

# Haoliang Wang

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## Education

- 2019- *PhD*, Psychology, UC San Diego  
Advisors: Judith E. Fan, Nadia Polikarpova
- 2015-2019 *BS*, Automation, Xi'an Jiaotong University  
Advisor: Pengju Ren  
Thesis: Spiking neural network learning algorithms based on temporal modulation.

## Research Interests

**Computational Cognitive Science:** intuitive physics, theory acquisition, concept learning  
**Machine Learning:** program synthesis, representation learning, neural-symbolic models

## Publications

- 2021 **Wang, H.**, Polikarpova, N., and Fan, J. (2021). Learning part-based abstractions for visual object concepts. *Proceedings of the 43rd Annual Meeting of the Cognitive Science Society*.
- 2021 **Wang, H.**, Vul, E., Polikarpova, N., and Fan, J. (2021). Theory acquisition as constraint-based program synthesis. *Proceedings of the 43rd Annual Meeting of the Cognitive Science Society*.
- 2021 McCarthy\*, W., Hawkins\*, R., **Wang, H.**, Holdaway, C., and Fan, J. (2021). Learning to communicate about shared procedural abstractions. *Proceedings of the 43rd Annual Meeting of the Cognitive Science Society*.
- 2020 **Wang, H.**, and Fan, J. (2020). Library learning for structured object concepts. *ICML Workshop on Object-Oriented Learning: Perception, Representation, and Reasoning*.

## Talks & Posters

- 2021 Talk: Learning to communicate about shared procedural abstractions at *43rd Annual Meeting of the Cognitive Science Society*.
- 2021 Poster: Learning part-based abstractions for visual object concepts at *43rd Annual Meeting of the Cognitive Science Society*.
- 2021 Poster: Theory acquisition as constraint-based program synthesis at *43rd Annual Meeting of the Cognitive Science Society*.
- 2020 Poster: Library learning for structured object concepts at *ICML Workshop on Object-Oriented Learning: Perception, Representation, and Reasoning*.

## Research experience

- 2019- **UC San Diego, Cognitive Tools Lab**  
*Graduate Student* (Principal Investigator: Judith E. Fan)
- Developed web-based experiments where participants infer alien physics dynamics.
  - Developed an algorithm for learning part-based structures of visual concepts represented as graphics programs; designed an efficient algorithm for learning latent physics theories from observations by augmenting traditional program synthesis techniques with constraints.
- 2018 **MIT, Computational Cognitive Science Group**  
*Research Assistant* (Principal Investigator: Josh Tenenbaum)
- Studied the impact of stimulus strength on the speed and accuracy of perceptual decisions.
  - Adopted both drift-diffusion model (DDM) and POMDP to explain reaction time in human's decision making and planning behavior in mazes under uncertainty.
- 2018 **UC Los Angeles, Center for Vision, Cognition, Learning, and Autonomy**  
*Research Assistant* (Principal Investigator: Song-Chun Zhu)
- Collected a large-scale dataset from Grand Theft Auto (GTA), annotated with rich information including 3D mesh for dynamic environment, human skeleton and pose.
  - Developed an EM-like algorithm to learn both the structure and the parameters of a probabilistic context-free grammar (PCFG) that models human-object interaction in the dataset.
- 2017 **The Chinese University of Hong Kong, Multimedia Laboratory**  
*Research Assistant* (Principal Investigator: Dahua Lin)
- Collected a new sketch-photo dataset containing over 8k sketch-photo face pairs.
  - Developed an ANN model for mapping examples in a weak modality (sketch) to examples in a stronger modality (photo) by inferring the conditional distribution of a semantic representation in the strong modality given an example from the weak modality using GANs.
- 2016 **Chinese Academy of Sciences, Institute of Artificial Intelligence and Robotics**  
*Research Assistant* (Principal Investigator: Ran He)
- Investigated the role of identity-preserving transformation in cross-modality face retrieval.
  - Designed and implemented a human-like Artificial Neural Network (ANN) architecture where a global encoder-decoder network and four local patch networks work jointly to perceive both global structures and local details of faces.

## Selected Academic Honors

- 2018 Samsung Scholarship, First Prize in Mathematical Modeling Contest

## Skills

Modelling and Analysis: Python, Julia, R, MATLAB, C++

Experimental Design: JavaScript, HTML, CSS

Software and Tools: git, Adobe CC,  $\LaTeX$