Indexing in databases

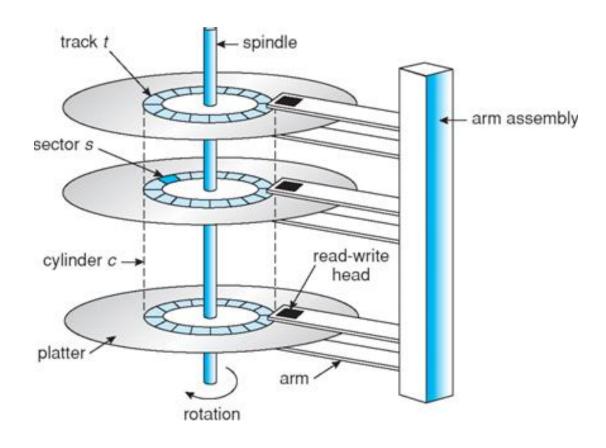
The problem



The problem

- Around 10.000.000 cars in the Netherlands
- Query: search a car based on license plate
- Assumptions:
 - A tuple (record) takes 400 bytes
 - A hard disk block contains 16 kbyte, so we have 40 records on a block
 - A disk IO takes ~5 msec
- Maximum search time (complete table scan)
 - \circ 10.000.000 / 40 = 250.000 disk IO
 - 1250 sec ~= 21 minutes
- Required search time : < 1 sec</p>

Hard disk



Main memory vs harddisk

Main memory

- Typical size : 4 256 GB
- Access time: ~ 100 nsec (10^{-7} sec)
- Volatile

Harddisk

- Typical size : 1 14 TB
- Access time: 5-10 msec (without clustering)
- Non-volatile

SSD

- Typical size: 128 GB 4 TB (expensive)
- Access time: ~ 0.1 msec (10^{-4} sec)
- Non-volatile
- Unit of traffic: block (2 32 kbyte)

The solution: indexing

- Indexing enables a quick table search, based on the value of a specific attribute
- Indexing also supports query processing and optimization
- Indexing (automatically) supports primary key maintenance and uniqueness constraints (other candidate keys)
- Syntax for SQL DDL:

```
CREATE INDEX Person_dob_ndx
ON Person (date_of_birth);
CREATE UNIQUE INDEX Person_ppn_ndx
ON Person (passport number);
```

Indexing: how does it work?

Two fundamental techniques

- Search tree
- 2. Hash index

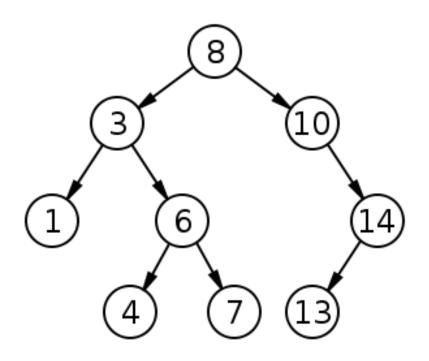
Both techniques applicable to main memory as well as external memory

Tree according to computer scientists

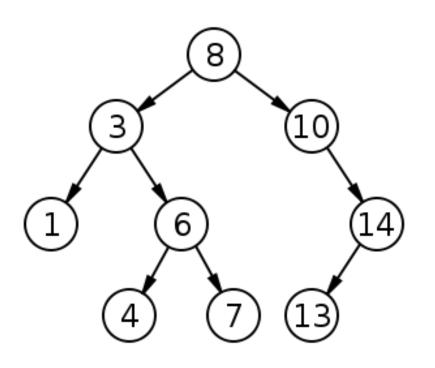
root



Binary search tree



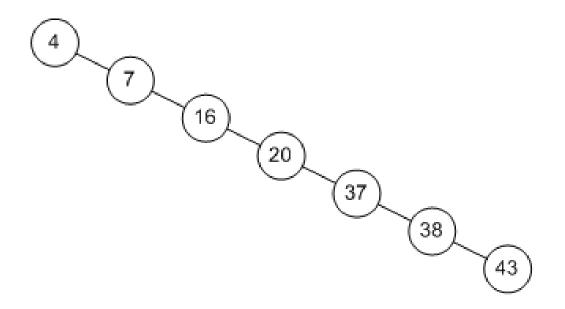
Intermezzo



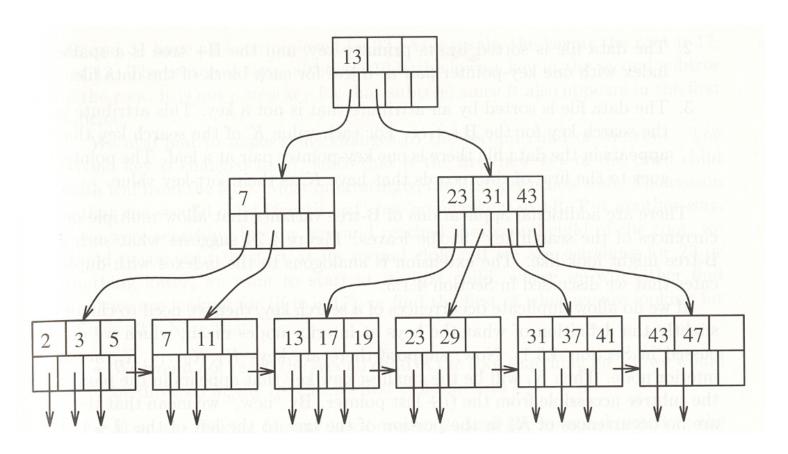
- Add: 2 18 9 5
- How many nodes could a tree with 3 levels contain?
- How many nodes could a tree with N levels contain?
- How many steps does it (roughly) take to fulfill a search action in a tree with M nodes?

• Add: 20 30 40 60 50

Binary search tree: balancing



B-tree (main memory & harddisk)



Update algorithm guarantees 50% filling of nodes

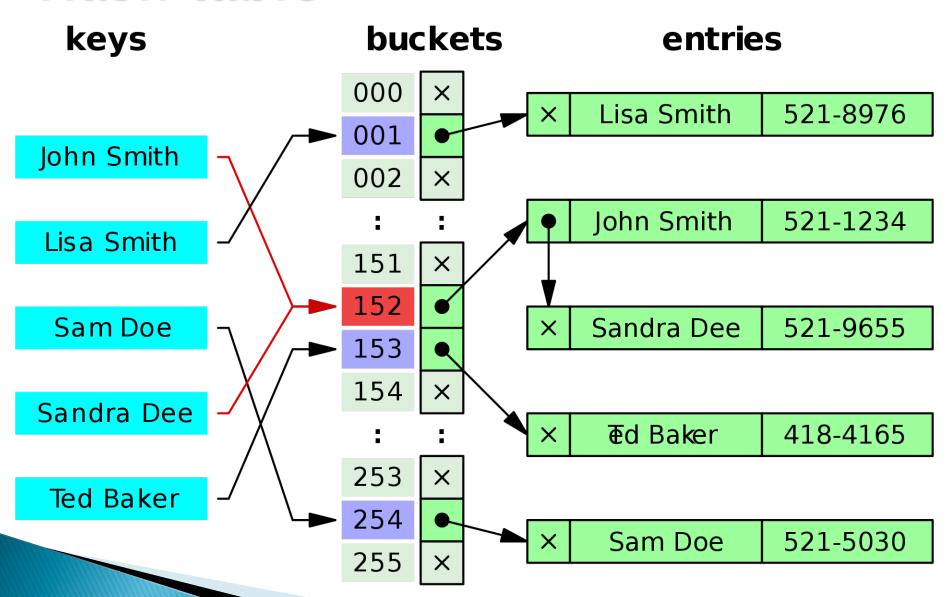
B-tree: characteristics

- Field: 4 byte integer
- Pointer: 8 bytes
- Block size: 16 kbyte
- Content: 683 1365 entries per block
- 2 levels: minimum nr of entries = 466489
- 3 levels: minimum nr of entries = 318 million
- 4 levels : minimum nr of entries = 217 billion

Hash table

- Memory reservation of N buckets: addresses 0..N-1
- Hashfunction f
 - Domain: all possible attribute values
 - Codomain: 0..N-1
- Hopefully, f distributes the values neatly

Hash table



Indexing: final words

- Hash indexing has a theoretical advantage: one disk access versus klog(M) for B-tree
- Hash indexing has a fundamental disadvantage: range queries are not supported
- The k of klog(M) is very large, so klog(M) hardly exceeds 3 ...
- ... while the root of the B-tree (and possible the second level nodes) are often kept in main memory
- Overall, the B-tree is the winner