view_frames Result Recorded at time: 583.245 world Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (583.245 sec old) Buffer length: 0.000 sec root Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (583.245 sec old) Buffer length: 0.000 sec j2n6s300_link_base Broadcaster: /robot_state_publisher Average rate: 50.210 Hz Most recent transform: 583.242 (0.003 sec old) Buffer length: 4.760 sec j2n6s300_link_1 Broadcaster: /robot_state_publisher Average rate: 50.210 Hz Most recent transform: 583.242 (0.003 sec old) Buffer length: 4.760 sec j2n6s300_link_2 Broadcaster: /robot_state_publisher Average rate: 50.210 Hz Most recent transform: 583.242 (0.003 sec old) Buffer length: 4.760 sec j2n6s300_link_3 Broadcaster: /robot_state_publisher Average rate: 50.210 Hz Most recent transform: 583.242 (0.003 sec old) Buffer length: 4.760 sec j2n6s300_link_4 Broadcaster: /robot_state_publisher Average rate: 50.210 Hz Most recent transform: 583.242 (0.003 sec old) Buffer length: 4.760 sec j2n6s300_link_5 Broadcaster: /robot_state_publisher Average rate: 50.210 Hz Most recent transform: 583.242 (0.003 sec old) Buffer length: 4.760 sec j2n6s300_link_6 Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /moveit_node Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 1636.383 Hz Average rate: 50.210 Hz Average rate: 50.210 Hz Average rate: 50.210 Hz Most recent transform: 0.000 (583.245 sec old) Most recent transform: 583.244 (0.001 sec old) Most recent transform: 583.242 (0.003 sec old) Most recent transform: 583.242 (0.003 sec old) Most recent transform: 583.242 (0.003 sec old) Buffer length: 0.000 sec Buffer length: 4.766 sec Buffer length: 4.760 sec Buffer length: 4.760 sec Buffer length: 4.760 sec j2n6s300_link_finger_1 j2n6s300_link_finger_2 j2n6s300_end_effector j2n6s300_link_finger_3 realsense Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 50.210 Hz Average rate: 50.210 Hz Average rate: 50.210 Hz Most recent transform: 583.242 (0.003 sec old) Most recent transform: 583.242 (0.003 sec old) Most recent transform: 583.242 (0.003 sec old) Buffer length: 4.760 sec Buffer length: 4.760 sec Buffer length: 4.760 sec j2n6s300_link_finger_tip_2 j2n6s300_link_finger_tip_1 j2n6s300_link_finger_tip_3