

Quiz

- Quiz

- Chapter 1

- 1-1 How many bits in ATmega16 controller
- 1-2 AVR could be classified into
- 1-3 The ATmega16 contains
- 1-4 The ATmega16 is equipped with memory components of
- 1-5 How many PORTs in ATmega16
- 1-6 How many relevant 8-bit registers for each port?
- 1-7 How to configure Data Direction Register as a specific port pin as output
- 1-8 Data Register (PORTx) is used to _____ data.
- 1-9 Register Input Pin Address (PINx) is used to _____ data.
- 1-10 If PORTxn is written logic _____, the port pin is driven high.
- 1-11 How many timers/counters in ATmega16?
- 1-12 How many PWM channels in ATmega16?
- 1-13 How many serial communication subsystems in ATmega16?
- 1-14 How many channels is the ATmega16 ADC equipped?
- 1-15 How many interrupt sources in ATmega16?
- 1-16 What is the resolution of ADC in ATmega16?
- 1-17 In ATmega16, fixed clock operating frequency is
- 1-18 What are serial communication subsystems?
- 1-19 Write a program to light the LED as the button is clicked.

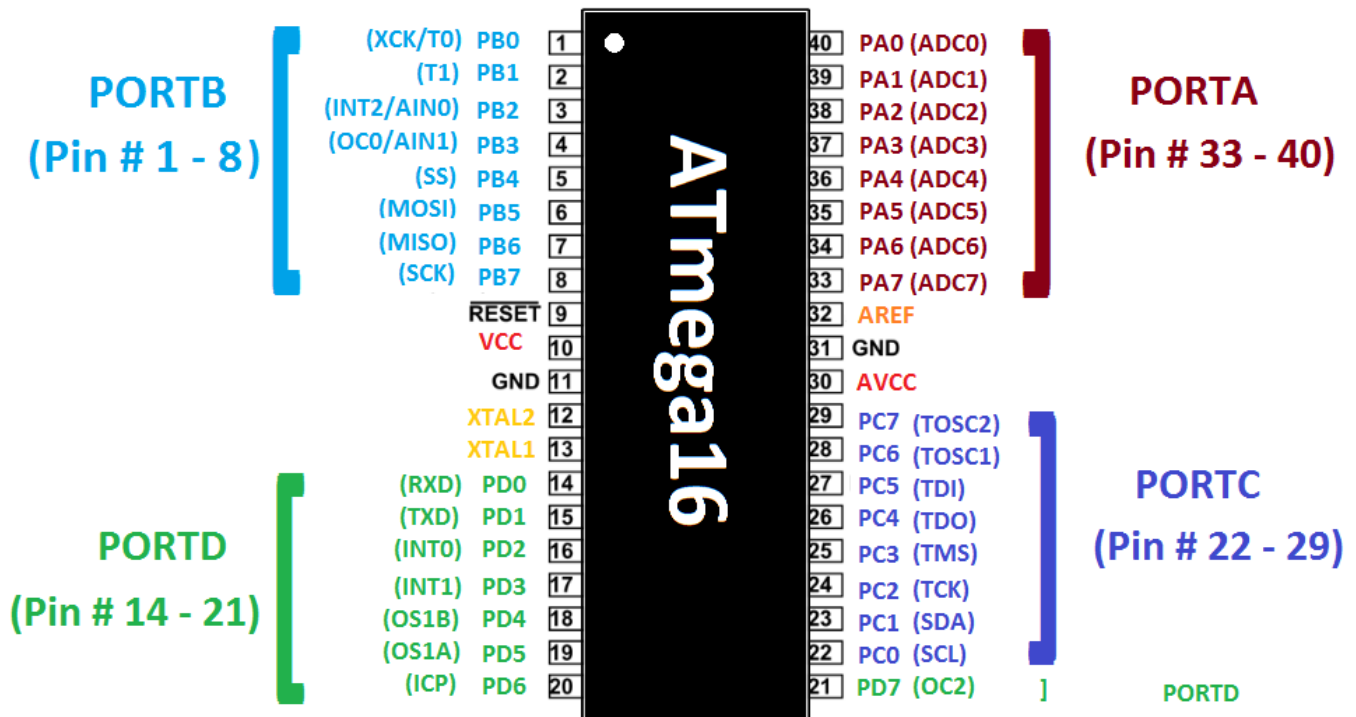
- Chapter 2

- 2-1 ASCII is a standardized _____-bit method of encoding alphanumeric data
- 2-2 RS232 Communication Protocol is a _____ communication
- 2-3 What is the voltage levels of RS232 to logic 1 and 0
- 2-4 What is the voltage levels of TTL to logic 1 and 0
- 2-5 There are _____ main tasks when using the serial port
- 2-6 USART mainly consists of _____ basic pieces
- 2-7 What does the serial communication often require?
- 2-8 The transfer of data using parallel lines is _____ (faster/slower) but _____ (more expensive/less expensive)
- 2-9 Sending data from a radio station is duplex. True or False?
- 2-10 In full duplex we must have two data lines, one for transfer and one for receive. True or False?
- 2-11 The start and stop bits are used in the _____ (synchronous/asynchronous) method

- 2-12 Assuming that we are transmitting the ASCII letter "E" (0100 0101) in binary with no parity bit and one stop bit, show the sequence of bits transferred serially.
- 2-13 Which register bit is monitored for sending(transmitting) data
- 2-14 Which register bit is monitored for receiving data
- 2-15 Which register bit is set when transmission is finished?
- 2-16 What is the definition of the baud rate?
- 2-17 How to configure the register in USART to the specific baud rate?
- 2-18 How to configure the register such that the USART would send data in 7-bit, double speed, asynchronous, 2 stop bit and even parity at 9600 baud rate
- 2-19 How many wires in SPI
- 2-20 How many registers are in SPI
- 2-21 In comparison between USART and SPI, which one is faster?
- 2-22 Which register in SPI is used to monitor the sending/receiving data?
- 2-23 How many wires in TWI?
- 2-24 Write a program of USART initialization, transmission and reception.
- 2-25 Write a program of SPI initialization, transmission and reception.
- Chapter 3
 - 3-1 ADC is used to convert _____ signals into _____ signals
 - 3-2 What is the sampling theory?
 - 3-3 What is the definition of resolution?
 - 3-4 How does the input transducer help in the ADC process?
 - 3-5 An amplifier provides an output voltage of 0 V and -2.50 V of output voltage. Please calculate the required values of K and B for this transducer, so it may be interfaced to a microcontroller's ADC system (usually 5 and 0)
 - 3-6 How many important processes associated with the ADC?
 - 3-7 How many different types of technologies are used in ADC?
 - 3-8 How many ADC channels in ATmega16?
 - 3-9 The resolution of ADC in ATmega16 is
 - 3-10 The port of ADC in ATmega16 is
 - 3-11 The default reference voltage V_{ref} is
 - 3-12 What is the absolute accuracy of ADC in ATmega16?
 - 3-13 What is the number of the clock cycles in a single ADC conversion?
 - 3-14 How many groups of relevant ADC registers?
 - 3-15 How many functions are needed to operate the ATmega16 ADC system?
 - 3-16 How to configure the register to use reference voltage for ADC
 - 3-17 Which flag will be set to 1 when conversion is completed?
 - 3-18 How many registers in the register SFOR are used to configure the auto-triggering event of ADC
 - 3-19 How many flags in register ADCSRA specify ADC prescaler selection?

- 3-20 Please write a program of ADC initialization and reading
- Chapter 4
 - 4-1 How many interrupt sources are in ATmega16
 - 4-2 How many methods to respond to the interrupt?
 - 4-3 What do the internal interrupt include?
 - 4-4 What do the internal interrupt of ATmega16 include?
 - 4-5 How to trigger the external interrupt?
 - 4-6 If 3 interrupts are triggered simultaneously, the interrupt with _____ will execute firstly.
 - 4-7 In the program, the code of _____ is written to service of handle the interrupt request
 - 4-8 How many steps to program an interrupt?
 - 4-9 Can a pin be triggered if the pin itself is configured as an output/input?
 - 4-10 How many registers are about interrupt in ATmega16?
 - 4-11 How to enable the global interrupt?
 - 4-12 How to disable the global interrupt?
 - 4-13 INFTx will be reset if
 - 4-14 The global interrupt bit set in
 - 4-15 Which register is used to check if an interrupt occurs?
 - 4-16 Draw the circuit of ATmega16 with switches and LED, code a program such the INT0 handles interrupt in any voltage change, INT1 in falling edge.
- Chapter 5
 - 5-1 How many Timers/Counters in ATmega16?
 - 5-2 What functions can a timer have?
 - 5-3 Timing-related terminology include
 - 5-4 What is the definition of the duty cycle?
 - 5-5 How many interrupt sources are in Timer 0/2
 - 5-6 The maximum frequency of Fast PWM is _____ that of the Phase Correct PWM mode
 - 5-7 How many groups of registers are in Timer 0?
 - 5-8 TCCR_x is used to
 - 5-9 TIMSK is used to
 - 5-10 TIFR is used to
 - 5-11 TCNT_x is used to
 - 5-12 OCR_x is used to
 - 5-13 The interrupt sources in Timer 1 contain
 - 5-14 How many groups of registers are in Timer 1?
 - 5-15 WGM bits in TCCR_x register is used for
 - 5-16 COM_x bits in TCCR_x register is used for

- 5-17 CSx bits in TCCR_x register is used for



Atmega16 Pinout

SPIE	SPE	DORD	MSTR	CPOL	CPHA	SPR1	SPR0	SPCR
------	-----	------	------	------	------	------	------	------

SPIF	WCOL	-	-	-	-	-	SPI2X	SPSR
------	------	---	---	---	---	---	-------	------

SM2	SE	SM1	SM0	ISC11	ISC10	ISC01	ISC00	MCUCR
-----	----	-----	-----	-------	-------	-------	-------	-------

JTD	ISC2	-	JTRF	WDRF	BORF	EXTRF	PORF	MCUCSR
-----	------	---	------	------	------	-------	------	--------

INT1	INT0	INT2	-	-	-	IVSEL	IVCE	GICR
------	------	------	---	---	---	-------	------	------

INTF1	INTF0	INTF2	-	-	-	-	-	GIFR
-------	-------	-------	---	---	---	---	---	------

REFS1	REFS0	ADLAR	MUX4	MUX3	MUX2	MUX1	MUX0	ADMUX
-------	-------	-------	------	------	------	------	------	-------

ADEN	ADSC	ADATE	ADIF	ADIE	ADPS2	ADPS1	ADPS0	ADCSRA
------	------	-------	------	------	-------	-------	-------	--------

RXC	TXC	UDRE	FE	DOR	PE	U2X	MPCM	UCSRA
RXCIE	TXCIE	UDRIE	RXEN	TXEN	UCSZ2	RXB8	TXB8	UCSRB
URSEL	UMSEL	UPM1	UPM0	USBS	UCSZ1	UCSZ0	UCPOL	UCSRC
COM1A1	COM1A0	COM1B1	COM1B0	FOC1A	FOC1B	WGM11	WGM10	TCCR1A
ICNC1	ICES1	–	WGM13	WGM12	CS12	CS11	CS10	TCCR1B
OCIE2	TOIE2	TICIE1	OCIE1A	OCIE1B	TOIE1	OCIE0	TOIE0	TIMSK
OCF2	TOV2	ICF1	OCF1A	OCF1B	TOV1	OCF0	TOV0	TIFR

Chapter 1

1-1 How many bits in ATmega16 controller

8

1-2 AVR could be classified into

mega, tiny, classic, special-purpose

1-3 The ATmega16 contains

timer subsystem, interrupt subsystem, communication subsystem, ADC and memory components

1-4 The ATmega16 is equipped with memory components of

In-system Programmable Flash EEPROM, Byte-Addressable EEPROM, Static Random Access Memory

1-5 How many PORTs in ATmega16

4, A, B, C and D

1-6 How many relevant 8-bit registers for each port?

3, PORTx, PINx, DDRx

1-7 How to configure Data Direction Register as a specific port pin as output

DDRxn = 1

1-8 Data Register (PORTx) is used to _____ data.

write

1-9 Register Input Pin Address (PINx) is used to _____ data.

read

1-10 If PORTxn is written logic _____, the port pin is driven high.

1

1-11 How many timers/counters in ATmega16?

3, 1 16-bit timer and 2 8-bit timers

1-12 How many PWM channels in ATmega16?

4

1-13 How many serial communication subsystems in ATmega16?

3, USART, SPI and TWI

1-14 How many channels is the ATmega16 ADC equipped?

8

1-15 How many interrupt sources in ATmega16?

21, 3 for external and 18 from internal

1-16 What is the resolution of ADC in ATmega16?

10-bit

1-17 In ATmega16, fixed clock operating frequency is

1, 2, 4 and 8 MHz

1-18 What are serial communication subsystems?

USART, SPI, TWI(IIC)

1-19 Write a program to lighten the LED as the button is clicked.

Chapter 2

2-1 ASCII is a standardized _____-bit method of encoding alphanumeric data

7

2-2 RS232 Communication Protocol is a _____ communication

serial

2-3 What is the voltage levels of RS232 to logic 1 and 0

logic 1 $[-15, -3]$, logic 0 $[3, 15]$

2-4 What is the voltage levels of TTL to logic 1 and 0

logic 1 $[2, 5]$, logic 0 $[0, 0.8]$

2-5 There are _____ main tasks when using the serial port

3, initialization, transmission and reception

2-6 USART mainly consists of _____ basic pieces

4, the clock generator, transmission hardware, receiver hardware and three control registers (UCSRA, UCSRB, UCSRC), two baud rate registers (UBRRH, UBRRL) and one data register (UDR)

2-7 What does the serial communication often require?

shift registers and modems

2-8 The transfer of data using parallel lines is _____ (faster/slower) but _____ (more expensive/less expensive)

faster, more expensive

2-9 Sending data from a radio station is duplex. True or False?

False, it is simplex since the listener could only receive the message sending from the radio.

2-10 In full duplex we must have two data lines, one for transfer and one for receive. True or False?

True

2-11 The start and stop bits are used in the _____ (synchronous/asynchronous) method

asynchronous

2-12 Assuming that we are transmitting the ASCII letter "E" (0100 0101) in binary with no parity bit and one stop bit, show the sequence of bits transferred serially.

0(start bit)->1->0->1->0->0->0->1->0->1(stop bit)

2-13 Which register bit is monitored for sending(transmitting) data

UDRE

2-14 Which register bit is monitored for receiving data

RXC

2-15 Which register bit is set when transmission is finished?

TXC

2-16 What is the definition of the baud rate?

the sending rate of the bytes

2-17 How to configure the register in USART to the specific baud rate?

configure the UBRRL and UBRRH with the value of $f_{OSC} / (16 \cdot \text{BAUD}) - 1$ for asynchronous normal mode and change 16 to 8 if in asynchronous double speed mode and 16 to 2 if in synchronous master mode

2-18 How to configure the register such that the USART would send data in 7-bit, double speed, asynchronous, 2 stop bit and even parity at 9600 baud rate

```
u16 myUBRR = F_CPU / (8 * 9600) - 1;
UBRRL = (u8)(myUBRR);
UBRRH = (u8)(myUBRR >> 8);

UCSRA = (1 << U2X);
UCSRB = (1 << TXEN);
USCR = (1 << 7) | (0 << UMSEL) | (1 << UPM1) | (1 << USBS) | (1 << UCSZ1);
```

2-19 How many wires in SPI

4, MOSI, MISO, SCK(Serial Clock) and \overline{SS} (slave select)

2-20 How many registers are in SPI

3, SPSR, SPCR and SPDR

2-21 In comparison between USART and SPI, which one is faster?

SPI

2-22 Which register in SPI is used to monitor the sending/receiving data?

SPIF

2-23 How many wires in TWI?

2, SDA and SCL

2-24 Write a program of USART initialization, transmission and reception.

2-25 Write a program of SPI initialization, transmission and reception.

Chapter 3

3-1 ADC is used to convert _____ signals into _____ signals

analog, digital

3-2 What is the sampling theory?

the sampling rate must satisfy the Nyquist sampling rate, which is $\text{Nyquist Rate} = 2 \times F_{max}$

3-3 What is the definition of resolution?

Resolution is the "distance" between two adjacent quantization levels, which is $\text{resolution} = \text{range} / 2^n$

3-4 How does the input transducer help in the ADC process?

The input transducer converts physical signals into electrical signals, which is **scaled and shifted** to map to the input of ADC

3-5 An amplifier provides an output voltage of 0 V and -2.50 V of output voltage. Please calculate the required values of K and B for this transducer, so it may be interfaced to a microcontroller's ADC system (usually 5 and 0)

$$\begin{cases} 5.0 = 0 \times K + B \\ 0.0 = -2.50 \times K + B \end{cases}$$

3-6 How many important processes associated with the ADC?

3, sampling, quantization and encoding

3-7 How many different types of technologies are used in ADC?

4, successive approximation conversion, integration conversion, counter-based conversion and parallel conversion

3-8 How many ADC channels in ATmega16?

8

3-9 The resolution of ADC in ATmega16 is

10 bit

3-10 The port of ADC in ATmega16 is

PORT A

3-11 The default reference voltage V_{ref} is

5 V

3-12 What is the absolute accuracy of ADC in ATmega16?

$\pm 2\text{LSB}$

3-13 What is the number of the clock cycles in a single ADC conversion?

3-14 How many groups of relevant ADC registers?

4, ADCMUX (ADC multiplexer selection register), ADCCSA (ADC control and status register), ADCH/L (ADC data register), SFIOR (special function I/O register)

3-15 How many functions are needed to operate the ATmega16 ADC system?

2, ADC_Init and ADC_Read

3-16 How to configure the register to use reference voltage for ADC

```
ADMUX = (1<<REFS0)|channel; // AVCC
ADMUX = channel;           // internal AREF
```

3-17 Which flag will be set to 1 when conversion is completed?

ADIF

3-18 How many registers in the register SFIOR are used to configure the auto-triggering event of ADC

3, ADTS2:0

3-19 How many flags in register ADCSRA specify ADC prescaler selection?

3, ADPS2:0

3-20 Please write a program of ADC initialization and reading

Chapter 4

4-1 How many interrupt sources are in ATmega16

21, external 3 and internal 18

4-2 How many methods to respond to the interrupt?

2, polling or register an interrupt

4-3 What do the internal interrupt include?

Timer/counter overflowed, ADC conversion completed, serial transfer completed and analog comparator

4-4 What do the internal interrupt of ATmega16 include?

INT0, INT1 and INT2

4-5 How to trigger the external interrupt?

Edge and level could trigger INT0 and INT1, INT2 could only triggered by edge

4-6 If 3 interrupts are triggered simultaneously, the interrupt with _____ will execute firstly.

lowest program address, highest priority

4-7 In the program, the code of _____ is written to service of handle the interrupt request

ISR

4-8 How many steps to program an interrupt?

5 in total

- Set up the stack
- Write the ISR
- Set up the interrupt details
- Enable the interrupt
- Enable the global interrupt

4-9 Can a pin be triggered if the pin itself is configured as an output/input?

Yes

4-10 How many registers are about interrupt in ATmega16?

5, MCUCR (Microcontroller Unit Control Register), MCUCSR (Microcontroller Unit Control and Status Register), GICR (General Interrupt Control Register), SREG (AVR Status Register) and GIFR (General Interrupt Flag Register)

4-11 How to enable the global interrupt?

```
sei();
```

4-12 How to disable the global interrupt?

```
cli();
```

4-13 INFTx will be reset if

an ISR executed or the flag is written with logic one

4-14 The global interrupt bit set in

SREG

4-15 Which register is used to check if an interrupt occurs?

GIFR

4-16 Draw the circuit of ATmega16 with switches and LED, code a program such the INT0 handles interrupt in any voltage change, INT1 in falling edge.

Chapter 5

5-1 How many Timers/Counters in ATmega16?

3, Timer 0/2 are 8 bit timers and Timer 1 is the 16-bit timer

5-2 What functions can a timer have?

Mostly counting events, comparing output, input capture and producing PWM signals

5-3 Timing-related terminology include

Frequency, period and duty cycle

5-4 What is the definition of the duty cycle?

A duty cycle or power cycle is the fraction of one period in which a signal or system is active

5-5 How many interrupt sources are in Timer 0/2

2, TOVx(Timer Overflow Flag) and OCFx(Output Compare Flag)

5-6 The maximum frequency of Fast PWM is _____ that of the Phase Correct PWM mode

twice

5-7 How many groups of registers are in Timer 0?

4, TCCR0(Timer/Counter Control Register), TIMSK(Timer Interrupt Mask Register)/TIFR(Timer Interrupt Flag Register), TCNT0(Timer/Counter Register) and OCR0(Output Compare Register)

5-8 TCCRx is used to

configure the timer operations

5-9 TIMSK is used to

enable and disable the timer interrupt

5-10 TIFR is used to

monitor the timer interrupt

5-11 TCNTx is used to

store the current value of the timer

5-12 OCRx is used to

store the preset values for output compares

5-13 The interrupt sources in Timer 1 contain

4, ICF1, OCF1A, OCF1B and TOV1

5-14 How many groups of registers are in Timer 1?

5, TCCR1A/B(Timer/Counter Control Register), TIMSK(Timer Interrupt Mask Register)/TIFR(Timer Interrupt Flag Register), TCNT1(Timer/Counter Register) ,OCR1A/B(Output Compare Register) and ICR1(Input Capture Register)

5-15 WGM bits in TCCRx register is used for

Waveform generation mode

5-16 COMx bits in TCCRx register is used for

Compare match output mode

5-17 CSx bits in TCCRx register is used for

Clock select