Math 4B: Differential Equations

Lecture 23: Basic Theory of Systems

- Generalizing Theorems...
- ... From First-Order Linear ODEs...
- ... To First-Order Linear Systems & More!

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General Idea:

Today we're going to talk about a system of n first-order linear equations

$$x'_{1} = p_{11}(t)x_{1} + \dots + p_{1n}(t)x_{n} + g_{1}(t)$$

$$x'_{2} = p_{21}(t)x_{1} + \dots + p_{2n}(t)x_{n} + g_{2}(t)$$

$$\vdots$$

$$x'_{n} = p_{n1}(t)x_{1} + \dots + p_{nn}(t)x_{n} + g_{n}(t)$$
or
$$\mathbf{x}'(t) = P(t)\mathbf{x} + \mathbf{g}(t).$$

If $\mathbf{g}(t) = \mathbf{0}$, we call this a **homogeneous system**. It's simplest to deal with this type of system first.

We get many of the same theorems as we had earlier.

Principle of Superposition

Principle of Superposition

If the vector functions $\mathbf{x}_1(t)$ and $\mathbf{x}_2(t)$ are solutions to the homogeneous system of first-order linear equations

$$\mathbf{x}'(t) = P(t)\mathbf{x}(t),$$

then so is the linear combination $c_1\mathbf{x}_1(t) + c_2\mathbf{x}_2(t)$.

Note 1: Our textbook uses $\mathbf{x}^{(1)}(t)$ rather than $\mathbf{x}_1(t)$.

Note 2: We can apply this repeatedly. If we have k solutions $\mathbf{x}_1, \dots, \mathbf{x}_k$ of this system, then the linear combination

$$c_1\mathbf{x}_1 + c_2\mathbf{x}_2 + \dots + c_k\mathbf{x}_k$$

is also a solution.

Question: So, how many solutions are enough?

We Need n Solutions

Theorem: n is Enough

If the vector functions $\mathbf{x}_1(t), \dots, \mathbf{x}_n(t)$ are n linearly independent solutions of $\mathbf{x}' = P\mathbf{x}$ (an $n \times n$ system) in the interval $\alpha < t < \beta$, then any IVP (with $\mathbf{x}(t_0) = \mathbf{x}_0$) has a unique solution

$$\mathbf{x}(t) = c_1 \mathbf{x}_1(t) + \dots + c_n \mathbf{x}_n(t).$$

That is, any solution $\mathbf{x}(t) = \phi(t)$ can be written uniquely in terms of the **fundamental set of solutions** $\{\mathbf{x}_1, \dots, \mathbf{x}_n\}$.

Question: So how can we tell if our set of n solutions is, in fact, a fundamental set? How do we know if this set of solutions is linearly independent?

The Wronskian Returns

How can we tell if $\mathbf{x}_1(t), \dots, \mathbf{x}_n(t)$ are linearly independent?

Answer: They are independent when the *Wronskian* is non-zero:

$$W[\mathbf{x}_1,\ldots,\mathbf{x}_n](t) = \det \begin{pmatrix} x_{11}(t) & \cdots & x_{1n}(t) \\ \vdots & & \vdots \\ x_{n1}(t) & \cdots & x_{nn}(t) \end{pmatrix}.$$

Abel's Theorem

Suppose $\mathbf{x}_1(t), \dots, \mathbf{x}_n(t)$ are solutions to the equation $\mathbf{x}'(t) = P(t)\mathbf{x}(t)$ on an interval $\alpha < t < \beta$. Then $W[\mathbf{x}_1, \dots, \mathbf{x}_n](t) = c \exp \int \left(p_{11}(t) + p_{22}(t) + \dots + p_{nn}(t)\right) dt$ is either identically zero or never vanishes.

$$W[\mathbf{x}_1, \dots, \mathbf{x}_n](t) = c \exp \int (p_{11}(t) + p_{22}(t) + \dots + p_{nn}(t)) dt$$

Are There Fundamental Sets?

Question: Can we always find a fundamental set of solutions?

Let

$$\mathbf{e}_1 = \begin{pmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{pmatrix}, \quad \mathbf{e}_2 = \begin{pmatrix} 0 \\ 1 \\ \vdots \\ 0 \end{pmatrix}, \quad \dots \quad \mathbf{e}_n = \begin{pmatrix} 0 \\ 0 \\ \vdots \\ 1 \end{pmatrix}.$$

By the existence-uniqueness theorem, we can find $\mathbf{x}_k(t)$ that solves

$$\mathbf{x}'(t) = P(t)\mathbf{x}(t)$$
 and $\mathbf{x}(t_0) = \mathbf{e}_k$

on some common interval I given by $\alpha < t < \beta$. Then the solution to

$$\mathbf{x}'(t) = P(t)\mathbf{x}(t)$$
 and $\mathbf{x}(t_0) = \begin{pmatrix} c_1 \\ c_2 \\ \vdots \\ c_n \end{pmatrix}$

is $\mathbf{x}(t) = c_1 \mathbf{x}_1(t) + c_2 \mathbf{x}_2(t) + \dots + c_n \mathbf{x}_n(t)$.

Moral: $\{\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_n\}$ is a fundamental set on I.

What About Complex Solutions?

Question: What if we find a complex solution to a real system? That is, suppose

$$\mathbf{x}'(t) = P(t)\mathbf{x}(t)$$

is a real system (so all the functions in the entries of P(t) are real-valued). Further suppose that $\mathbf{x}(t) = \mathbf{u}(t) + i\mathbf{v}(t)$ is a solution, where \mathbf{u} and \mathbf{v} are real-valued functions and $\mathbf{v} \neq \mathbf{0}$. Can we find **real** solution(s) to this system?

Theorem: Real Solutions from Complex

If $\mathbf{x}(t) = \mathbf{u}(t) + i\mathbf{v}(t)$ is a solution to the real-valued homogeneous linear system

$$\mathbf{x}'(t) = P(t)\mathbf{x}(t),$$

then both $\mathbf{u}(t)$ and $\mathbf{v}(t)$ are solutions as well.