Since 
$$\bar{W} = \begin{bmatrix} W_1 \\ W_2 \end{bmatrix}$$
,  $W_1 = 0$ 

Is See figuregui, we could conclude gui is convex and the stationary point. is a global minimum.

c, d, see figure.

d). Compared with the global minimum of gow), to = 4.1 pvx1 is a large number So, log(Itet) &t. the second order Taylor series approximation is:

For Iventon method, Thow)=0. -> W's is the stationary point of how) is also the stationary point of gow), so the situation makes sense,

3.3

a) 
$$g(\vec{w}) = \sum_{p=1}^{\infty} \left( \frac{\vec{x}_p \cdot \vec{x}_p \cdot \vec{w}_p}{\vec{x}_p \cdot \vec{w}_p} - \lambda \cdot \vec{x}_p \cdot \vec{w}_p + \lambda_p^2 \right) = \frac{1}{2} \vec{w} \cdot \left( 2 \sum_{p=1}^{\infty} \vec{x}_p \cdot \vec{x}_p \right) \vec{w} + \sum_{p=1}^{\infty} \lambda_p^2 \cdot \vec{x}_p^2 \cdot \vec{x}_$$

$$\nabla g(\vec{\omega}) = \sum_{i} 2 \tilde{\chi}_{i} (\tilde{\chi}_{i}^{T} \tilde{\omega} - y_{i}) \qquad \nabla g(\vec{\omega}) = 2 \sum_{i} \tilde{\chi}_{i}^{T} \tilde{\chi}_{i}^{T} = \overline{Q}$$

b) 
$$\nabla g(\bar{\omega}) = \sum_{p=1}^{r} 2\tilde{\chi}_{p} (\tilde{\chi}_{p} \tilde{\omega} - y_{p}) \quad \nabla g(\bar{\omega}) = 2\sum_{p=1}^{r} \tilde{\chi}_{p} \tilde{\chi}_{p} = \overline{Q}$$

C) 
$$\nabla g(\tilde{\omega}) = \overline{Q} \tilde{\omega} + \overline{r}$$
  $\nabla^2 g(\tilde{\omega}) = \overline{Q}$ 

$$\nabla^{2}g(\bar{w}^{\circ})\bar{w}' = \nabla^{2}g(\bar{w}^{\circ})\bar{w}^{\circ} - \nabla g(\bar{w}^{\circ})$$

$$Q\bar{w}' = Q\bar{w}^{\circ} - Q\bar{w}^{\circ} - \bar{\gamma}$$

$$Q\bar{w}' = -\gamma$$
.

$$S_{\theta}(\sum_{p=1}^{1^{2}}\widetilde{\chi}_{p}\widetilde{\chi}_{p}^{T})\widetilde{W} = \sum_{p=1}^{1^{2}}\widetilde{\chi}_{p}\mathscr{Y}_{p}.$$