

Quizzes of TTK4225 - Systems Theory, Autumn 2020

Damiano Varagnolo



Question 103

The following definition of simple stability is correct:

\mathbf{y}_{eq} is simply stable if $\forall \varepsilon > 0 \exists \delta > 0$ s.t. if $\|\mathbf{y}_0 - \mathbf{y}_{eq}\| \leq \varepsilon$ then $\|\mathbf{y}(t) - \mathbf{y}_{eq}\| \leq \delta \quad \forall t \geq 0$

- 1 true
- 2 false
- 3 it depends
- 4 I do not know

Question 104

The origin is always an equilibrium for a LTI system of the type $\dot{\mathbf{y}} = A\mathbf{y} + B\mathbf{u}$.

- ① true
- ② false
- ③ it depends
- ④ I do not know

Question 105

The origin is always an equilibrium for a generic system of the type $\dot{y} = f(y, u)$.

- 1 true
- 2 false
- 3 it depends
- 4 I do not know

Question 106

A system with periodic orbits may exhibit single equilibria.

- ① true
- ② false
- ③ it depends
- ④ I do not know

Question 107

The step-response of a system with transfer function $H(s) = \frac{1 + 2s}{2s}$ contains always both positive and negative values

- ① true
- ② false
- ③ I do not know

Question 108

A strictly proper linear time-invariant system can never have a step-response that starts in 0

- ① true
- ② false
- ③ I do not know

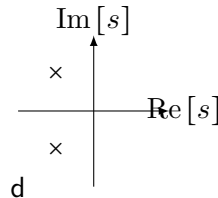
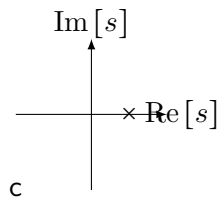
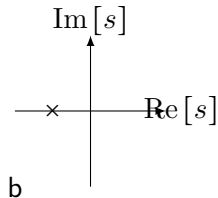
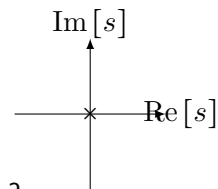
Question 109

A strictly proper linear time-invariant system will always have a step-response that starts in 0

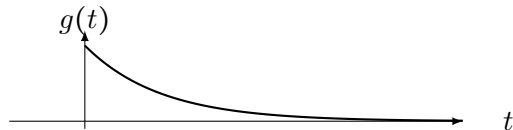
- ① true
- ② false
- ③ I do not know

Question 110

Which of the pole zeros plots



corresponds to the following impulse response?



1 a

2 b