

Aarhus University

3. Semesterprojekt

MEKANIK

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LIST OF FIGURES

LINK::SEND

```
#!/usr/bin/env python3
import socket

UDP_IP = "10.0.0.2"
UDP_PORT_NO = 9000
U_OR_L = input('Enter U or L: ')

print "Requist target IP:", UDP_IP
print "Target port no:", UDP_PORT_NO
print "Messege sent:", U_OR_L

sock = socket.socket(socket.AF_INET, socket.SOCK_DGRAM)
sock.sendto(U_OR_L, (UDP_IP, UDP_PORT_NO))

while True:
    data, addr = sock.recvfrom(1024)
    print ("Received:")
    print (data)

    print("Socket client closing")
    sock.close()
    quit()
```

LINK::RECIEVE

HØJTALER MONTERING

MIKROFON MONTERING

MOTOR MONTERING

VEROBOARD MONTERING

VIPPEFUNKTIONALITET

HJULSENSOR MONTERING

Bibliography