

Graphical Models

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Assigned reading: Ch. 11

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outline

- ▶ Markov chains
- ▶ Hidden Markov models (HMM)
- ▶ Probabilistic graphical models (PGM)
 - › reading **conditional independence** from directed graphs
 - › atomic independence structures on triples
 - › d(irected)-separation
- ▶ $\text{HMM} \subset \text{PGM}$



Markov chains

- ▶ So far in the course we have assumed independent and identically distributed (i.i.d.) datasets. But we now consider a **sequence** of random variables

$$X_{1:T} := (X_1, X_2, \dots, X_T)$$

where the random variables are dependent $X_t \not\perp X_{t'}$:

$$P(X_t | X_{t'}) \neq P(X_t).$$

- ▶ The (first order) Markov condition:

In predicting the future, the past doesn't matter, only the present.

- ▶ In other words,

$$P(X_{t+1} | X_{1:t}) = P(X_{t+1} | X_t).$$

- ❓ Prove the following:

$$P(X_{1:T}) = P(X_1) \prod_{t=1}^{T-1} P(X_{t+1} | X_t)$$

- ❓ How many parameters are needed to identify a Markov chain? Assume $\mathcal{X} = [K]$.

(time) **homogenous** Markov chains

- ▶ Consider our **discrete** setup where $X_t \in \mathcal{X} = [K]$
- ▶ For many problems of practical interest we assume the transition probabilities $P(X_{t+1} = c \mid X_t = c')$ does not depend on (time) t :

$$P(X_{t+1} = k' \mid X_t = k) = A_{kk'}$$

- ▶ Such Markov chains are referred to as **time homogenous**.
- ▶ The matrix A is referred to as **transition probability matrix**.
- ? What is the dimension of A ?
- ? What are the properties the transition probability matrix A should satisfy?
- ? Does A have to be symmetric?
- ? Define the row vector π_t to be the distribution of $P(X_t)$:

$$\pi_t(k) = P(X_t = k).$$

(a) Prove that

$$\pi_{t+1} = \pi_t A.$$

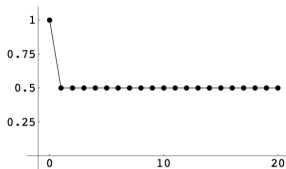
(b) What is π_t in terms of π_1 ?

example: randomly jumping frog

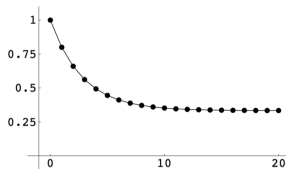
- ▶ Consider a randomly jumping frog with $\mathcal{X} = \{e, w\}$. Whenever he tosses heads, he jumps to the other lily pad:



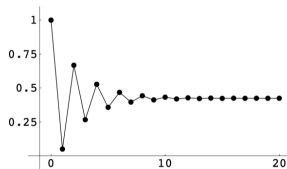
- ▶ Say the coin on the east pad has probability p of landing heads up, while the coin on the west pad has probability q of landing heads up.
- ? Can we write $P(X_{1:T})$ as a Markov chain? Is it homogenous? If so, what is A ?
- ? The probability of being on the east pad (started from the east pad) plotted below versus time in three different scenarios. Let's guess if $p > q$ or not in each case.



(a)



(b)



(c)

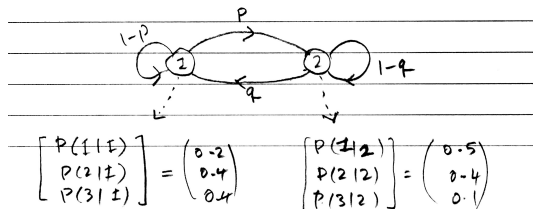
the chirping-jumping frog HMM

A Markov chain is useful when we need to compute a probability for a sequence of observable events. In many cases, however, the events we are interested in are **hidden**: we don't observe them directly. A hidden Markov model (HMM) allows us to talk about both observed events and hidden events that we think of as “causal” factors in our probabilistic model.

- ▶ Our jumping frog **emits** $y \in \mathcal{Y} = [L]$ chirps when he jumps on each lily pad.
- ▶ In this example we do not observe the frog location, we only hear the chirps.
- ▶ The **emission** of y chirps is **probabilistic** captured by

$$P(Y_t = l \mid X_t = k)$$

and is shown diagrammatically¹ as:



¹Soon we will learn a more elegant way to describe an HMM diagrammatically.

hidden Markov models

A hidden Markov model has the following ingredients:

- ▶ A set of K states in $[K] = \{1, \dots, K\}$.
- ▶ A transition probability matrix $A \in \mathbb{R}^{K \times K}$, whose rows must add to 1.
- ▶ A sequence of observations $Y_{1:T} = (Y_1, \dots, Y_T)$ with $Y_t \in \mathcal{Y}$, where $|\mathcal{Y}| = L$.
- ▶ A sequence of observation likelihoods, also called emission probabilities,

$$B_{kl} = P(Y_t = l \mid X_t = k),$$

i.e., the probability of an observation $Y_t = l$ being generated from a state $X_t = k$.

- ▶ An initial probability distribution over states denoted by π_1 .

learning and inference in HMMs

There are three fundamental problems concerning HMMs:

- ▶ **Likelihood:** Given an HMM (A, B, π) and the observation $Y_{1:T}$, determine the likelihood $P(Y_{1:T})$.
- ▶ **Decoding:** Given an observation sequence $Y_{1:T}$ and an HMM (A, B, π) discover the **most likely** hidden state sequence $X_{1:T}$.
- ▶ **Learning:** Given an observation sequence $Y_{1:T}$ and the initial probabilities π , learn the HMM parameters (A, B) .

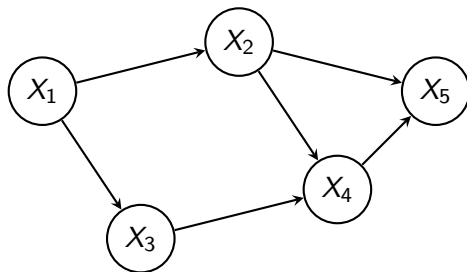
probabilistic graphical models

For directed acyclic graphs (DAGs) with d nodes representing random variables $X_{1:d} = (X_1, \dots, X_d)$, the joint probability distribution is factorized as

$$P(X_{1:d}) = \prod_{i=1}^d P(X_i \mid \text{pa}(X_i)),$$

where $\text{pa}(X_i)$ is the set of nodes that point to X_i (“pa” stands for parents).

? Write down $P(X_{1:5})$ in the example below:

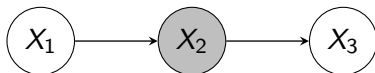


? How many parameters are needed to identify $P(X_{1:5})$ in the above example?

? Prove that $P(X_{1:d})$ is NOT a proper probability in the presence of cycles.

atomic graphs I

The case of single and two node graphs are trivial. The first level of complexity starts with three-node graphs. We start with the following (Markov) **chain** configuration²:



Reading the joint distribution from the graph, we have

$$P(X_{1:3}) = \prod_{i=1}^d P(X_i \mid \text{pa}(X_i)) = P(X_1)P(X_2 \mid X_1)P(X_3 \mid X_2).$$

? Prove $X_1 \perp\!\!\!\perp X_3 \mid X_2$, i.e. given X_2 , X_1 and X_3 are independent:

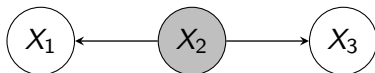
$$P(X_1, X_3 \mid X_2) = P(X_1 \mid X_2)P(X_3 \mid X_2)$$

? In addition, show the chain is Markovian:

$$P(X_3 \mid X_{1:2}) = P(X_3 \mid X_2)$$

²In the book this is called head-to-tail.

We continue with following **fan-OUT** (tail-to-tail) configuration:



Reading the joint distribution from the graph, we have

$$P(X_{1:3}) = \prod_{i=1}^d P(X_i \mid \text{pa}(X_i)) = P(X_1 \mid X_2)P(X_2)P(X_3 \mid X_2).$$

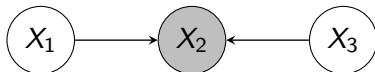
? Prove $X_1 \perp\!\!\!\perp X_3 \mid X_2$, i.e. given X_2 , X_1 and X_3 are independent:

$$P(X_1, X_3 \mid X_2) = P(X_1 \mid X_2)P(X_3 \mid X_2)$$

? Argue that X_1 and X_3 are not marginally independent: $X_1 \not\perp\!\!\!\perp X_3$

atomic graphs III

We finish with following **fan-IN** (head-to-head) configuration:



Reading the joint distribution from the graph, we have

$$P(X_{1:3}) = \prod_{i=1}^d P(X_i \mid \text{pa}(X_i)) = P(X_1)P(X_2 \mid X_1, X_3)P(X_3).$$

? Prove $X_1 \perp\!\!\!\perp X_3$, i.e. X_1 and X_3 marginally independent:

$$P(X_1, X_3) = P(X_1)P(X_3)$$

? Argue that after observing X_2 , X_1 and X_3 are not guaranteed to be independent³:

$$X_1 \not\perp\!\!\!\perp X_3 \mid X_2$$

³This is sometimes referred to as the *explaining away* phenomenon.

d-separation

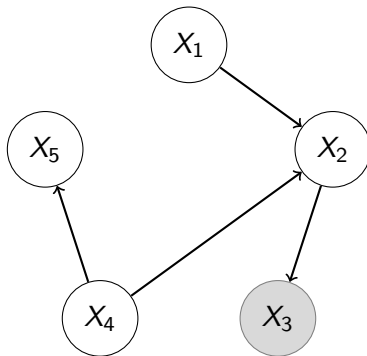
- ▶ A , B , and C are arbitrary non-intersecting set of nodes in a general PGM.
- ▶ We wish to know whether $A \perp\!\!\!\perp B \mid C$ holds or not.
- ▶ Construct all possible (undirected) paths from any node in A to any node in B .
- ▶ A path (with respect to C) is set to be **blocked** if it **includes a node** such that
 - the arrows form a \in chain/fan-OUT config at the node and the node $\in C$.
 - a **fan-IN** config at the node, and the node (and all its descendants) $\notin C$
- If all paths from A to B are blocked, then A is **d-separated** from B by C .

Theorem (d-separation)

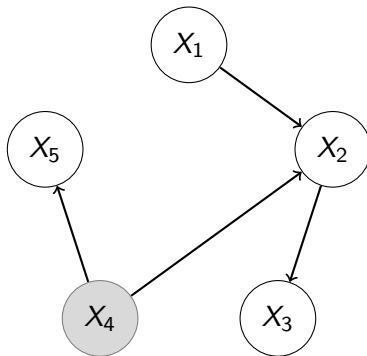
If A is d-separated from B by C on a directed graphical model, then the joint distribution over all the variables in the graph will satisfy

$$A \perp\!\!\!\perp B \mid C$$

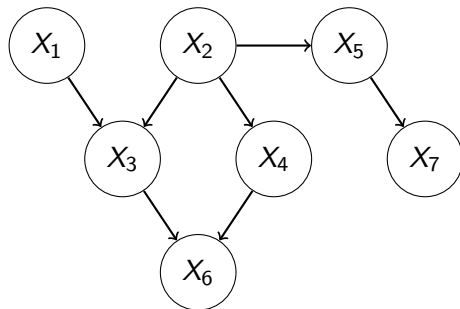
$$X_1 \not\perp\!\!\!\perp X_5 \mid X_3$$



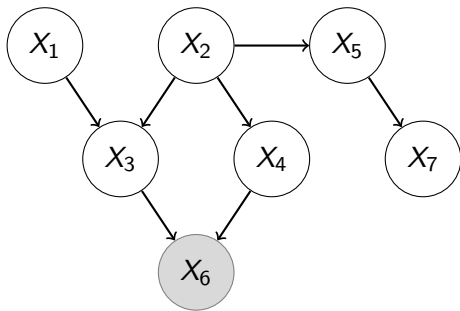
$$X_1 \perp\!\!\!\perp X_5 \mid X_4$$



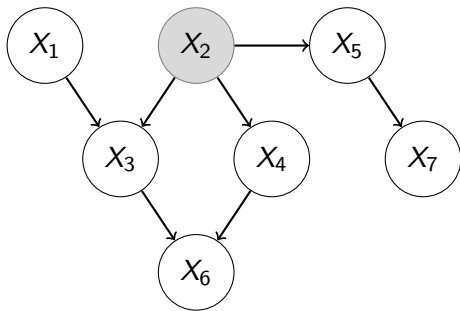
$$X_1 \perp\!\!\!\perp X_2$$



$$X_1 \not\perp\!\!\!\perp X_2 \mid X_6$$

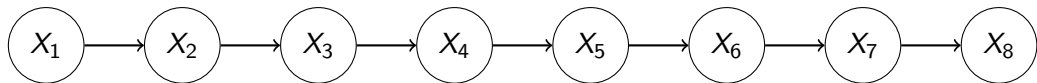


$X_3 \perp\!\!\!\perp X_7 \mid X_2$?



Markov meets Pearl

- ▶ Equipped with this graphical language we can represent Markov chains as



? What can we say about $X_{t_1} \perp\!\!\!\perp X_{t_2}$? What about $X_{t_1} \perp\!\!\!\perp X_{t_2} \mid X_{t_3}$?

- ▶ The corresponding hidden Markov model is represented by:

