

```

> # Execute every statement in order
> restart;
>
> # for 3-species networks with exactly 2 reactions, polynomials from the ODE
    system are:
    
$$f_1 := (x_P \ x_2 \ x_3) \rightarrow (b_{11} - a_{11}) \cdot k_1 \cdot x_1^{a_{11}} \cdot x_2^{a_{21}} \cdot x_3^{a_{31}} + (b_{12} - a_{12}) \cdot k_2 \cdot x_1^{a_{12}} \cdot x_2^{a_{22}} \cdot x_3^{a_{32}} :$$

    
$$f_2 := (x_P \ x_2 \ x_3) \rightarrow (b_{21} - a_{21}) \cdot k_1 \cdot x_1^{a_{11}} \cdot x_2^{a_{21}} \cdot x_3^{a_{31}} + (b_{22} - a_{22}) \cdot k_2 \cdot x_1^{a_{12}} \cdot x_2^{a_{22}} \cdot x_3^{a_{32}} :$$

    
$$f_3 := (x_P \ x_2 \ x_3) \rightarrow (b_{31} - a_{31}) \cdot k_1 \cdot x_1^{a_{11}} \cdot x_2^{a_{21}} \cdot x_3^{a_{31}} + (b_{32} - a_{32}) \cdot k_2 \cdot x_1^{a_{12}} \cdot x_2^{a_{22}} \cdot x_3^{a_{32}} :$$

> # if the network has one-dimensional stoichiometric subspace, then the above
    three polynomials can be simplified:
    
$$f_1 := (x_P \ x_2 \ x_3) \rightarrow (b_{11} - a_{11}) \cdot \left( k_1 \cdot x_1^{a_{11}} \cdot x_2^{a_{21}} \cdot x_3^{a_{31}} - \text{lambda} \cdot k_2 \cdot x_1^{a_{12}} \cdot x_2^{a_{22}} \cdot x_3^{a_{32}} \right) :$$

    
$$f_2 := (x_P \ x_2 \ x_3) \rightarrow (b_{21} - a_{21}) \cdot \left( k_1 \cdot x_1^{a_{11}} \cdot x_2^{a_{21}} \cdot x_3^{a_{31}} - \text{lambda} \cdot k_2 \cdot x_1^{a_{12}} \cdot x_2^{a_{22}} \cdot x_3^{a_{32}} \right) :$$

    
$$f_3 := (x_P \ x_2 \ x_3) \rightarrow (b_{31} - a_{31}) \cdot \left( k_1 \cdot x_1^{a_{11}} \cdot x_2^{a_{21}} \cdot x_3^{a_{31}} - \text{lambda} \cdot k_2 \cdot x_1^{a_{12}} \cdot x_2^{a_{22}} \cdot x_3^{a_{32}} \right) :$$

> # below, we combine the conservation law equation
    
$$h_1 := (x_P \ x_2 \ x_3) \rightarrow (b_{11} - a_{11}) \cdot \left( k_1 \cdot x_1^{a_{11}} \cdot x_2^{a_{21}} \cdot x_3^{a_{31}} - \text{lambda} \cdot k_2 \cdot x_1^{a_{12}} \cdot x_2^{a_{22}} \cdot x_3^{a_{32}} \right) :$$

    
$$h_2 := (x_P \ x_2) \rightarrow (b_{21} - a_{21}) \cdot x_1 - (b_{11} - a_{11}) \cdot x_2 - c_1 :$$

    
$$h_3 := (x_P \ x_3) \rightarrow (b_{31} - a_{31}) \cdot x_1 - (b_{11} - a_{11}) \cdot x_3 - c_2 :$$

> # stability criterion
    
$$\text{tr} := D[1](f_1)(x_P \ x_2 \ x_3) + D[2](f_2)(x_P \ x_2 \ x_3) + D[3](f_3)(x_P \ x_2 \ x_3) :$$

>
> sol := [ 0, 0, 0 ] : evasol := [ 0, 0, 0 ] : evatr := [ 0, 0, 0 ] :
>
> # below, we show witness of multistability for networks in Row (3) and Row (7)
    in Table 2 (see main manuscript)
> # -----
    # Row (3)
    #  $X_1 + 3X_2 \rightarrow 4X_2 + X_3$ 
    #  $X_2 + X_3 \rightarrow X_1$ 

```

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> a11 := 1 : a21 := 3 : a31 := 0 : a12 := 0 : a22 := 1 : a32 := 1 :
  b11 := 0 : b21 := 4 : b31 := 1 : b12 := 1 : b22 := 0 : b32 := 0 :
  h1(x1, x2, x3) ; h2(x1, x2) ; h3(x1, x3) ;

```

$$\frac{-k_1 x_1 x_2^3 + \lambda k_2 x_2 x_3}{x_1 + x_2 - c_1} \\ x_1 + x_3 - c_2$$

(1)

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> # choose witness

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  lambda := 1 : k1 := 9 : k2 := 50 : c1 := 6 : c2 :=  $\frac{59}{10}$  :
  h1(x1, x2, x3) ; h2(x1, x2) ; h3(x1, x3) ;

```

$$\frac{-9 x_1 x_2^3 + 50 x_2 x_3}{x_1 + x_2 - 6} \\ x_1 + x_3 - \frac{59}{10}$$

(2)

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> # 3 positive steady states

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  # stable, if tr<0;

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  shsol := solve(h1(x1, solve(h2(x1, x2), x2), solve(h3(x1, x3), x3)), x1) :

```

```

  for n from 2 to 4 do

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    sol[n-1] := [x1 = shsol[n], x2 = solve(h2(shsol[n], x2), x2), x3
      = solve(h3(shsol[n], x3), x3)] ;

```

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    evasol[n-1] := evalf(sol[n-1], 5);

```

```

    evatr[n-1] := if_tr = evalf(subs(sol[n-1][1], sol[n-1][2], sol[n-1][3], tr),
      5);

```

```

  end do;

```

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  # 1st column: Solutions; 2nd column: Approximate Values; 3rd column: Trace of
    Jacobian(f).

```

```

  [Steady States, Approximate Values, Trace of Jacobian(f)] ;

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```

  [sol[2], evasol[2], evatr[2]] ;

```

```

  [sol[1], evasol[1], evatr[1]] ;

```

```

  [sol[3], evasol[3], evatr[3]] ;

```

```

  [Steady States, Approximate Values, Trace of Jacobian(f)]

```

$$\left[\left[x_1 = \frac{7}{2} - \frac{\sqrt{205}}{6}, x_2 = \frac{5}{2} + \frac{\sqrt{205}}{6}, x_3 = \frac{12}{5} + \frac{\sqrt{205}}{6} \right], \left[x_1 = 1.1136, x_2 = 4.8864, x_3 \right. \right. \\ \left. \left. = 4.7864 \right], \text{ if_tr} = -815.74 \right]$$

$$\left[\left[x_1 = 5, x_2 = 1, x_3 = \frac{9}{10} \right], \left[x_1 = 5., x_2 = 1., x_3 = 0.90000 \right], if_tr = 31. \right]$$

$$\left[\left[x_1 = \frac{7}{2} + \frac{\sqrt{205}}{6}, x_2 = \frac{5}{2} - \frac{\sqrt{205}}{6}, x_3 = \frac{12}{5} - \frac{\sqrt{205}}{6} \right], \left[x_1 = 5.8864, x_2 = 0.1136, x_3 \right. \right. \quad (3)$$

$$\left. \left. = 0.0136 \right], if_tr = -4.32 \right]$$

```

>
>
> # -----
> # Row (7)

```

```

#  $X_1 + 2 X_2 + X_3 \rightarrow b_{21} X_2$ 
#  $3 X_3 \rightarrow b_{12} X_1 + b_{22} X_2 + b_{32} X_3$ 
#  $b_{21} = 0$ 

```

```

>
> unassign( 'b12', 'b22', 'b32' );
a11 := 1 : a21 := 2 : a31 := 1 : a12 := 0 : a22 := 0 : a32 := 3 :
b11 := 0 : b21 := 0 : b31 := 0 : b12 := b12 : b22 := 2·b12 : b32 := b12 + 2 :
h1(x1, x2, x3); h2(x1, x2); h3(x1, x3);

```

$$\frac{-9 x_1 x_2^2 x_3 + 50 x_3^3}{-2 x_1 + x_2 - 6} \quad (4)$$

$$\frac{-x_1 + x_3 - \frac{59}{10}}{10}$$

```

> # choose witness

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```

lambda := b12 : k1 := 1 : k2 :=  $\frac{48}{b_{12}}$  : c1 :=  $\frac{13}{2}$  : c2 :=  $\frac{1}{4}$  :

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```

h1(x1, x2, x3); h2(x1, x2); h3(x1, x3);

```

$$\frac{-x_1 x_2^2 x_3 + 48 x_3^3}{-2 x_1 + x_2 - \frac{13}{2}}$$

$$\frac{-2 x_1 + x_2 - \frac{13}{2}}{2}$$

$$\frac{-x_1 + x_3 - \frac{1}{4}}{4} \quad (5)$$

```

> # 3 positive steady states

```

```

# stable, if tr<0;

```

```

shsol := solve( h1(x1, solve( h2(x1, x2), x2), solve( h3(x1, x3), x3)), x1) :

```

```

for n from 2 to 4 do

```

```

sol[n-1] := [ x1 = shsol[n], x2 = solve( h2(shsol[n], x2), x2), x3

```

```

= solve(h3(shsol[n], x3), x3);
evasol[n-1] := evalf(sol[n-1], 5);
evatr[n-1] := if_tr = evalf(subs(sol[n-1][1], sol[n-1][2], sol[n-1][3], tr),
5);
end do:

```

1st column: Solutions; 2nd column: Approximate Values; 3rd column: Trace of Jacobian(f).

```

[Steady States, Approximate Values, Trace of Jacobian(f)];
[sol[2], evasol[2], evatr[2]];
[sol[1], evasol[1], evatr[1]];
[sol[3], evasol[3], evatr[3]];

```

[Steady States, Approximate Values, Trace of Jacobian(f)]

$$\left[\left[x_1 = \frac{19}{8} - \frac{3\sqrt{33}}{8}, x_2 = \frac{45}{4} - \frac{3\sqrt{33}}{4}, x_3 = \frac{21}{8} - \frac{3\sqrt{33}}{8} \right], [x_1 = 0.2208, x_2 = 6.9416, x_3 = 0.4708], \text{if_tr} = -4.293 \right]$$

$$\left[\left[x_1 = \frac{3}{4}, x_2 = 8, x_3 = 1 \right], [x_1 = 0.75000, x_2 = 8., x_3 = 1.], \text{if_tr} = 8. \right]$$

$$\left[\left[x_1 = \frac{19}{8} + \frac{3\sqrt{33}}{8}, x_2 = \frac{45}{4} + \frac{3\sqrt{33}}{4}, x_3 = \frac{21}{8} + \frac{3\sqrt{33}}{8} \right], [x_1 = 4.5292, x_2 = 15.558, x_3 = 4.7792], \text{if_tr} = -311.1 \right]$$

(6)

```

=>
=>
> # -----
# Row (7)

```

```

# X1 + 2 X2 + X3 → b21X2
# 3 X3 → b12X1 + b22X2 + b32X3
# b21 = 1

```

```

=>
> unassign('b12', 'b22', 'b32');
a11 := 1 : a21 := 2 : a31 := 1 : a12 := 0 : a22 := 0 : a32 := 3 :
b11 := 0 : b21 := 1 : b31 := 0 : b12 := b12 : b22 := b12 : b32 := b12 + 2 :
h1(x1, x2, x3); h2(x1, x2); h3(x1, x3);

```

$$-x_1 x_2^2 x_3 + 48 x_3^3$$

$$\begin{aligned} & -x_1 + x_2 - \frac{13}{2} \\ & -x_1 + x_3 - \frac{1}{4} \end{aligned} \quad (7)$$

> # choose witness

$$\text{lambda} := b_{12} : k_1 := 1 : k_2 := \frac{12}{b_{12}} : c_1 := \frac{13}{4} : c_2 := \frac{1}{4} :$$

$$h_1(x_1, x_2, x_3); h_2(x_1, x_2); h_3(x_1, x_3);$$

$$-x_1 x_2^2 x_3 + 12 x_3^3$$

$$-x_1 + x_2 - \frac{13}{4}$$

$$-x_1 + x_3 - \frac{1}{4}$$

(8)

> # 3 positive steady states

stable, if $tr < 0$;

$$\text{shsol} := \text{solve}(h_1(x_1, \text{solve}(h_2(x_1, x_2), x_2), \text{solve}(h_3(x_1, x_3), x_3))), x_1) :$$

for n from 2 to 4 do

$$\begin{aligned} \text{sol}[n-1] &:= [x_1 = \text{shsol}[n], x_2 = \text{solve}(h_2(\text{shsol}[n], x_2), x_2), x_3 \\ &= \text{solve}(h_3(\text{shsol}[n], x_3), x_3)]; \end{aligned}$$

$$\text{evasol}[n-1] := \text{evalf}(\text{sol}[n-1], 5);$$

$$\text{evatr}[n-1] := \text{if_tr} = \text{evalf}(\text{subs}(\text{sol}[n-1][1], \text{sol}[n-1][2], \text{sol}[n-1][3], \text{tr}), 5);$$

end do;

1st column: Solutions; 2nd column: Approximate Values; 3rd column: Trace of Jacobian(f).

[Steady States, Approximate Values, Trace of Jacobian(f)];

$$[\text{sol}[2], \text{evasol}[2], \text{evatr}[2]];$$

$$[\text{sol}[1], \text{evasol}[1], \text{evatr}[1]];$$

$$[\text{sol}[3], \text{evasol}[3], \text{evatr}[3]];$$

[Steady States, Approximate Values, Trace of Jacobian(f)]

$$\left[\left[x_1 = \frac{19}{8} - \frac{3\sqrt{33}}{8}, x_2 = \frac{45}{8} - \frac{3\sqrt{33}}{8}, x_3 = \frac{21}{8} - \frac{3\sqrt{33}}{8} \right], [x_1 = 0.2208, x_2 = 3.4708, x_3 = 0.4708], \text{if_tr} = -1.0733 \right]$$

$$\left[\left[x_1 = \frac{3}{4}, x_2 = 4, x_3 = 1 \right], [x_1 = 0.75000, x_2 = 4., x_3 = 1.], \text{if_tr} = 2. \right]$$

$$\left[\left[x_1 = \frac{19}{8} + \frac{3\sqrt{33}}{8}, x_2 = \frac{45}{8} + \frac{3\sqrt{33}}{8}, x_3 = \frac{21}{8} + \frac{3\sqrt{33}}{8} \right], [x_1 = 4.5292, x_2 \right] \quad (9)$$

