

RosUtils.h

```
graph TD; A[RosUtils.h] --> B[sensor_msgs/RegionOfInterest.h]; A --> C[opencv2/core/core.hpp];
```

A diagram showing a header file, RosUtils.h, at the top. Two blue arrows point downwards from it to two other header files: sensor_msgs/RegionOfInterest.h on the left and opencv2/core/core.hpp on the right. The top box is shaded gray, while the bottom two are white with gray borders.

sensor_msgs/RegionOfInterest.h

opencv2/core/core.hpp