Recorded at time: 1594323827.118 world Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 ( 1594323827.118 sec old) Buffer length: 0.000 sec base\_link Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Average rate: 10.204 Hz Most recent transform: 1594323827.115 ( 0.003 sec old) Most recent transform: 0.000 ( 1594323827.118 sec old) Buffer length: 0.000 sec Buffer length: 4.900 sec shoulder\_link base Broadcaster: /robot\_state\_publisher Average rate: 10.204 Hz Most recent transform: 1594323827.115 ( 0.003 sec old) Buffer length: 4.900 sec upper\_arm\_link Broadcaster: /robot\_state\_publisher Average rate: 10.204 Hz Most recent transform: 1594323827.115 ( 0.003 sec old) Buffer length: 4.900 sec forearm\_link Broadcaster: /robot\_state\_publisher Average rate: 10.204 Hz Most recent transform: 1594323827.115 ( 0.003 sec old) Buffer length: 4.900 sec wrist\_1\_link Broadcaster: /robot\_state\_publisher Average rate: 10.204 Hz Most recent transform: 1594323827.115 ( 0.003 sec old) Buffer length: 4.900 sec wrist\_2\_link Broadcaster: /robot\_state\_publisher Average rate: 10.204 Hz Most recent transform: 1594323827.115 ( 0.003 sec old) Buffer length: 4.900 sec wrist\_3\_link Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 ( 1594323827.118 sec old) Most recent transform: 0.000 ( 1594323827.118 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec tool0 ee\_link Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 ( 1594323827.118 sec old) Buffer length: 0.000 sec measurement\_tool Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 ( 1594323827.118 sec old) Buffer length: 0.000 sec

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view\_frames Result