# Quizzes of TTK4225 - Systems Theory, Autumn 2020

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Consier a generic matrix  $A \in \mathbb{R}^{n \times n}$ , and its characteristic polynomial, i.e., the scalars  $\alpha_0, \alpha_1, \dots, \alpha_{n-1}$  such that

$$A^n = -\alpha_{n-1}A^{n-1} - \ldots - \alpha_1A - \alpha_0I$$

and forming the polynomial

$$s^{n} + \alpha_{n-1}s^{n-1} + \ldots + \alpha_{1}s + \alpha_{0}.$$

Then the characteristic polynomial is the lowest order polynomial that is nullified by A. I.e., there are no other scalars  $\beta_0, \beta_1, \ldots, \beta_{m-1}$  with m < n such that

$$A^{m} = -\beta_{m-1}A^{m-1} - \dots - \beta_{1}A - \beta_{0}I$$

- true
- false
- it depends
- 4 I don't know

Assume that a system is s.t. its state update matrix A is s.t.  $A^m = \mathbf{0}$  for some m. How does this help computing the forced response of the system?

Consider a real symmetric  $n \times n$  matrix. Is it possible to diagonalize it, or may there exist cases for which it is not possible to diagonalize it? Why?

Consider a LTI system of order 5 for which all its poles are distinct. Must the associated impulse response comprise at least one mode of the type  $e^{\lambda t}$ ? If so, why?

Consider a LTI system of order 4 for which all its poles are distinct. Must the associated impulse response comprise at least one mode of the type  $e^{\lambda t}$ ? If so, why?