view\_frames Result Recorded at time: 1592003016.669 world Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 ( 1592003016.669 sec old) Buffer length: 0.000 sec base\_link Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Average rate: 41.739 Hz Most recent transform: 1592003016.624 ( 0.044 sec old) Most recent transform: 0.000 ( 1592003016.669 sec old) Buffer length: 0.000 sec Buffer length: 4.887 sec shoulder\_link Broadcaster: /robot\_state\_publisher Broadcaster: /ur\_hardware\_interface Average rate: 125.255 Hz Average rate: 41.739 Hz Most recent transform: 1592003016.624 ( 0.044 sec old) Most recent transform: 1592003016.656 ( 0.012 sec old) Buffer length: 4.887 sec Buffer length: 4.950 sec upper\_arm\_link tool0\_controller Broadcaster: /robot\_state\_publisher Average rate: 41.739 Hz Most recent transform: 1592003016.624 ( 0.044 sec old) Buffer length: 4.887 sec forearm\_link Broadcaster: /robot\_state\_publisher Average rate: 41.739 Hz Most recent transform: 1592003016.624 ( 0.044 sec old) Buffer length: 4.887 sec wrist\_1\_link Broadcaster: /robot\_state\_publisher Average rate: 41.739 Hz Most recent transform: 1592003016.624 ( 0.044 sec old) Buffer length: 4.887 sec wrist\_2\_link Broadcaster: /robot\_state\_publisher Average rate: 41.739 Hz Most recent transform: 1592003016.624 ( 0.044 sec old) Buffer length: 4.887 sec wrist\_3\_link Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 ( 1592003016.669 sec old) Most recent transform: 0.000 ( 1592003016.669 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec

tool0

base

ee\_link