

# Math 174E

## Lecture 14

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# References



Hull

Chapter 13.7, 13.8, 13.9

# Increasing the Number of Steps

- ▶ one or two stock price movements during the life of an option are not very realistic
- ▶ when binomial trees are used in practice one can use a much higher numbers of steps (or, equivalently, a smaller step size  $\Delta t = \frac{T}{N}$ )
  - ▶  $N$  steps =  $N + 1$  terminal stock price values  $S_T$
  - ▶  $2^N$  possible trajectories
- ▶ risk-neutral valuation approach for computing arbitrage-free stock option prices as in the one- and two-step trees still applies and holds true

Binomial tree formulas:  $S_0, r, T, \Delta t, \sigma$  are given parameters

$$u = e^{\sigma\sqrt{\Delta t}}, \quad d = e^{-\sigma\sqrt{\Delta t}}, \quad p^* = \frac{e^{r\Delta t} - d}{u - d}$$

# Mathematical Comments 1/4

Binomial tree model = **Cox-Ross-Rubinstein model (1979)**

- ▶ simplest multi-period financial market model
- ▶ *discrete time* model for the stock price  $(S_n)_{n=0,\dots,N}$
- ▶ split the time interval  $[0, T]$  into  $N$  equidistant time steps of size  $\Delta t = \frac{T}{N}$

$$S_n = S_0 \cdot \prod_{i=1}^n R_i, \quad R_i = \begin{cases} u & \text{prob. } p^* \\ d & \text{prob. } 1 - p^* \end{cases} \quad \text{i.i.d.} \quad (1)$$

for all  $n = 1, \dots, N$

- ▶ we have

$$\mathbb{P}^*[S_n = S_0 \cdot u^j \cdot d^{n-j}] = \binom{n}{j} \cdot (p^*)^j \cdot (1 - p^*)^{n-j}$$

for all  $n = 1, \dots, N$  and  $j = 1, \dots, n$  (**binomial distribution**)

## Mathematical Comments 2/4

- risk-neutral European call option pricing formula

$$\begin{aligned}C_0(K, T) &= \mathbb{E}^*[e^{-rT}(S_N - K)^+] \\&= e^{-rT} \sum_{j=0}^N (S_0 u^j d^{N-j} - K)^+ \cdot \mathbb{P}^*[S_N = S_0 u^j d^{N-j}] \\&= e^{-rT} \sum_{j=0}^N (S_0 u^j d^{N-j} - K)^+ \cdot \binom{N}{j} \cdot (p^*)^j \cdot (1 - p^*)^{N-j} \\&= e^{-rT} \sum_{j=0}^N (S_0 u^j d^{N-j} - K)^+ \cdot \frac{N!}{(N-j)! j!} \cdot (p^*)^j \cdot (1 - p^*)^{N-j}\end{aligned}$$

(compare with formula in Theorem 13.3 for  $N = 1$  and in Theorem 13.5 for  $N = 2$  )

- similar for European put options and any other European option with payoff function  $h(S_N)$  (e.g., power option, binary option etc.)

## Mathematical Comments 3/4

- note that we obtain from (1)

$$\log\left(\frac{S_n}{S_0}\right) = \sum_{i=1}^n \underbrace{\log(R_i)}_{=L_i}$$

where

$$L_i = \begin{cases} \log(u) > 0 & \text{prob. } p^* \\ \log(d) < 0 & \text{prob. } 1 - p^* \end{cases} \quad \text{i.i.d.}$$

- hence, we can write the evolution of the stock price process  $(S_n)_{n=0,\dots,N}$  as

$$S_n = S_0 e^{\sum_{i=1}^n L_i}$$

- a process of the form  $X_n = \sum_{i=1}^n L_i$  with i.i.d. increments  $L_1, L_2, \dots, L_n$  which take only two values (positive and negative, respectively) is called a **simple random walk**

## Mathematical Comments 4/4

- ▶ under suitable technical assumptions one can show via the **Central Limit Theorem** that

$$\text{distribution of } \log \left( \frac{S_N}{S_0} \right) \xrightarrow{N \uparrow \infty} \mathcal{N} \left( \left( r - \frac{\sigma^2}{2} \right) T, \sigma^2 T \right)$$

- ▶ here  $\mathcal{N}((r - \sigma^2/2)T, \sigma^2 T)$  denotes the **normal distribution** with **mean** parameter  $(r - \sigma^2/2)T$  and **variance** parameter  $\sigma^2 T$
- ▶ this leads to the continuous time **Black-Scholes-Merton model (1973)** in the limit as the step size  $\Delta t = \frac{T}{N}$  converges to 0 when the number of steps  $N$  goes to  $+\infty$
- ▶ in particular, an **option price** computed in the binomial tree model converge to the **Black-Scholes-Merton price** as the number of time steps  $N$  goes to  $+\infty$  (see Appendix of Chapter 13 in Hull for a non-rigorous proof)

# Chapter 14: Wiener Processes and Itô's Lemma



Hull

Chapter 14.1, 14.2



# Preliminaries

## Definition 14.1

A **stochastic process** (random process) is a collection of random variables  $(S_t)_{t \in I}$  with index set  $I$ , taking values in a state space  $\mathcal{S}$ .

Typically: index  $t$  represents time!

- ▶  $I = \{0, 1, 2, \dots\}$ : discrete time
- ▶  $I = [0, +\infty)$ : continuous time

State space:

- ▶  $\mathcal{S} \subseteq \mathbb{N}$ : “discrete” random variables
- ▶  $\mathcal{S} \subseteq \mathbb{R}$ : “continuous” random variables

Most important examples:

- ▶ discrete time: **random walk**
- ▶ continuous time: **Brownian motion**

# Markov Process

A very informal definition:

## Definition 14.2

A **Markov process** is a particular type of stochastic process where the future evolution of the process only depends on its current value but not on the past.

Most important examples of Markov processes:

- ▶ discrete time: **random walk**
- ▶ continuous time: **Brownian motion**

Stock prices are assumed to follow a Markov process

- ▶ consistent with the weak form of “market efficiency” (current price of a stock impounds all relevant information)

# Brownian Motion

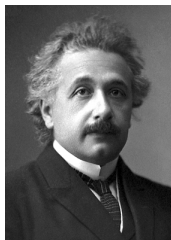
**Brownian motion:** Continuous-time, continuous-state stochastic process, also called the **Wiener process**.

Some history:

- ▶ 1827: Botanist ROBERT BROWN observed pollen grains suspended in water, noted the erratic and continuous movement of tiny particles ejected from the grains.
- ▶ 1905: ALBERT EINSTEIN gave a theoretical explanation for this physical phenomenon (atomic nature of matter) and introduced the Brownian motion.
- ▶ 1923: American mathematician NORBERT WIENER rigorously proved the existence of the Brownian Motion.
- ▶ 1900: French mathematician LOUIS BACHELIER is credited with being the first person to introduce a mathematical model of Brownian motion; used it for valuing stock options in his PhD thesis (forefather of financial mathematics).

## Some History

Robert Brown (1773 – 1858), Albert Einstein (1879 – 1955),  
Norbert Wiener (1894 – 1964), Louis Bachelier (1870 – 1946).



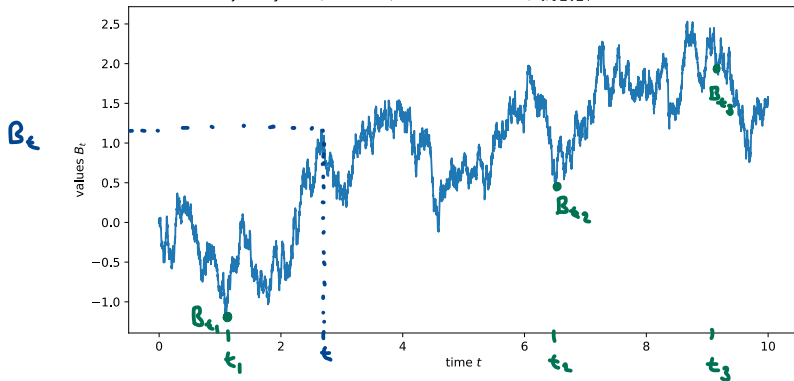
Source of pictures: Wikipedia.

# Illustration: Brownian Motion on $\mathbb{R}$

$$B_t \sim N(0, t) : \mathbb{E}[B_t] = 0, \text{Var}(B_t) = t$$

$t \mapsto B_t$  continuous

Trajectory of a (Standard) Brownian Motion  $(B_t)_{0 \leq t \leq T}$  on  $\mathbb{R}$  with  $T = 10$

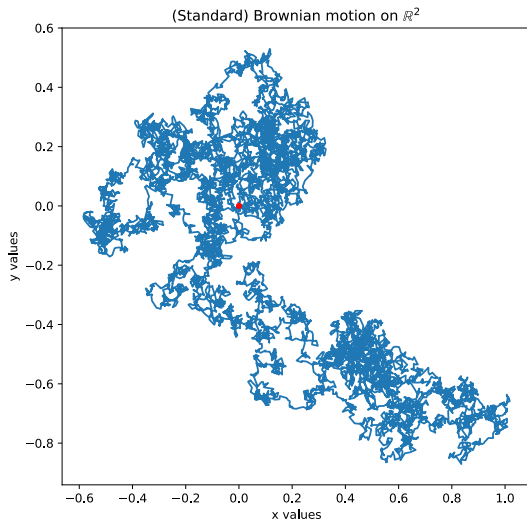


$$B_{t_2} - B_{t_1} \sim N(0, t_2 - t_1)$$

$$B_{t_3} - B_{t_2} \sim N(0, t_3 - t_2)$$

independent

# Illustration: Brownian Motion on $\mathbb{R}^2$



# Standard Brownian Motion

## Definition 14.3

A continuous-time stochastic process  $(B_t)_{t \geq 0}$  is called a **standard Brownian motion** on  $\mathbb{R}$  if it satisfies the following properties:

1.  $B_0 = 0$ .
2. (*Independent increments*)  
For all  $n \in \mathbb{N}$ ,  $0 \leq t_1 < t_2 < \dots < t_{n-1} < t_n$ , the random variables  $B_{t_2} - B_{t_1}, B_{t_3} - B_{t_2}, \dots, B_{t_n} - B_{t_{n-1}}$  are independent.
3. (*Stationary increments*)  
For all  $0 \leq s < t$  the random variable  $B_t - B_s$  is **normally distributed** with mean 0 and variance  $t - s$ , i.e.,  
 $B_t - B_s \sim \mathcal{N}(0, t - s)$ .
4. (*Continuous paths*)  
The function  $t \mapsto B_t$  is continuous.

In particular:  $B_t - B_s \sim \mathcal{N}(0, t - s)$

- $B_t \sim \mathcal{N}(0, t)$  with  $\mathbb{E}[B_t] = 0$  and  $\text{Var}(B_t) = t$  for all  $t > 0$

# Simulating Brownian Motion

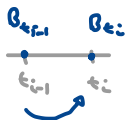
Consider simulating a Brownian motion on  $[0, T]$ :

- ▶ grid of discrete time points

$$0 = t_0 < t_1 < \dots < t_{n-1} < t_n = T$$



- ▶ by stationary and independent increments, with  $B_{t_0} = B_0 = 0$ ,



$$B_{t_i} = B_{t_{i-1}} + (B_{t_i} - B_{t_{i-1}}) \stackrel{d}{=} B_{t_{i-1}} + X_i \quad (i = 1, 2, \dots, n)$$

where  $X_i \sim \mathcal{N}(0, t_i - t_{i-1})$  independent of  $B_{t_{i-1}}$

- ▶ recursive representation:  $Z_1, \dots, Z_n$  i.i.d.  $\sim \mathcal{N}(0, 1)$

$$B_{t_i} = B_{t_{i-1}} + \sqrt{t_i - t_{i-1}} \cdot Z_i \quad (i = 1, 2, \dots, n)$$

- ▶ generates the samples  $B_{t_0}, B_{t_1}, B_{t_2}, \dots, B_{t_n}$  on the discrete time grid
- ▶ typically equally spaced time points:  $t_i = i \cdot \frac{T}{n}$  and hence  $t_i - t_{i-1} = T/n$



## Reminder: Normal Distribution 1/3

### Definition 14.4

The **normal distribution (Gaussian distribution)** is a (continuous) probability distribution on  $\mathbb{R}$  and is characterized by the *probability density function (PDF)*

$$f(x) = \frac{1}{\sqrt{2\pi\sigma^2}} \cdot e^{-\frac{1}{2} \frac{(x-\mu)^2}{\sigma^2}} \quad (x \in \mathbb{R})$$

with mean parameter  $\mu \in \mathbb{R}$  and variance parameter  $\sigma^2 \in \mathbb{R}_+$ .

A random variable  $X$  is called **normally distributed (Gaussian distributed)** with parameters  $\mu$  and  $\sigma^2$  (notation  $X \sim \mathcal{N}(\mu, \sigma^2)$ ) if its *cumulative distribution function (CDF)* is given by

$$F(x) = \mathbb{P}[X \leq x] = \int_{-\infty}^x f(z) dz = \int_{-\infty}^x \frac{1}{\sqrt{2\pi\sigma^2}} \cdot e^{-\frac{1}{2} \frac{(z-\mu)^2}{\sigma^2}} dz$$

for all  $x \in \mathbb{R}$ .

## Reminder: Normal Distribution 2/3

**Important properties and computational rules:**  $X \sim \mathcal{N}(\mu, \sigma^2)$

- ▶ mean and variance:

$$\mathbb{E}[X] = \mu \quad \text{Var}(X) = \mathbb{E}[(X - \mathbb{E}[X])^2] = \sigma^2$$

- ▶ computing probabilities

$$\mathbb{P}[a \leq X \leq b] = \int_a^b \frac{1}{\sqrt{2\pi\sigma^2}} \cdot e^{-\frac{1}{2} \frac{(x-\mu)^2}{\sigma^2}} dx = F(b) - F(a)$$

- ▶ computing expected values (function  $g: \mathbb{R} \rightarrow \mathbb{R}$ ):

$$\mathbb{E}[g(X)] = \int_{-\infty}^{+\infty} g(x) \cdot \frac{1}{\sqrt{2\pi\sigma^2}} \cdot e^{-\frac{1}{2} \frac{(x-\mu)^2}{\sigma^2}} dx$$

- ▶ linear transformation:  $Z \sim \mathcal{N}(0, 1)$  (**standard normal**)

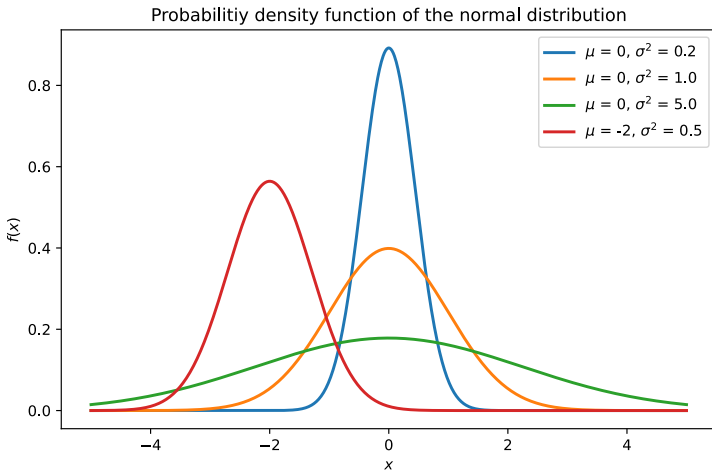
$$X = \mu + \sigma \cdot Z \sim \mathcal{N}(\mu, \sigma^2) \quad \Leftrightarrow \quad Z = \frac{X - \mu}{\sigma} \sim \mathcal{N}(0, 1)$$

- ▶ Moment-generating function (MGF):

$$M(u) = \mathbb{E}[e^{u \cdot X}] = e^{\mu \cdot u + \frac{1}{2} \sigma^2 u^2} \quad (u \in \mathbb{R})$$

- ▶  $X_1 \sim \mathcal{N}(\mu_1, \sigma_1^2)$ ,  $X_2 \sim \mathcal{N}(\mu_2, \sigma_2^2)$  independent:  
 $X_1 + X_2 \sim \mathcal{N}(\mu_1 + \mu_2, \sigma_1^2 + \sigma_2^2)$

## Reminder: Normal Distribution 3/3



## Some History

The **normal distribution**, also known as the **Gaussian distribution**, is named after JOHANN CARL FRIEDRICH GAUSS (1777 – 1855), a German mathematician and physicist who made significant contributions to many fields in mathematics and sciences.



Source: Wikipedia