HANSI ZENG

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EDUCATION

Nankai University, China
Major in Mathematics, (Major) GPA 85/100

University of Wisconsin Madison
Major in Mathematics, GPA 3.7/4.0

Major in Mathematics, GPA 3.7/4.0

Major in Mathematics, GPA 3.7/4.0

University of Utah Master
Major in Computer Science, GPA 3.9/4.0 09/2019-06/20021

University of Massachusetts Amherst
Major in Computer Science

PhD
09/2021-

RESEARCH TOPICS

Dense Retrieval, Neural Ranking, Recommender System, Natural Language Processing.

RESEARCH EXPERIENCE

University of Utah, School of Computing, utahIR Lab

09/2019-Present

Research Assistant, advised by Prof. Qinqyao Ai

- · Build a toolbox for the **e-commerce product search** containing several state-of-art neural network based models.
- · Write a short conference paper for review-based recommendation where the main technique we use is **transformer-like** model.
- · Write a full conference paper based on the previous work. In this work, we use text **relevance matching model** originated from IR community for better user and item modeling. Also, other techniques like **zero-attention**, **multi-task learning** are added for boosting model performance.

University of Massachusetts Amherst, Manning College of Information & Computer Sciences 09/2021-Present

Research Assistant, advised by Prof. Hamed Zamani

- · Build novel negative sampling strategies for optimizing the dense retrieval model.
- · Transfer knowledge from complex but more powerful neural re-ranking models for guiding the simple dense retrieval model training.
- · Reduce GPU and memory resources needed when training and using dense retrieval model.

PUBLICATIONS

- Hansi Zeng, Hamed Zamani, Vishwa Vinay,. Curriculum Learning for Dense Retrieval Distillation. In *Proceedings of the 45th International ACM SIGIR Conference on Research and Development in Information Retrieval* (SIGIR'22). [paper] [poster] [code] Best Short Paper Award
- Hansi Zeng, Zhichao Xu, Qingyao Ai. A Zero Attentative Relevance Matching Network for Review Modeling in Recommnder System. In *Proceedings of the 41st European Conference on Information Retrieval* (ECIR'21), oral presentation, Lucca, Italy, March 28-April 1, 2021.

- Hansi Zeng, Qingyao Ai. A Hierarchical Self-attentive Convolution Network for Review Modeling in Recommendation Systems. arXiv preprint arXiv:2011.13436.
- Zhichao Xu, **Hansi Zeng**, Qingyao Ai. Understanding the Effectiveness of Reviews in E-commerce Top-N Recommendation. In Proceedings of the 7th ACM International Conference on the Theory of Information Retrieval (ICTIR'21), Virtual, July 11, 2021.

PROJECTS

Toolbox for E-commerce Product Search github repo

09/2019-12/2020

Independent Study, advised by Professor Qingyao Ai, School of Computing, University of Utah

- · Build a toolbox for e-commerce product search followed by several software design patterns like **abstract factory pattern** to keep the code simplicity, extensibility and readability.
- · The toolbox implements several state-of-art models by **TensorFlow** with thorough hyperparameter tuning and performance comparison.
- · The main techniques used in the models are doc2vec, attention network, knowledge graph embedding.

Toolbox for Text Semantic Matching github repo

04/2020-Present

Extracurricular Activity

- · Implement several state-of-art text semantic matching models like **RE2**, **CAFE**, **ESIM** using **Pytorch** with performance comparison.
- · Organize the toolbox for easy training, hyperparameter tuning and model extension.

Toolbox for Review-Based Recommendation System github repo

05/2020-Present

Extracurricular Activity

- · Implement several state-of-art for review-based recommendation systems like **NARRE**, **DeepCoNN** using **Pytorch** with hyperparameter tuning and performance comparison.
- · Organize the toolbox for easy training, hyperparameter tuning and model extension.
- · Severed as strong baselines for our new proposed model on research.

Comparative Study of Reinforcement Learning-based and Traditional Motion Planning Algorithms presentation 09/2020-12/2020

Course project, advised by Alan Kuntz, School of Computing and the Robotics Center, University of Utah

- · Design the simulation environment based on **racecarGymEnv** from the pybullet to compare the performance between traditional motion planning algorithms and reinforcement learning algorithms.
- · Implement **RRT**(Rapidly-exploring random tree), **DQN**, **Reinforce**, **PPO**, and compare their training time, inference time, time to reach the goal in different environment settings.

TEACHING EXPERIENCES

• Teaching Assistant of ECE 3530 Engineering Probability and Statistics

Fall 2020, UoU

SKILLS

Computer Languages Python/Java/R/C++/JavaScript/MATLAB/Linux/Unix/TensorFlow/Pytorch GRE Verbal:153, Quantitative:168, Analytical Writing: 3.0

AWARDS

Second-class Scholarship, Nankai University

2015-2016