# AMATH / PMATH 332 Course Notes

**Applied Complex Analysis** 

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## Chapter 1 Complex Numbers

### 1.1 Intro, Properties of Complex Numbers

Intro:

- What it's about: <u>not</u> like real analysis; some of intro to calculus on  $\mathbb C$
- Goal: extend calculus on  $\mathbb R$  to  $\mathbb C$  many results become <u>simpler!</u> (more complete picture here)
- Can be used to solve some  $\mathbb{R}$  problems.

The Fundamentals:

- Basic idea: define solutions to  $x^2 + 1 = 0$
- Early Mathematicians:  $x = \pm \sqrt{-1}$ . For  $\sqrt{-1}$ , should we call it i?
- Note: "\sqrt{"}" always denotes positive root, e.g.  $\sqrt{4} = 2$
- Problem:

$$\sqrt{-1}\sqrt{-1} = -1$$
 by definition of  $\sqrt{-1}\sqrt{-1} = \sqrt{(-1)(-1)} = \sqrt{1} = 1$  since  $\sqrt{ab} = \sqrt{a}\sqrt{b}$ 

• Fix: interret " $\sqrt{\phantom{a}}$ " differently for complex numbers - it must be multivalued, and define the imaginary unit i by  $i^2=1$ 

## Definition 1.1. Complex number:

$$z = \underbrace{a}_{\text{"real part"}} + i \underbrace{b}_{\text{Im}(z) \text{ which is real!}} \text{ where } a, b \in \mathbb{R}$$

 $\mathbb{C} = \text{set of complex numbers. Note that } \mathbb{R} \subset \mathbb{C}$ 

**Definition 1.2.** Let z = a + bi, and w = c + di. Then:

- z = w if and only if a = c and b = d
- z + w = (a + bi) + (c + di) = a + c + (b + d)i
- z w = z + (-w) = (a + bi) + (-c di) = a c + (b d)i
- $zw = (a+bi)(c+di) = ac+bdi^2+adi+bci = ac-bd+(ad+bc)i$
- $\bullet \ \frac{z}{w} = \frac{a+bi}{c+di} \cdot \frac{c-di}{c-di} = \frac{ac+bd}{c^2+d^2} + i \cdot \frac{bc-ad}{c^2+d^2}$

Example 1.3.

$$\frac{2+i}{1+2i} = \frac{2+i}{1+2i} \cdot \frac{1-2i}{1-2i} = \frac{4}{5} - \frac{3}{5}i$$
$$\frac{1}{i} = \frac{1}{i} \cdot \frac{-i}{-i} = \frac{-i}{-i^2} = -i$$

**Theorem 1.4.** z + w = w + z, k(z + w) = kz + kw apply as usual. zw = wz

Note: We can't classify complex numbers as "positive" or "negative", and can't use inequalities, e.g. z>w doesn't make sense.

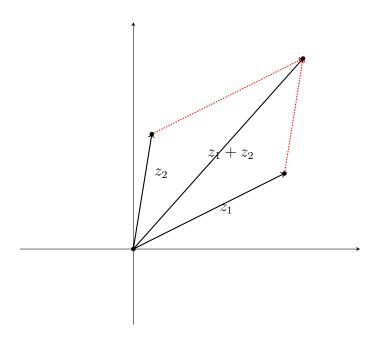
**Definition 1.5. Conjugate** of z = a + bi is

$$\overline{z} = a - bi$$

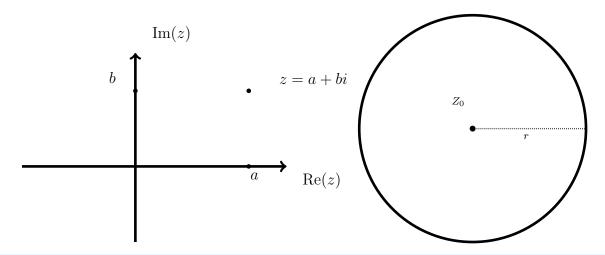
(Sometimes written as  $z^*$  as well)

**Proposition 1.6.** The following rules apply:

- $1. \ \overline{\overline{z}} = z$
- $2. \ \overline{z \pm w} = \overline{z} \pm \overline{w}$
- 3.  $\overline{zw} = \overline{z} \, \overline{w} \text{ and } \overline{\left(\frac{z}{w}\right)} = \frac{(\overline{z})}{(\overline{w})}$
- 4.  $z + \overline{z} = 2Re(z) \implies Re(z) = \frac{1}{2}(z + \overline{z})$
- 5.  $z \overline{z} = 2iIm(z) \implies Im(z) = \frac{1}{2i}(z \overline{z})$
- 6.  $z\overline{z} = a^2 + b^2$  which is real!



## 1.2 The Complex Plane, Polar form



**Definition 1.7.** The <u>modulus</u> of z = a + bi is  $|z| = \sqrt{a^2 + b^2}$ 

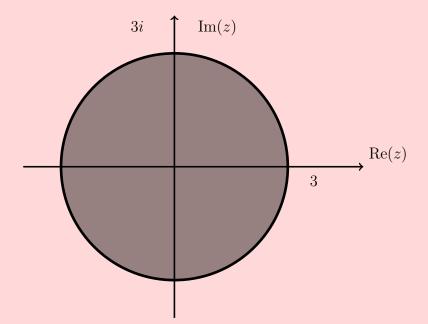
The <u>distance</u> between two numbers z and w is |z - w|

Notes:

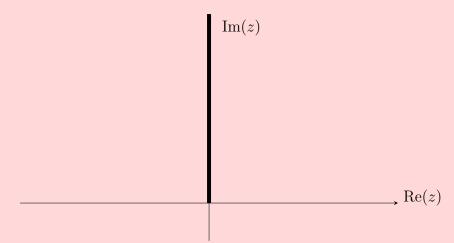
- $|z| \ge 0$  and is real
- $\bullet \ z\overline{z} = a^2 + b^2 = |z|^2$
- $|z z_0| = r$  describes a circule of radius r centered at  $z_0$

#### Example 1.8. Sketch the sets:

1. |z| < 3



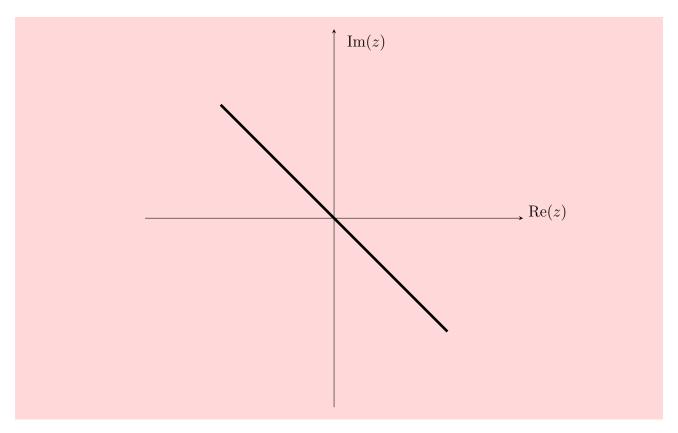
2. |z|=Im(z). Let z=a+ib. So,  $\sqrt{a^2+b^2}=b$ , which gives  $a^2+b^2=b^2$ , so  $a=0,b\geq 0$ 



3. |z-1| = |z+i|. So

$$\sqrt{(a-1)^2 + b^2} = \sqrt{a^2 + (b+1)^2}$$
$$(a-1)^2 + b^2 = a^2 + (b+1)^2$$
$$a^2 - 2a + 1 + b^2 = a^2 + b^2 + 2b + 1$$
$$b = -a$$

This is the set of points that are equidistant from z=1 and z=-i



We will often use z = x + yi, so we are in the xy-plane, still not called  $\mathbb{R}^2$  though.

Useful inequalities:

$$|z_1 + z_2| \le |z_1| + |z_2|$$

This is known as "Triangle Inequality". This also extends to

$$|z_1 = z_2 + \dots + z_n| \le |z_1| + \dots + |z_n|$$

Corollary 1.9.

$$|z_1 + z_2| \ge \left| |z_1| - |z_2| \right|$$

Proof 1.10.

$$|z_1| = |z_1 + (z_2 - z_2)|$$

$$= |(z_1 + z_2) + (-z_2)|$$

$$\leq |z_1 + z_2| + |z_2|$$

$$|z_2| = |z_2 + (z_1 - z_1)|$$

$$= |(z_1 + z_2) + (-z_1)|$$

$$\leq |z_1 + z_2| + |z_1|$$

So  $|z_1 + z_2| \ge |z_1| - |z_2|$  and  $|z_2| - |z_1|$ . So

$$|z_1 + z_2| \ge \left| |z_1| - |z_2| \right|$$

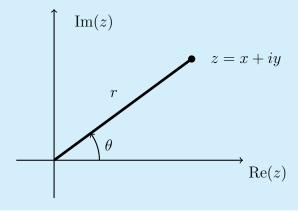
#### Definition 1.11. Polar Form

$$x = r\cos\theta, \ y = r\sin\theta$$

So,

$$z = r \cos \theta + ir \sin \theta$$
$$= r(\cos \theta + i \sin \theta)$$
$$= r \underbrace{\cos}_{\text{common abreviation}} \theta$$

$$r = \sqrt{x^2 + y^2}, \tan \theta = \frac{y}{x}$$



Notes:

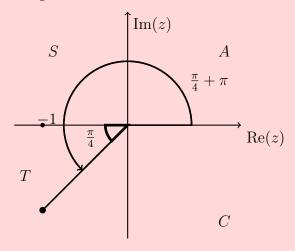
- This is not unique. e.g.  $z=2=2\operatorname{cis}0=2\operatorname{cis}2\pi=\cdots$ , also  $z=0=0\operatorname{cis}\theta$  for any  $\theta$
- $\theta = \tan^{-1}(\frac{y}{x})[\pm 2k\pi]$  if x > 0, but must add  $\pi$  if x < 0 Recall principal values

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**Example 1.12.** Say we want to express z = -1 - i in polar form.

We compute  $r = \sqrt{(-1)^2 + (-1)^2} = \sqrt{2}$ .  $\tan \theta = \frac{-1}{-1} = 1$ . Note that  $\theta \neq \tan^{-1}(1) = \frac{\pi}{4}$ , instead,  $\theta = \frac{5\pi}{4}$ .

So, 
$$z = \sqrt{2}\operatorname{cis}\frac{5\pi}{4}$$
 or  $\sqrt{2}\operatorname{cis}(\frac{5\pi}{4} + 2k\pi)$ 



Note:

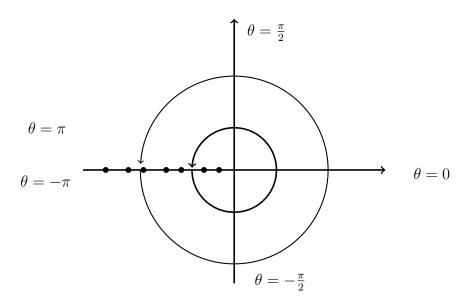
$$z = \underbrace{r}_{=\sqrt{x^2 + y^2}, r = |z|, \text{``modulus''}} \text{cis } \underbrace{\theta}_{\text{``argument''}} \text{ of } z$$

Also, "arg z" = set of all possible values of  $\theta$ . "Arg z" = principle values of  $\theta$ , usually in  $(\pi, \pi]$ 

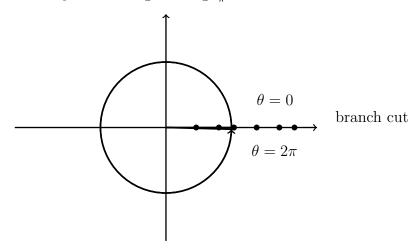
**Example 1.13.** For 
$$z = -1 + \sqrt{3}i$$
. Arg  $z = \frac{2\pi}{3}$ , arg  $z = \frac{2\pi}{3} + 2k\pi$ ,  $k \in \mathbb{Z}$ 

Also, |z| = 2, so  $-1 + \sqrt{3}i = 2\operatorname{cis} \frac{2\pi}{3}$ 

We sometimes think of  $\arg z$  as a multivalued "function" of z. For a single-valued function, we could use  $\operatorname{Arg} z$ , but it has discontinuity on negative real axis.



Another way: we can define  ${\rm Arg}(z)$  to have range  $[0,2\pi)$ . In general,  ${\rm Arg}_{\theta_0}\,z$  has range  $[\theta_0,\theta_0+2\pi)$ , and usually we use  ${\rm Arg}\,z={\rm Arg}_{-\pi}\,z$ 



## 1.3 Complex Exponential, Powers and Roots

Reading textbook Section 1.4, 1.5

**Definition 1.14.** If z = x + iy, then  $e^z$  is defined to be the complex number

$$e^z := e^x(\cos y + i\sin y)$$

Proposition 1.15. Euler's equation is formally consistent with the usual Taylor series ex-

pansions:

$$e^{x} = 1 + x + \frac{x^{2}}{2!} + \frac{x^{3}}{3!} + \cdots$$

$$\cos x = 1 - \frac{x^{2}}{2!} + \frac{x^{4}}{4!} - \cdots$$

$$\sin x = x - \frac{x^{3}}{3!} + \frac{x^{5}}{5!} - \cdots$$

**Proof 1.16.** Let's substitute x = iy into the exponential series:

$$e^{iy} = 1 + iy + \frac{(iy)^2}{2!} + \frac{(iy)^3}{3!} + \cdots$$

$$= (1 - \frac{y^2}{2!} + \frac{y^4}{4!} - \cdots) + i(y - \frac{y^3}{3!} + \frac{y^5}{5!} - \cdots)$$

$$= \cos y + i \sin y$$

As a result, we may introduce the standard polar representation

$$z = r \operatorname{cis} \theta = r(\cos \theta + i \sin \theta) = re^{i\theta} = |z|e^{i \operatorname{arg} z}$$

Notice that

$$e^{i0} = e^{2\pi i} = e^{-2\pi i} = e^{4\pi i} = e^{-4\pi i} = \dots = 1$$
  
 $e^{(\pi/2)i} = i$   $e^{(-\pi/2)i} = -i$   $e^{\pi i} = -1$ 

Also notice that

$$\cos \theta = Re(e^{i\theta}) = \frac{e^{i\theta} + e^{-i\theta}}{2}$$
$$\sin \theta = Im(e^{i\theta}) = \frac{e^{i\theta} - e^{-i\theta}}{2i}$$

Hence,

$$z_1 z_2 = (r_1 e^{i\theta_1})(r_2 e^{i\theta_2}) = (r_1 r_2) e^{i(\theta_1 + \theta_2)}$$
$$\frac{z_1}{z_2} = \frac{r_1 e^{i\theta_1}}{r_2 e^{i\theta_2}} = \frac{r_1}{r_2} e^{i(\theta_1 - \theta_2)}$$
$$\overline{z} = r e^{-i\theta}, \text{ given that } z = r e^{i\theta}$$

**Example 1.17.** Compute the following:

1.  $(1+i)/(\sqrt{3}-i)$ .

Notice that  $1 + i = \sqrt{2}\operatorname{cis}(\pi/4) = \sqrt{2}e^{i\pi/4}$ , and  $\sqrt{3} - i = 2\operatorname{cis}(-\pi/6) = 2e^{-i\pi/6}$ . So,

$$\frac{1+i}{\sqrt{3}-i} = \frac{\sqrt{2}e^{i\pi/4}}{2e^{-i\pi/6}} = \frac{\sqrt{2}}{2}e^{i5\pi/12}$$

2.  $(1+i)^{24}$ 

We have

$$(1+i)^{24} = (\sqrt{2}e^{i\pi/4})^{24} = (\sqrt{2})^{24}e^{i24\pi/4} = 2^{12}e^{i6\pi} = 2^{12}$$

Theorem 1.18.

$$(\cos \theta + i \sin \theta)^n = \cos n\theta + i \sin n\theta \quad n = 1, 2, 3, \dots$$

**Definition 1.19.** There are exactly m distinct m-th <u>roots of unity</u>, denoted by  $1^{1/m}$ , and they are given by

$$1^{1/m} = e^{i2k\pi/m} = \cos\frac{2k\pi}{m} + i\sin\frac{2k\pi}{m} \quad (k = 0, 1, 2, ..., m - 1)$$

Take k = 1 into the above equation, we can get

$$\omega_m := e^{i2\pi/m} = \cos\frac{2\pi}{m} + i\sin\frac{2\pi}{m}$$

So the complete set of roots can be displayed as

$$\{1, \omega_m, \omega_m^2, \cdots, \omega_m^{m-1}\}$$

Note that a number w is said to be a <u>primitive</u> m-th root of unity if  $w^m = 1$  but  $w^k \neq 1$  for k = 1, 2, ..., m - 1. Clearly,  $\omega_m$  is a <u>primitive</u> root.

Theorem 1.20.

$$1 + \omega_m + \omega_m^2 + \dots + \omega_m^{m-1} = 0$$

**Proof 1.21.** Note that

$$(\omega_m - 1)(1 + \omega_m + \omega_m^2 + \dots + \omega_m^{m-1}) = (\omega_m - 1) = 0$$

Since  $\omega_m \neq 1$ , the result follows.

To obtain the m-th root of an arbitrary (non-zero) complex number  $z = re^{i\theta}$ , we can obtain the following generalized result.

**Definition 1.22.** The m-th distinct roots of z are given by

$$z^{1/m} = \sqrt[m]{|z|}e^{i(\theta + 2k\pi)/m}$$

**Example 1.23.** Find all the cube roots of  $\sqrt{2} + i\sqrt{2}$ 

The polar form for  $\sqrt{2} + i\sqrt{2}$  is

$$\sqrt{2} + i\sqrt{2} = 2e^{i\pi/4}$$

Putting  $|z|=2, \theta=\pi/4, m=3$  into the above definition, we obtain

$$(\sqrt{2} + i\sqrt{2})^{1/3} = \sqrt[3]{2}e^{i(\pi/12 + 2k\pi/3)}, \quad (k = 0, 1, 2)$$

Hence, the three cube roots of  $\sqrt{2} + i\sqrt{2}$  are:

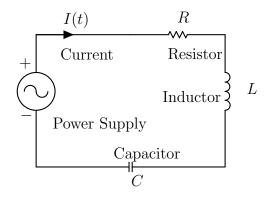
- $\sqrt[3]{2}(\cos \pi/12 + i\sin \pi/12)$
- $\sqrt[3]{2}(\cos 3\pi/4 + i\sin 3\pi/4)$
- $\sqrt[3]{2}(\cos 17\pi/12 + i\sin 17\pi/12)$

## 1.4 Application to Electrical Circuits

A typical electrical circuits is like the following:

Laws:

- 1. Resistor: V = IR
- 2. Inductor:  $V = L \frac{dI}{dt}$
- 3. Capacitor:  $C \frac{dV}{dt} = I$



Suppose the current is

$$I(t) = \underbrace{I_0}_{\text{amplitude}} \cos \underbrace{\omega}_{\text{frequency}} t = Re(\underbrace{I_0 e^{i\omega t}}_{\text{call it } \widetilde{I}(t)})$$

Then

1. Law 1 tells us  $V=(I_0\cos\omega t)(R)=Re(\widetilde{I}(t)\cdot R).$  So "complex voltage" is

$$\widetilde{V} = R\widetilde{I}$$

2. Law 2 tells us

$$V = L \cdot (-\omega I_0 \sin \omega t)$$

$$= -\omega L I_0 \cdot \underbrace{Re(e^{i(\omega t - \frac{\pi}{2})})}_{=\cos(\omega t - \frac{\pi}{2}) = \sin \omega t}$$

$$= Re(-\omega L I_0 e^{i\omega t} e^{-i\frac{\pi}{2}})$$

$$= Re(i\omega L I_0 e^{i\omega t})$$

So

$$\widetilde{V} = i\omega L\widetilde{I}$$

3. Law 3 tells us

$$\begin{split} V &= \frac{1}{C} \int I(t) \\ &= \frac{I_0}{C\omega} \sin \omega t \\ &= Re(\frac{I_0}{C\omega} e^{i(\omega t - \frac{\pi}{2})}) \\ &= Re(\frac{I_0}{iC\omega} e^{i\omega t}) \end{split}$$

So

$$\widetilde{V} = \frac{1}{iC\omega}\widetilde{I}$$

So, with the complex representation, all three circuit elements behave like resistors with a complex "Ohm's Law'

$$\widetilde{V} = Z\widetilde{I} \quad \text{where } Z = \begin{cases} R & \text{for resistors} \\ i\omega L & \text{for inductors} \\ \frac{1}{i\omega C} & \text{for inductors} \end{cases}$$

Moreover, Z is called "impedance"

Combining the components:

• In series:

$$R$$

$$R_1$$

$$R_2$$

$$R_3$$

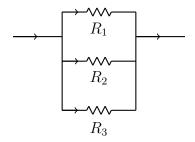
$$R = R_1 + R_2 + R_3 + \cdots$$

$$L = L_1 + L_2 + L_3 + \cdots$$

$$\frac{1}{C} = \frac{1}{C_1} + \frac{1}{C_2} + \frac{1}{C_3} + \cdots$$

$$Z = Z_1 + Z_2 + Z_3 + \cdots$$

• In parallel:



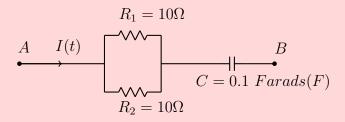
$$\frac{1}{R} = \frac{1}{R_1} + \frac{1}{R_2} + \frac{1}{R_3} + \cdots$$

$$\frac{1}{L} = \frac{1}{L_1} + \frac{1}{L_2} + \frac{1}{L_3} + \cdots$$

$$C = C_1 + C_2 + C_3 + \cdots$$

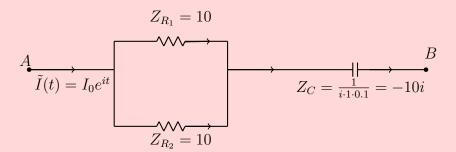
$$\frac{1}{Z} = \frac{1}{Z_1} + \frac{1}{Z_2} + \frac{1}{Z_3} + \cdots$$

**Example 1.24.** Suppose a current  $I(t) = I_0 \cos t$ , passes through this:



Find V(t), the difference in electrical potential energy between A and B

#### **Solution**:



Let's use the complex version of "Ohm's Law". We have  $\frac{1}{Z_R} = \frac{1}{Z_{R_1}} + \frac{1}{Z_{R_2}} = \frac{1}{10} + \frac{1}{10} = \frac{1}{5}$ , so  $Z_R = 5$ .

Combine the resistor and capacitor in series:  $Z = Z_R + Z_C = 5 - 10i$ .

So, the complex voltage is

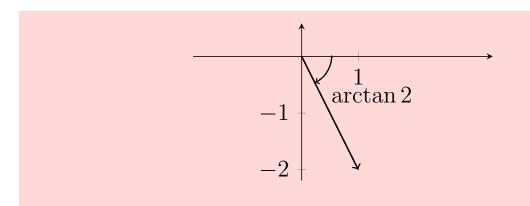
$$\widetilde{V} = Z\widetilde{I}$$

$$= (5 - 10i)I_0e^{it}$$

$$= 5I_0(1 - 2i)e^{it}$$

$$= 5I_0\sqrt{5}e^{i\arctan - 2}e^{it}$$

So, 
$$V(t) = Re(\widetilde{V}(t)) \approx 5\sqrt{5}I_0\cos(t - 1.107)$$



## 1.5 Sets in the Complex Plane

Definition 1.25. Neighborhood of  $z_0$  is

$$N_{\epsilon}(z_0) = \{ z \in \mathbb{C} : |z - z_0| < \epsilon \}$$

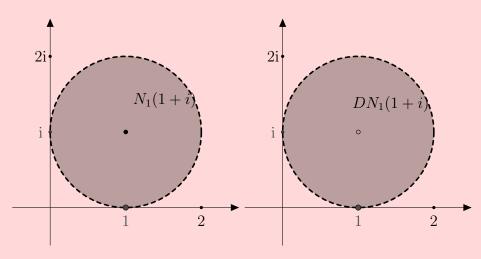
where  $\epsilon > 0$  is real

Definition 1.26. Deleted Neighborhood of  $z_0$  is

$$DN_{\epsilon}(z_0) = \{ z \in \mathbb{C} : 0 < |z - z_0| < \epsilon \}$$

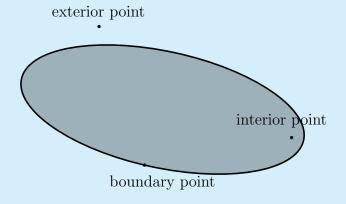
where  $\epsilon > 0$  is real

**Example 1.27.** For  $z_0 = 1 + i$ , consider |z - (1 + i)| < 1. The neighborhood of  $z_0$  and deleted neighborhood of  $z_0$  is as follows:



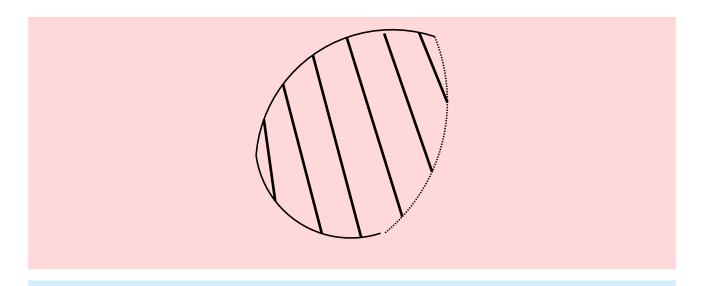
#### **Definition 1.28.** Let $S \subseteq \mathbb{C}$ :

- $z_0$  is an <u>interior point</u> of S if there exists a neighborhood of  $z_0$  which contains only points in S
- $z_0$  is an **exterior point** of S if there exists a neighborhood of  $z_0$  which contains no points in S
- $z_0$  is a **boundary point** of S if every neighborhood of  $z_0$  contains some points in S and some points not.
- Boundary of S is the set of all boundary points of S
- $\bullet$  S is **open** if it contains none of its boundary points
- S is <u>closed</u> if it contains all of its boundary points, equivalently if its complement is open.
- Note that S could be both open and closed, when it does not have any boundary points



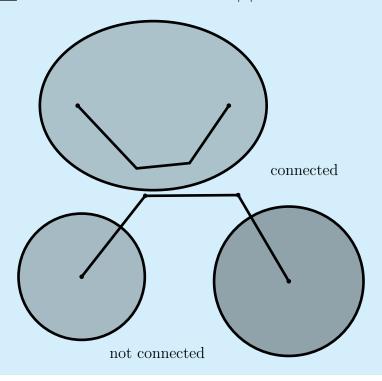
#### Example 1.29. Note that

- $N_1(1+i)$  is open
- $\bullet$   $\mathbb{C}$  is both open and closed
- $|z z_0| \le 1$  is closed
- The figure below: it is neither open nor closed.



#### **Definition 1.30.** For $S \subseteq \mathbb{C}$ :

- Closure of S is S plus its boundary.
- An open set S is **connected** if any two points in S can be connected by a polygonal path lying entirely in S
- A <u>domain</u> is an open connected set. We should not confuse this with "domain of a function"
- A region is a domain plus some, none, or all of its boundary points.
- S is **bounded** if there exists  $R \in \mathbb{R}$  such that |z| < R for all  $z \in S$

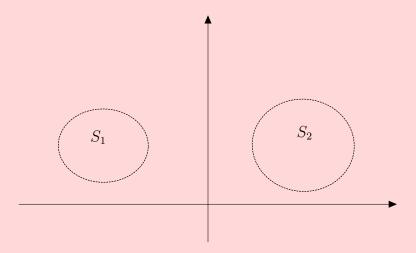


**Theorem 1.31.** If u(x,y), defined on a domain D, satisfies

$$\frac{\partial u}{\partial x} = \frac{\partial u}{\partial y} = 0$$

for all points in D, then u(x,y) = constant in D.

#### **Example 1.32.** Suppose we have $S_1$ and $S_2$ like this:



in which we have u(x,y) = 0 on  $S_1$  and u(x,y) = 1 on  $S_2$ .

Then,  $\frac{\partial u}{\partial x} = \frac{\partial u}{\partial y} = 0$  on  $S_1 \cup S_2$ , but u(x, y) is not constant on  $S_1 \cup S_2$ .

Why does not the theorem hold? Well this is because  $S_1 \cup S_2$  is not connected, so it's not a domain.

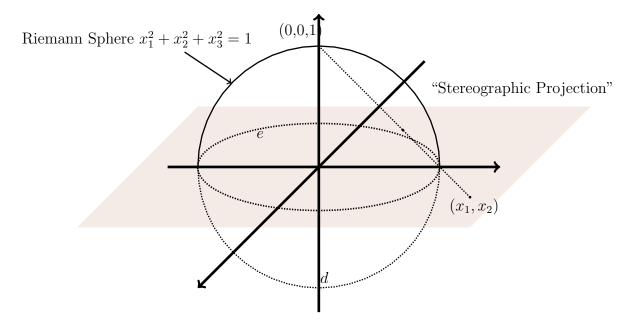
The Extended Complex Plane:

The "neighborhood of  $\infty$  " is defined as:

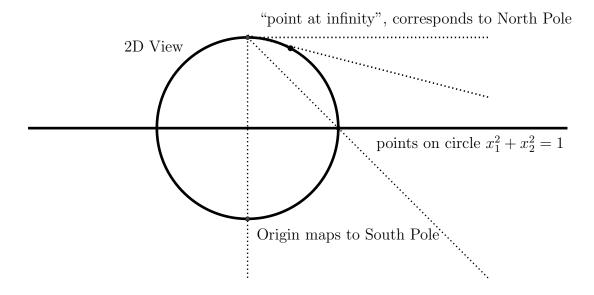
$$N_{\epsilon}(\infty) = \{z \in \mathbb{C} : |z| > \frac{1}{\epsilon}\}$$

for some real  $\epsilon > 0$ 

#### The Riemann sphere:



We can define a one-to-one mapping between  $x_1x_2$ -plane and the sphere:



See the course text for more detail, in particular:

- Circles and lines all map circles on the sphere
- Lines are just circles which pass through the "point at infinity"

## Chapter 2 Analytic Functions

#### 2.1 Functions

For a function on complex numbers:

$$\omega = f(z)$$

$$= f(x + iy)$$

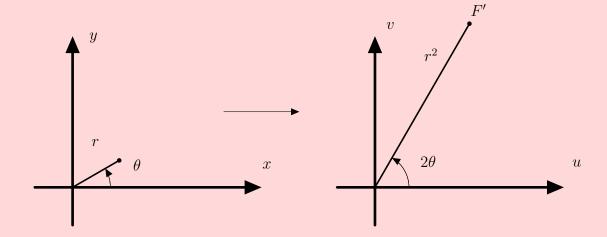
$$= u(x, y) + iv(x, y)$$

We can think of it as a mapping.

**Example 2.1.** 1.  $f(z) = z^2$ . Find the images of

(a) the first quadrant.

$$f(z) = (x + iy)^2 = \underbrace{(x^2 - y^2)}_{u} + i\underbrace{2xy}_{v}$$



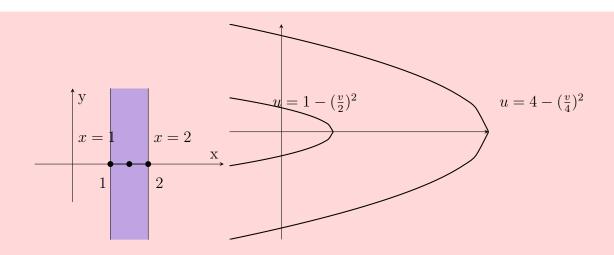
Note that  $f(z) = (re^{i\theta})^2 = r^2 e^{i2\theta}$  (angle is doubled)

(b) the strip  $1 \le Re(z) \le 2$ 

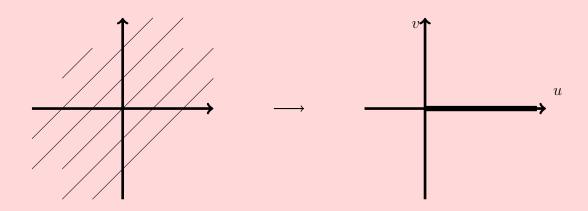
With  $1 \le x \le 2$ , the boundaries become:

• 
$$x = 1 \Rightarrow \begin{cases} u = 1 - y^2 \\ v = 2y \end{cases} \Rightarrow u = 1 - \left(\frac{v}{2}\right)^2$$
, which is a parabola

• 
$$x = 2 \Rightarrow \begin{cases} u = 4 - y^2 \\ v = 4y \end{cases} \Rightarrow u = 4 - \left(\frac{v}{4}\right)^2$$
, which is a parabola



2. f(z) = |z|. This one maps complex plane to non-negative real axis.

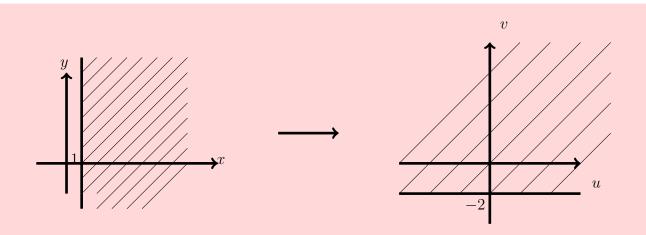


- 3.  $f(z) = z z_0 = (x + iy) (x_0 + iy_0) = (x x_0) + i(y y_0)$ . This is a translation.
- 4.  $f(z) = z_0 z$ , so

$$f(z) = r_0 e^{i\theta_0} r e^{i\theta} = \underbrace{r_0}_{\text{magnification}} r e^{i\underbrace{\theta_0}_{\text{rotation}} + \theta} = r_0 r e^{i\theta_0 + \theta}$$

- 5.  $f(z) = \overline{z} = x iy \rightarrow \begin{cases} u = x \\ v = -y \end{cases}$ . This is a reflection on y-axis.
- 6. Find image of half-plane  $Re(z) \ge 1$  under the map  $\omega = f(z) = iz 3i$ .

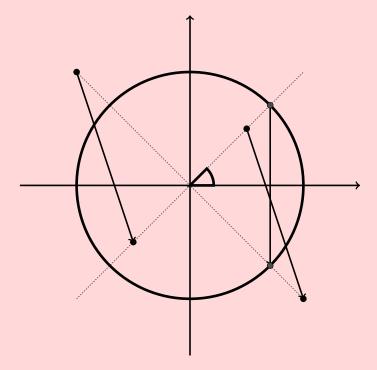
We can do this step by step. First it's a rotation of  $\frac{\pi}{2}$  (comes from the first i), then its a shift down 3 units.



The image is the half-plane  $v \geq -2$ .

7. Inversion mapping.  $f(z)=\frac{1}{z}=\frac{1}{re^{i\theta}}=\frac{1}{r}e^{-i\theta}$ . So, it's a scaling by r, and then reflection through the x-axis.

For this mapping, unit circle maps to the unit circle. Outside points go to inside, and inside points go to outside.



8. Image of circle  $(x-1)^2 + y^2 = 1$  under  $f(z) = \frac{1}{z}$ .

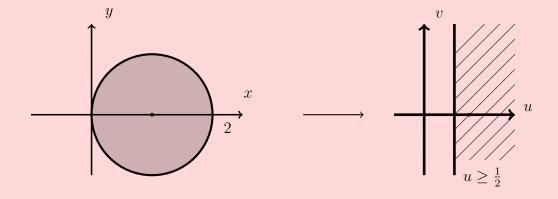
The trick is to use polar fomulas. Recall  $x^2 + y^2 = r^2, x = r \cos \theta, y = r \sin \theta$ .

So,  $x^2 - 2x + 1 + y^2 = 1$  yields that  $r^2 = 2r\cos\theta$ . Since  $r \neq 0$ , we then have  $r = 2\cos\theta$ .

To apply the map, replace r with  $\frac{1}{r}$ , and  $\theta$  with  $-\theta$ :

$$\frac{1}{r} = 2\cos(-\theta) \Rightarrow r = \frac{1}{2\cos\theta} \Rightarrow r\cos\theta = \frac{1}{2}$$

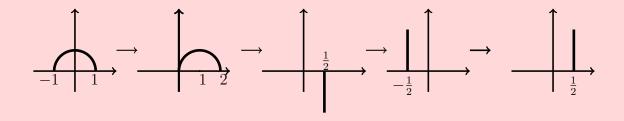
So  $u = \frac{1}{2}$  since  $\begin{cases} u = r \cos \theta \\ v = r \sin \theta \end{cases}$  in the uv plane.



9.  $w = f(z) = \frac{z}{z+1}$ , find the image of upper-half of unit circle.

First,  $f(z) = \frac{z+1-1}{z+1} = 1 - \frac{1}{z+1}$ . This is a sequence of transformations:

$$z \to \underbrace{z+1}_{\text{shift right}} \to \underbrace{\frac{1}{z+1}}_{\text{invert}} \to \underbrace{\frac{-1}{z+1}}_{\text{reflect and rotate }\pi} \to \underbrace{1-\frac{1}{z+1}}_{\text{shift right}}$$



#### 2.2 Limits and Differentiation

#### Definition 2.2. <u>Limits</u>:

$$\lim_{z \to z_0} f(z) = w_0$$

means that for any  $\epsilon > 0$ , there exists  $\delta > 0$  such that

$$0 < |z - z_0| < \delta \quad \Rightarrow \quad |f(z) - w_0| < \epsilon$$

**Example 2.3.** Prove that  $\lim_{z\to 1+i} (2+i)z = 1+3i$ .

**Solution**: We first do some preliminary work:

$$|(2+i)z - (1+3i)| = |2+i| \cdot |z - \frac{1+3i}{2+i}| = \sqrt{5} \cdot |z - (1+i)|$$

So, let  $\epsilon > 0$ , with  $|z - z_0| < \frac{\epsilon}{\sqrt{5}} (= \delta)$ , we have

$$|(2+i)z - (1+3i)| = \sqrt{5} \cdot |z - (1+i)|$$

$$< \sqrt{5} \cdot \frac{\epsilon}{\sqrt{5}}$$

$$= \epsilon$$

So, 
$$\lim_{z\to 1+i} (2+i)z = 1+3i$$

Note that similar definitions apply when dealing with infinity, e.g.  $\lim_{z\to z_0} f(z) = \infty$  means that for any  $\epsilon > 0$ , there exists  $\delta > 0$  such that  $0 < |z - z_0| < \delta \implies |f(z)| > \frac{1}{\epsilon}$ 

**Definition 2.4. Continuity**: f is **continuous** at  $z_0$  means that

$$\lim_{z \to z_0} f(z) = f(z_0)$$

The usual limit and continuity theorems hold, e.g.

$$\lim_{z \to z_0} f(z)g(z) = \lim_{z \to z_0} f(z) \cdot \lim_{z \to z_0} g(z)$$

**Theorem 2.5.** Let f(z) = u + iv,  $z_0 = x_0 + iy_0$ ,  $w_0 = u_0 + iv_0$ , then

$$\lim_{z \to z_0} f(z) = w_0 \quad \text{if and only if} \quad \begin{cases} \lim_{(x,y) \to (x_0,y_0)} u(x,y) = u_0 \\ \lim_{(x,y) \to (x_0,y_0)} v(x,y) = v_0 \end{cases}$$

#### Definition 2.6. <u>Differentiation</u>:

$$f'(z_0) = \lim_{z \to z_0} \frac{f(z) - f(z_0)}{z - z_0} \left( = \lim_{\Delta z \to 0} \frac{f(z_0 + \Delta z) - f(z_0)}{\Delta z} \right)$$

Derivative function is

$$f'(z) = \lim_{\Delta z \to 0} \frac{f(z + \Delta z) - f(z)}{\Delta z}$$

For functions with real analogues (e.g.  $f(z) = z^2$  analogous to  $f(x) = x^2$ ), the usual rules (power, quotient, etc.) apply, e.g.

$$f(z) = 3z^2 + z^4 \implies f'(z) = 6z + 4z^3$$

What about functions without real analogues?

**Example 2.7.**  $f(z) = \overline{z}$ . Is it differentiable?

**Solution**:

$$f'(z_0) = \lim_{z \to z_0} \frac{\overline{z} - \overline{z_0}}{z - z_0}$$

$$= \lim_{z \to z_0} \frac{\overline{z} - \overline{z_0}}{z - z_0}$$

$$= \lim_{z \to z_0} \frac{\overline{re^{i\theta}}}{re^{i\theta}} \quad \text{where} \quad z - z_0 = e^{i\theta}$$

$$= \lim_{z \to z_0} \frac{e^{-i\theta}}{e^{i\theta}}$$

$$= \lim_{z \to z_0} e^{-i2\theta}$$

which depends on  $\theta$ ! No unique value, so limit DNE. So, f is not differentiable anywhere.

Theorem 2.8. <u>Cauchy-Riemann Equations</u>: If f(z) = u(x, y) + iv(x, y) and  $f'(z_0)$  exists, then

$$u_x = v_y$$
 and  $v_x = -u_y$  at  $(x_0, y_0)$ 

Note that for notation,

$$u_x = \frac{\partial u}{\partial x}$$

$$u_y = \frac{\partial u}{\partial y}$$

$$v_x = \frac{\partial v}{\partial x}$$

$$v_y = \frac{\partial v}{\partial y}$$

#### Proof 2.9.

$$f'(z_0) = \lim_{\Delta z \to 0} \frac{f(z_0 + \Delta z) - f(z_0)}{\Delta z}$$

$$= \lim_{(\Delta x, \Delta y) \to (0, 0)} \left( \frac{u(x_0 + \Delta x, y_0 + \Delta y) - u(x_0, y_0)}{\Delta x + i\Delta y} + i \frac{v(x_0 + \Delta x, y_0 + \Delta y) - v(x_0, y_0)}{\Delta x + i\Delta y} \right)$$

Since the limit exists, it must be independent of path, so

• Along  $\Delta y = 0$ :

$$f'(z_0) = \lim_{\Delta x \to 0} \frac{u(x_0 + \Delta x, y_0) - u(x_0, y_0)}{\Delta x} + i(\cdots) = \frac{\partial u}{\partial x} + i\frac{\partial v}{\partial x}$$

• Along  $\Delta x = 0$ :

$$f'(z_0) = \lim_{\Delta y \to 0} \frac{u(x_0, y_0 + \Delta y) - u(x_0, y_0)}{i\Delta y} + i(\cdots) = -i\frac{\partial u}{\partial y} + \frac{\partial v}{\partial y}$$

Equating the real and imaginary part yields the result.

## 2.3 Differentiability Continued

**Example 2.10.** Is  $f(z) = |z|^2$  differentiable? Where?

Solution:  $f(z) = \sqrt{x^2 + y^2}^2 = \underbrace{x^2 + y^2}_u + \underbrace{0}_v i$ . So, by CRE, we know that  $\begin{cases} u_x = v_y & \Rightarrow 2x = 0 \\ v_x = -u_y & \Rightarrow 0 = -2y \end{cases}$ 

It's clear that this is satisfied only at x = y = 0.

So, if  $(x, y) \neq (0, 0)$ , i.e.  $z \neq 0$ , then f is not differentiable.

When 
$$z = 0$$
,  $f'(z) = \lim_{\Delta z \to 0} \frac{f(0 + \Delta z) - f(0)}{\Delta z} = \lim_{\Delta z \to 0} \frac{|\Delta z|^2 - 0}{\Delta z} = 0$ . This is because  $\left| \frac{|\Delta z|^2}{\Delta z} - 0 \right| \le |\Delta z| \to 0$  as  $\Delta z \to 0$  (by applying the squeeze theorem).

Hence, CRE are necessary but not sufficient conditions.

**Theorem 2.11.** Let f be defined in some neighborhood of  $z_0$ . If  $u_x, u_y, v_x, v_y$  exist in that neighborhood, satisfying CRE at  $z_0$ , and are **continuous** at  $z_0$ , then f is differentiable at  $z_0$ .

**Definition 2.12.** f(z) is <u>analytic at  $z_0$  if f'(z) exists at every point in some neighborhood of  $z_0$ .</u>

f(z) is analytic on an open set S if it is analytic at every point of S.

Example 2.13. 
$$f(z) = z^3 = \dots = \underbrace{(x^3 - 3xy^2)}_{u(x,y)} + i\underbrace{(3x^2y - y^2)}_{v(x,y)}$$
.

We have

$$u_x = 3x^2 - 3y^2$$

$$u_y = -6xy$$

$$v_x = 6xy$$

$$v_y = 3x^2 - 3y^2$$

So, CRE satisfied everywhere. All partial derivatives are continuous. By theorem, f is differentiable everywhere, so is analytic everywhere. We refer to "analytic everywhere" as "entire"

**Example 2.14.** Where is  $f(z) = x^2 + iy^2$  analytic?

We have

$$u_x = 2x$$

$$u_y = 0$$

$$v_x = 0$$

$$v_y = 2y$$

We need x = y to satisfy CRE.

- If  $x \neq y$ , f is not differentiable, so not analytic.
- If x = y, f cannot be analytic because we are not on an open set.

So, f is not analytic nowhere.

**Theorem 2.15.** Sums, products, and compositions of analytic functions are also analytic, except when  $\div 0$ 

**Example 2.16.**  $f(z) = \frac{z^3 + 2}{z^2 + 1}$  is analytic everywhere except at  $z = \pm i$ .

 $g(z) = f(z^2)$  is analytic everywhere except where  $z^2 = \pm i$ , i.e. except

$$\begin{split} z &= e^{i(\frac{n\pi + \pi/2}{2})} \\ &= e^{i(n\pi/2 + \pi/4)} \\ &= e^{i(n\pi/4)}, e^{i(n3\pi/4)}, e^{i(n5\pi/4)}, e^{i(n7\pi/4)} \\ &= \frac{1}{\sqrt{2}} + \frac{i}{\sqrt{2}}, -\frac{1}{\sqrt{2}} + \frac{i}{\sqrt{2}}, -\frac{1}{\sqrt{2}} - \frac{i}{\sqrt{2}}, \frac{1}{\sqrt{2}} - \frac{i}{\sqrt{2}}, \end{split}$$

**Theorem 2.17.** Suppose f is analytic in a domain D. If f'(z) = 0 for all  $z \in D$ , then f is constant in D

**Proof 2.18.**  $f'(z) = u_x + iv_x = v_y - iu_y$ . So,  $f'(z) = 0 \Rightarrow u_x = v_y = 0 = v_y = u_y$ . So, u and v are constant, since D is connected.

**Theorem 2.19.** Suppose f is analytic in a domain D. If |f(z)| = M for all  $z \in D$ , where M is constant, then f(z) is constant in D.

**Proof 2.20.**  $|f(z)|^2 = u^2 + v^2 = M^2$ .

We differentiate:

• with respect to x:  $2uu_x + 2vv_x = 0$  – (1)

• with respect to y:  $2uu_y + 2vv_y = 0$  – (2)

Now  $u_x = v_y$ , and  $v_x = -u_y$ , so the (2) gives  $-uv_x + vu_x = 0$  – (3).

Multiply (1) by  $u_x$ .

$$uu_x^2 + vu_xv_x = 0$$
  

$$\Rightarrow uux^2 + (uv_x)v_x = 0 \text{ by (3)}$$
  

$$\Rightarrow u(u_x^2 + v_x^2) = 0$$

So, unless u = 0 for all  $z \in D$ , we must have  $u_x^2 + v_x^2 = 0$ . So,  $u_x = v_x = 0$ , implying that u, v are constant. Hence, f is constant.

What if u = 0 for all  $z \in D$ ? Then,  $u_x = u_y = 0$ , so  $v_x = v_y = 0$  by CRE. f is constant as well.

#### 2.4 Harmonic Functions

Recap:

$$f'(z) = u_x + iv_x = \frac{u_y + iv_y}{i} = v_y - iu_y$$
$$CRE: \quad u_x = v_y \quad v_x = -u_y$$

Also, "analytic" means differentiable on a open set.

Suppose f(z) = u(x, y) + iv(x, y) is analytic in a domain D. Then u and v satisfy CRE.

Also, which will be shown later,  $u, v \in C^2$  (continuous under second partial derivatives), and this implies that  $u_{xy} = u_{yx}$ , and  $v_{xy} = v_{yx}$ .

From CRE:

$$\underbrace{u_x - v_y}_{\Rightarrow u_{xx} = v_{yx}}$$
 and  $\underbrace{v_x = -u_y}_{\Rightarrow u_{yy} = -v_{xy}}$ 

**Definition 2.21.** From the above derivation, we see

$$u_{xx} + u_{yy} = v_{yx} - v_{xy} = 0$$

and

$$v_{xx} + v_{yy} = 0$$

We refer to these as "Laplace's equation"

Solution to Laplace's equation are called <u>"harmonic functions"</u>

Notes:

- We've shown that if f(z) = u + iv is analytic, then u and v must be harmonic
- Laplace's equation is very useful! We will see that later.
- $u_{xx} + u_{yy} = 0$  is also denoted as  $\Delta^2 u = 0$ , and we denote  $\Delta$  as "Laplacian operator".

**Example 2.22.** Suppose  $u(x,y) = e^{-2x}\cos 2y + 2y$ . Find v(x,y) such that f(z) = u + iv is analytic.

**Solution**: u and v must satisfy CRE. So,  $v_y = u_x = -2e^{-2x}\cos 2y$ . Hence,

$$v = \int -2e^{-2x} \cos 2y dy$$
$$= -e^{2x} \sin 2y + C(x)$$

Note that C(x) is a function of all other variables.

Now we try to make it satisfy other CRE:

$$v_x = -u_y \implies 2e^{-2x}\sin 2y + C'(x) = 2e^{-2x}\sin 2y - 2$$
$$\implies C'(x) = -2$$
$$\implies C(x) = -2x + k$$

Therefore,  $v(x,y) = -e^{-2x} \sin 2y - 2x + k$ 

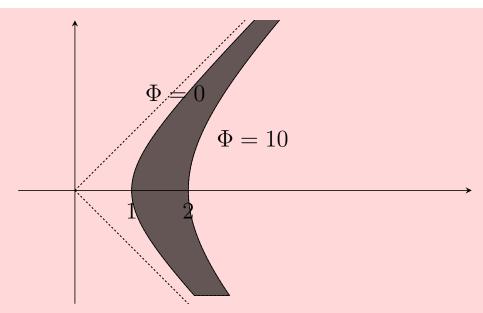
Note that v(x, y) is called the "harmonic conjugate" of u.

Exercise: show that if v is the harmonic conjugate of u, then -u is the harmonic conjugate of v.

**Example 2.23.** Solve Laplace's equation  $\Phi_{xx} + \Phi_{yy} = 0$  on region between hyperbolas  $x^2 - y^2 = 1$  and  $x^2 - y^2 = 4$ , x > 0, with "boundary conditions"

$$\begin{cases} \Phi = 0 & \text{on } x^2 - y^2 = 1\\ \Phi = 10 & \text{on } x^2 - y^2 = 4 \end{cases}$$

i.e. Find  $\Phi(x,y)$ 



**Solution**: Consider 
$$f(z) = z^2 = (x + yi)^2 = \underbrace{x^2 - y^2}_{u(x,y)} + i \underbrace{2xy}_{v(x,y)}$$

Since f(z) is already analytic, we have that  $u(x,y) = x^2 - y^2$  is harmonic. Boundary curves of region are level curves of a harmonic function.

Is the solution  $\Phi(x,y) = x^2 - y^2$ ? No.

Try  $\Phi(x,y) = A \cdot (x^2 - y^2) + B$  (also harmonic by linearity).

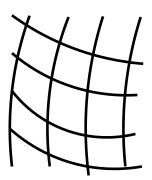
Applying the Boundary Conditions:

$$0 = A \cdot 1 + B \Rightarrow B = -A$$
  
$$10 = A \cdot 4 + B \Rightarrow A = \frac{10}{3}, B = -\frac{10}{3}$$

So the solution is  $\Phi(x,y) = \frac{10}{3}(x^2 - y^2) - \frac{10}{3}$ 

Notes:

- $\bullet\,$  It can be used in temperature distribution
- What about more complicated regions?
- Orthogonal trajectories



• list of harmonic functions

## Chapter 3 Elementary Functions

#### 3.1 Elementary Functions

#### Definition 3.1. Polynomials:

$$p(z) = a_0 + a_1 z + a_2 z^2 + \dots + a_n z^n$$
,  $a_i \in \mathbb{C}$ 

There are obviously entire.

The fundamental theorem of algebra guarantees that we can factor this as

$$p(z) = a_n(z - z_1)(z - z_2) \cdots (z - z_n)$$

Note that  $z_i$  are not necessarily distinct.

 $z_0$  is a "zero of multiplicity" k if and only if

$$p(z) = (z - z_0)^k q(z)$$

where q(z) is a polynomial such that  $q(z_0) \neq 0$ 

#### **Definition 3.2. Rational Functions:**

$$R(z) = \frac{p(z)}{q(z)} = \frac{a_n(z - z_1)(z - z_2) \cdots (z - z_n)}{b_m(z - w_1)(z - w_2) \cdots (z - w_n)}$$

Suppose all common factors have been cancelled, then

- the roots (or zeroes) of p(z) are called the **roots/zeroes** of R(z)
- the roots (or zeroes) of q(z) are called the **poles** of R(z)

#### Example 3.3.

$$R(z) = \frac{3i(z-1)(z-\frac{1}{3}i)^2(z+i)}{(z-i)^3(z-2-i)}$$

Zeroes at 1 and -i (order 1 would be a "simple zero"), and  $\frac{1}{3}i$  (order 2).

Poles at i (order 3) and 2 + i (order 1 would be a "simple pole")

Partial Fractions has simpler rules:

**Example 3.4.** Decompose  $R(z) = \frac{1}{(z+4)^2(z^2+1)}$ 

**Solution**: Factor and expand

$$\frac{1}{(z+4)^2(z^2+1)} = \frac{A}{z+4} + \frac{B}{(z+4)^2} + \frac{C}{z+i} + \frac{D}{z-i}$$

This gives us

$$1 = A \cdot (z+4)(z+i)(z-i) + B(z+i)(z-i) + C(z+4)^{2}(z-i) + D(z+4)^{2}(z+i)$$

We can solve this by:

- set z = -4, this gives us 1 = 0 + (-4 + i)(-4 i)B + 0 + 0, so  $B = \frac{1}{17}$
- set z = -i, this gives us  $1 = 0 + 0 + (-i + 4)^2(-2i)C + 0$ . Then we compute (-2i)(15 8i) = 16 30i, also  $(-16 30i) = \frac{(-16 30i)(-16 + 30i)}{(-16 + 30i)} = \frac{1156}{(-16 + 30i)} = \frac{578}{-8 + 15i}$ .

Hence,  $C = \frac{-8 + 15i}{578}$ .

• set z = -4, this gives us  $1 = 0 + 0 + 0 + (i + 4)^2(2i)D$ , so  $D = \frac{-8 - 15i}{578}$ . The trick to compute things here is that, we can replace i with -i from C since the expression is similar to C.

Now what about A? We can try another z, or just compare the coefficients of  $z^3$ . By comparing the coefficients of  $z^3$ , we get that

$$0 + A + C + D = A + \frac{-8 + 15i}{578} + \frac{-8 - 15i}{578}$$

So 
$$A = \frac{16}{578} = \frac{8}{289}$$

Hence,

$$\frac{1}{(z+4)^2(z^2+1)} = \frac{8/289}{z+4} + \frac{1/17}{(z+4)^2} + \frac{\frac{-8+15i}{578}}{z+i} + \frac{\frac{-8-15i}{578}}{z-i}$$

Actually, often we will only need one of the coefficients, and there's a quick way which will be covered later in the course.

**Definition 3.5.** Exponential Function: We already defined that  $e^z = e^{x+iy} = e^x(\cos y + i\sin y)$ .

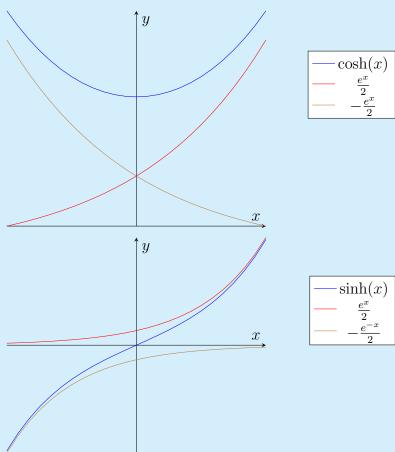
Note that  $e^{z_1+z_2}=e^{z_1}e^{z_2}$ ,  $\frac{d}{dz}e^z=e^z$ . Also,  $e^z$  is **periodic** with period  $2\pi i$ 

## Definition 3.6. Hyperbolic Functions: From real calculus, we seen that

$$\cosh x = \frac{1}{2}(e^x + e^{-x})$$
 this is the even component of  $e^x$   $\sinh x = \frac{1}{2}(e^x - e^{-x})$  this is the odd component of  $e^x$ 

It can be shown that

$$\cosh x + \sinh x = e^{x}$$
$$\cosh^{2} x - \sinh^{2} x = 1$$
$$\frac{d}{dx} \sinh x = \cosh x$$
$$\frac{d}{dx} \cosh x = \sinh x$$



To extend these to  $\mathbb{C}$ , we define

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$$\cosh z = \frac{1}{2}(e^z + e^{-z}) \quad \sinh z = \frac{1}{2}(e^z - e^{-z})$$

## 3.2 Trigonometric and Logarithmic Function

### Definition 3.7. Trigonometric Functions: Recall

$$e^{i\theta} = \cos \theta + i \sin \theta$$
  
 $e^{-i\theta} = \cos \theta - i \sin \theta$ 

Sum to get 
$$\cos \theta = \frac{e^{i\theta} + e^{-i\theta}}{2}$$
, and  $\sin \theta = \frac{e^{i\theta} - e^{-i\theta}}{2i}$ 

We define

$$\cos z = \frac{1}{2}(e^{iz} + e^{-iz}) = \cosh(iz) \quad \sin z = \frac{1}{2i}(e^{iz} - e^{-iz}) = \frac{1}{i}\sinh(iz)$$

Furthermore:

$$\cos(iz) = \frac{e^{-z} + e^z}{2} = \cosh z$$
$$\sin(iz) = \frac{e^{-z} - e^z}{2i} = i \sinh z$$

For real 
$$z$$
,  $e^z = e^x = \cosh x + \sinh x$   
For imaginary  $z$ ,  $e^z = e^{iy} = \cos y + i \sin y$ 

The  $\cosh x$  and  $\cos y$  are the even parts, and  $\sinh x$  and  $i \sin y$  are the odd parts

| Functions                      | Along Real Axis    | Along Imaginary Axis |
|--------------------------------|--------------------|----------------------|
| $e^{iz}$ , $\cos z$ , $\sin z$ | periodic           | grow exponentially   |
| $e^z$ , $\cosh z$ , $\sinh z$  | grow exponentially | periodic             |

Familiar identities hold true.

#### Example 3.8.

$$\cos^4 \theta = (\frac{e^{i\theta} + e^{-i\theta}}{2})^4$$

$$= \frac{1}{16}(e^{i4\theta} + 4e^{2\theta} + 6 + 4e^{-i2\theta} + e^{-i4\theta})$$

$$= \frac{1}{8}\cos 4\theta + \frac{1}{2}\cos 2\theta + \frac{3}{8}$$

#### Example 3.9.

$$\cos^{2}\theta + \sin^{2}\theta = 1$$

$$\Rightarrow \cos^{2}(iy) + \sin^{2}(iy) = 1$$

$$\Rightarrow \cosh^{2}y + i^{2}\sinh^{2}y = 1$$

$$\Rightarrow \cosh^{2}y - \sinh^{2}y = 1$$

By using the rules  $\begin{cases} \cos(iz) = \cosh z \\ \sin(iz) = i \sinh z \end{cases}$ 

Notice the "Obsborne's rule" here: Hyperbolic function satisfy the same identities as trigonometric functions except that we must change the sign of every product of two sines.

Derivatives:  $e^z$  is entire, and so is  $\cos z$ ,  $\sin z$ ,  $\cosh z$ ,  $\sinh z$ . Also,

$$\frac{d}{dz}(\cos z) = \frac{d}{dz}(\frac{e^{iz} + e^{-iz}}{2}) = \frac{ie^{iz} - ie^{-iz}}{2} = \frac{e^{iz} - e^{-iz}}{-2i} = -\sin z$$

Other as expected as well

Note: we can also define  $\tan z$ ,  $\sec z$  etc. in the usual ways, and derivatives of them are as expected.

**Example 3.10.** What is the value of  $\sin(\pi + i)$ ?

Solution:

$$\sin(\pi + i) = \sin \pi \cos(i \cdot 1) + \cos \pi \sin(i \cdot 1)$$
$$= \sin \pi \cosh 1 + \cos \pi i \sinh(1)$$
$$= 0 + (-1) \cdot i \cdot \sinh(1)$$
$$= -\sin i$$

**Example 3.11.** Find all solutions of  $\sin z = 1000$ 

**Solution**: We write  $\sin(x + yi) = 1000$ , and get that

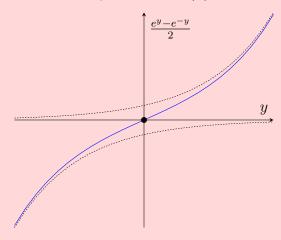
 $\sin x \cosh y + i \cos x \sinh y = 1000$ 

So

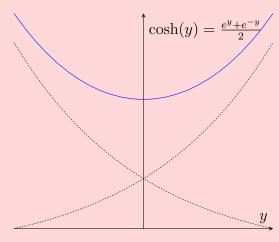
$$\begin{cases} \sin x \cosh y = 1000 & \cdots & (1) \\ \cos x \sinh y = 0 & \cdots & (2) \end{cases}$$

Equation 2 gives that  $\cos x = 0$  or  $\sinh y = 0$ , which yields that  $x = (2n+1)\frac{\pi}{2}$  or y = 0.

The following figure shows that the only x that sinh(x) = 0 is at x = 0.



- If y = 0, equation 1 gives that  $\sin x \cosh(0) = \sin x = 1000$ . This is impossible
- If  $x = (2n+1)\frac{\pi}{2}$ , then equation 1 gives  $\sin\left((2n+1)\frac{\pi}{2}\right)\cosh y = 1000$ , so  $\cosh y = 1000 \cdot (-1)^n$



But  $\cosh y > 0$ , so use n = 2N (always even). So  $\cosh y = 1000$ , and  $y = \pm \cosh^{-1}(1000) \approx \pm 7.6$  (There are two solutions, i.e. note the  $\pm$  sign, as the figure

above shows).

The final answer is that  $z = x + iy = (4N + 1)\frac{\pi}{2} \pm i \cosh^{-1}(1000)$ 

## 3.3 Logarithmic Functions

How to define  $\log z$ ? Let  $z = e^w$  and solve for w. Note that:

- exponential function is periodic, so log will be a "multi-valued function"
- in  $\mathbb{C}$ , we use "log" instead of "ln"

Definition 3.12. Now,

$$z = e^{w} \Rightarrow re^{i\theta + 2\pi k} = e^{u + iv}$$
$$\Rightarrow r = e^{u}, \ \theta + 2\pi k = v$$
$$\Rightarrow u = \ln r, \ v = \theta + 2\pi k$$

So, we define

$$\log z = \ln|z| + i\arg z$$

Example 3.13. • 
$$\log(1+i) = \ln|1+i| + i\arg(1+i) = \ln\sqrt{2} + i\left(\frac{\pi}{4} + 2\pi k\right)$$

• 
$$\log(i) = \ln|i| + i \arg(i) = 0 + i \left(\frac{\pi}{2} + 2\pi k\right)$$

**Proposition 3.14.** We have the following identity:

$$\log(z_1 z_2) = \ln|z_1 z_2| + i \arg(z_1 z_2)$$
  
= \* \ln |z\_1| + \ln |z\_2| + i (\arg z\_1 + \arg z\_2)  
= \log(z\_1) + \log(z\_2)

Similarly

$$\log\left(\frac{z_1}{z_2}\right) = *\log(z_1) - \log(z_2)$$

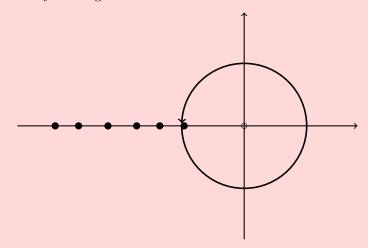
By  $=^*$ , we actually mean that <u>the set of values</u> of  $\log(z_1 z_2)$  is equal to <u>the set of values</u> of  $\log(z_1) + \log(z_2)$ , due to the multi-valuedness of log.

## Definition 3.15. The principle value of the Logarithm is

$$Log(z) = \ln|z| + i \underbrace{Arg(z)}_{\in (-\pi,\pi] \text{ usually}}$$

**Example 3.16.** •  $Log(1+i) = \ln|1+i| + i Arg(1+i) = \ln \sqrt{2} + i \frac{\pi}{4}$ 

- $\operatorname{Log}(i) = \ln|i| + i\operatorname{Arg}(i) = 0 + i\pi$
- Log  $e^z=z$  if and only if  $Im(z)\in (-\pi,\pi]$
- $\bullet$  Log z has discontinuity on negative real axis



 $\bullet$  Log z is analytic everywhere else, with

$$\frac{d}{dz} \operatorname{Log} z = \frac{1}{z}$$

#### Proof 3.17. Let

$$w = \operatorname{Log} z = \ln|z| + i\operatorname{Arg}(z)$$
$$= \frac{1}{2}\ln(x^2 + y^2) + i\left(\arctan(\frac{y}{x}) \pm \pi\right)$$
$$= u(x, y) + iv(x, y)$$

Now,

$$\begin{aligned} \frac{dw}{dz} &= \frac{\partial u}{\partial x} - i \frac{\partial u}{\partial y} \\ &= \frac{x}{x^2 + y^2} - i \frac{y}{x^2 + y^2} \\ &= \frac{x - iy}{x^2 + y^2} \cdot \frac{x + iy}{x + iy} \\ &= \frac{1}{z} \end{aligned}$$

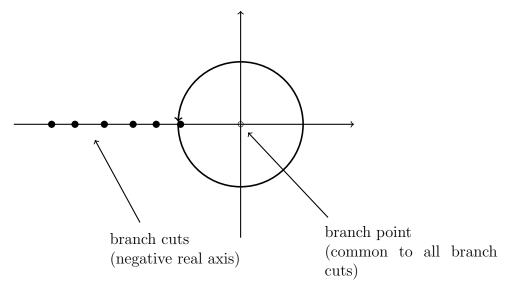
**Definition 3.18.** <u>Branch Cuts</u>: Let f(z) be a multivalued function. F(z) is said to be a <u>branch</u> of f(z) on a domain D if F(z) is continuous on D and for each  $z \in D$ , F(z) is one and only one of the values of f(z).

### **Example 3.19.** Log z is a branch of $\log z$

We could define different branches of  $\log z$  by

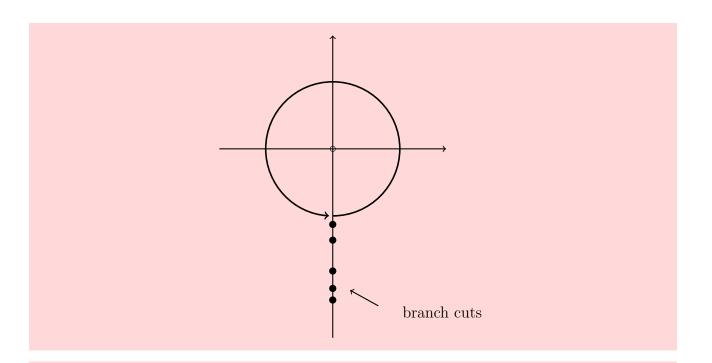
$$\operatorname{Log}_{\tau} z = \ln|z| + i \operatorname{Arg}_{\tau}(z)$$

where  $\operatorname{Arg}_{\tau}(z) \in (\tau, \tau + 2\pi]$ . Note that  $\operatorname{Log} z = \operatorname{Log}_{-\pi}$ 



Example 3.20.

$$\operatorname{Log}_{-\frac{\pi}{2}} \ln |z| + i \operatorname{Arg}_{-\frac{\pi}{2}}(z)$$



**Example 3.21.** Find a branch of  $f(z) = \log(z+4)$  that is analytic at z = -5 and equals  $7\pi i$  there.

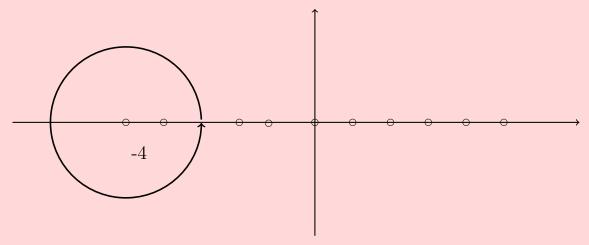
**Solution**: We want  $\operatorname{Log}_{\tau}(-5+4) = \operatorname{Log}_{\tau}(-1) = 7\pi i$  for some  $\tau$ .

So,  $\ln |-1| + i \operatorname{Arg}_{\tau}(-1) = 7\pi i$  for some k, i.e.

$$0 + i \underbrace{(\pi + 2k\pi)}_{\in (\tau, \tau + 2\pi]} = 7\pi i \quad \text{for some } k$$

Hence, k=3. We can choose  $\tau=6\pi$  so that  $7\pi\in(6\pi,8\pi]$ .

The final answer would be  $F(z) = \text{Log}_{6\pi}(z+4)$ 



**Example 3.22.** Where is  $f(z) = \text{Log}(z^2 + 1)$  analytic?

**Solution**: We need  $z^2 + 1 \neq 0$  and not equal to negative real number.

So, 
$$z^2 + 1 = (x + yi)^2 + 1 = (x^2 - y^2 + 1) + i(2xy)$$
.

$$z^2 + 1 = 0 \text{ when } \begin{cases} x = 0 \text{ and } y = \pm 1 \\ \text{or} \\ y = 0 \text{ and } x^2 + 1 = 0 \text{ This is impossible for } x \in \mathbb{R} \end{cases}$$

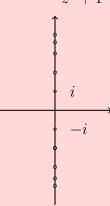
Hence,  $z = \pm i$  here.

$$z^2 + 1 < 0 \text{ (real) when } \begin{cases} x = 0 \text{ and } 1 - y^2 < 0 & \Rightarrow y^2 > 1 \Rightarrow y > 1 \text{ or } y < -1 \\ \text{or } \\ y = 0 \text{ and } 1 + x^2 < 0 & \text{Impossible} \end{cases}$$

Hence, z = iy where |y| > 1.

For all other points,

$$f'(z) = \frac{2z}{z^2 + 1}$$



Here is another way to solve the above problem.

$$Log(z^{2}+1) = Log((z+i)(z-i)) = Log_{\tau_{1}}(z+i) + Log_{\tau_{2}}(z-i)$$

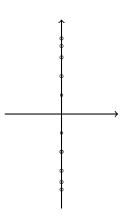
for some  $\tau_1, \tau_2$ 

Some possibilities are:

- $\tau_1 = \frac{-\pi}{2}, \ \tau_2 = \frac{-3\pi}{2}$
- $\tau_1 = \frac{3\pi}{2}, \, \tau_2 = \frac{-7\pi}{2}$

• . . .

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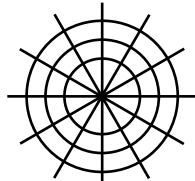


Finally, note that

$$\text{Log } z = \ln|z| + i \operatorname{Arg} z$$

Log z is analytic, so  $\ln |z|$  and Arg z are harmonic.

Level curves of  $\ln |z| = k$  and  $\operatorname{Arg} z = k$  are circles and rays. This would be particularly useful when we deal with temperature problems later.



useful for temp problems later

# 3.4 Complex Powers and Inverse Trigonometric Functions

Definition 3.23. Complex Powers: We define

$$z^{\alpha} = e^{\alpha \log z}$$
 for  $\alpha \in \mathbb{C}, z \neq 0$ 

#### Example 3.24. 1.

$$\begin{split} 4^{1/2} &= e^{\frac{1}{2}\log 4} \\ &= e^{\frac{1}{2}(\ln|4| + i\arg(4))} \\ &= e^{\frac{1}{2}\ln 4 + i\frac{1}{2}(0 + 2\pi k)} \\ &= e^{\frac{1}{2}\ln 2 + i\pi k} \\ &= e^{\ln 2}e^{i\pi k} \\ &= 2\cdot (\pm 1) \\ &= \pm 2 \end{split}$$

2.

$$(1+i)^{3} = e^{3\log(1+i)}$$

$$= e^{3\left(\ln\sqrt{2} + i\arg(1+i)\right)}$$

$$= e^{\frac{3}{2}\ln 2}e^{i3\left(\frac{\pi}{4} + 2k\pi\right)}$$

$$= (e^{\ln 2})^{\frac{3}{2}} \cdot \left(\cos\frac{3\pi}{4} + i\sin\frac{3\pi}{4}\right)$$

$$= 2^{\frac{3}{2}} \cdot \left(\frac{-1}{\sqrt{2}} + i\frac{1}{\sqrt{2}}\right)$$

$$= -2 + 2i$$

3.

$$i^{i} = e^{i \ln |i| + i \arg i}$$

$$= e^{i \left(0 + i\left(\frac{\pi}{2} + 2k\pi\right)\right)}$$

$$= e^{-\left(\frac{\pi}{2} + 2\pi k\right)}$$

$$= \cdots, e^{\frac{-5\pi}{2}}, e^{\frac{-\pi}{2}}, e^{\frac{3\pi}{2}}, \cdots$$

If we want a single value, take the principal branch to be  $e^{\alpha \log z}$ , which is analytic everywhere  $\log z$  is, and

$$\frac{d}{dz}z^{\alpha} = \frac{d}{dz}e^{\alpha \operatorname{Log} z} = e^{\alpha \operatorname{Log} z} \cdot \frac{\alpha}{z} = z^{\alpha} \cdot \frac{\alpha}{z} = \alpha z^{\alpha}$$

as expected.

**Definition 3.25.** Inverse Trigonometric Functions: First, we see that  $w = \sin^{-1} z$  means  $z = \sin w$ , etc. Also, we've accepted multivalued functions.

In  $\mathbb{R}$ , the inverse hyperbolic function can be expressed in terms of logs:

$$y=\sinh x=\frac{1}{2}(e^x-e^{-x})$$
 
$$e^x-2y-e^{-x}=0$$
 
$$(e^x)^2-2y(e^x)-1=0\quad \text{note that this is a quadratic equation for }e^x$$
 
$$e^x=\frac{2y\pm\sqrt{4y^2+4}}{2}=y\pm\sqrt{y^2+1}\text{ we take the plus sign since }e^x>0$$

So, 
$$x = \ln(y + \sqrt{y^2 + 1}) = \sinh^{-1} y$$
.

In  $\mathbb{C}$ , we define  $\sinh^{-1} z = \log(z + \sqrt{z^2 + 1})$ .

Similarly,  $\sin^{-1} z = -i \log(iz + (1-z^2)^{\frac{1}{2}})$ . Note that for this fefinition, it involves two sets of branches, one with  $\log$ , and the other one with  $(1-z^2)^{\frac{1}{2}}$ 

# Chapter 4 Complex Integration

#### 4.1 Contours

How to integrate in  $\mathbb{C}$ ?

Complex values functions of a real variable are easy to integrate:

$$\int_{a}^{b} \left( u(t) + iv(t) \right) dt = \int_{a}^{b} u(t) dt + i \int_{a}^{b} v(t) dt$$

**Example 4.1.** 1.

$$\int_0^1 (t+i)^2 dt \int_0^1 \left( (t^2 - 1) + i(2t) \right) dt = \frac{-2}{3} + 2i$$

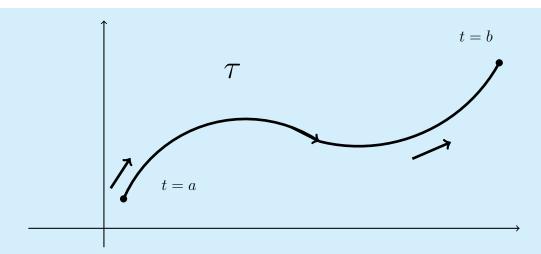
2. We can use a special trick (instead of using integration by parts twice).

$$\begin{split} \int_0^{\pi} e^{2\pi} \cos x dx &= \int_0^{\pi} e^2 x (Re(e^i x)) dx \\ &= Re \bigg( \int_0^{\pi} e^{(2+i)\pi} \bigg) \\ &= Re \bigg( \frac{e^{(2+i)}}{2+i} \bigg|_0^{\pi} \bigg) \\ &= Re \bigg( \frac{e^{2x} (\cos x + i \sin x)}{2+i} \cdot \frac{2-i}{2-i} \bigg|_0^{\pi} \bigg) \\ &= \bigg[ \frac{2}{5} e^{2x} \cos x + \frac{1}{5} e^{2x} \sin x \bigg] \bigg|_0^{\pi} \\ &= -\frac{2}{5} e^{-2\pi} + \frac{2}{5} \end{split}$$

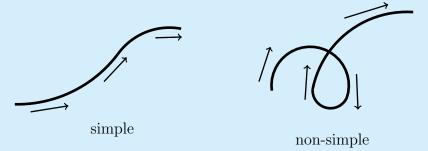
What about integrating a function of a complex variable?

We will replace the intervals with paths.

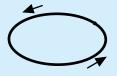
**Definition 4.2.** Let z(t) = x(t) + iy(t) on  $t \in [a, b]$  be continuous. The range is a <u>curve</u> C, and is called a <u>smooth curve</u> if z'(t) is continuous and non-zero on [a, b]



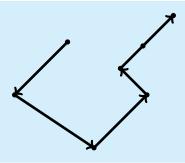
A curve is called <u>simple</u> if  $z(t_1) \neq z(t_2)$  whenever  $t_1 \neq t_2$  for  $a < t_i < b$  (basically no self intersection)



If z(a) = z(b), then the curve is called a **closed** curve.



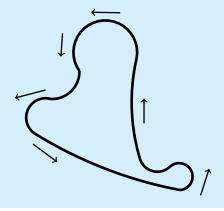
simple closed curve



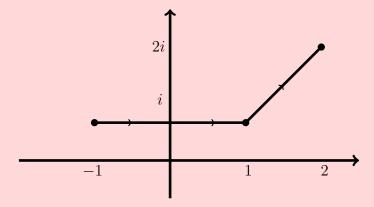
Definition 4.4. <u>Jordan Curve</u>: a simple closed contour.



**Definition 4.5.** Positively Oriented: means its interior lies to the <u>left</u> as we follow the curve



Example 4.6. Parameterize this:



**Solution**: Line segment from  $z_0$  to  $z_1$  can be parameterized as:  $z(t) = z_0 + (z_1 - z_0)t$ ,  $t \in [0, 1]$ . For the first curve,

$$z_1(t) = (-1+i) + (1+i-(-1+i))t$$
  
= -1+i+2t,  $t \in [0,1]$ 

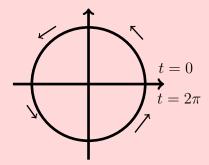
For the second curve,

$$z_2(t) = (1+i) + (2+2i - (1+i))t$$
  
= 1+i+(1+i)t,  $t \in [0,1]$ 

Put everything together we get

$$z(t) = \begin{cases} -1 + i + 2t & t \in [0, 1) \\ 1 + i + (1 + i)(t - 1) & t \in [1, 2] \end{cases}$$

**Example 4.7.** Let C be a unit circle centered at 0.



Solution:  $C: z(t) = e^{it}$   $t \in [0, 2\pi]$ 

**Example 4.8.** Circle, radius  $r_0$ , centered at  $z_0$ ?

Solution:  $C: z(t) = z_0 + r_0 e^{it}$   $t \in [0, 2\pi]$ 

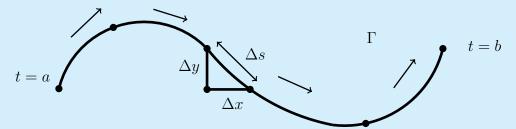
**Example 4.9.** Parameterize  $y = f(x), x \in [a, b]$ 

**Solution**: just let x(t) = t,

$$z(t) = x(t) + iy(t) = t + if(t), \quad t \in [a, b]$$

For example,  $y = x^2$  will be parameterized as  $z(t) = t + it^2$ 

**Definition 4.10. Arclength**: We define the arclength as follows:



Partition the curve

$$\Delta s \approx \sqrt{\Delta x^2 + \Delta y^2}$$

$$= \sqrt{\left(\frac{\Delta x}{\Delta t}\right)^2 + \left(\frac{\Delta y}{\Delta t}\right)^2} \Delta t$$

Sum all pieces and let  $\Delta t \to 0$  (Performing a Riemann Sum there):

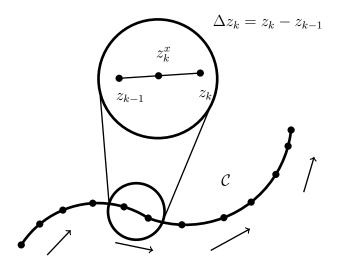
$$L = \int_{R} ds = \int_{a}^{b} \sqrt{\left(\frac{dx}{dt}\right)^{2} + \left(\frac{dy}{dt}\right)^{2}} dt$$
$$= \int_{a}^{b} \left|\frac{dz}{dt}\right| dt \quad \text{we use modulus here}$$

The physical interpretation could be: total\_distance =  $\int_a^b$  (speed) dt

Now we are ready to integrate f(z) along a curve.

# 4.2 Contour Integrals

Partition curve  $\mathcal{C}$  as shown.



Sum, and let  $\max |\Delta z_k| \to 0$ :

$$\int_{\mathcal{C}} f(z)dz = \lim_{\max |\Delta z_k| \to 0} \sum_{k} f(z_k^*) \Delta z_k$$

See the text for more detail.

If C is a single point, define  $\int_C f(z)dz = 0$ .

How to calculate?

**Definition 4.11.** Assume C has a parameterization. Call it  $z(t), t \in [a, b]$ . Then:

$$\int_{\mathcal{C}} f(z)dz = \lim_{\max|\Delta z_k| \to 0} \sum_{k} f(z_k^*) \underbrace{\frac{z_k}{z(t_k)} - \frac{z_{k-1}}{z(t_{k-1})}}_{\Delta t_k} \Delta t_k$$
$$= \int_{a}^{b} f(z)z'(t)dt$$

Proposition 4.12. Properties:

- $\int_{\mathcal{C}} \left( f(z) + g(z) \right) dz = \int_{\mathcal{C}} f(z) dz + \int_{\mathcal{C}} g(z) dz$
- $\int_{\mathcal{C}} kf(z)dz = k \int_{\mathcal{C}} f(z)dz$
- $\int_{-\mathcal{C}} f(z)dz = -\int_{\mathcal{C}} f(z)dz$ . Here  $-\mathcal{C}$  means  $\mathcal{C}$  traversed in the opposite direction
- $\int_{\mathcal{C}_1+\mathcal{C}_2} f(z)dz = \int_{\mathcal{C}_1} f(z)dz + \int_{\mathcal{C}_2} f(z)dz$ . Here it means that we traverse  $\mathcal{C}_1$  then traverse  $\mathcal{C}_2$ .



Is there a triangle inequality? i.e.

$$\left| \int_{\mathcal{C}} f(z) dz \right| \le_{?} \int_{\mathcal{C}} |f(z)| \, dz$$

No! LHS is real, but RHS is complex. "≤" does NOT make any sense here.

**Proposition 4.13. The "ML" Inequality**: If f(z) is continuous on a contour C, then

$$\left| \int_{\mathcal{C}} f(z) dz \right| \le ML$$

where M is an upper bound for |f(z)| on C and L is the length of C.

**Proof 4.14.** Let  $z(t), t \in [a, b]$  be a parameterization of  $\mathcal{C}$ . Then

$$\left| \int_{\mathcal{C}} f(z)dz \right| = \left| \int_{a}^{b} f(z(t))z'(t)dt \right|$$

$$\leq \int_{a}^{b} \left| f(z(t))z'(t) \right| dt \quad \text{by triangle inequality for integrals w.s.t. real variables}$$

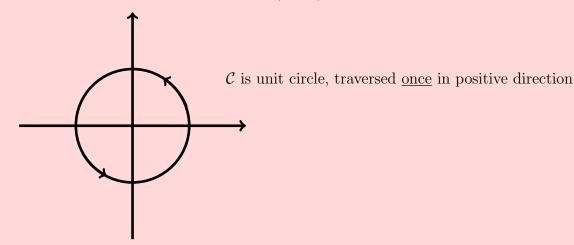
$$= M \int_{a}^{b} \left| z'(t) \right| dt$$

$$= ML$$

Second last step: since  $|f(z)| \leq M$  on C.

Last step: from last lecture. See Definition 4.10.

**Example 4.15.** Find an upper bound on  $\left| \int_{\mathcal{C}} e^{\frac{1}{z}} \right|$ 



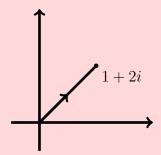
Solution: M = ?

$$\begin{aligned} \left| e^{\frac{1}{z}} \right| &= \left| e^{\frac{1}{x+iy}} \right| \\ &= \left| e^{\frac{x-iy}{x^2+y^2}} \right| \\ &= \left| e^{\frac{x}{x^2+y^2}} \cdot e^{-i\frac{y}{x^2+y^2}} \right| \\ &\leq e^{\frac{x}{1}} \quad \text{since } x^2 + y^2 = 1 \\ &\leq e^1 \quad \text{since } x \leq 1 \end{aligned}$$

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Clearly,  $L=2\pi$ , so  $\left|e^{\frac{1}{z}}\right| \leq e^1 \cdot 2\pi = 2\pi e$  by ML inequality.

**Example 4.16.** Evaluate  $\int_{\mathcal{C}} \cos z dz$  where  $\mathcal{C}$  is the line segment from 0 to 1+2i.



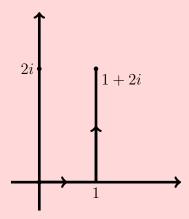
**Solution**: Parameterize C by

$$z(t) = 0 + (1 + 2i - 0)t, \quad t \in [0, 1]$$

Then

$$\int_{\mathcal{C}} \cos z dx = \int_{0}^{1} \underbrace{\cos \left( (1+2i)t \right)}_{f(z(t))} \cdot \underbrace{(1+2i)}_{z'(t)} dt = \sin \left( (1+2i)t \right) \Big|_{0}^{1} = \sin(1+2i) - 0 = \sin(1+2i)$$

**Example 4.17.** Evaluate  $\int_{\mathcal{C}} \cos z dz$  where  $\mathcal{C}$  is:



Solution: 
$$C = C_1 \cup C_2$$
 where 
$$\begin{cases} C_1 : & z(t) = t, \ t \in [0, 1) \\ C_2 : & z(t) = 1 + (t - 1)i, \ t \in [1, 3] \end{cases}$$
. So

$$\int_{\mathcal{C}} \cos z dx = \int_{\mathcal{C}_1} \cos z dx + \int_{\mathcal{C}_2} \cos z dx$$

$$= \int_0^1 \cos t dt + \int_1^3 \cos(1 + (t - 1)i)i dt$$

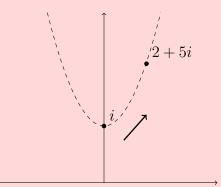
$$= \sin t |_0^1 + \sin(1 + (t - 1)i)|_1^3$$

$$= \sin(1) + (\sin(1 + 2i) - \sin(1))$$

$$= \sin(1 + 2i)$$

As before

**Example 4.18.** Evaluate  $\int_{\mathcal{C}} e^z dz$  where  $\mathcal{C}$  is part of  $y = x^2 + 1$  from z = i to z = 2 + 5i.



**Solution**: Let  $z(t) = \underbrace{t}_{x} + \underbrace{(t^2 + 1)}_{y} i$ ,  $t \in [0, 2]$ . Then,

$$\int_{\mathcal{C}} e^z dz = \int_0^2 e^{z(t)} z'(t) dt$$

$$= \int_0^2 e^{t^2 + (t^2 + 1)i} (1 + 2ti) dt$$

$$= e^{t^2 + (t^2 + 1)i} \Big|_0^2$$

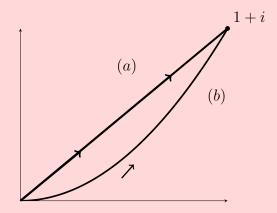
$$= e^{2 + 5i} - e^i$$

$$= e^z \Big|_i^{2 + 5i}$$

Does it always work that way? See the following example

# **Example 4.19.** Evaluate $\int_{\mathcal{C}} \overline{z} dz$ where

- 1. C is line segment from 0 to 1+i
- 2. C is the smallest arc of circle  $x^2 + (y-1)^2 = 1$  from 0 to 1+i



### Solution:

1. parameterization:  $z(t) = t(1+i), t \in [0,1]$ 

$$\int_{\mathcal{C}} \overline{z}dz = \int_{0}^{1} t(1-i) \cdot (1+i)dt$$
$$= \int_{0}^{1} 2tdt$$
$$= 1$$

2. parameterization:  $z(t) = e^{it} + i$ ,  $t \in [\frac{-\pi}{2}, 0]$ . It's the unit circle, shifted up by 1 unit.

$$\int_{\mathcal{C}} \overline{z} dz = \int_{-\pi/2}^{0} (e^{-it} - i)(ie^{it}) dt$$

$$= \cdots$$

$$= 1 + i(\frac{\pi}{2} - 1) dt$$

$$\neq 1$$

So, the general answer is no. Different paths might yield different results.

# 4.3 Independence of Path

### Theorem 4.20. Complex Extension of Fundamental Theorem of Calculus:

If f(z) is continuous in a domain D and has antiderivative F(z) throughout D, then, for any contour C lying in D with initial point  $z_1$  and terminal point  $z_2$ , we have

$$\int_{\mathcal{C}} f(z)dz = F(z_2) - F(z_1)$$



**Proof 4.21.** First, suppose C is smooth, i.e.  $z'(t) \neq 0$ , continuous.

Parameterize by  $z(t), t \in [a, b]$ . Then,

$$\int_{\mathcal{C}} f(z)dz = \int_{a}^{b} f(z(t))z'(t)dt$$

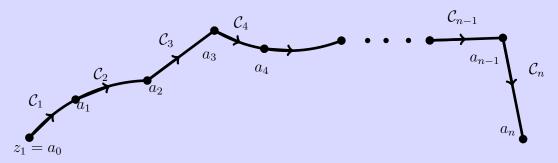
$$= \int_{\mathcal{C}} \frac{d}{dt} \left( F(z(t)) \right) dt \text{ by chain rule}$$

$$= F(z(t)) \Big|_{t=a}^{b}$$

$$= F(z(b)) - F(z(a))$$

$$= F(z_{2}) - F(z_{1})$$

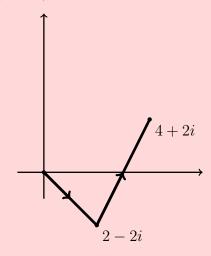
Next, if C is not smooth, it has a finite number of smooth pieces, since it's a contour.



Apply the result above to each piece:

$$\int_{\mathcal{C}} f(z)dz = \int_{\mathcal{C}_1} f(z)dz + \dots + \int_{\mathcal{C}_n} f(z)dz 
= \left(F(a_1) - F(a_0)\right) + \left(F(a_2) - F(a_1)\right) + \dots + \left(F(a_n) - F(a_{n-1})\right) 
= F(a_n) - F(a_0) 
= F(z_2) - F(z_1)$$

**Example 4.22.** Evaluate  $\int_{\mathcal{C}} (1+z^2)dz$  where  $\mathcal{C}$  is:



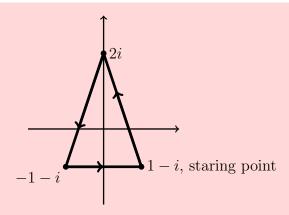
**Solution**:

$$\int_{\mathcal{C}} (1+z^2)dz = \left(z + \frac{z^3}{4}\right) \Big|_{z=0}^{z=4+2i}$$

$$= \cdots$$

$$= \frac{28}{3} + \frac{94}{3}i$$

**Example 4.23.** Evaluate  $\int_{\mathcal{C}} e^z dz$  where  $\mathcal{C}$  is:



Solution:

$$\int_{\mathcal{C}} (1+z^2)dz = e^z \Big|_{z=1-i}^{z=1-i}$$

$$= e^{1-i} - e^{1-i}$$

$$= 0$$

**Theorem 4.24.** Let f be a continuous function in a domain D. Then, the following statements are equivalent:

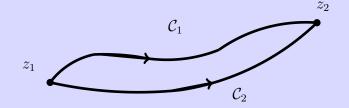
- 1. f has an antiderivative in D.
- 2. If C is any closed contour in D, then  $\int_{C} f(z)dz = 0$ .
- 3. The contour integrals of f are independent of path in D.

**Proof 4.25.**  $1 \Rightarrow 2$ : It follows immediately from Theorem 4.20 with C being a closed contour.

 $2 \Rightarrow 3$ : Let  $C_1$  and  $C_2$  be any two contours in D with same end points. Let C be the closed contour  $C_1 + (-C_2)$ .

Then,  $\int_{\mathcal{C}} f(z)dz = 0$ . So  $\int_{\mathcal{C}_1} f(z)dz + \int_{-\mathcal{C}_2} f(z)dz = 0$ . So  $\int_{\mathcal{C}_1} f(z)dz - \int_{\mathcal{C}_2} f(z)dz = 0$ , implying that

$$\int_{\mathcal{C}_1} f(z)dz = \int_{\mathcal{C}_2} f(z)dz$$



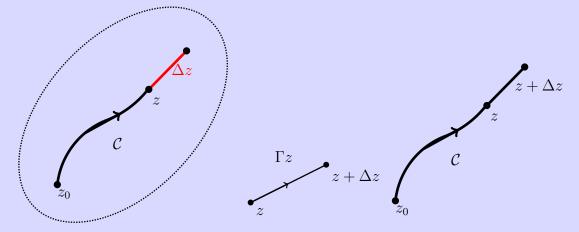
 $3 \Rightarrow 1$ : Construct the antiderivative. Choose a point  $z_0 \in D$ , and let  $\mathcal{C}$  be the contour as shown. Recall the D is a connected set.

Define  $F(z) = \int_{\mathcal{C}} f(w)dw$ . By 3, F(z) is single valued; We will show that F'(z) = f(z).

For any point z, choose  $\Delta z$  small enough such that the line segment  $\Gamma$  parameterized by

$$z(t) = z + t\Delta z, \ t \in [0, 1]$$

is in D (This is possible since D is open)



Then

$$F(z + \Delta z) - F(z) = \left( \int_{\mathcal{C}} f(w)dw + \int_{\Gamma} f(w)dw \right) - \int_{\mathcal{C}} f(w)dw$$

$$= \int_{\Gamma} f(w)dw$$

$$= \int_{0}^{1} f(z(t))z'(t)dt$$

$$= \int_{0}^{1} f(z + t\Delta z)(\Delta z)dt$$

$$\Rightarrow \frac{F(z + \Delta z) - F(z)}{\Delta z} = \int_{0}^{1} f(z + t\Delta z)dt$$

Let  $\Delta z \to 0$ .

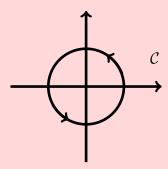
$$F'(z) = \int_0^1 f(z)dt = f(z) \int_0^1 dt = f(z)$$

We showed that  $\overline{z}$  can be integreated, but the result depends on path. So  $\overline{z}$  is integrable, but not anti-differentiable. Also, functions with antiderivatives are easy; for those without, we must parameterize.

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## 4.4 Cauchy's Integral Theorem

Example 4.26. Most Important Example in this Course: Evaluate  $\int_{\mathcal{C}} \frac{1}{z} dz$  where  $\mathcal{C}$  is the unit circle.

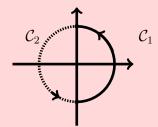


<u>Solution</u>:  $\frac{1}{z}$  does not have antiderivative over all of  $\mathcal{C}$ . Any branch of  $\log z$  will have a problem, i.e.  $\mathcal{C}$  will cross a branch cut.

Method 1: Parameterize C by  $e^{it}$ ,  $t \in [0, 2\pi]$ . By definition,

$$\int_{\mathcal{C}} \frac{1}{z} dz = \int_0^{2\pi} \frac{1}{e^{it}} \cdot i e^{it} dt = 2\pi i$$

Method 2: Split  $\mathcal{C}$  in two, and use Theorem 4.20 on each.



$$\int_{\mathcal{C}_1} \frac{1}{z} dz = \operatorname{Log} z \Big|_{-i}^{i} \quad \text{branch cut at } \theta = -\pi$$

$$= \operatorname{Log} i - \operatorname{Log}(-i)$$

$$= i \frac{\pi}{2} - i \left(\frac{-\pi}{2}\right)$$

$$= \pi i$$

$$\int_{\mathcal{C}_2} \frac{1}{z} dz = \operatorname{Log}_0 z \Big|_{i}^{-i}$$

$$= \operatorname{Log}_0(-i) - \operatorname{Log}_0(i)$$

$$= \frac{3\pi}{2} i - \frac{\pi}{2} i$$

$$= \pi i$$

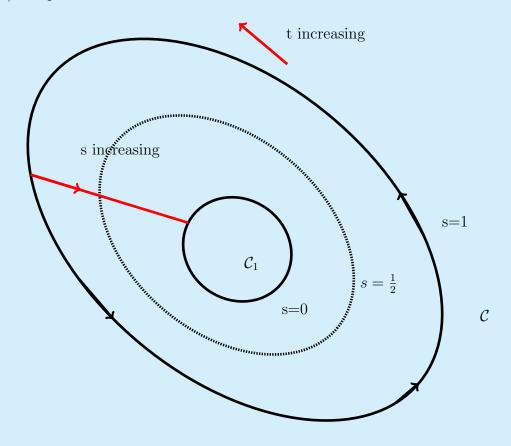
Therefore,

$$\int_{\mathcal{C}} \frac{1}{z} dz = \int_{\mathcal{C}_1} \frac{1}{z} dz + \int_{\mathcal{C}_2} \frac{1}{z} dz = \pi i + \pi i = 2\pi i$$

Go around the contour twice, what's the result? It would be  $4\pi i$ . Also, going counter-clockwise would yield the result  $-2\pi i$ 

**Definition 4.27.** A closed contour C is said to be <u>continuously deformable</u> to a contour  $C_1$  in a domain D if there exists a function z(s,t), continuous for  $s \in [0,1], t \in [0,1]$ , such that

- 1. z(s,t) is a closed contour in D for each  $s \in [0,1]$
- 2. z(0,t) is a parameterization of C
- 3. z(1,t) is a parameterization of  $\mathcal{C}_1$



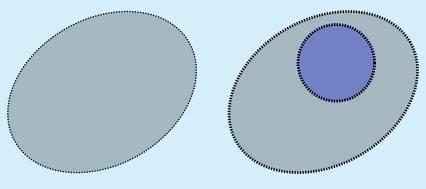
**Theorem 4.28.** Deformation Invariance Theorem: Let f be analytic in a domain D,

containing closed contours  $C_1$  and  $C_2$ . If  $C_1$  can be continuously deformed into  $C_2$ , then

$$\int_{\mathcal{C}_1} f(z)dz = \int_{\mathcal{C}_2} f(z)dz$$

**Proof 4.29.** It's too hard - 12 pages long in one text.

**Definition 4.30.** A <u>simply connected domain</u> is a domain in which every "loop" (closed contour) in D can be continuously deformed to a point (while remaining in D).



simply connected

Not simply connected

# Theorem 4.31. Cauchy's Integral Theorem (Cauchy-Goursat Theorem):

If f is analytic in a simply connected domain D, and  $\mathcal{C}$  is a closed contour in D, then

$$\int_{\mathcal{C}} f(z)dz = 0$$

**Proof 4.32.** Follows from Theorem 4.28 by shrinking C continuously to a point.

Corollary 4.33. Since  $\int_{\mathcal{C}} f(z)dz = 0 \Leftrightarrow f$  has an antiderivative in D, we have that if f is analytic, then f also has an antiderivative, which is analytic. So every analytic function is infinitely antidifferentiable.

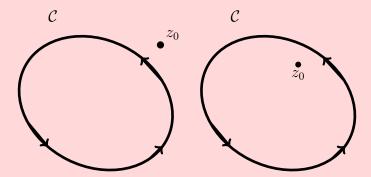
**Example 4.34.** Back to Example 4.26. We know that  $\int_{\mathcal{C}} \frac{1}{z} dz = 2\pi i$  for <u>any</u> closed contour

enclosing the origin.

Also,  $\int_{\mathcal{C}} \frac{1}{z} dz = 0$  for any closed contours <u>not</u> enclosing the origin.

Could shift results:

$$\int_{\mathcal{C}} \frac{1}{z - z_0} dz = \begin{cases} 0 & \text{if } z_0 \text{ is exterior to } \mathcal{C} \\ 2\pi i & \text{if } z_0 \text{ is interior to } \mathcal{C} \end{cases}$$



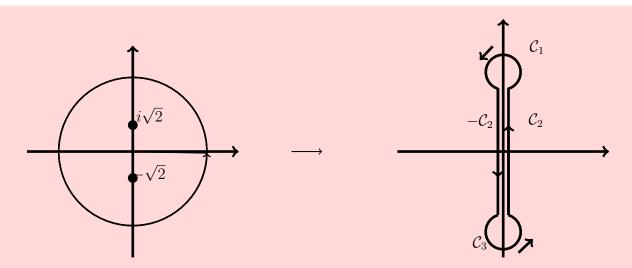
**Example 4.35.** Evaluate  $\int_{\mathcal{C}} \frac{2z}{z^2+2} dz$  where  $\mathcal{C}$  is the positively oriented circle of radius 2 centered at origin.

**Solution**: We can do partial fractions:

$$\frac{2z}{z^2 + 2} = \frac{1}{z + i\sqrt{2}} + \frac{1}{z - i\sqrt{2}}$$

So we have singularities at  $z = \pm i\sqrt{2}$ . We can use the **Deformation Invariance Theorem** to deform  $\mathcal{C}$  like below. So

$$\int_{\mathcal{C}} = \int_{\mathcal{C}_2} + \int_{\mathcal{C}_1} + \int_{-\mathcal{C}_2} + \int_{\mathcal{C}_3}$$
$$= \int_{\mathcal{C}_1} + \int_{\mathcal{C}_3}$$



And

$$\int_{\mathcal{C}} \frac{2z}{z^2 + 2} dz = \int_{\mathcal{C}} \left( \frac{1}{z + i\sqrt{2}} + \frac{1}{z - i\sqrt{2}} \right) dz$$

$$= \int_{\mathcal{C}_1} \left( \frac{1}{z + i\sqrt{2}} + \frac{1}{z - i\sqrt{2}} \right) dz + \int_{\mathcal{C}_3} \left( \frac{1}{z + i\sqrt{2}} + \frac{1}{z - i\sqrt{2}} \right) dz$$

$$= \int_{\mathcal{C}_1} \frac{1}{z + i\sqrt{2}} dz + \int_{\mathcal{C}_1} \frac{1}{z - i\sqrt{2}} dz + \int_{\mathcal{C}_3} \frac{1}{z + i\sqrt{2}} dz + \int_{\mathcal{C}_3} \frac{1}{z - i\sqrt{2}} dz$$

$$= 0 + 2\pi i + 2\pi i + 0$$

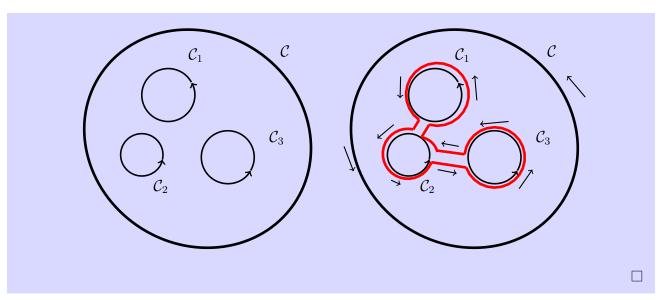
$$= 4\pi i$$

#### Theorem 4.36. Extended Cauchy-Goursat Theorem:

$$\int_{\mathcal{C}} f(z)dz = \sum_{i=1}^{n} \int_{\mathcal{C}_{i}} f(z)dz$$

**Proof 4.37.** Ideas (for the case of n = 3): Deform C to  $\Gamma$  as shown:

$$\int_{\mathcal{C}} = \int_{\widetilde{\mathcal{C}}} = \int_{\mathcal{C}_1} + \int_{\mathcal{C}_2} + \int_{\mathcal{C}_3}$$



What about  $\int_{\mathcal{C}} \frac{1}{(z-z_0)^2} dz$  or other powers of  $z-z_0$ ?

Consider  $\int_{\mathcal{C}} (z-z_0)^n dz$  where  $n \neq -1$ .

- If  $z_0$  is external to C, the integral is zero, by Cauchy's Integral Theorem.
- If  $z_0$  is internal to  $\mathcal{C}$ , deform  $\mathcal{C}$  to the unit circle  $|z z_0| = 1$ , parameterized by  $z = z_0 + e^{it}$ ,  $t \in [0, 2\pi]$ . We may use the radius  $\epsilon$  if the circle is not small enough. The result would be the same.

Then

$$\int_{\mathcal{C}} (z - z_0)^n dz = \int_{\mathcal{C}} (e^{it})^n i e^{it} dt$$
$$= \frac{i}{n+1} e^{i(n+1)t} \Big|_{0}^{2\pi}$$
$$= 0$$

Thus for an interioir point  $z_0$  in C

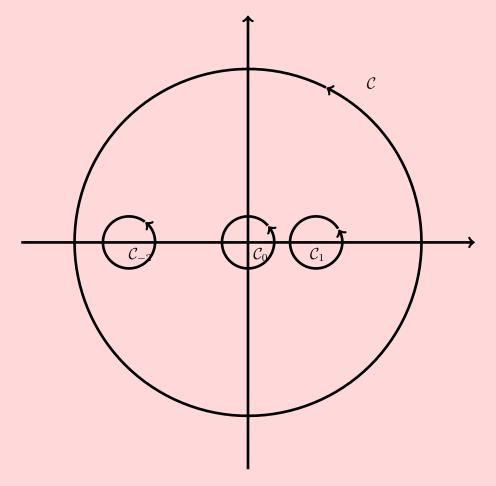
$$\int_{\mathcal{C}} (z - z_0)^n dz = \begin{cases} 0 & \text{if } n \neq -1\\ 2\pi i & \text{if } n = -1 \end{cases}$$

**Example 4.38.** Let C be the positively oriented circle of radius 3 centered at the origin. Evaluate  $\int_{C} \frac{3z^3 + 2}{z^4 + z^3 - 2z^2} dz$ 

<u>Solution</u>: Note that  $z^4 + z^3 - 2z^2 = z^2(z^2 + z - 2) = z^2(z - 1)(z + 2)$ . These give us the location of the singularities.

Note the partial fractions:

$$\frac{3z^3 + 2}{z^4 + z^3 - 2z^2} = \frac{-1/2}{z} + \frac{-1}{z} + \frac{5/3}{z - 1} + \frac{11/6}{z + 2}$$



By the Extended Cauchy-Goursat Theorem,

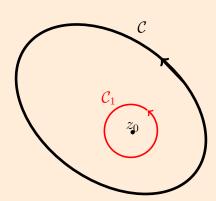
$$\int_{\mathcal{C}} f(z)dz = \int_{\mathcal{C}_{-2}} f(z)dz + \int_{\mathcal{C}_{0}} f(z)dz + \int_{\mathcal{C}_{1}} f(z)dz$$
$$= \frac{11}{6} \cdot (2\pi i) + \frac{-1}{2} \cdot (2\pi i) + \frac{5}{3} \cdot (2\pi i)$$
$$= 6\pi i$$

# 4.5 Cauchy's Integral Formula

Theorem 4.39. Cauchy's Integral Formula (CIF): Let C be a simple, closed, positively-oriented contour. If f is analytic in some simply connected domain D containing

C, and  $z_0$  is any point inside C. Then,

$$\int_{\mathcal{C}} \frac{f(z)}{z - z_0} dz = 2\pi i f(z_0)$$



**Proof 4.40.** deform C to  $C_r$ , a positively oriented circle of radius r centered at  $z_0$ :  $|z-z_0|=r$ . We will let  $r\to 0$ .

Then,

$$\int_{\mathcal{C}} \frac{f(z)}{z - z_0} dz = \int_{\mathcal{C}_r} \frac{f(z)}{z - z_0} dz$$

$$= \int_{\mathcal{C}_r} \frac{f(z) - f(z_0)}{z - z_0} dz + \int_{\mathcal{C}_r} \frac{f(z_0)}{z - z_0} dz \text{ by linearity}$$

$$= 0 + 2\pi i f(z_0)$$

$$= 2\pi i f(z_0)$$

To show  $\int_{\mathcal{C}_r} \frac{f(z) - f(z_0)}{z - z_0} dz = 0$ , we consider the following:

On  $C_r$ , we have  $|f(z) - f(z_0)| \leq M$  for some M. Then

$$\left| \frac{f(z) - f(z_0)}{z - z_0} \right| \le \frac{M}{r}$$
 since  $|z - z_0| = r$  on  $C_r$ 

By ML inequality,

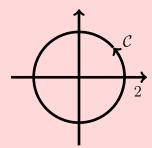
$$\left| \int_{\mathcal{C}_r} \frac{f(z) - f(z_0)}{z - z_0} dz \right| \le \frac{M}{r} \cdot \operatorname{length}(\mathcal{C}_r) = \frac{M}{r} 2\pi r = 2\pi M$$

Let  $r \to 0$ , then  $M \to 0$  by continuity of f, and so

$$\int_{\mathcal{C}_r} \frac{f(z) - f(z_0)}{z - z_0} dz = 0$$

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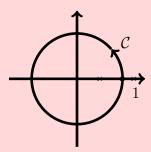
**Example 4.41.** Evaluate  $\int_{\mathcal{C}} \frac{e^z}{z-1} dz$ .



**Solution**: Let  $f(z) = e^z$ . Since f(z) is entire, and  $z_0 = 1$  is inside C, we have, by **CIF**,

$$\int_{\mathcal{C}} \frac{e^z}{z-1} dz = 2\pi i f(1) = 2\pi i e^1 = 2\pi e i$$

**Example 4.42.** Evaluate  $\int_{\mathcal{C}} \frac{e^{i\pi z}}{2z^2 - 5z + 2} dz$ .



Solution:

$$\int_{\mathcal{C}} \frac{e^{i\pi z}}{2z^2 - 5z + 2} dz = \int_{\mathcal{C}} \frac{e^{i\pi z}}{2(z - \frac{1}{2})(z - 2)} dz$$

$$= \int_{\mathcal{C}} \frac{\frac{e^{i\pi z}}{2(z - 2)}}{z - \frac{1}{2}} dz \quad \text{regard the numerator as } f(z)$$

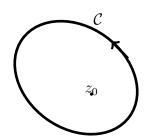
$$= 2\pi i f(\frac{1}{2}) \quad \text{by CIF}$$

$$= 2\pi i \frac{e^{i\pi/2}}{2(\frac{-3}{2})}$$

$$= \frac{2\pi}{3}$$

From CIF, we know

$$f(z_0) = \frac{1}{2\pi i} \int_{\mathcal{C}} \frac{f(z)}{z - z_0} dz$$



So the value of f at any point inside C is determined by the values of f on C

**Proposition 4.43. Mean Value Property**: If C is a circle of radius R centered at  $z_0$ :

$$f(z_0) = \frac{1}{2\pi i} \int_0^{2\pi} \frac{f\left(\overbrace{z_0 + Re^{it}}\right)}{z_0 + Re^{it} - z_0} \underbrace{\overbrace{(iRe^{it})}^{z'(t)}}_{\text{by parameterizing circle}}$$
$$= \frac{\int_0^{2\pi} f\left(z_0 + Re^{it}\right)}{2\pi - 0}$$

= averge value of f on the circle, recall that  $\frac{\int_a^b f(x)dx}{b-a} = \overline{f}$ 

# Theorem 4.44. Derivatives of f:

$$f(z_0) = \frac{1}{2\pi i} \int_{\mathcal{C}} \frac{f(z)}{z - z_0} dz = \frac{1}{2\pi i} \int_{\mathcal{C}} \frac{f(w)}{w - z} dw$$

Differentiate:

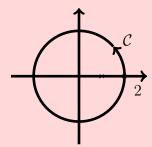
$$f'(z) = \frac{1}{2\pi i} \int_{\mathcal{C}} f(w) \frac{d}{dz} \left(\frac{1}{w-z}\right) dw \quad \text{by Leibniz's rule}$$
$$= \frac{1}{2\pi i} \int_{\mathcal{C}} \frac{f(w)}{(w-z)^2} dw$$

which is also differentiable.

Repeating and switch back to  $z_0$  we get Cauchy's Integral Formula for Derivatives (CIFD):

$$f^{(n)}(z_0) = \frac{n!}{2\pi i} \int_{\mathcal{C}} \frac{f(z)}{(z-z_0)^{n+1}} dz$$
 where  $z_0$  is inside  $\mathcal{C}$ 

**Example 4.45.** Evaluate  $\int_{\mathcal{C}} \frac{z^3 + 2z + 1}{(z-1)^3} dz$ .



**Solution**: Use **CIFD** with n = 2.

$$f''(z_0) = \frac{2!}{2\pi i} \int_{\mathcal{C}} \frac{f(z)}{(z-z_0)^3} dz$$

Let  $f(z) = z^3 + 2z + 1$  and  $z_0 = 1$ . Then we have

$$(6z + 0 + 0) \Big|_{z=1} = \frac{1}{\pi i} \int_{\mathcal{C}} \frac{f(z)}{(z - z_0)^3} dz$$
$$6\pi i = \int_{\mathcal{C}} \frac{z^3 + 2z + 1}{(z - 1)^3} dz$$

# 4.6 Implication of CIFD

Corollary 4.46. An analytic function is infinitely differentiable. Furthermore, with f(z) = u(x, y) + iv(x, y), u and  $v \in C^{\infty}$  (i.e. have continuous partials of all order)

**Proof 4.47.** f = u + iv, then

$$f' = \begin{cases} u_x + iv_x & \Rightarrow f'' = \begin{cases} u_{xx} + iv_{xx} & \cdots \\ v_{xy} - iu_{xy} & \cdots \end{cases} \\ v_y - iu_y & \Rightarrow f'' = \begin{cases} v_{yx} - iu_{yx} & \cdots \\ -u_{yy} - iv_{yy} & \cdots \end{cases} \end{cases}$$

Existence of f'' implies  $u_x, u_y, v_x, v_y$  are all continous. Also, observe that  $u_{xx} = -u_{yy}$ ,  $v_{xx} = -v_{yy}$ ,  $v_{xy} = v_{yx}$ ,  $u_{xy} = u_{yx}$ 

Theorem 4.48. Morera's Theorem: (the converse of Cauchy's Integral Theorem)

Let f be a continuous function in a simply connected domain D. If  $\int_{\mathcal{C}} f(z)dz = 0$  for every closed contour  $\mathcal{C}$  in D, then f is analytic in D.

**Proof 4.49.** We've shown that  $\int_{\mathcal{C}} f(z)dz = 0$  for all  $\mathcal{C}$  implies that f has antiderivative in D, call it F(z).

Now D is open, and F is differentiable in D (F' = f), so therefore F is analytic, therefore F' = f is analytic.

**Lemma 4.50.** "Cauchy's Estimate": Let f be analytic on and inside a circle  $\mathcal{C}$  of radius R centered at  $z_0$ .

If  $|f(z)| \leq M$  for all z on C, then  $|f^{(n)}(z_0)| \leq \frac{n!M}{R^n}$ .

Proof 4.51. From CIFD,

$$\left| f^{(n)}(z_0) \right| = \left| \frac{n!}{2\pi i} \int_{\mathcal{C}} \frac{f(z)}{(z - z_0)^{n+1}} dz \right| \le \left| \frac{n!}{2\pi i} \right| \underbrace{\left( \frac{M}{R^{n+1}} \right)}^{\text{"}M"} \cdot \underbrace{\left( 2\pi R \right)}^{\text{"}\ell''}$$

since  $|z - z_0| = R$  and the  $M\ell$ -inequality.

**Theorem 4.52.** Liouville's Theorem: If f is entire, and bounded for all  $z \in \mathbb{C}$ , then f is constant.

**Proof 4.53.** Have  $|f(z)| \leq M$  for all  $z \in \mathbb{C}$ . Consider  $z_0 \in \mathbb{C}$ , and let  $\mathcal{C}$  be circle of radius R centered at  $z_0$ . Cauchy's estimate yields  $|f'(z_0)| \leq \frac{M}{R}$ . True for all R, no matter how large. So  $|f'(z_0)| = 0 \Rightarrow f'(z_0) = 0$ .

 $z_0$  is arbitrary, so f must be constant.

Corollary 4.54. Every non-constant, entire function is unbounded.

We can use this to prove the **Fundamental Theorem of Algebra**.

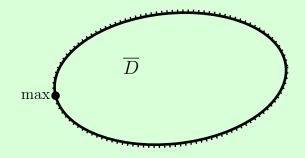
Theorem 4.55. Fundamental Theorem of Algebra: Every nonconstant polynomial with complex coefficients has at least one zero.

**Proof 4.56.** If P(z) has no zeros, then  $\frac{1}{P(z)}$  is entire. Since it is continuous, we must have  $|P(z)| \ge \epsilon$  for some  $\epsilon > 0$ .

So,  $\frac{1}{|P(z_0)|} \leq \frac{1}{\epsilon}$ , implying that  $\frac{1}{P(z_0)}$  is constant, by **Liouville's Theorem**.

So,  $P(z_0)$  is constant. Hence, a non-constant polynomial must have a zero.

**Proposition 4.57.** <u>Maximum Modulus Principle</u>: If f(z) is analytic on a bounded domain D, and continuous on  $\overline{D}$ , the closure of D. Then, |f(z)| attains a maximum value on  $\overline{D}$  and it occurs on the boundary.



# Chapter 5 Series Representation for Analytic Functions

## 5.1 Sequences and Series

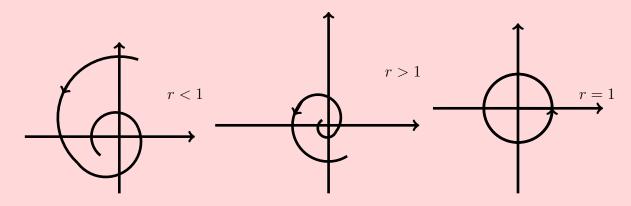
**Definition 5.1.** A sequence  $\{z_n\}_{n=1}^{\infty}$  converges to  $z_0$  if for any  $\epsilon > 0$ , there exists an integer N such that  $n > N \Rightarrow |z_n - z_0| < \epsilon$ .

**Theorem 5.2.** Let  $z_n = x_n + iy_n$  for n = 1, 2, ..., and  $z_0 = x_0 + iy_0$ . Then,  $z_n \to z_0$  if and only if  $x_n \to x_0$  and  $y_n \to y_0$  as  $n \to \infty$ .

## **Example 5.3.** Consider $\{z^n\}_{n=1}^{\infty}$ .

Notice that  $z^n = (re^{i\theta})^n = r^n e^{in\theta} \to 0$  as  $n \to \infty$  if and only if r < 1.

In other words,  $\{z^n\}_{n=1}^{\infty}$  converges to 0 as  $n \to \infty$  if and only if |z| < 1.



#### Definition 5.4. Series:

$$\sum_{n=1}^{\infty} z_n = \lim_{k \to \infty} \sum_{n=1}^{k} z_n$$

is **convergent** if the limit exists (called the <u>sum</u> of the series); otherwise is **divergent**.

Note that the LHS does not need to start at n = 1. The RHS is just the partial sum.

## Proposition 5.5. Divergence Test/nth-term Test:

If  $\sum_{n=1}^{\infty} z_n$  converges, then  $\lim_{n\to\infty} z_n = 0$ .

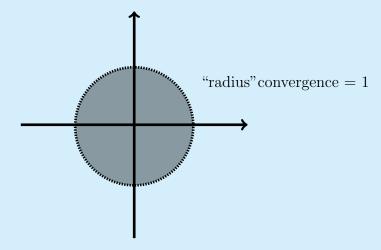
Contrapositive: if  $z_n \not\to 0$ , then  $\sum_{n=1}^{\infty} z_n$  diverges.

### Definition 5.6. Geometric Series:

$$\sum_{n=0}^{\infty} z_n = \begin{cases} \frac{1}{1-z} & \text{if } |z| < 1\\ \text{divergent} & \text{if } |z| \ge 1 \end{cases}$$

We can see that

- in  $\mathbb{R}$ ,  $\sum x^n$  converges for |x| < 1.
- in  $\mathbb{C}$ ,  $\sum z^n$  converges for |z| < 1.



**Example 5.7.**  $\sum_{n=0}^{\infty} \left(\frac{1}{2} + i\right)^n$  and  $\sum_{n=0}^{\infty} i^n$  divergent.

 $\sum_{n=0}^{\infty} \left(\frac{i}{2}\right)^n \text{ is convergent, and equals } \frac{1}{1-\frac{i}{2}} = \frac{2}{2-i} = \frac{4+2i}{3}$ 

**Proposition 5.8.** Comparison Test: If  $\sum_{k=1}^{\infty} M_k$  is a convergent series of real numbers and  $|z_k| \leq M_k$  for all sufficiently large k, then  $\sum_{k=1}^{\infty} z_k$  converges.

**Definition 5.9.**  $\sum z_n$  is absolutely convergent if  $\sum |z_n|$  converges.

**Proposition 5.10.** Ratio Test: If  $\lim_{n\to\infty} \left| \frac{z_{n+1}}{z_n} \right| = L$ , then  $\sum_{n=0}^{\infty} z_n$  is absolutely convergent if L < 1, and divergent if L > 1. No conclusion if L = 1.

### Example 5.11.

$$\sum_{n=0}^{\infty} \frac{(1-i)^n}{n!} = 1 + \frac{1-i}{1!} + \frac{(1-i)^2}{2!} + \dots \quad [0! = 1]$$

Ratio is

$$\left| \frac{z_{n+1}}{z_n} \right| = \left| \frac{(1-i)^{n+1}}{(n+1)n!} \cdot \frac{n!}{(1-i)^n} \right| = \frac{|1-i|}{n+1} = \frac{\sqrt{2}}{n+1} \to 0$$

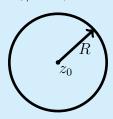
as  $n \to \infty$ , so the series converges.

#### Definition 5.12. Power Series:

$$\sum_{k=0}^{\infty} c_k (z - z_0)^k$$

This series could

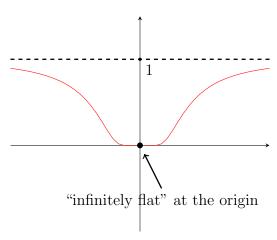
- 1. Converge only at  $z = z_0$
- 2. Converge for all z; or
- 3. Converge for all z such that  $|z z_0| < R$ , and diverge for all z such that  $|z z_0| > R$ .



**Definition 5.13.** The <u>Taylor Series</u> of f(z) centered at  $z_0$  is

$$\sum_{n=0}^{\infty} \frac{f^{(n)}(z_0)}{n!} (z - z_0)^n$$

Convergence of Taylor Series: In MATH138, we assumed that  $\sum_{n=0}^{\infty} \frac{f^{(n)}(x_0)}{n!}(x-x_0)^n$  converges to f(x) for each x in interval for convenience. This is not always true. Consider the following famous examle.



$$g(x) = \begin{cases} e^{-1/x^2} & \text{if } x \neq 0 \\ 0 & \text{if } x = 0 \end{cases} \Rightarrow f(x) = \sum_{n=0}^{\infty} \frac{g^{(n)}(0)}{n!} (x - 0)^n = \dots = 0$$

which converges for all x, but f(x) = g(x) at only one point.

Good news is that in  $\mathbb{C}$ , things make more sense

## 5.2 Taylor Series and Convergence

**Theorem 5.14.** If f is analytic in the disk  $|z - z_0| < R$ , then its Taylor series converges to f(z) for all z in this disc. The convergence is uniform on any closed subdisc  $|z - z_0| \le R_0 < R$ .

In  $\mathbb{R}$ , "analytic" means "has a power series representation".

What's wrong with g(x) above?

- In  $\mathbb{R}$ ,  $g^{(n)}(0) = 0$  for all n
- In  $\mathbb{C}$ ,  $g^{(n)}(0) = \begin{cases} e^{-1/z^2} & \text{if } z \neq 0 \\ 0 & \text{if } z = 0 \end{cases}$  is not even **continuous** at z = 0.

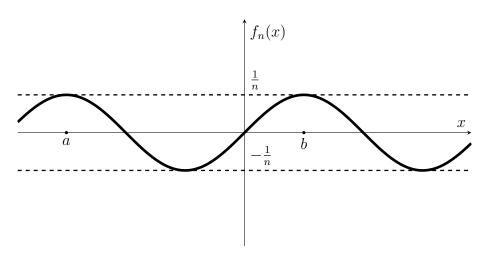
In  $\mathbb{R}$ , we only saw a cross-section, the "bad behaviour" was missed.

Uniform Convergence: Consider the following sequence of function:

$$1. \ f_n(x) = \frac{\sin x}{n}.$$

What happens as  $n \to \infty$ ?  $f_n(x) \to 0$  as  $n \to \infty$ .  $f_n \to 0$  "pointwise"

Over some interval:



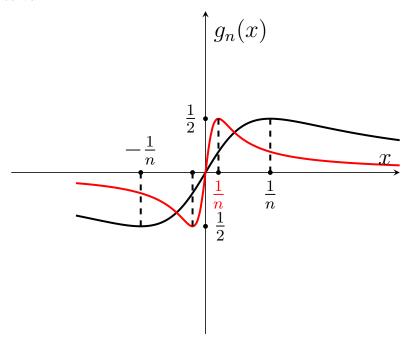
 $f_n(x)$  approaches zero function on [a,b].

In this case, we say " $f_n \to 0$  uniformly"

2. 
$$g_n(x) = \frac{nx}{1 + n^2 x^2}$$

What happens as  $n \to \infty$ ?  $g_n(x) \to 0$  as  $n \to \infty$ .  $g_n \to 0$  "pointwise"

Over some interval:



 $g_n(x)$  still has "spikes" even as  $n \to \infty$ .

In this case, we say " $g_n \to 0$  does <u>not</u> converge uniformly to 0"

For series, we apply the above ideas to the sequence of partial sums:  $S_n(x) = \sum_{k=0}^n f_k(x)$ . AMATH231 covers more on this.

Proposition 5.15. Manipulation of Taylor Series: a few known series regarding

$$f(z) = \sum_{n=0}^{\infty} \frac{f^{(n)}(z_0)}{n!} (z - z_0)^n \quad |z - z_0| < R$$

$$\begin{cases} \frac{1}{1-z} = \sum_{n=0}^{\infty} z^n & R = 1 \quad \text{radius of convergence} \\ e^z = \sum_{n=0}^{\infty} \frac{1}{n!} z^n & R = \infty \end{cases}$$

$$\begin{cases} \cos z = \sum_{n=0}^{\infty} \frac{(-1)^n z^{2n}}{(2n)!} & R = \infty \\ \sin z = \sum_{n=0}^{\infty} \frac{(-1)^n}{(2n+1)!} z^{2n+1} & R = \infty \end{cases}$$

**Example 5.16.** Expand  $e^z$  about z = i.

Solution:  $f(z) = e^z \implies f^{(n)}(i) = e^i$ , so

$$e^z = \sum_{n=0}^{\infty} \frac{e^i}{n!} (z-i)^n$$

Radius? We want

$$\lim_{n \to \infty} \left| \frac{e^i}{(n+1)!} (z-i)^{n+1} \cdot \frac{n!}{e^i} \cdot \frac{1}{(z-i)^n} \right| = \left| \frac{z-i}{n+1} \right| < 1$$

by Ratio test. So the above is true for all z. We have  $R = \infty$ .

**Example 5.17.** Maclaurin Series for  $\frac{1}{8+z^3}$ ?

**Solution:** 

$$\frac{1}{8+z^3} = \frac{1}{8} \cdot \frac{1}{1-\left(\frac{-z^3}{8}\right)} = \frac{1}{8} \sum_{n=0}^{\infty} \left(\frac{-z^3}{8}\right)^n = \sum_{n=0}^{\infty} \frac{(-1)^n z^{3n}}{2^{3n+3}}$$

Radius?

$$\left| \frac{-z^3}{8} \right| < 1 \implies |z|^3 < 2^3 \implies |z| < 2$$

So R=2