Query processing

From SQL-query to result
Let's have a look under the hood



Query processing: overview

```
query in SQL
equivalent XRA-expression
modified XRA-expression
     access strategy
```

Algebraic operators

Classical view on RA: sets

Theory of relational databases: table is a set

Practice (SQL): a relation is a bag of tuples

R

Α	В
1	1
2	1
3	2
4	2

 $\pi_B(R)$

В	
1	
2	

 $\pi_B(R)$

В
1
1
2
2

Bags (multisets) versus sets

Union

$${a,b,c} U {a,a,c,d} = {a,a,a,b,c,c,d}$$

Intersection

$$\{a,a,a,b,c,c,d\} \cap \{a,a,b,e\} = \{a,a,b\}$$

Difference (minus)

$${a,a,a,b,c,c,d} - {a,a,b,e} = {a,c,c,d}$$

New operators in XRA: projection

Extended projection

R

Α	В
1	1
2	1
3	2

$$\pi_{A, A+B}(R)$$

Α	AplusB
1	2
2	3
3	5

New operators in XRA: sorting

 $\tau_L(R) =$ list of tuples in R sorted on attributes in L

R

В	С
2	6
4	3
1	3

 $\tau_{C,B\uparrow}(R)$

С	В
3	1
3	4
6	2

Grouping en aggregate functions

Trip

Γ_{destination, min(price)} (Trip)

Company	Destination	Price
Easyjet	Barcelona	65
Ryanair	Barcelona	59
KLM	Barcelona 80	
Easyjet	London	45
Lufthansa	London	58
KLM	Paris	69

Destination	MinPrice
Barcelona	59
London	45
Paris	69

Query processing: overview

```
query in SQL
equivalent XRA-expression
modified XRA-expression
     access strategy
```

Recall: algebraic properties

Commutativity

$$\circ$$
 $a + b = b + a$

$$\circ$$
 $a * b = b * a$

$$\circ$$
 $a - b \neq b - a$

Associativity

$$\circ$$
 $(a + b) + c = a + (b + c)$

$$\circ$$
 (a * b) * c = a * (b * c)

$$\circ$$
 $(a - b) - c \neq a - (b - c)$

Distributivity

$$\circ$$
 $a * (b + c) = a*b + a*c$

$$\circ$$
 $a * (b - c) = a*b - a*c$

Algebraic rewriting

cascading and commuting selections:

$$\sigma_{p \wedge q}(R) \equiv \sigma_p(\sigma_q(R)) \equiv \sigma_q(\sigma_p(R))$$

cascading projections:

$$\pi_{L1}(\pi_{L2}(R)) \equiv \pi_{L1}(R)$$

IF
$$L1 \subseteq L2$$

commuting selections and projections:

$$\pi_L(\sigma_p(R)) \equiv \sigma_p(\pi_L(R))$$
 IF $attr(p) \subseteq L$

Algebraic rewriting

commutativity of binary operators:

$$R\bowtie_{\theta} S\equiv S\bowtie_{\theta} R$$
 (?!) also for \times,\cup,\cap

distribution of selection over join:

$$\sigma_{p1 \wedge p2 \wedge p3}(R \bowtie S) \equiv \sigma_{p3}(\sigma_{p1}(R) \bowtie \sigma_{p2}(S))$$

IF
$$attr(p1) \subseteq attr(R), attr(p2) \subseteq attr(S)$$

distribution of selection over union:

$$\sigma_p(R \cup S) \equiv \sigma_p(R) \cup \sigma_p(S)$$

Intermezzo

Describe how a Selection distributes over a Minus

- Describe how a GroupBy distributes over a Union
- Rewrite the following expression for schema R(ABCD), S(AEFG), T(EHK)

$$\pi_{CG}(\sigma_{D>=10\land E<=20\land (G>0\lor K>0)}(R\bowtie S\bowtie T))$$

Access strategies

- Focus on selection, sorting and equijoin
- Other operators are either simple (projection) or variants of join methods

Access strategies

- We will have a look at datastructures and algorithms to support execution of algebraic operators
- (Blok 4 INFODS) Algorithmic analysis in main memory: count the number of steps of an algorithm (= , <, +)
- Our approach: count the number of accesses to external memory (IO) and ignore data processing in CPU and main memory

How to do: duplicate elimination?

- method 1: sorting
 external sorting of R can be done using merge sort
- method 2: hashing hashing will be explained when discussing join methods

IO: 4 * B, with B = the number of blocks used to store R

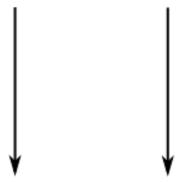
External merge sort: sort R[A,B] on A

DISK

<7,a> <3,b> <9,c>	<8,d> <3,e> <5,f>	<1,g> <4,h> <9,i>	<4,j> <2,k>

MEMORY

phase 1: 2 blocks availabe



<7,a> <3,b> <9,c>	<8,d> <3,e> <5,f>
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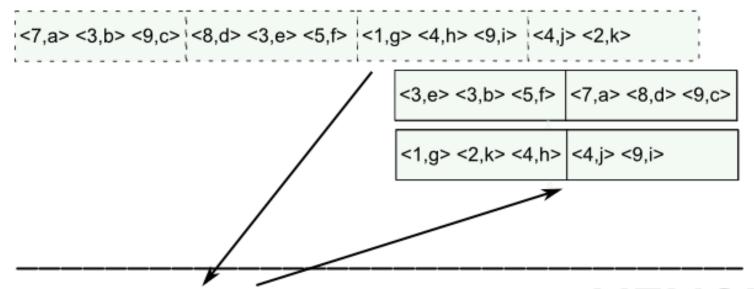
MEMORY

phase 1: 2 blocks availabe

<3,e> <3,b> <5,f> |<7,a> <8,d> <9,c>

MEMORY

phase 1: internal sort; first list to disk



MEMORY

phase 1: internal sort; second list to disk

output window

MEMORY

output window

MEMORY

output window

MEMORY

output window

MEMORY

output window

MEMORY

<5,f>

output window

MEMORY

<5,f>

output window

MEMORY

output window

MEMORY

output window

MEMORY

External sorting: analysis

- R fits in B(R) blocks
- Scanning R initially requires B(R) disk accesses
- Writing sorted sublists

 (using window block for each bucket)
 requires roughly B(R) disk accesses
- Scanning each sublist for merging requires (roughly) B(R) disk accesses
- Writing results requires again (roughly)
 B(R) disk accesses

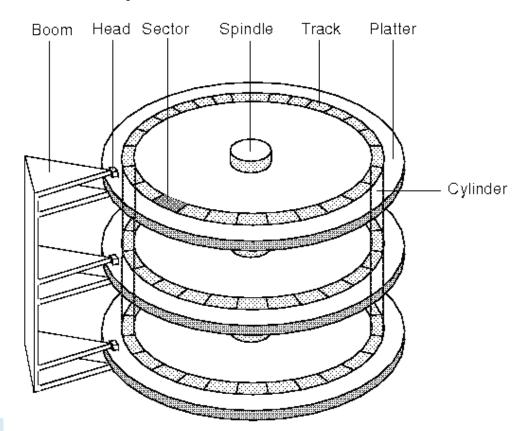
$$IO = 4 * B(R)$$

External sorting: example calculation

- IO = 4 * B(R)
- R contains one million tuples
- A tuple contains 400 bytes
- File containing R is 400 MB
- Disk block size is 32 kB
- Number of blocks is 12.500
- Number of IO's is 50.000
- Suppose one IO takes 5 msec
- Sorting requires 250 sec

External sorting: clustering

- Sorting requires 250 sec, but ...
- Assumption: file is clustered
- For instance: several blocks on one cylinder...
- ... requires 1 x disk arm positioning ...
- ... and less rotation latency



How to do: a selection?

$$S := \sigma_{A1 = C1, ..., An = Cn}(R)$$

Several access paths

- Scan the complete table and check the conditions for each tuple
- If possible, use an index on an attribute contained in A₁,..., A_n

How to do: a selection?

$$S := \sigma_{A1 = C1, \dots, An = Cn}(R)$$

Suppose you have more than one index available

- Option 1: use both indices and calculate the intersection
- Option 2: use the most selective index

Choosing a join order

- Suppose you have to join three tables: R, S and T
- Option 1: (R ⋈ S) ⋈ T
- Option 2: R ⋈ (S ⋈ T)
- Option 3: S ⋈ (R ⋈ T)
- Which one is the best?
- Estimate the size of the intermediate result
- Choose the method with the smallest size
- For more than 3 relations, this is a heuristic method
- More sophisticated methods exist, but the search space grows exponentially in the number of relations

Statistics supporting estimations

T(R): the number of tuples in R

B(R): the number of blocks of R on disk

V(R,A): the number of different values of attribute A in R

Challenge: try to estimate the effect of algebraic operators on statistics of intermediate results

Statistics supporting estimations

$$R' := \sigma_{A=c}(R)$$

$$T(R') = \dots$$

$$T(R') = T(R)/V(R,A)$$

Assumption: homogeneous distribution of A-values in R

Better: histograms

Disadvantage: maintenance

Alternative (very large databases): sampling

Statistics supporting estimations

$$U := R \bowtie_{\theta} S$$

$$\theta$$
: $R.A = S.A$

$$T(U) = ...$$

$$T(U) = T(R)*T(S)/V(S,A)$$

$$T(U) = T(S)*T(R)/V(R,A)$$

Choose minimum?!

$$U := R \bowtie_{\theta} S$$

$$\theta$$
: $R.A = S.A$

Horrible feeling: the number of IO's required to calculate the result is proportional to

$$T(R) * T(S)$$

... or at least B(R) * B(S)

$$T := R \bowtie_{\theta} S$$

$$\theta$$
: $R.A = S.A$

- Block-nested loop
- Index-nested loop
- Sort-Merge
- Hash-Join

Buffer in main memory: M pages/blocks

```
Block-nested loop
S = smallest relation (nr of blocks)
foreach chunk of M-1 blocks of S do
   read these blocks into main memory;
   foreach block B2 of R do {
       read B2 into the free memory buffer;
       check all possible combinations
       of tuple t1 in chunk and t2 in B2;
       if (t1.A = t2.A) write the join of these
          tuples to output;
```

Block-nested loop
S = smallest relation (nr of blocks)

IO:
$$B(S) + B(R) * \Gamma B(S)/(M-1)^{T}$$

But note that if S fits in main memory and we have at least one buffer free:

IO: B(S) + B(R) // optimal!

```
Index-nested loop assumption: index on S.A
```

```
foreach block B of R do
  foreach tuple t in B do {
    suppose t.A = a;
    use the index to find all t2 in S
    with t2.A = a;
    write the join of t with each t2 to
    output;
  }
```

Analysis index-nested loop
c = cost of access index (~2 for B-tree)

µ = average number of tuples found
(estimate from statistics)

IO:
$$B(R) + (c + \mu) T(R)$$

$$\mu \sim T(S)/V(S,A)$$

If A is superkey in S: $\mu = 1$

Sort-merge

(If necessary) sort R on A
 (If necessary) sort S on A
 repeat
 read the blocks from
 R and S containing the smallest
 common A-values;
 join the tupels in these blocks;
 until R is empty or S is empty

Sort-merge

Α	В
а	11
b	12
а	13
С	14
С	15
а	16

Α	С
b	21
а	22
С	23
b	24
С	25
а	26

1. Sort

Α	В
а	11
а	13
а	16
b	12
С	14
С	15

Α	C
а	22
a	26
b	21
b	24
С	23
С	25

A	В	Α	С
a	11	а	22
a	13	а	26
a	16	b	21
b	12	b	24
С	14	С	23
С	15	С	25

Α	В	A	C
a	11	а	22
a	13	а	26
а	16	b	21

Α	В	Α	C
a	11	а	22
a	13	а	26
a	16	b	21
b	12	b	24
С	14	С	23
С	15	С	25

Α	В	A	C
а	11	а	22
а	13	а	26
a	16	b	21

Α	В	C
а	11	22
а	11	26
a	13	22
a	13	26
а	16	22
a	16	26

Α	В	A	C
a	11	а	22
a	13	а	26
a	16	b	21
b	12	b	24
С	14	С	23
С	15	С	25

Α	В	Α	C
b	12	b	21
С	14	b	24
С	15	С	23

Α	В	C
а	11	22
а	11	26
а	13	22
а	13	26
a	16	22
a	16	26

Α	В	Α	C
a	11	а	22
a	13	а	26
a	16	b	21
b	12	b	24
С	14	С	23
С	15	С	25

Α	В	Α	C
b	12	b	21
С	14	b	24
С	15	С	23

Α	В	С
•••	•••	•••
а	16	26
b	12	21
b	12	24

Α	В	A	C
a	11	а	22
a	13	а	26
a	16	b	21
b	12	b	24
С	14	C	23
С	15	C	25

A	В	A	С
С	14	С	23
С	15	С	25

Α	В	C
•••	•••	
b	12	24

Α	В	A	С
a	11	а	22
a	13	а	26
a	16	b	21
b	12	b	24
С	14	С	23
С	15	С	25

Α	В	A	С
С	14	С	23
С	15	С	25

A	В	C
•••	•••	•••
b	12	24
С	14	23
С	14	25
С	15	23
С	15	25

Sort-merge Join on A: analysis

- R and S fit in B(R) and B(S) blocks
- Sorting R and S requires 4*(B(R) + B(S)) disk accesses (if necessary)
- Scanning the sorted sublists requires (roughly) B(R) + B(S) disk accesses
- Ignore writing resulting tuples in analysis (all methods have to do that)

$$IO = 5 *(B(R) + B(S))$$

Applying some smart tricks:

$$IO = 3 *(B(R) + B(S))$$

Hash Join

- 1. Choose the size M (nr of buckets) of the hash table
- 2. Choose a hash functie for the domain of A with codomain 0..M-1
- 3. Hash every tuple of R to the corresponding bucket
- 4. Hash every tuple of R to the corresponding bucket
- 5. Get each bucket into main-memory and construct the resulting tuples

Join R[A,B] with S[A,C] h(a) = a DIV 10

A	В
12	а
3	b
29	С
7	d
13	е
12	f
27	g

Α	C
29	h
7	i
8	j
28	k
12	1

Hash Join on A

Α	В	A	С
12	a	29	h
3	b	7	i
29	С	8	j
7	d	28	k
13	е	12	1
12	f		
27	g		

Bucket: h(a) = 0A B A C

Bucket: h(a) = 1A B A C

Bucket: h(a) = 2

Hash Join on A

Α	В	Α
12	а	29
3	b	7
29	С	8
7	d	28
13	е	12
12	f	
27	g	

A	С
29	h
7	i
8	j
28	k
12	

Bucket: h(a) = 0

Α	В	Α	C
3	b	7	i
7	d	8	j

Bucket: h(a) = 1

Α	В	A	С
12	a	12	
13	е		
12	f		

Bucket: h(a) = 2

A	В	A	С
29	С	29	h
27	g	28	k

Hash Join on A

Bucket: h(a) = 0

A	В	A	С
3	b	7	i
7	d	8	j

Bucket: h(a) = 1

Α	В	A	С
12	а	12	1
13	е		
12	f		

Bucket: h(a) = 2

Α	В	A	C
29	С	29	h
27	g	28	k

Join each bucket in main memory:

Α	В	Α	C
3	b	7	i
7	d	8	j

adds:

A	В	C
7	d	i

Bucket:
$$h(a) = 0$$

Jo	in	eac	h	bι	uck	et
in	m	ain	m	er	no	ry:

Α	В	Α	С
12	а	12	1
13	е		
12	f		

Bucket: h(a) = 1

Α	В
12	а
13	е
12	f

A	C
12	1

Bucket: h(a) = 2

Α	В	Α	С
29	С	29	h
27	g	28	k

adds:

Α	В	C
7	d	i
12	а	1
12	f	1

Bucket:
$$h(a) = 0$$

Α	В	A	С
3	b	7	i
7	d	8	j

Join each bucket in main memory:

Buck	et	
h(a)	=	1

В
а
e
f

A	C
12	I

Α	В	A	C
29	С	29	h
27	g	28	k

Bucket:

$$h(a) = 2$$

Α	В	A	С
29	С	29	h
27	g	28	k

adds:

Α	В	С
7	d	i
12	а	
12	f	
29	С	h

Hash Join on A: analysis

- R and S fit in B(R) and B(S) blocks
- Scanning R and S to hash the tuples requires B(R) + B(S) disk accesses
- Writing tuples to hash table

 (using window block for each bucket)
 requires roughly B(R) + B(S) disk accesses
- Fetching each bucket for joining requires
 (roughly) B(R) + B(S) disk accesses for reading
- Ignore writing resulting tuples in analysis (all methods have to do that)

$$IO = 3 *(B(R) + B(S))$$

Physical tuning

- Presence of physical structures facilitates efficient query processing
- Possibilities:
 - indexes
 - keeping tables sorted on a specific attribute
 - keeping tables clustered on a specific index
 - maintaining materialized views
- Task for the DBA: monitor performance and reconsider physical database organization
- Challenge: automatic support for optimizing physical database organization

Dual architecture: OLTP vs OLAP

- OLTP = On Line Transaction Processing
- High volumes of small updating transactions, often in combination with simple queries to identify primary key values
- Typical domain: support of commercial activities
- Real time performance requirements
- High requirements with respect to transaction integrity: concurrency, recovery, constraint satisfaction
- Term: "production database"
- Relatively low number of indexes

Dual architecture: OLTP vs OLAP

- OLAP = On Line Analytical Processing
- Low volumes of massive read-only queries, often changing perspective (sales per week, month, year, article, region, ...)
- Typical domain: management information systems
- No real time performance requirements, although ...
- No updates, no transaction processing; periodical reloading of preprocessed snapshots from production database
- Physical organization tuned toward read queries: many indices, materialized views, precomputed aggregates, ...
- Term: "data warehouse"

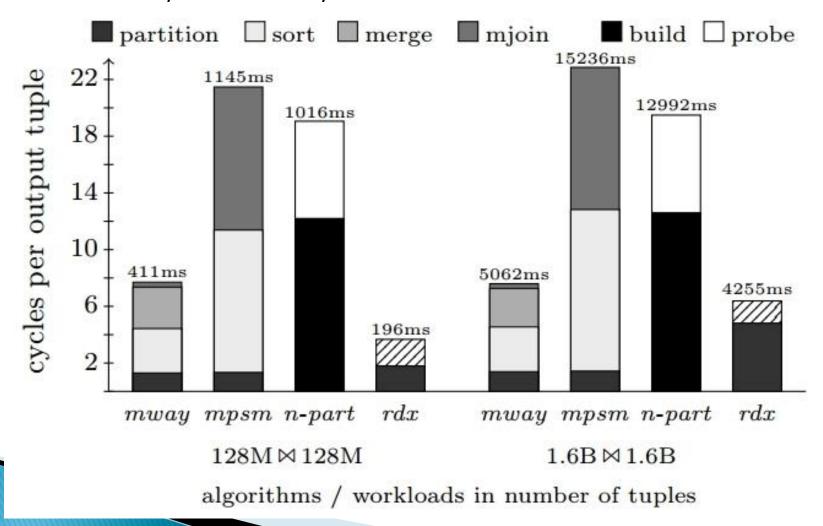
OLAP: main memory databases

- Relevant parts of database resident
- Query processing: focus on minimizing cache misses instead of minimizing IO
- Column stores instead of row stores
 - Irrelevant attributes not loaded
 - Column processing better suited for cache size
 - No overhead w.r.t. tuple management (pack/unpack)
 - But: additional joining required

OLAP: main memory databases

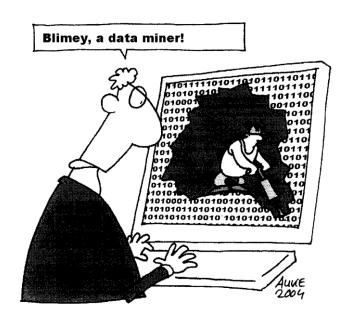
Recent research on join processing

- Intel Sandy Bridge 4*8 cores
- 32kB L1, 256 kB L2, 20 MB L3 cache



Beyond OLAP: data mining

Discovery of interesting patterns and models in data bases



Data mining example

Market basket analysis:

Find groups of products that are often bought together



Data mining example

Market basket analysis folklore: diapers & beer

