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3.1 Introduction

Torsion

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Pure Torsion

Angle of Twist

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3.3 Circular Bars of Linearly Elastic Materials

the Torsion Formula

Solid Shaft

Tubular Shaft

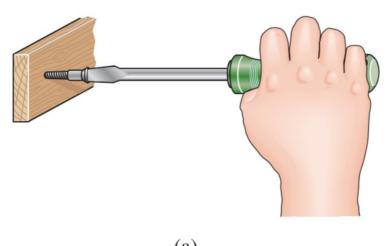
Angle of Twist

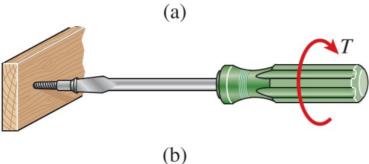
Torsional Stiffness and Torsional Flexibility

3.1 Introduction

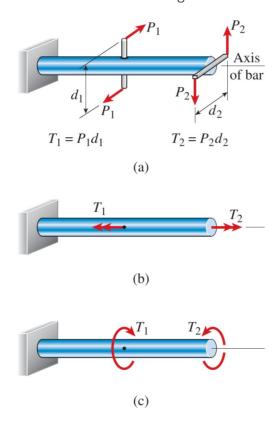
Torsion

the twisting of a straight bar when it is loaded by moment (or torque) that tends to produce rotation about the longitudinal axis of the bar





a moment that twists/deforms a member about its longitudinal axis



Shaft

cylindrical members that are subjected to torques and transmit power through rotation

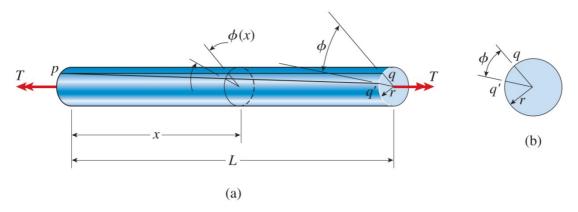
3.2 Torsional Deformation of a Circular Bar

Pure Torsion

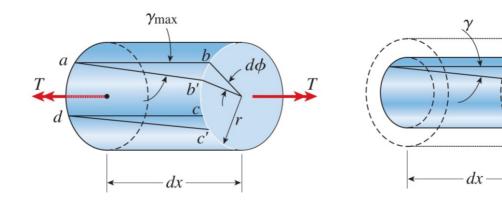
the bar is in pure torsion when every cross section of the bar is identical and subjected to the same internal torque T

Angle of Twist

under the action of the torque \it{T} , the right-hand end will rotate (with respect to the left-handed) through a small angle $\it{\phi}$



Shear Strain at the Outer Surface



$$\gamma_{max} = rac{bb'}{ab}$$
 $\Rightarrow \quad \gamma_{max} = rac{r d\phi}{dx}$

denote the symbol $\boldsymbol{\theta}$ as the **rate of twist**

$$\theta = \frac{\mathrm{d}\phi}{\mathrm{d}x}$$

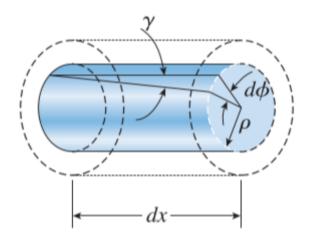
$$\Rightarrow \quad \gamma_{max} = r heta$$

for pure torsion only, we can obtain that

$$\gamma_{max} = rac{r\phi}{L}$$

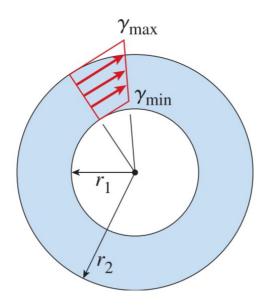
Shear Strain within the bar

$$\gamma =
ho heta = rac{
ho}{r} \gamma_{max}$$



Circular Tube

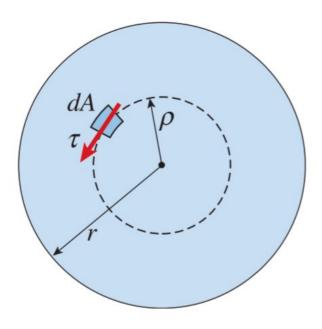
$$\gamma_{max} = rac{r_2 \phi}{L} \qquad \gamma_{min} = rac{r_1}{r_2} \gamma_{max} = rac{r_2 \phi}{L}$$



3.3 Circular Bars of Linearly Elastic Materials

the shear stresses acting on a cross-sectional plane are accompanied by shear stresses of the same magnitude acting on longitudinal planes.

the Torsion Formula



$$\mathrm{d}M = au
ho\mathrm{d}A = rac{ au_{max}}{r}
ho^2\mathrm{d}A$$

the resultant moment is the summation over the entire cross-sectional area

$$T = \int_A \mathrm{d}M = rac{ au_{max}}{r} \int_A
ho^2 \mathrm{d}A$$

in which

$$I_P = \int_A
ho^2 \mathrm{d}A$$

is the **polar moment of inertia** of the circular cross section

The shear stress at distance ρ from the center of the bar is

$$au_{max} = rac{Tr}{I_P} \qquad au = rac{T
ho}{I_P} ag{tosion formula}$$

Solid Shaft

$$\mathrm{d}A=2\pi\rho\mathrm{d}\rho$$

$$I_P=rac{\pi}{32}d^4$$

Tubular Shaft

$$I_P = rac{\pi}{32}(d_0^4 - d_i^4)$$

Angle of Twist

according to Hooke's Law in shear

$$au = G \gamma = G
ho heta = rac{
ho}{r} au_{max}$$

using the torsion formula

$$G
ho heta = rac{
ho}{r} rac{Tr}{I_P}$$
 $\Rightarrow heta = \sum rac{TL}{GI_P} = rac{\mathrm{d}\phi}{\mathrm{d}x}$

for a bar in **pure torsion**, the total angle of the twist ϕ , equal to the rate of twist time the length of the bar

$$\phi = \frac{TL}{GI_P} = \int_0^L \frac{T(x) dx}{GI_P(x)}$$

Torsional Stiffness and Torsional Flexibility

$$k_T = rac{GI_P}{L} \qquad f_T = rac{L}{GI_P}$$