# Convex Optimization Homework Solutions

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### 1 Homework 1

#### 1.1 Exercise 2.1

Showing the definition of convexity for arbitrary k.  $\theta_1 x_1 + \cdots + \theta_k x_k \in C$ .

$$\theta_1 x_1 + \dots + \theta_k x_k = \theta_1 x_1 + (1 - \theta_1)(\mu_2 x_2 + \mu_3 x_3 + \dots + \mu_k x_k) \tag{1}$$

Where each  $\mu_n = \frac{\theta_n}{1-\theta_1}$ 

$$\sum_{i} \mu_{i} = \frac{\sum_{i} \theta_{i}}{1 - \theta_{1}} = \frac{1 - \theta_{1}}{1 - \theta_{1}} = 1$$
 (2)

#### 1.2 Exercise 2.2

The intersection between any two convex sets is convex. A line segment by definition is convex because it contains itself. Therefore, if there is any line segment L that intersects C, for C to be convex, the intersection must also be convex.

Similarly, for an affine set, the definition is that the set must contain he line through any distinct points in the set. Therefore if there is a line that line segment L that intersects an affine set A, its intersection is also affine.

#### 1.3 Exercise 2.5

Distance between two parallel hyperplanes  $\{x \in \mathbb{R}^n | a^T x = b_1\}, \{x \in \mathbb{R}^n | a^T x = b_2\}$ :

$$a^T(x_1 + at) = b_2 \tag{3}$$

$$a^T x_1 + a^T a t = b_2 (4)$$

$$t = \frac{b_2 - a^T x_1}{a^T a} \tag{5}$$

$$t = \frac{b_2 - b_1}{a^T a} \tag{6}$$

$$\frac{|b_1 - b_2|}{||a||_2} \tag{7}$$

#### 1.4 Exercise 2.7

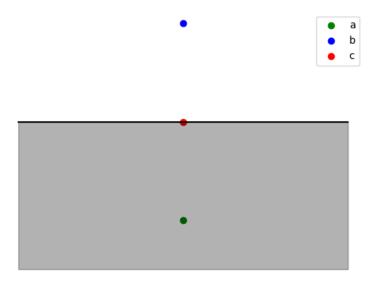
The image below illustrates the intuition behind this in  $\mathbb{R}^2$ . The set of all points that are closer to a than b  $\{x|||x-a||_2 \leq ||x-b||_2\}$ , is a halfspace of the form

$$\{x|c^T x \le d\} \tag{8}$$

where c is the normal vector that points from a to b,  $c = \frac{a-b}{||a-b||_2}$  and  $d = (\frac{a-b}{||a-b||_2})^T \frac{a+b}{2}$ 

### 1.5 Exercise 2.8

Finding which of the sets are polyhedra



# 1.5.1 a

 $S = \{y_1a_1 + y_2a_2 | -1 \le y_1 \le 1, -1 \le y_2 \le 1\}, a_1, a_2 \in \mathbb{R}^n$  This set is a 2D parallelogram in any  $\mathbb{R}^n$ . The image shown is one that is generated with  $\mathbb{R}^3$  coordinates  $a_1 = (1, 2, 3)$  and  $a_2 = (4, 5, 2)$ . It can be defined as the intersection between four halfspaces with their normals pointing from the origin to and centered on  $a_1, a_2, -a_1, -a_2$ .



The normal vectors for the halfspaces are:

$$A = \begin{bmatrix} \frac{a_1}{||a_1||_2} \\ \frac{a_2}{||a_2||_2} \\ -\frac{a_1}{||a_1||_2} \\ \frac{-a_2}{||a_2||_2} \end{bmatrix}$$
(9)

and the b vector is:

$$b = \begin{bmatrix} ||a_1||_2 \\ ||a_2||_2 \\ ||a_1||_2 \\ ||a_2||_2 \end{bmatrix}$$
(10)

Therefore, the set S can be expressed as  $S = \{x | Ax \leq b\}$ 

#### 1.5.2 b

This is a polyhedra where:

$$A = I^n (11)$$

$$b = 0 (12)$$

$$C = \begin{bmatrix} \mathbf{1} \\ a \\ a^2 \end{bmatrix} \tag{13}$$

$$d = \begin{bmatrix} 1 \\ b_1 \\ b_2 \end{bmatrix} \tag{14}$$

#### 1.5.3 c

Not attempted

# 1.5.4 d

Not attempted

## 1.6 Exercise 2.11

Showing that the hyperbolic set  $\{x \in \mathbb{R}^2_{++} | x_1 x_2 \ge 1\}$  is convex. As a generalization, show that  $\{x \in \mathbb{R}^2_+ | \Pi_{i=1}^n x_i \ge 1\}$ 

#### 1.7 Exercise 2.12

Finding which of the following sets are convex:

#### 1.7.1 a. slab

A set of the form  $\{x \in \mathbb{R}^n | \alpha \leq a^T x \leq \beta\}$ , A slab is the intersection of two halfspaces  $\mathbb{C}$  and  $\mathbb{D}$  where  $\mathbb{C} = \{x | a^T x \leq \beta\}$  and  $\mathbb{D} = \{x | -a^T x \leq -\alpha\}$ 

#### 1.7.2 b. rectangle

A set of the form  $\{x \in \mathbb{R}^n | \alpha_i \leq x_i \leq \beta_i, i = 1, ..., n\}$ . This is also the intersection of halfspaces, but this time it is the intersection of four halfspaces (in  $\mathbb{R}^2$ ). But this is a polyhedra.

#### 1.7.3 c. wedge

A set of the form  $\{x \in \mathbb{R}^n | a_1^T x \leq b_1, a_2^T x \leq b_2\}$ . Intersection of two halfspaces

#### 1.7.4 d. point-set distance

A set of the form  $\{x|||x-x_0||_2 \leq ||x-y||_2 \forall y \in S\}$  where  $S \subseteq \mathbb{R}^n$ . This can be viewed as the intersection of many euclidean balls. The intersection of convex spaces is convex so the here, the set can be turned into  $\bigcap_{y \in S} \{x|||x-x_0||_2 \leq ||x-y||_2\}$ 

#### 1.7.5 e. set-set distance

A set of the form  $\{x|\mathbf{dist}(x,S) \leq \mathbf{dist}(x,T)\}$  This set is not convex. Consider two crescent-moon shaped sets that lie next to each other so the tip of one moon is in the center of the other moon. The set that is closer to either of them is not convex because the crescent shape would stay in the set and is not convex.

#### 1.7.6 f. affine set combo

A set of the form  $\{x|x+S_2\subseteq S_1\}$ , where  $S_1,S_2\subseteq \mathbb{R}^n$  Yes, this is essentially the section of  $S_2$  that can be translated to the convex  $S_1$ 

#### 1.7.7 g. fraction distance

Not attempted

#### 1.8 Exercise 2.15

Finding which conditions sets are convex that are conditions on the probability simplex  $\{p|\mathbf{1}^Tp=1, p\succeq 0\}$ :

#### 1.8.1 a. bounded expectation

This is a linear bound, so this set is convex.

#### **1.8.2** b. prob a and b

Not attempted

# 2 Homework 2

### 2.1 Exercise 2.28

A matrix is positive semi-definite if we define two matrices symmetric A and Q, such that  $Q(\mathbf{x}) = \mathbf{x}^T A \mathbf{x}$ , Q and A are positive semidefinite if  $Q(\mathbf{x}) \geq 0$  for all  $\mathbf{x}$ .

In other words, for a matrix A to be positive semidefinite, these two conditions must be satisfied:

- A is symmetric
- $x^T A x \ge 0$  for all x

The second condition can be broadened to multiple equivalent definitions:

- $x^T A x \ge 0$  for all x
- All eigenvalues are non-negative
- There exists a matrix B s.t.  $B^TB = A$
- All principal minors are non-negative

#### 2.1.1 n=1

For n=1, the cone is defined by the inequality  $x_1 \geq 0$ 

#### 2.1.2 n=2

$$x_1x_3 - x_2^2 \ge 0$$
 and  $x_1, x_3 \ge 0$ 

#### 2.1.3 n=3

All principal minors must be non-negative, so blocking off each row and column of the matrix.

Diagonals:  $x_1, x_4, x_6 \ge 0$ 

Full matrix determinant:  $x_1(x_4x_6-x_5^2)-x_2(x_2x_6-x_3x_5)+x_3(x_2x_5-x_3x_4)\geq 0$  2x2 determinants:  $x_4x_6-x_5^2\geq 0,\ x_1x_6-x_3^2\geq 0$   $x_1x_4-x_2^2\geq 0$ 

#### 2.2 Exercise 2.33

#### 2.2.1 part a

A convex cone  $K \subseteq \mathbb{R}^n$  is a proper cone if

- K is closed (contains its boundary)
- K is solid (nonempty interior)
- K is pointed (contains no line)

For this problem, we must show that the monotone non-negative cone defined as

$$K_{m+} = \{ \mathbf{x} \in \mathbb{R}^n | x_1 \ge x_2 \ge \dots \ge x_n \ge 0 \}$$

$$\tag{15}$$

is a proper cone.

Proving the first, where  $K_{m+}$  is closed and contains its boundary, we first find the boundary of  $K_{m+}$ . The boundaries are the two vectors in the direction of

$$\begin{bmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ \vdots \\ 1 \end{bmatrix}$$

$$(16)$$

With magnitude  $x_1$ . These boundaries clearly satisfy the  $\geq$  requirements of the set. If one of the conditions was a strict equality, then the convex cone would be open.

Proving the second, since all vectors are contained in between the boundaries, the set is solid.

Proving the third, because of the  $\geq 0$  requirement, the  $\mathbf{x} \in \mathbb{R}^n$  of the set also have the  $\mathbf{x} \succeq 0$  applicable. Therefore the cone is pointed.

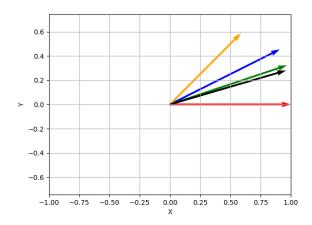


Figure 1: Image of a monotone non-negative cone in  $\mathbb{R}^2$ 

# **2.2.2** part b

Finding the dual cone  $K_{m+}^*$ . A dual cone is defined as

$$K^* = \{y | x^T y \ge 0 \text{ for all } x \in K\}$$

$$\tag{17}$$

$$x^T y \tag{18}$$

$$=\sum_{i=1}^{n} x_i y_i \tag{19}$$

$$= (x_1 - x_2)y_1 + (x_2 - x_3)(y_1 + y_2) + \dots + (x_{n-1} - x_n)(y_1 + \dots + y_n - 1) + x_n(y_1 + \dots + y_n)$$
(20)

Since each term of y is getting multiplied by  $x_i - x_{i+1}$ , and  $x_i \ge x_{i+1}$ , each y term is getting multiplied by a non-negative x term, so if we want  $x^T y \ge 0$  for all x, then we will need in the worst case scenario, for each one of the y terms to be positive.

$$y_1 \ge 0, y_1 + y_2 \ge 0, y_1 + y_2 + y_3 \ge 0, \dots, \sum_{i=1}^{n} y_i \ge 0$$
 (21)

These conditions are all satisfied when  $y_n \ge y_{n-1} \ge \cdots \ge y_2 \ge y_1 \ge 0$ . Therefore, the dual cone is

$$K^* = \{ y \in \mathbb{R}^n | y_n \ge y_{n-1} \ge \dots \ge y_2 \ge y_1 \ge 0 \}$$
 (22)

- 2.3 Exercise 3.2
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