

Quizzes of TTK4225 - Systems Theory, Autumn 2020

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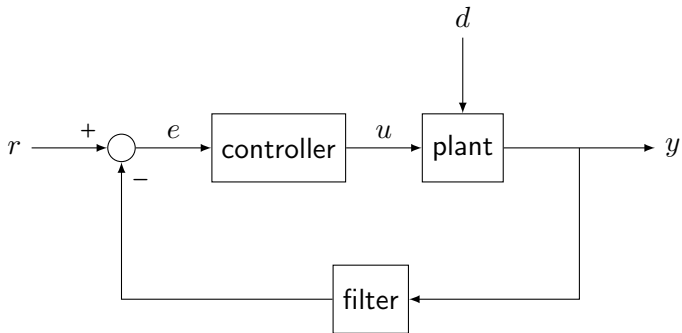
Question 1

automatic control is ...

- ① applying mechanisms so to operate processes manually but smartly, so they need little direct human intervention
- ② applying mechanisms so to operate processes automatically, so they don't need continuous direct human intervention
- ③ applying mechanisms so to analyse processes numerically, so they can be controlled when there is some direct human intervention
- ④ I do not know

Question 2

This is the only type of control we can do control:



- ① true
- ② false
- ③ it depends
- ④ I do not know

Question 3

TTK4225 is about learning how to design control systems

- ① true
- ② false
- ③ it depends
- ④ I do not know

Question 4

in our acception, dynamics means . . .

- ① the study of the motion of the variables that characterize a system
- ② the physics concerned with the effects of forces on the motion of bodies
- ③ the study of the forces or processes that produce changes inside a group or system
- ④ I do not know

Question 5

the Lotka-Volterra and Van der Pol systems are intrinsically different mainly because

...

- ❶ in the first each trajectory somehow is defined by the initial condition, while in the second they eventually are all the same independently of the initial condition
- ❷ in the first one we have a connection with animal population dynamics, while in the second we have a connection with clocks
- ❸ in the first each trajectory somehow stays by itself, while in the second there is a sort of limit cycle that attracts all the trajectories
- ❹ I do not know

Question 6

modelling a dynamical system requires defining ...

- ① only the variables of the system
- ② only the structure of the function connecting the various variables and variables' time derivatives
- ③ only the value of the parameters defining the function above
- ④ both the variables and the function
- ⑤ all the ingredients above, i.e., variables, function, and value of the parameters
- ⑥ I do not know

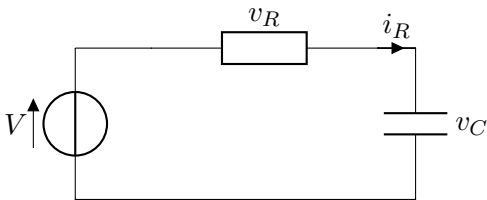
Question 7

to simulate a system it is enough to have its model

- ① true
- ② false
- ③ it depends
- ④ I do not know

Question 8

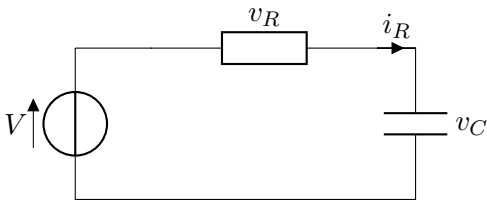
which order is this system?



- 1 1
- 2 2
- 3 3
- 4 4+
- 5 I do not know

Question 9

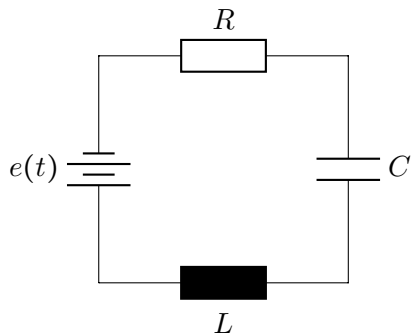
is this system linear?



- 1 yes
- 2 no
- 3 it depends
- 4 I do not know

Question 10

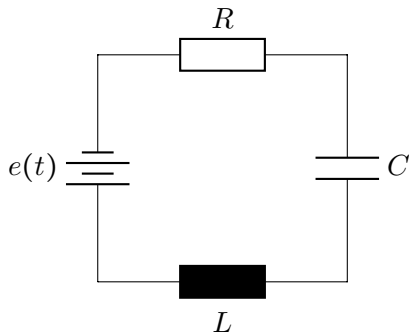
which order is this system?



- 1 1
- 2 2
- 3 3
- 4 4+

Question 11

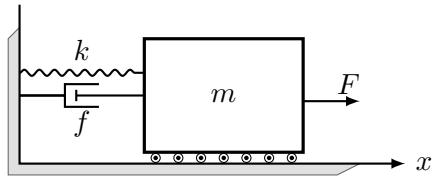
is this system linear?



- 1 yes
- 2 no
- 3 it depends
- 4 I do not know

Question 12

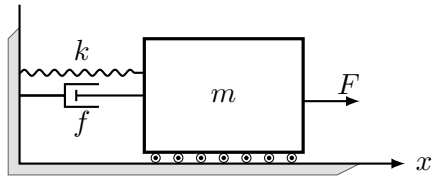
which order is this system?



- 1 1
- 2 2
- 3 3
- 4 4+
- 5 I do not know

Question 13

is this system linear?



- 1 yes
- 2 no
- 3 it depends
- 4 I do not know

Question 14

which order is this system?

$$\begin{cases} \dot{y}_1 &= \mu \left(y_1 - \frac{y_1^3}{3} - y_2 \right) \\ \dot{y}_2 &= \frac{y_1}{\mu} \end{cases}$$

- 1 1
- 2 2
- 3 3
- 4 4+
- 5 I do not know

Question 15

is this system linear?

$$\begin{cases} \dot{y}_1 &= \mu \left(y_1 - \frac{y_1^3}{3} - y_2 \right) \\ \dot{y}_2 &= \frac{y_1}{\mu} \end{cases}$$

- 1 yes
- 2 no
- 3 it depends
- 4 I do not know

Question 16

the model-free feedback-based control paradigm, where u is built without knowing the dynamics f but rather built starting from an error e , is in first approximation a reactive way of doing control

- ① true
- ② false
- ③ it depends
- ④ I do not know

Question 17

where is $e^{-\frac{3}{4}\pi j}$?

- 1 on the real axis
- 2 on the bisector of the first and third quadrant
- 3 on the imaginary axis
- 4 on the bisector of the second and fourth quadrant
- 5 I do not know

Question 18

How would you describe a derivative, $\frac{d}{dx}$?

- ① the instantaneous rate of change of something with respect to time
- ② the instantaneous velocity of the variable
- ③ the tangent of a graph
- ④ the rate of change of something with respect to x
- ⑤ none of the above
- ⑥ I do not know

Question 19

Consider $f(x) = \frac{\sin x}{x}$. Is the limit $\lim_{x \rightarrow 0} f(x) = f(0)$ correct?

- ① no, since $f(x)$ is not continuous at $x = 0$, thus $f(0)$ is not defined
- ② no, since the limit when $x \rightarrow 0$ does not exist
- ③ yes, since $\lim_{x \rightarrow 0} f(x) = f(0) = \frac{0}{0} = 0$
- ④ yes, since $f(x)$ is not continuous at $x = 0$
- ⑤ none of the above
- ⑥ I do not know

Question 20

What is the expansion of the derivative $\frac{d}{dx}f(x)g(x)$?

- 1 $f'(x)g'(x)$
- 2 $\frac{f'(x)g(x) - f(x)g'(x)}{g(x)^2}$
- 3 $f(x)g'(x) - f'(x)g(x)$
- 4 $f'(x)g(x) + f(x)g'(x)$
- 5 I do not know

Question 21

is this matrix multiplication feasible?

$$\begin{bmatrix} \star & \star & \star \\ \star & \star & \star \end{bmatrix} \begin{bmatrix} \star & \star & \star \\ \star & \star & \star \\ \star & \star & \star \end{bmatrix}$$

- 1 yes
- 2 no
- 3 it depends
- 4 I do not know

Question 22

is this matrix multiplication feasible?

$$\begin{bmatrix} \star & \star & \star & \star \\ \star & \star & \star & \star \end{bmatrix} \begin{bmatrix} \star & \star & \star \\ \star & \star & \star \\ \star & \star & \star \end{bmatrix}$$

- 1 yes
- 2 no
- 3 it depends
- 4 I do not know