

# Math 4B: Differential Equations

## Lecture 02: Solutions & Terminology

- Solutions of DEs
- Some New Terminology,
- & More!

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# Solutions & Terminology

## Differential equation of order $n$

We will say that a differential equation is order  $n$  if it can be written

$$F(t, y, y', y'', y^{(3)}, \dots, y^{(n)}) = 0.$$

In this course we will also assume that this can be written as

$$y^{(n)} = G(t, y, y', y'', y^{(3)}, \dots, y^{(n-1)}). \quad (*)$$

A **solution** to equation  $(*)$  on the interval  $\alpha < t < \beta$  is a function  $y = \phi(t)$  such that  $\phi', \phi'', \dots, \phi^{(n)}$  are all defined and

$$\phi^{(n)} = G(t, \phi, \phi', \phi'', \phi^{(3)}, \dots, \phi^{(n-1)})$$

for all  $t$  in the interval  $\alpha < t < \beta$ .

# Linear ODEs

## Linear ODEs of order $n$

We will say that a differential equation of order  $n$  is *linear* if it can be written

$$F(t, y, y', y'', y^{(3)}, \dots, y^{(n)}) = 0,$$

where  $F$  is linear in  $y$  and its derivatives. This means linear first-order ODEs are those of the form

$$a_1(t) \frac{dy}{dt} + a_0(t)y = g(t).$$

Similarly, linear second-order ODEs are those of the form

$$a_2(t) \frac{d^2y}{dt^2} + a_1(t) \frac{dy}{dt} + a_0(t)y = g(t).$$

# Homogeneous ODEs

## Homogeneous ODEs of order $n$

We will say that a linear differential equation of order  $n$  is *homogeneous* if it is of the form

$$a_n(t)y^{(n)} + a_{n-1}(t)y^{(n-1)} + \cdots + a_2(t)y'' + a_1(t)y' + a_0(t)y = 0,$$

where each  $a_k$  is a function of the independent variable  $t$ . This means homogeneous linear first-order ODEs are those of the form

$$a_1(t)\frac{dy}{dt} + a_0(t)y = 0.$$

Similarly, homogeneous linear second-order ODEs are those of the form

$$a_2(t)\frac{d^2y}{dt^2} + a_1(t)\frac{dy}{dt} + a_0(t)y = 0.$$

# Solutions of ODEs and IVPs

- What can we say about solutions of ODEs?
- Can we find solutions of ODEs?
- In the Direction Fields slides, we've seen that there are *lots* of solutions.
- An ODE like  $\frac{dy}{dt} = 2(y - 1)$  together with an *initial condition* like  $y(0) = 5$  is called an *initial value problem* (or IVP).
- We might expect that there is exactly one solution to the IVP given above. (This is two statements: There's at least one solution. There are not two different solutions.)
- This isn't true in general – that IVPs always have a unique solution – but we'll see some conditions this quarter. If we are modeling physical phenomena, we expect solutions.

# Examples of Solutions

**Question:** Which of the following ODEs has  $y = \sin(t)$  as a solution?

- (A)  $(y')^2 + y^2 = 1$       (B)  $y' = y$       (C)  $y'' = y$       (D)  $y'' = -y$

**Answer:** Both **A** and **D**:

$$y = \sin(t) \quad y' = \cos(t) \quad y'' = -\sin(t)$$

So...

(A) says  $(+\cos(t))^2 + (\sin(t))^2 = 1$  **True!**

(B) says  $\cos(t) = \sin(t)$  **False!**

(C) says  $-\sin(t) = \sin(t)$  **False!**

(D) says  $-\sin(t) = -(\sin(t))$  **True!**

## Examples of Solutions II

**Question:** Which of the following functions is a solution of the IVP

$$\begin{cases} y' = \frac{1}{2}y - t \\ y(0) = 6 \end{cases}$$

(A)  $y = 2t + 6$

(B)  $y = 2t + 6 - 3e^{t/2}$

(C)  $y = 6e^{t/2}$

(D)  $y = 2t + 4 + 2e^{t/2}$

(A)  $y' = 2$  but  $\frac{1}{2}y - t = (t + 3) - t = 3 \neq 2$

(B)  $y(0) = 0 + 6 - 3 = 3 \neq 6$

(C)  $y' = 3e^{t/2}$  but  $\frac{1}{2}y - t = 3e^{t/2} - t$

(D) satisfies both!

**Answer:** D