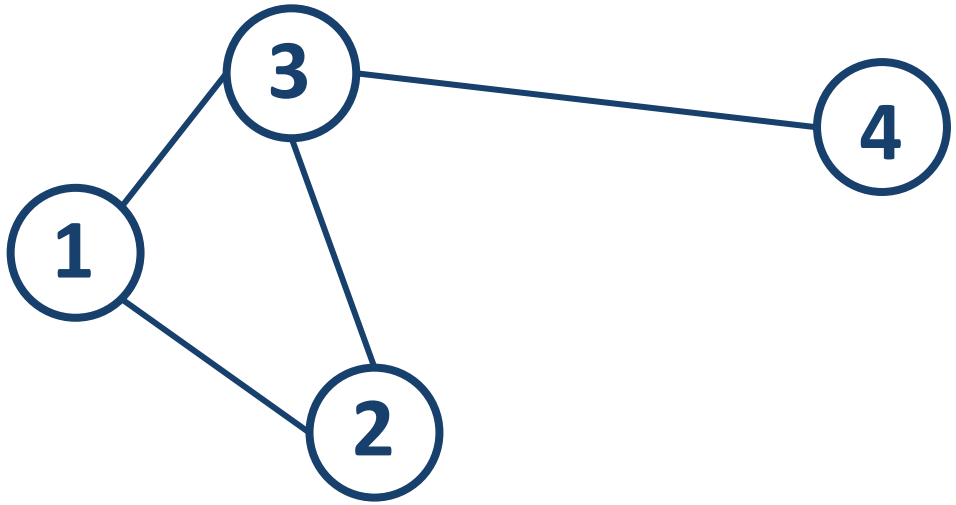
B-CPE-200 – Adjacency matrix

EPITECH. TECHNOLOGY



	1	2	3	4
1	0	0	0	0
2	0	0	0	0
3	0	0	0	0
4	0	0	0	0

B-CPE-200 – Adjacency matrix



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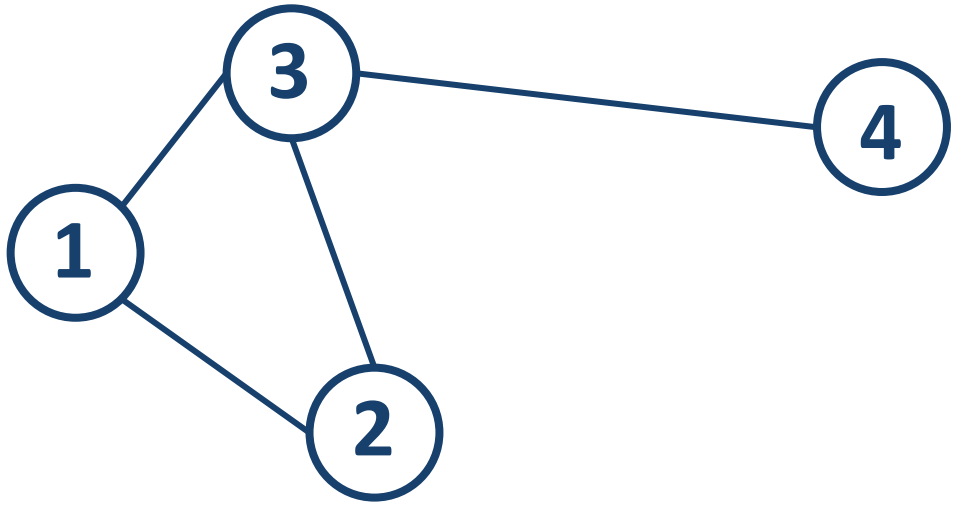
B-CPE-200 – Adjacency matrix

EPITECH. TECHNOLOGY



	1	2	3	4
1	0	1	1	0
2	1	0	1	0
3	1	1	0	1
4	0	0	1	0

Config

B-CPE-200 – Config

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Terminal

```
~/B-CPE-200> cat anthill
3
##start
0 1 0
##end
1 13 0 #bedroom
2 5 0
# The next room is the kitchen
3 9 0
0-2
2-3
3-1
```

Ants number.

Rooms :
The rooms have a name **(alpha-numeric)** and a position (the position is not important).
There is a ##start and an ##end room.

There can be comments anywhere

Tunnels :
The tunnels are links between each room.

B-CPE-200 – Config

EPITECH. TECHNOLOGY

Terminal

```
~/B-CPE-200> ./lem_in < anthill
#number_of_ants
3
#rooms
##start
0 1 0
##end
1 13 0
2 5 0
3 9 0
#tunnels
0-2
2-3
3-1
#moves
P1-2
P1-3 P2-2
P1-1 P2-3 P3-2
P2-1 P3-3
P3-1
```

Config display :
"#number_of_ants", "#rooms", "tunnels" are added and comments are removed for clarity.

Solution :
We display at each "**tick**" the movement of the ants with **Pn-r (n: the ant, r: the room)**

The **Parsing** skill is an important part of the project

Pathfinding is the most important skill of the project

Be careful about the **Error Management**

A "tick" represents the ability of each ant to move one square

B-CPE-200 – Example

EPITECH. TECHNOLOGY

Terminal

```
~/B-CPE-200> ./lem_in < anthill
#number_of_ants
3
#rooms
##start
0 1 0
##end
1 13 0
2 5 0
3 9 0
#tunnels
0-2
2-3
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#moves
P1-2
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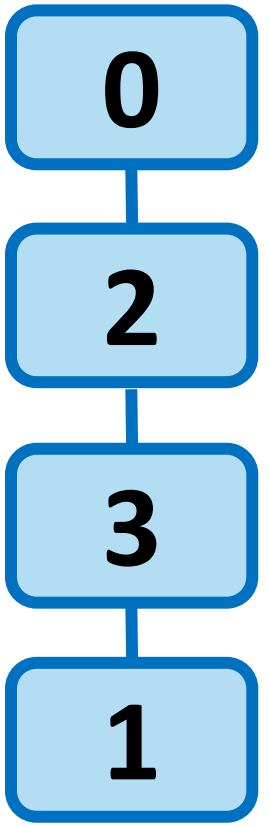

B-CPE-200 – Example

EPITECH. TECHNOLOGY

Terminal

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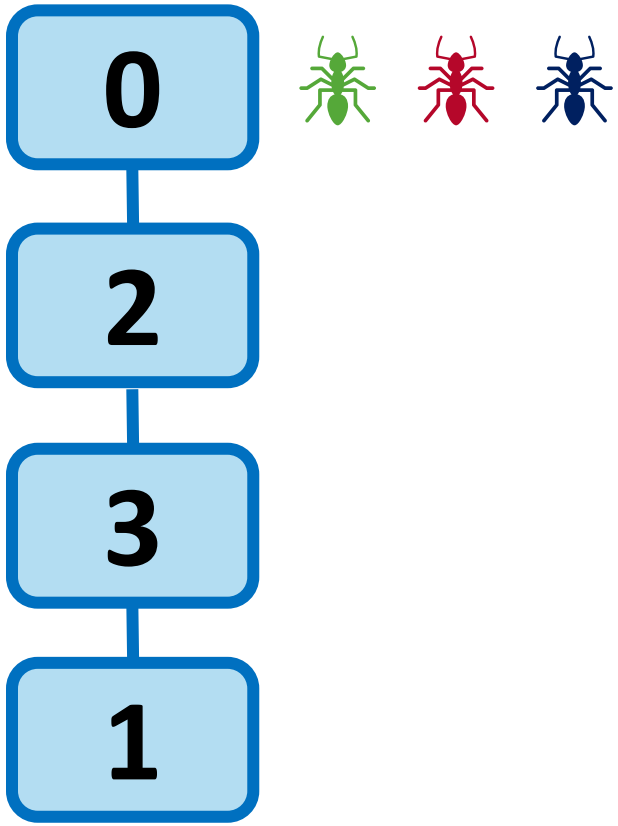

B-CPE-200 – Example

EPITECH. TECHNOLOGY

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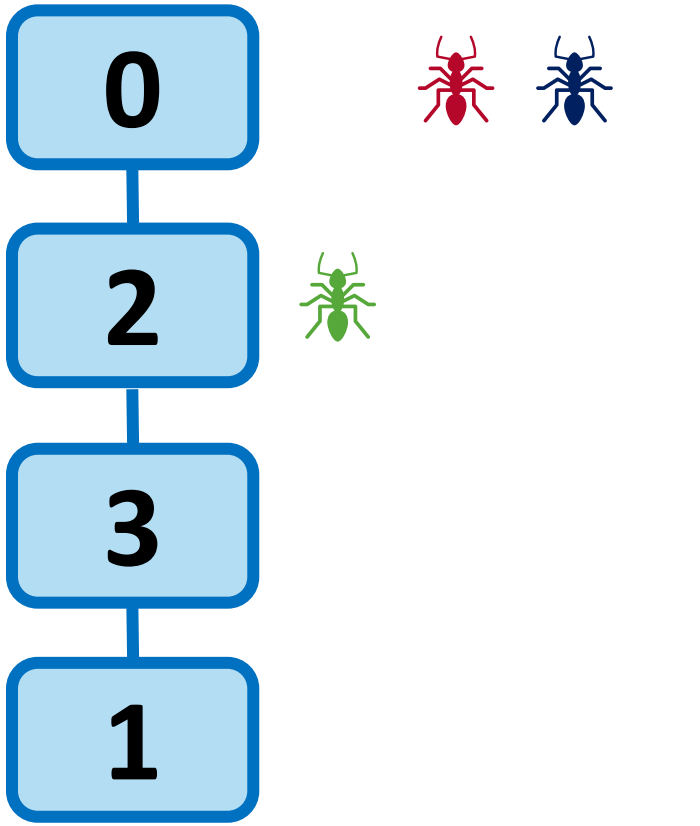
```

P1-2



B-CPE-200 – Example

EPITECH. TECHNOLOGY

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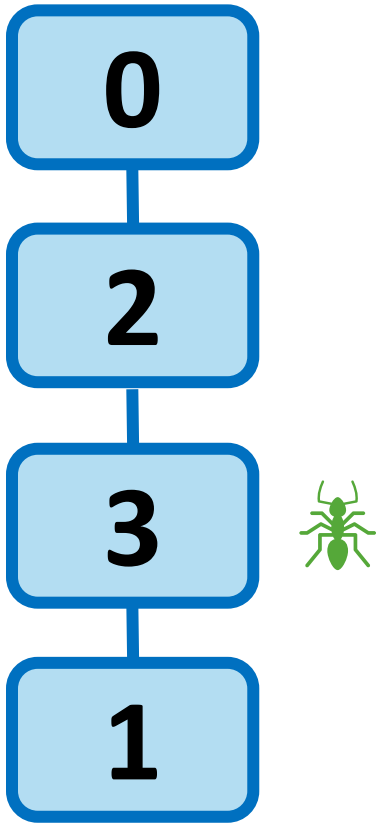
```

P1-3, P2-2



B-CPE-200 – Example

EPITECH. TECHNOLOGY

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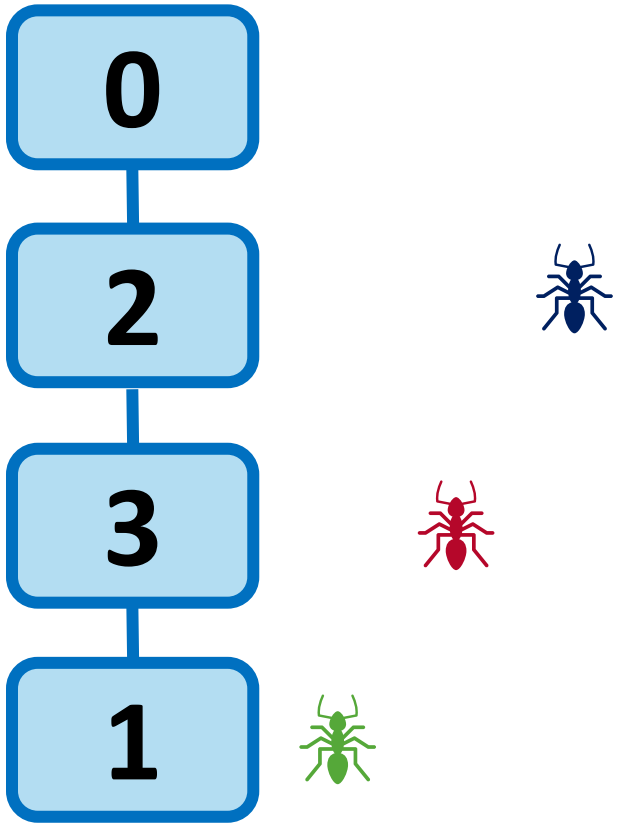
P1-1, P2-3, P3-2



B-CPE-200 – Example

EPITECH. TECHNOLOGY

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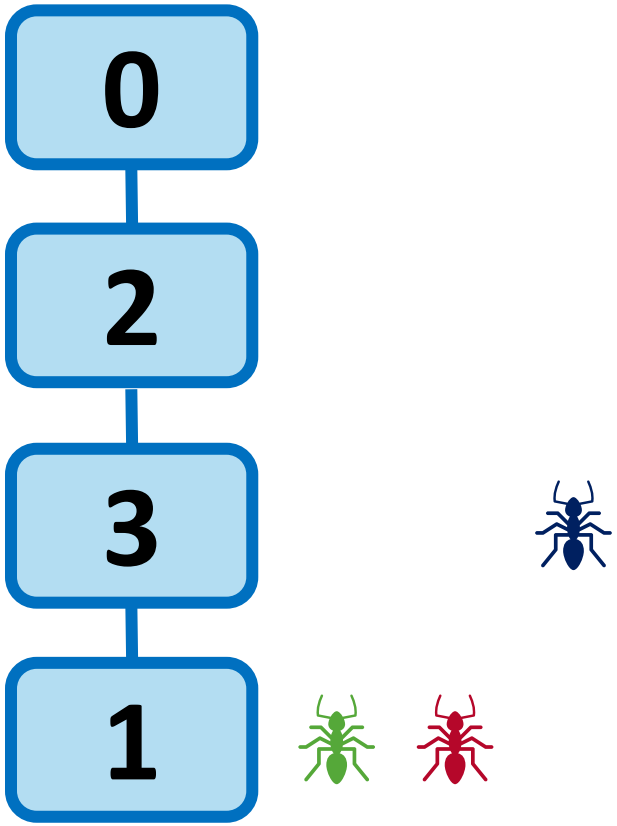
```

P2-1, P3-3



B-CPE-200 – Example

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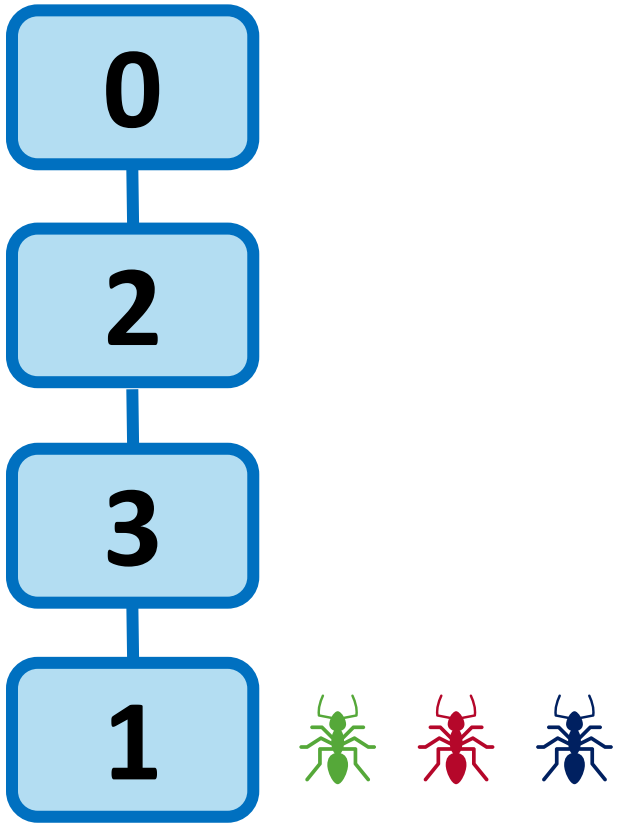
P3-1
```

P3-1



B-CPE-200 – Lem-in

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What skills are evaluated?

Algorithm	**Data structure**	Parsing	Optimization	Robustness
Path finding algorithm	Graph application (adjacency matrix)	Yes	Ability to pass many ants	Error handling

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Questions ?