

Strong form

$$\begin{cases} -\operatorname{div} (C : \varepsilon(\vec{u})) = 0 & \text{in } \Omega \\ \vec{u} = 0 & \text{on } \Gamma_D \\ (C : \varepsilon(\vec{u})) \cdot \vec{n} = \vec{g} & \text{on } \Gamma_N \end{cases}$$

where,

$$C_{ijkl} := \lambda \delta_{ij} \delta_{kl} + \mu (\delta_{ik} \delta_{jl} + \delta_{il} \delta_{jk})$$

$$\mu = \frac{E}{2(1+\nu)}, \quad \lambda = \frac{E\nu}{(1-2\nu)(1+\nu)}$$

* δ_{ij} is the Kronecker delta function

$$\delta_{ij} = \begin{cases} 1, & \text{if } i=j \\ 0, & \text{if } i \neq j \end{cases}$$

Weak formulation

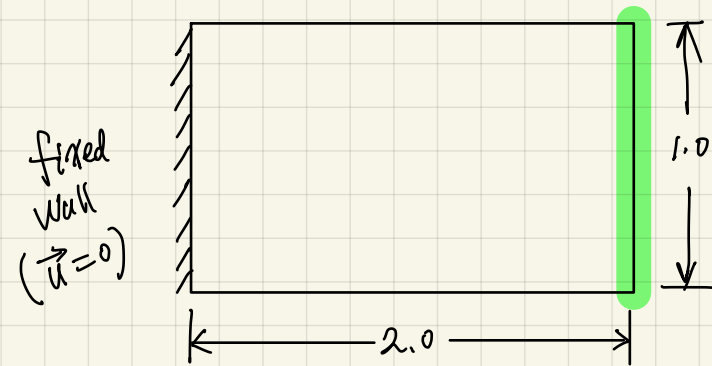
$$-\int_{\Omega} (\varepsilon(\vec{u}) : C) : \varepsilon(\vec{u}) \, d\Omega + \int_{\Gamma_N} \vec{g} \cdot \vec{u} \, d\Gamma = 0 \quad \forall \vec{u} \in \bar{U}$$

Tensor form \rightarrow Vector form

i.e., $\Omega \subset \mathbb{R}^d$, $d=2$

$$(\varepsilon(\vec{u}) : C) : \varepsilon(\vec{u}) = \begin{bmatrix} \frac{\partial u_1}{\partial x_1} \\ \frac{\partial u_2}{\partial x_2} \\ \frac{\partial u_1}{\partial x_2} + \frac{\partial u_2}{\partial x_1} \end{bmatrix}^T \begin{bmatrix} \lambda+2\mu & \lambda & 0 \\ \lambda & \lambda+2\mu & 0 \\ 0 & 0 & \mu \end{bmatrix} \begin{bmatrix} \frac{\partial \tilde{u}_1}{\partial x_1} \\ \frac{\partial \tilde{u}_2}{\partial x_2} \\ \frac{\partial \tilde{u}_1}{\partial x_2} + \frac{\partial \tilde{u}_2}{\partial x_1} \end{bmatrix}$$

Numerical Example



surface traction
 $\vec{g} = \begin{pmatrix} 0 \\ -1 \end{pmatrix}$

$$E = 1.0$$

$$\nu = 0.3$$