view_frames Result Recorded at time: 1462269402.529 world Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 20.203 Hz Average rate: 20.203 Hz Most recent transform: 1462269402.490 (0.040 sec old) Most recent transform: 1462269402.490 (0.040 sec old) Buffer length: 4.950 sec Buffer length: 4.950 sec shoulder_mount camera_link Broadcaster: /robot_state_publisher Average rate: 12.040 Hz Most recent transform: 1462269402.436 (0.094 sec old) Buffer length: 4.900 sec shoulder_link1 Broadcaster: /robot_state_publisher Average rate: 12.040 Hz Most recent transform: 1462269402.436 (0.094 sec old) Buffer length: 4.900 sec shoulder_link2 Broadcaster: /robot_state_publisher Average rate: 12.040 Hz Most recent transform: 1462269402.436 (0.094 sec old) Buffer length: 4.900 sec upper_arm Broadcaster: /robot_state_publisher Average rate: 12.040 Hz Most recent transform: 1462269402.436 (0.094 sec old) Buffer length: 4.900 sec elbow_link4 Broadcaster: /robot_state_publisher Average rate: 12.040 Hz Most recent transform: 1462269402.436 (0.094 sec old) Buffer length: 4.900 sec fore_arm Broadcaster: /robot_state_publisher Average rate: 12.040 Hz Most recent transform: 1462269402.436 (0.094 sec old) Buffer length: 4.900 sec wrist_link6 Broadcaster: /robot_state_publisher Average rate: 12.040 Hz Most recent transform: 1462269402.436 (0.094 sec old) Buffer length: 4.900 sec hand Broadcaster: /robot_state_publisher Average rate: 12.040 Hz Most recent transform: 1462269402.436 (0.094 sec old) Buffer length: 4.900 sec

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