

CH_2

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Intro Linear Time-invariant system

- linear
- time-invariant

2.1 Linear Constant-Coefficient Differential Equation

Linear constant-coefficient differential equation is the mathematical repression of a continuous-time LTI system.

Classical Solution of Differential Equations

$$C_0 \frac{d^n r(t)}{dt^n} + C_1 \frac{d^{n-1} r(t)}{dt^{n-1}} + \dots + C_{n-1} \frac{dr(t)}{dt} + C_n r(t) = E_0 \frac{d^m e(t)}{dt^m} + E_1 \frac{d^{m-1} e(t)}{dt^{m-1}} + \dots + E_{m-1} \frac{de(t)}{dt} + E_m e(t) \quad (1)$$

$$C_0 \frac{d^n r(t)}{dt^n} + C_1 \frac{d^{n-1} r(t)}{dt^{n-1}} + \dots + C_{n-1} \frac{dr(t)}{dt} + C_n r(t) = 0 \quad (2)$$

- Homogeneous solution (natural response)

1. Characteristic equation

$$C_0 \alpha^n + C_1 \alpha^{n-1} + \dots + C_{n-1} \alpha + C_n = 0 \quad (3)$$

2. Characteristic roots $\alpha_1, \alpha_2, \dots, \alpha_n$ satisfy the characteristic equation

3. Homogeneous solution

$$r_h(t) = \sum_{i=1}^n A_i e^{\alpha_i t}$$

If α_1 is the k -th repeated roots, then there will be k number of α_1 : $\sum_{i=1}^k A_i t^{k-i} e^{\alpha_1 t}$

- Particular solution (forced response)

1. Table look-up

Exciting $e(t)$	Response $r(t)$
t^p	$B_1 t^p + B_2 t^{p-1} + L + B_p t + B_{p+1}$
$e^{\alpha t}$	$B e^{\alpha t}$
$\sin(\omega t)/\cos(\omega t)$	$B_1 \sin(\omega t) + B_2 \cos(\omega t)$
$t^p e^{\alpha t} \sin(\omega t)/$ $t^p e^{\alpha t} \cos(\omega t)$	$(B_1 t^p + B_2 t^{p-1} + L + B_p t + B_{p+1}) e^{\alpha t} \sin(\omega t) + (D_1 t^p + D_2 t^{p-1} + L + D_p t + D_{p+1}) e^{\alpha t} \cos(\omega t)$

- Auxiliary conditions (initial conditions)

1. Determine the coefficients

$$r(t_0), \frac{dr(t_0)}{dt}, \frac{d^2 r(t_0)}{dt^2}, L, \frac{d^{n-1} r(t_0)}{dt^{n-1}}$$

2.2 Partial Initial Conditions

The Law of Switching

$$v_c(0_-) = v_c(0_+), i_L(0_-) = i_L(0_+)$$

Impulse Function Matching Method

$$\delta(t) \quad \delta'(t) \quad \delta''(t) \quad \dots$$

The Laplace Transform

$$X(s) = \int_0^\infty x(t) e^{-st} dt$$